I IITSIU diwith DISTII I

SUBCHAPTER D-AIRMEN

PART 60—FLIGHT SIMULATION TRAINING DEVICE INITIAL AND CONTINUING QUALIFICATION AND USE

Sec.

- 60.1 Applicability.
- 60.2 Applicability of sponsor rules to persons who are not sponsors and who are engaged in certain unauthorized activities.
- 60.3 Definitions.
- 60.4 Qualification Performance Standards.
- 60.5 Quality management system.
- 60.7 Sponsor qualification requirements.
- 60.9 Additional responsibilities of the sponsor.
- 60.11 FSTD use.
- 60.13 FSTD objective data requirements.
- 60.14 Special equipment and personnel requirements for qualification of the FSTD.
- 60.15 Initial qualification requirements.
- 60.16 Additional qualifications for a currently qualified FSTD.
- 60.17 Previously qualified FSTDs.
- 60.19 Inspection, continuing qualification evaluation, and maintenance requirements.
- 60.20 Logging FSTD discrepancies.
- 60.21 Interim qualification of FSTDs for new aircraft types or models.
- 60.23 Modifications to FSTDs.
- 60.25 Operation with missing, malfunctioning, or inoperative components.
- 60.27 Automatic loss of qualification and procedures for restoration of qualification.
- 60.29 Other losses of qualification and procedures for restoration of qualification.
- 60.31 Recordkeeping and reporting.
- 60.33 Applications, logbooks, reports, and records: Fraud, falsification, or incorrect statements.
- 60.35 Specific full flight simulator compliance requirements.
- 60.37 FSTD qualification on the basis of a Bilateral Aviation Safety Agreement (BASA).
- APPENDIX A TO PART 60—QUALIFICATION PER-FORMANCE STANDARDS FOR AIRPLANE FULL FLIGHT SIMULATORS
- APPENDIX B TO PART 60—QUALIFICATION PER-FORMANCE STANDARDS FOR AIRPLANE FLIGHT TRAINING DEVICES
- APPENDIX C TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR HELICOPTER FULL FLIGHT SIMULATORS
- APPENDIX D TO PART 60—QUALIFICATION PER-FORMANCE STANDARDS FOR HELICOPTER FLIGHT TRAINING DEVICES

- APPENDIX E TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR QUALITY MANAGEMENT SYSTEMS FOR FLIGHT SIMULATION TRAINING DEVICES
- APPENDIX F TO PART 60—DEFINITIONS AND ABBREVIATIONS FOR FLIGHT SIMULATION TRAINING DEVICES

AUTHORITY: 49 U.S.C. 106(f), 106(g), 40113, and 44701; Pub. L. 111-216, 124 Stat. 2348 (49 U.S.C. 44701 note)

SOURCE: Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, unless otherwise noted.

§ 60.1 Applicability.

- (a) This part prescribes the rules governing the initial and continuing qualification and use of all aircraft flight simulation training devices (FSTD) used for meeting training, evaluation, or flight experience requirements of this chapter for flight crewmember certification or qualification.
- (b) The rules of this part apply to each person using or applying to use an FSTD to meet any requirement of this chapter.
- (c) The requirements of §60.33 regarding falsification of applications, records, or reports also apply to each person who uses an FSTD for training, evaluation, or obtaining flight experience required for flight crewmember certification or qualification under this chapter.

§ 60.2 Applicability of sponsor rules to persons who are not sponsors and who are engaged in certain unauthorized activities.

- (a) The rules of this part that are directed to a sponsor of an FSTD also apply to any person who uses or causes the use of an FSTD when—
- (1) That person knows that the FSTD does not have an FAA-approved sponsor; and
- (2) The use of the FSTD by that person is nonetheless claimed for purposes of meeting any requirement of this chapter or that person knows or should have known that the person's acts or omissions would cause another person to mistakenly credit use of the FSTD for purposes of meeting any requirement of this chapter.

§ 60.3

- (b) A situation in which paragraph (a) of this section would not apply to a person would be when each of the following conditions are met:
- (1) The person sold or leased the FSTD and merely represented to the purchaser or lessee that the FSTD is in a condition in which it should be able to obtain FAA approval and qualification under this part;
- (2) The person does not falsely claim to be the FAA-approved sponsor for the FSTD:
- (3) The person does not falsely make representations that someone else is the FAA-approved sponsor of the FSTD at a time when that other person is not the FAA-approved sponsor of the FSTD; and
- (4) The person's acts or omissions do not cause another person to detrimentally rely on such acts or omissions for the mistaken conclusion that the FSTD is FAA-approved and qualified under this part at the time the FSTD is sold or leased.

§ 60.3 Definitions.

In addition to the definitions in part 1 of this chapter, other terms and definitions applicable to this part are found in appendix F of this part.

§ 60.4 Qualification Performance Standards.

The Qualification Performance Standards (QPS) are published in appendices to this part as follows:

- (a) Appendix A contains the QPS for Airplane Flight Simulators.
- (b) Appendix B contains the QPS for Airplane Flight Training Devices.
- (c) Appendix C contains the QPS for Helicopter Flight Simulators.
- (d) Appendix D contains the QPS for Helicopter Flight Training Devices.
- (e) Appendix E contains the QPS for Quality Management Systems for FSTDs.
- (f) Appendix F contains the QPS for Definitions and Abbreviations for FSTDs.

§ 60.5 Quality management system.

(a) After May 30, 2010, no sponsor may use or allow the use of or offer the use of an FSTD for flight crewmember training or evaluation or for obtaining flight experience to meet any require-

- ment of this chapter unless the sponsor has established and follows a quality management system (QMS), currently approved by the responsible Flight Standards office, for the continuing surveillance and analysis of the sponsor's performance and effectiveness in providing a satisfactory FSTD for use on a regular basis as described in QPS appendix E of this part.
- (b) The QMS program must provide a process for identifying deficiencies in the program and for documenting how the program will be changed to address these deficiencies.
- (c) Whenever the responsible Flight Standards office finds that the QMS program does not adequately address the procedures necessary to meet the requirements of this part, the sponsor must, after notification by the responsible Flight Standards office, change the program so the procedures meet the requirements of this part. Each such change must be approved by the responsible Flight Standards office prior to implementation.
- (d) Within 30 days after the sponsor receives a notice described in paragraph (c) of this section, the sponsor may file a petition with the Executive Director of Flight Standards Service (the Executive Director) for reconsideration of the responsible Flight Standards office finding. The sponsor must address its petition to the Executive Director, Flight Standards Service. Federal Aviation Administration, 800 Independence Ave., SW., Washington, DC 20591. The filing of such a petition to reconsider stays the notice pending a decision by the Executive Director. However, if the Executive Director finds that there is a situation that requires immediate action in the interest of safety in air commerce, he may, upon a statement of the reasons, require a change effective without stay.

[Doc. No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006; Amdt. 60-2, 72 FR 59599, Oct. 22, 2007, as amended by Docket FAA-2018-0119, Amdt. 60-5, 83 FR 9170, Mar. 5, 2018; Docket No. FAA-2022-1355; Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.7 Sponsor qualification requirements.

- (a) A person is eligible to apply to be a sponsor of an FSTD if the following conditions are met:
- (1) The person holds, or is an applicant for, a certificate under part 119, 141, or 142 of this chapter; or holds, or is an applicant for, an approved flight engineer course in accordance with part 63 of this chapter.
- (2) The FSTD will be used, or will be offered for use, in the sponsor's FAA-approved flight training program for the aircraft being simulated as evidenced in a request for evaluation submitted to the responsible Flight Standards office.
- (b) A person is a sponsor if the following conditions are met:
- (1) The person is a certificate holder under part 119, 141, or 142 of this chapter or has an approved flight engineer course in accordance with part 63 of this chapter.
 - (2) The person has—
- (i) Operations specifications authorizing the use of the specific aircraft or set of aircraft and has an FAA-approved training program under which at least one FSTD, simulating the aircraft or set of aircraft and for which the person is the sponsor, is used by the sponsor as described in paragraphs (b)(5) or (b)(6) of this section; or
- (ii) Training specifications or an FAA-approved course of training under which at least one FSTD, simulating that aircraft or set of aircraft and for which the person is the sponsor, is used by the sponsor as described in paragraphs (b)(5) or (b)(6) of this section.
- (3) The person has a quality management system currently approved by the responsible Flight Standards office in accordance with \$60.5.
- (4) The responsible Flight Standards office has accepted the person as the sponsor of the FSTD and that acceptance has not been withdrawn by the FAA.
- (5) At least one FSTD (as referenced in paragraph (b)(2)(i) or (b)(2)(ii) of this section) that is initially qualified on or after May 30, 2008, is used within the sponsor's FAA-approved flight training program for the aircraft or set of aircraft at least once within the 12-month period following the initial/upgrade

evaluation, and at least once within each subsequent 12-month period thereafter.

- (6) At least one FSTD (as referenced in paragraph (b)(2)(i) or (b)(2)(ii) of this section) that was qualified before May 30, 2008, is used within the sponsor's FAA-approved flight training program for the aircraft or set of aircraft at least once within the 12-month period following the first continuing qualification evaluation conducted by the responsible Flight Standards office after May 30, 2008 and at least once within each subsequent 12-month period thereafter.
- (c) If the use requirements of paragraphs (b)(2) and either (b)(5) or (b)(6) of this section are not met, the person will forfeit the right to sponsor that FSTD and that person will not be eligible to apply to sponsor that FSTD for at least 12 calendar months following the expiration of the qualification status.
- (d) In addition to the FSTD described in paragraph (b) of this section, an FSTD sponsor may sponsor any number of other FSTDs regardless of specific aircraft or set of aircraft provided either—
- (1) During the preceding 12-month period, all of the other FSTDs are used within the sponsor's or another certificate holder's FAA-approved flight training program for the aircraft or set of aircraft simulated; or
- (2) The sponsor obtains a written statement at least annually from a qualified pilot who has flown the aircraft or set of aircraft (as appropriate) during the preceding 12-month period stating that the subject FSTD's performance and handling qualities, within the normal operating envelope, represent the aircraft or set of aircraft described in the FAA Type Certificate and the type data sheet, if appropriate. The sponsor must retain the two most current written statements for review by the responsible Flight Standards of

[Doc. No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006; Amdt. 60-2, 72 FR 59599, Oct. 22, 2007, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.9

§ 60.9 Additional responsibilities of the sponsor.

- (a) The sponsor must allow the responsible Flight Standards office upon request to inspect the FSTD as soon as practicable. This inspection may include all records and documents relating to the FSTD, to determine its compliance with this part.
- (b) The sponsor must do the following for each FSTD:
- (1) Establish a mechanism to receive written comments regarding the FSTD and its operation in accordance with the QPS appendix E of this part.
- (2) Post in or adjacent to the FSTD the Statement of Qualification issued by the responsible Flight Standards office. An electronic copy of the Statement of Qualification that may be accessed by an appropriate terminal or display in or adjacent to the FSTD is satisfactory.
- (c) Each sponsor of an FSTD must identify to the responsible Flight Standards office by name, one individual to be the management representative (MR).
- (1) One person may serve as an MR for more than one FSTD, but one FSTD must not have more than one person serving in this capacity.
- (2) Each MR must be an employee of the sponsor with the responsibility and authority to—
- (i) Monitor the on-going qualification of assigned FSTDs to ensure that all matters regarding FSTD qualification are being carried out as provided for in this part:
- (ii) Ensure that the QMS is properly established, implemented, and maintained by overseeing the structure (and modifying where necessary) of the QMS policies, practices, and procedures; and
- (iii) Regularly brief sponsor's management on the status of the on-going FSTD qualification program and the effectiveness and efficiency of the QMS.
- (3) The MR serves as the primary contact point for all matters between the sponsor and the responsible Flight Standards office regarding the qualification of that FSTD as provided for in this part.
- (4) The MR may delegate the duties described in paragraph (c)(2) and (c)(3)

of this section to an individual at each of the sponsor's locations.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 20221

§ 60.11 FSTD use.

No person may use or allow the use of or offer the use of an FSTD for flight crewmember training or evaluation or for obtaining flight experience to meet any of the requirements under this chapter unless, in accordance with the QPS for the specific device, the FSTD meets all of the following:

- (a) Has a single sponsor who is qualified under §60.7. The sponsor may arrange with another person for services of document preparation and presentation, as well as FSTD inspection, maintenance, repair, and servicing; however, the sponsor remains responsible for ensuring that these functions are conducted in a manner and with a result of continually meeting the requirements of this part.
- (b) Is qualified as described in the Statement of Qualification.
- (c) Remains qualified, through satisfactory inspection, continuing qualification evaluations, appropriate maintenance, and use requirements in accordance with this part and the applicable QPS.
- (d) Functions during day-to-day training, evaluation, or flight experience activities with the software and hardware that was evaluated as satisfactory by the responsible Flight Standards office and, if modified, modified only in accordance with the provisions of this part. However, this section does not apply to routine software or hardware changes that do not fall under the requirements of §60.23.
- (e) Is operated in accordance with the provisions and limitations of §60.25.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.13 FSTD objective data requirements.

(a) Except as provided in paragraph (b) and (c) of this section, for the purposes of validating FSTD performance

and handling qualities during evaluation for qualification, the data made available to the responsible Flight Standards office (the validation data package) must include the aircraft manufacturer's flight test data and all relevant data developed after the type certificate was issued (e.g., data developed in response to an airworthiness directive) if such data results from a change in performance, handling qualities, functions, or other characteristics of the aircraft that must be considered for flight crewmember training, evaluation, or for meeting experience requirements of this chapter.

- (b) The validation data package may contain flight test data from a source in addition to or independent of the aircraft manufacturer's data in support of an FSTD qualification, but only if this data is gathered and developed by that source in accordance with flight test methods, including a flight test plan, as described in the applicable QPS.
- (c) The validation data package may also contain predicted data, engineering simulation data, data from pilot owner or pilot operating manuals, or data from public domain sources, provided this data is acceptable to the responsible Flight Standards office. If found acceptable the data may then be used in particular applications for FSTD qualification.
- (d) Data or other material or elements must be submitted in a form and manner acceptable to the responsible Flight Standards office.
- (e) The responsible Flight Standards office may require additional objective data, which may include flight testing if necessary, if the validation data package does not support FSTD qualification requirements as described in this part and the applicable QPS appendix.
- (f) When an FSTD sponsor learns, or is advised by an aircraft manufacturer or other data provider, that an addition to, an amendment to, or a revision of data that may relate to FSTD performance or handling characteristics is available, the sponsor must notify the

responsible Flight Standards office as described in the applicable QPS.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.14 Special equipment and personnel requirements for qualification of the FSTD.

When notified by the responsible Flight Standards office, the sponsor must make available all special equipment and qualified personnel needed to accomplish or assist in the accomplishment of tests during initial qualification, continuing qualification, or special evaluations.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.15 Initial qualification requirements.

- (a) For each FSTD, the sponsor must submit a request to the responsible Flight Standards office to evaluate the FSTD for initial qualification at a specific level and simultaneously request the Training Program Approval Authority (TPAA) forward a concurring letter to the responsible Flight Standards office. The request must be submitted in the form and manner described in the applicable QPS.
- (b) The management representative described in §60.9(c) must sign a statement (electronic signature is acceptable for electronic transmissions) after confirming the following:
- (1) The performance and handling qualities of the FSTD represent those of the aircraft or set of aircraft within the normal operating envelope. This determination must be made by a pilot(s) meeting the requirements of paragraph (d) of this section after having flown all of the Operations Tasks listed in the applicable QPS appendix relevant to the qualification level of the FSTD. Exceptions, if any, must be noted. The name of the person(s) making this determination must be available to the responsible Flight Standards office upon request.
- (2) The FSTD systems and sub-systems (including the simulated aircraft systems) functionally represent those

- (3) The cockpit represents the configuration of the specific type; or aircraft make, model, and series aircraft being simulated, as appropriate. This determination must be made by the pilot(s) described in paragraph (b)(1) of this section, or by a person(s) trained on the configuration and operation of the aircraft simulated. Exceptions, if any, must be noted. The name of the person(s) making this determination must be available to the responsible Flight Standards office upon request.
- (c) Except for those FSTDs previously qualified and described in §60.17, each FSTD evaluated for initial qualification must meet the standard that is in effect at the time of the evaluation. However—
- (1) If the FAA publishes a change to the existing standard or publishes a new standard for the evaluation for initial qualification, a sponsor may request that the responsible Flight Standards office apply the standard that was in effect when an FSTD was ordered for delivery if the sponsor—
- (i) Within 30 days of the publication of the change to the existing standard or publication of the new standard, notifies the responsible Flight Standards office that an FSTD has been ordered;
- (ii) Within 90 days of the responsible Flight Standards office notification described in paragraph (c)(1)(i) of this section, requests that the standard in effect at the time the order was placed be used for the evaluation for initial qualification; and
- (iii) The evaluation is conducted within 24 months following the publication of the change to the existing standard or publication of the new standard.

- (2) This notification must include a description of the FSTD; the anticipated qualification level of the FSTD; the make, model, and series of aircraft simulated; and any other pertinent information.
- (3) Any tests, tolerances, or other requirements that are current at the time of the evaluation may be used during the initial evaluation, at the request of the sponsor, if the sponsor provides acceptable updates to the required qualification test guide.
- (4) The standards used for the evaluation for initial qualification will be used for all subsequent evaluations of the FSTD.
- (5) An FSTD sponsor or FSTD manufacturer may submit a request to the Administrator for approval of a deviation from the QPS requirements as defined in Appendix A through Appendix D of this part.
- (i) Requests for deviation must be submitted in a form and manner acceptable to the Administrator and must provide sufficient justification that the deviation meets or exceeds the testing requirements and tolerances as specified in the part 60 QPS or will otherwise not adversely affect the fidelity and capability of the FSTDs evaluated and qualified under the deviation.
- (ii) The Administrator may consider deviation from the minimum requirements tables, the objective testing tables, the functions and subjective testing tables, and other supporting tables and requirements in the part 60 QPS.
- (iii) Deviations may be issued to an FSTD manufacturer for the initial qualification of multiple FSTDs, subject to terms and limitations as determined by Administrator. Approved deviations will become a part of the permanent qualification basis of the individual FSTD and will be noted in the FSTD's Statement of Qualification.
- (iv) If the FAA publishes a change to the existing part 60 standards as described in paragraph (c)(1) of this section or issues an FSTD Directive as described in §60.23(b), which conflicts with or supersedes an approved deviation, the Administrator may terminate or revise a grant of deviation authority issued under this paragraph.

- (d) The pilot(s) who contributes to the confirmation statement required by paragraph (b) of this section must—
 - (1) Be designated by the sponsor; and
 - (2) Be qualified in-
- (i) The aircraft or set of aircraft being simulated; or
- (ii) For aircraft not yet issued a type certificate, or aircraft not previously operated by the sponsor or not having previous FAA-approved training programs conducted by the sponsor, an aircraft similar in size and configuration.
- (e) The subjective tests that form the basis for the statements described in paragraph (b) of this section and the objective tests referenced in paragraph (f) of this section must be accomplished at the sponsor's training facility or other sponsor designated location where training will take place, except as provided for in the applicable QPS.
- (f) The person seeking to qualify the FSTD must provide the responsible Flight Standards office access to the FSTD for the length of time necessary for the responsible Flight Standards office to complete the required evaluation of the FSTD for initial qualification, which includes the conduct and evaluation of objective and subjective tests, including general FSTD requirements, as described in the applicable QPS, to determine that the FSTD meets the standards in that QPS.
- (g) When the FSTD passes an evaluation for initial qualification, the responsible Flight Standards office issues a Statement of Qualification that includes all of the following:
 - (1) Identification of the sponsor.
- (2) Identification of the make, model, and series of the aircraft or set of aircraft being simulated.
- (3) Identification of the configuration of the aircraft or set of aircraft being simulated (e.g., engine model or models, flight instruments, or navigation or other systems).
- (4) A statement that the FSTD is qualified as either a full flight simulator or a flight training device.
- (5) Identification of the qualification level of the FSTD.
- (6) A statement that (with the exception of the noted exclusions for which the FSTD has not been subjectively

- tested by the sponsor or the responsible Flight Standards office and for which qualification is not sought) the qualification of the FSTD includes the tasks set out in the applicable QPS appendix relevant to the qualification level of the FSTD.
- (7) A statement referencing any deviations that have been granted and included in the permanent qualification basis of the FSTD.
- (h) After the responsible Flight Standards office completes the evaluation for initial qualification, the sponsor must update the Qualification Test Guide (QTG), with the results of the FAA-witnessed tests together with the results of all the objective tests described in the applicable QPS.
- (i) Upon issuance of the Statement of Qualification the updated QTG becomes the Master Qualification Test Guide (MQTG). The MQTG must be made available to the responsible Flight Standards office upon request.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket FAA-2014-0391, Amdt. 60-4, 81 FR 18217, Mar. 30, 2016; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§60.16 Additional qualifications for a currently qualified FSTD.

- (a) A currently qualified FSTD is required to undergo an additional qualification process if a user intends to use the FSTD for meeting training, evaluation, or flight experience requirements of this chapter beyond the qualification issued for that FSTD. This process consists of the following:
 - (1) The sponsor:
- (i) Must submit to the responsible Flight Standards office all modifications to the MQTG that are required to support the additional qualification.
- (ii) Must describe to the responsible Flight Standards office all modifications to the FSTD that are required to support the additional qualification.
- (iii) Must submit to the responsible Flight Standards office a confirmation statement as described in §60.15(c) that a pilot, designated by the sponsor in accordance with §60.15(d), has subjectively evaluated the FSTD in those areas not previously evaluated.
- (2) The FSTD must successfully pass an evaluation—

§ 60.17

- (i) Consisting of all the elements of an initial evaluation for qualification in those circumstances where the responsible Flight Standards office has determined that all the elements of an initial evaluation for qualification is necessary; or
- (ii) Consisting of those elements of an initial evaluation for qualification designated as necessary by the responsible Flight Standards office.
- (b) In making the determinations described in paragraph (a)(2) of this section, the responsible Flight Standards office considers factors including the existing qualification of the FSTD, any modifications to the FSTD hardware or software that are involved, and any additions or modifications to the MQTG.
- (c) The FSTD is qualified for the additional uses when the responsible Flight Standards office issues an amended Statement of Qualification in accordance with §60.15(h).
- (d) The sponsor may not modify the FSTD except as described in §60.23.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.17 Previously qualified FSTDs.

- (a) Unless otherwise specified by an FSTD Directive, further referenced in the applicable QPS, or as specified in paragraph (e) of this section, an FSTD qualified before May 31, 2016 will retain its qualification basis as long as it continues to meet the standards, including the objective test results recorded in the MQTG and subjective tests, under which it was originally evaluated, regardless of sponsor. The sponsor of such an FSTD must comply with the other applicable provisions of this part.
- (b) For each FSTD qualified before May 30, 2008, no sponsor may use or allow the use of or offer the use of such an FSTD after May 30, 2014 for flight crewmember training, evaluation or flight experience to meet any of the requirements of this chapter, unless that FSTD has been issued a Statement of Qualification, including the Configuration List and the List of Qualified Tasks in accordance with the procedures set out in the applicable QPS.
- (c) If the FSTD qualification is lost under § 60.27 and—

- (i) Restored under §60.27 in less than (2) years, then the qualification basis (in terms of objective tests and subjective tests) for the re-qualification will be those against which the FSTD was originally evaluated and qualified.
- (ii) Not restored under §60.27 for two (2) years or more, then the qualification basis (in terms of objective tests and subjective tests) for the re-qualification will be those standards in effect and current at the time of re-qualification application.
- (d) Except as provided in paragraph (e) of this section, any change in FSTD qualification level initiated on or after May 30, 2008 requires an evaluation for initial qualification in accordance with this part.
- (e) A sponsor may request that an FSTD be permanently downgraded. In such a case, the responsible Flight Standards office may downgrade a qualified FSTD without requiring and without conducting an initial evaluation for the new qualification level. Subsequent continuing qualification evaluations will use the existing MQTG, modified as necessary to reflect the new qualification level.
- (f) When the sponsor has appropriate validation data available and receives approval from the responsible Flight Standards office, the sponsor may adopt tests and associated tolerances described in the current qualification standards as the tests and tolerances applicable for the continuing qualification of a previously qualified FSTD. The updated test(s) and tolerance(s) must be made a permanent part of the MQTG.

[Doc. No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006; Amdt. 60-2, 72 FR 59599, Oct. 22, 2007, as amended by Docket FAA-2014-0391, Amdt. 60-4, 81 FR 18218, Mar. 30, 2016; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.19 Inspection, continuing qualification evaluation, and maintenance requirements.

(a) Inspection. No sponsor may use or allow the use of or offer the use of an FSTD for flight crewmember training, evaluation, or flight experience to meet any of the requirements of this chapter unless the sponsor does the following:

- (1) Accomplishes all appropriate objective tests each year as specified in the applicable QPS.
- (2) Completes a functional preflight check within the preceding 24 hours.
- (b) Continuing qualification evaluation.
 (1) This evaluation consists of objective tests, and subjective tests, including general FSTD requirements, as described in the applicable QPS or as may be amended by an FSTD Directive.
- (2) The sponsor must contact the responsible Flight Standards office to schedule the FSTD for continuing qualification evaluations not later than 60 days before the evaluation is due.
- (3) The sponsor must provide the responsible Flight Standards office responsible Flight Standards office access to the objective test results in the MQTG and access to the FSTD for the length of time necessary for the responsible Flight Standards office to complete the required continuing qualification evaluations.
- (4) The frequency of the responsible Flight Standards office-conducted continuing qualification evaluations for each FSTD will be established by the responsible Flight Standards office and specified in the Statement of Qualification.
- (5) Continuing qualification evaluations conducted in the 3 calendar months before or after the calendar month in which these continuing qualification evaluations are required will be considered to have been conducted in the calendar month in which they were required.
- (6) No sponsor may use or allow the use of or offer the use of an FSTD for flight crewmember training or evaluation or for obtaining flight experience for the flight crewmember to meet any requirement of this chapter unless the FSTD has passed a responsible Flight Standards office-conducted continuing qualification evaluation within the time frame specified in the Statement of Qualification or within the grace period as described in paragraph (b)(5) of this section.
- (c) Maintenance. The sponsor is responsible for continuing corrective and preventive maintenance on the FSTD to ensure that it continues to meet the requirements of this part and the appli-

- cable QPS appendix. No sponsor may use or allow the use of or offer the use of an FSTD for flight crewmember training, evaluation, or flight experience to meet any of the requirements of this chapter unless the sponsor does the following:
 - (1) Maintains a discrepancy log.
- (2) Ensures that, when a discrepancy is discovered, the following requirements are met:
- (i) A description of each discrepancy is entered in the log and remains in the log until the discrepancy is corrected as specified in §60.25(b).
- (ii) A description of the corrective action taken for each discrepancy, the identity of the individual taking the action, and the date that action is taken is entered in the log.
- (iii) The discrepancy log is kept in a form and manner acceptable to the Administrator and is kept in or adjacent to the FSTD. An electronic log that may be accessed by an appropriate terminal or display in or adjacent to the FSTD is satisfactory.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket FAA-2014-0391, Amdt. 60-4, 81 FR 18218, Mar. 30, 2016; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 20221

§ 60.20 Logging FSTD discrepancies.

Each instructor, check airman, or representative of the Administrator conducting training, evaluation, or flight experience, and each person conducting the preflight inspection who discovers a discrepancy, including any missing, malfunctioning, or inoperative components in the FSTD, must write or cause to be written a description of that discrepancy into the discrepancy log at the end of the FSTD preflight or FSTD use session.

§ 60.21 Interim qualification of FSTDs for new aircraft types or models.

(a) A sponsor may apply for and the responsible Flight Standards office may issue an interim qualification level for an FSTD for a new type or model of aircraft, even though the aircraft manufacturer's aircraft data package is preliminary, if the sponsor provides the following to the satisfaction of the responsible Flight Standards office—

§ 60.23

- (1) The aircraft manufacturer's data, which consists of at least predicted data, validated by a limited set of flight test data;
- (2) The aircraft manufacturer's description of the prediction methodology used to develop the predicted data; and
 - (3) The QTG test results.
- (b) An FSTD that has been issued interim qualification is deemed to have been issued initial qualification unless the responsible Flight Standards office rescinds the qualification. Interim qualification terminates two years after its issuance, unless the responsible Flight Standards office determines that specific conditions warrant otherwise.
- (c) Within twelve months of the release of the final aircraft data package by the aircraft manufacturer, but no later than two years after the issuance of the interim qualification status, the sponsor must apply for initial qualification in accordance with §60.15 based on the final aircraft data package approved by the aircraft manufacturer, unless the responsible Flight Standards office determines that specific conditions warrant otherwise.
- (d) An FSTD with interim qualification may be modified only in accordance with §60.23.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 20221

§ 60.23 Modifications to FSTDs.

- (a) Description of a modification. For the purposes of this part, an FSTD is said to have been modified when:
- (1) Equipment or devices intended to simulate aircraft appliances are added to or removed from FSTD, which change the Statement of Qualification or the MQTG; or
- (2) Changes are made to either software or hardware that are intended to impact flight or ground dynamics; changes are made that impact performance or handling characteristics of the FSTD (including motion, visual, control loading, or sound systems for those FSTD levels requiring sound tests and measurements); or changes are made to the MQTG. Changes to the MQTG which do not affect required ob-

jective testing results or validation data approved during the initial evaluation of the FSTD are not considered modifications under this section.

- (b) FSTD Directive. When the FAA determines that FSTD modification is necessary for safety of flight reasons, the sponsor of each affected FSTD must ensure that the FSTD is modified according to the FSTD Directive regardless of the original qualification standards applicable to any specific FSTD.
- (c) Using the modified FSTD. The sponsor may not use, or allow the use of, or offer the use of, the FSTD with the proposed modification for flight crewmember training or evaluation or for obtaining flight experience for the flight crewmember to meet any requirement of this chapter unless:
- (1) The sponsor has notified the responsible Flight Standards office and the TPAA of their intent to incorporate the proposed modification, and one of the following has occurred;
- (i) Twenty-one days have passed since the sponsor notified the responsible Flight Standards office and the TPAA of the proposed modification and the sponsor has not received any response from either the responsible Flight Standards office or the TPAA;
- (ii) Twenty-one days have passed since the sponsor notified the responsible Flight Standards office and the TPAA of the proposed modification and one has approved the proposed modification and the other has not responded;
- (iii) Fewer than twenty-one days have passed since the sponsor notified the responsible Flight Standards office and the TPAA of the proposed modification and the responsible Flight Standards office and TPAA both approve the proposed modification;
- (iv) The sponsor has successfully completed any evaluation the responsible Flight Standards office may require in accordance with the standards for an evaluation for initial qualification or any part thereof before the modified FSTD is placed in service.
- (2) The notification is submitted with the content as, and in a form and manner as, specified in the applicable QPS.
- (d) User notification. When a modification is made to an FSTD that affects

the Statement of Qualification, the sponsor must post an addendum to the Statement of Qualification until such time as a permanent, updated statement is posted.

(e) MQTG update. The MQTG must be updated with current objective test results in accordance with §60.15(h) and (i) and appropriate objective data in accordance with §60.13, each time an FSTD is modified and an objective test or other MQTG section is affected by the modification. If an FSTD Directive is the cause of this update, the direction to make the modification and the record of the modification completion must be filed in the MQTG.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket FAA-2014-0391, Amdt. 60-4, 81 FR 18218, Mar. 30, 2016; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.25 Operation with missing, malfunctioning, or inoperative components.

- (a) No person may knowingly use or allow the use of or misrepresent the capability of an FSTD for any maneuver, procedure, or task that is to be accomplished to meet training, evaluation, or flight experience requirements of this chapter for flight crewmember certification or qualification when there is a missing, malfunctioning, or inoperative (MMI) component that is required to be present and correctly operate for the satisfactory completion of that maneuver, procedure, or task.
- (b) Each MMI component as described in paragraph (a) of this section, or any MMI component installed and required to operate correctly to meet the current Statement of Qualification, must be repaired or replaced within 30 calendar days, unless otherwise required or authorized by the responsible Flight Standards office.
- (c) A list of the current MMI components must be readily available in or adjacent to the FSTD for review by users of the device. Electronic access to this list via an appropriate terminal or display in or adjacent to the FSTD is satisfactory. The discrepancy log may be used to satisfy this requirement provided each currently MMI

component is listed in the discrepancy log.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§ 60.27 Automatic loss of qualification and procedures for restoration of qualification.

- (a) An FSTD qualification is automatically lost when any of the following occurs:
- (1) The FSTD is not used in the sponsor's FAA-approved flight training program in accordance with 60.7(b)(5) or (b)(6) and the sponsor does not obtain and maintain the written statement as described in 60.7(d)(2).
- (2) The FSTD is not inspected in accordance with §60.19.
- (3) The FSTD is physically moved from one location and installed in a different location, regardless of distance.
- (4) The MQTG is missing or otherwise not available and a replacement is not made within 30 days.
- (b) If FSTD qualification is lost under paragraph (a) of this section, qualification is restored when either of the following provisions is met:
- (1) The FSTD successfully passes an evaluation:
- (i) For initial qualification, in accordance with §§ 60.15 and 60.17(c) in those circumstances where the responsible Flight Standards office has determined that a full evaluation for initial qualification is necessary; or
- (ii) For those elements of an evaluation for initial qualification, in accordance with §§ 60.15 and 60.17(c), as determined to be necessary by the responsible Flight Standards office.
- (2) The responsible Flight Standards office advises the sponsor that an evaluation is not necessary.
- (c) In making the determinations described in paragraph (b) of this section, the responsible Flight Standards office considers factors including the number of continuing qualification evaluations missed, the number of sponsor-conducted quarterly inspections missed,

§ 60.29

and the care that had been taken of the device since the last evaluation.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§60.29 Other losses of qualification and procedures for restoration of qualification.

- (a) Except as provided in paragraph (c) of this section, when the responsible Flight Standards office determines that the FSTD no longer meets qualification standards, the following procedure applies:
- (1) The responsible Flight Standards office notifies the sponsor in writing that the FSTD no longer meets some or all of its qualification standards.
- (2) The responsible Flight Standards office sets a reasonable period (but not less than 7 days) within which the sponsor may submit written information, views, and arguments on the FSTD qualification.
- (3) After considering all material presented, the responsible Flight Standards office notifies the sponsor about the determination with regard to the qualification of the FSTD.
- (4) When the responsible Flight Standards office notifies the sponsor that some or all of the FSTD is no longer qualified, the action described in the notification becomes effective not less than 30 days after the sponsor receives that notice unless—
- (i) The responsible Flight Standards office finds under paragraph (c) of this section that there is an emergency requiring immediate action with respect to safety in air commerce; or
- (ii) The sponsor petitions the Executive Director of Flight Standards Service for reconsideration of the responsible Flight Standards office finding under paragraph (b) of this section.
- (b) When a sponsor seeks reconsideration of a decision from the responsible Flight Standards office concerning the FSTD qualification, the following procedure applies:
- (1) The sponsor must petition for reconsideration of that decision within 30 days of the date that the sponsor receives a notice that some or all of the FSTD is no longer qualified.

- (2) The sponsor must address its petition to the Executive Director, Flight Standards Service, Federal Aviation Administration, 800 Independence Ave., SW., Washington, DC 20591.
- (3) A petition for reconsideration, if filed within the 30-day period, suspends the effectiveness of the determination by the responsible Flight Standards office that the FSTD is no longer qualified unless the responsible Flight Standards office has found, under paragraph (c) of this section, that an emergency exists requiring immediate action with respect to safety in air commerce.
- (c) If the responsible Flight Standards office find that an emergency exists requiring immediate action with respect to safety in air commerce that makes the procedures set out in this section impracticable or contrary to the public interest:
- (1) The responsible Flight Standards office withdraws qualification of some or all of the FSTD and makes the withdrawal of qualification effective on the day the sponsor receives notice of it.
- (2) In the notice to the sponsor, the responsible Flight Standards office articulates the reasons for its finding that an emergency exists requiring immediate action with respect to safety in air transportation or air commerce or that makes it impracticable or contrary to the public interest to stay the effectiveness of the finding.
- (d) FSTD qualification lost under paragraph (a) or (c) of this section may be restored when either of the following provisions are met:
- (1) The FSTD successfully passes an evaluation for initial qualification, in accordance with §§ 60.15 and 60.17(c) in those circumstances where the responsible Flight Standards office has determined that a full evaluation for initial qualification is necessary; or
- (2) The FSTD successfully passes an evaluation for those elements of an initial qualification evaluation, in accordance with §§ 60.15 and 60.17(c), as determined to be necessary by the responsible Flight Standards office.
- (e) In making the determinations described in paragraph (d) of this section, the responsible Flight Standards office considers factors including the reason

for the loss of qualification, any repairs or replacements that may have to have been completed, the number of continuing qualification evaluations missed, the number of sponsor-conducted quarterly inspections missed, and the care that had been taken of the device since the loss of qualification.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket FAA-2018-0119, Amdt. 60-5, 83 FR 9170, Mar. 5, 2018; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

§60.31 Recordkeeping and reporting.

- (a) The FSTD sponsor must maintain the following records for each FSTD it sponsors:
- (1) The MQTG and each amendment thereto.
- (2) A record of all FSTD modifications affected under §60.23 since the issuance of the original Statement of Qualification.
 - (3) A copy of all of the following:
- (i) Results of the qualification evaluations (initial and each upgrade) since the issuance of the original Statement of Qualification.
- (ii) Results of the objective tests conducted in accordance with §60.19(a) for a period of 2 years.
- (iii) Results of the previous three continuing qualification evaluations, or the continuing qualification evaluations from the previous 2 years, whichever covers a longer period.
- (iv) Comments obtained in accordance with §60.9(b) for a period of at least 90 days.
- (4) A record of all discrepancies entered in the discrepancy log over the previous 2 years, including the following:
- (i) A list of the components or equipment that were or are missing, malfunctioning, or inoperative.
- (ii) The action taken to correct the discrepancy.
- (iii) The date the corrective action was taken.
- (iv) The identity of the person determining that the discrepancy has been corrected.
- (b) The records specified in this section must be maintained in plain language form or in coded form if the coded form provides for the preservation and retrieval of information in a

manner acceptable to the responsible Flight Standards office.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 20221

§ 60.33 Applications, logbooks, reports, and records: Fraud, falsification, or incorrect statements.

- (a) No person may make, or cause to be made, any of the following:
- (1) A fraudulent or intentionally false statement in any application or any amendment thereto, or any other report or test result required by this part.
- (2) A fraudulent or intentionally false statement in or a known omission from any record or report that is kept, made, or used to show compliance with this part, or to exercise any privileges under this chapter.
- (3) Any reproduction or alteration, for fraudulent purpose, of any report, record, or test result required under this part.
- (b) The commission by any person of any act prohibited under paragraph (a) of this section is a basis for any one or any combination of the following:
 - (1) A civil penalty.
- (2) Suspension or revocation of any certificate held by that person that was issued under this chapter.
- (3) The removal of FSTD qualification and approval for use in a training program.
- (c) The following may serve as a basis for removal of qualification of an FSTD including the withdrawal of approval for use of an FSTD; or denying an application for a qualification:
- (1) An incorrect statement, upon which the FAA relied or could have relied, made in support of an application for a qualification or a request for approval for use.
- (2) An incorrect entry, upon which the FAA relied or could have relied, made in any logbook, record, or report that is kept, made, or used to show compliance with any requirement for an FSTD qualification or an approval for use.

§ 60.35

§ 60.35 Specific full flight simulator compliance requirements.

(a) No device will be eligible for initial or upgrade qualification to a FFS at Level C or Level D under this part unless it includes the equipment and appliances installed and operating to the extent necessary for the issuance of an airman certificate or rating.

(b) No device will be eligible for initial or upgrade qualification to a FFS at Level A or Level B under this part unless it includes the equipment and appliances installed and operating to the extent necessary for the training, testing, and/or checking that comprise the simulation portion of the requirements for issuance of an airman certificate or rating.

§ 60.37 FSTD qualification on the basis of a Bilateral Aviation Safety Agreement (BASA).

(a) The evaluation and qualification of an FSTD by a contracting State to the Convention on International Civil Aviation for the sponsor of an FSTD located in that contracting State may be used as the basis for issuing a U.S. statement of qualification (see applicable QPS, attachment 4, figure 4) by the responsible Flight Standards office to the sponsor of that FSTD in accordance with—

- (1) A BASA between the United States and the Contracting State that issued the original qualification; and
- (2) A Simulator Implementation Procedure (SIP) established under the BASA.
- (b) The SIP must contain any conditions and limitations on validation and issuance of such qualification by the U.S.

[Docket No. FAA-2002-12461, 71 FR 63426, Oct. 30, 2006, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 2022]

APPENDIX A TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR AIR-PLANE FULL FLIGHT SIMULATORS

BEGIN INFORMATION

This appendix establishes the standards for Airplane FFS evaluation and qualification. The Flight Standards Service is responsible for the development, application, and implementation of the standards contained within this appendix. The procedures and criteria specified in this appendix will be used by the responsible Flight Standards office, when conducting airplane FFS evaluations.

TABLE OF CONTENTS

- 1. Introduction.
- 2. Applicability (§§ 60.1 and 60.2).
- 3. Definitions (§ 60.3).
- 4. Qualification Performance Standards (§60.4).
- 5. Quality Management System (§60.5).
- 6. Sponsor Qualification Requirements (§60.7).
- 7. Additional Responsibilities of the Sponsor (\$60.9).
- 8. FFS Use (§60.11).
- 9. FFS Objective Data Requirements (§60.13).
- Special Equipment and Personnel Requirements for Qualification of the FFS (§60.14).
- 11. Initial (and Upgrade) Qualification Requirements (§ 60.15).
- 12. Additional Qualifications for a Currently Qualified FFS (§ 60.16).
- 13. Previously Qualified FFSs (§ 60.17).
- Inspection, Continuing Qualification Evaluation, and Maintenance Requirements (§60.19).
- 15. Logging FFS Discrepancies (§60.20).
- 16. Interim Qualification of FFSs for New Airplane Types or Models (§ 60.21).
- 17. Modifications to FFSs (§ 60.23).
- 18. Operations With Missing, Malfunctioning, or Inoperative Components (§ 60.25).
- 19. Automatic Loss of Qualification and Procedures for Restoration of Qualification (§ 60.27).
- 20. Other Losses of Qualification and Procedures for Restoration of Qualification (§60.29).
- 21. Record Keeping and Reporting (§60.31).
- Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements (§60.33).
- 23. Specific FFS Compliance Requirements (§60.35).
- 24. [Reserved]
- 25. FFS Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA) (§60.37).
- Attachment 1 to Appendix A to Part 60—General Simulator Requirements.
- Attachment 2 to Appendix A to Part 60—FFS Objective Tests.
- Attachment 3 to Appendix A to Part 60—Simulator Subjective Evaluation.
- Attachment 4 to Appendix A to Part 60—Sample Documents.
- Attachment 5 to Appendix A to Part 60—Simulator Qualification Requirements for Windshear Training Program Use.
- Attachment 6 to Appendix A to Part 60—FSTD Directives Applicable to Airplane Flight Simulators.

1. Introduction

BEGIN INFORMATION

- a. This appendix contains background information as well as regulatory and informative material as described later in this section. To assist the reader in determining what areas are required and what areas are permissive, the text in this appendix is divided into two sections: "QPS Requirements" and "Information." The QPS Requirements sections contain details regarding compliance with the part 60 rule language. These details are regulatory, but are found only in this appendix. The Information sections contain material that is advisory in nature, and designed to give the user general information about the regulation.
- b. [Reserved]
- c. The responsible Flight Standards office encourages the use of electronic media for all communication, including any record, report, request, test, or statement required by this appendix. The electronic media used must have adequate security provisions and be acceptable to the responsible Flight Standards office.
 - d. Related Reading References.
 - (1) 14 CFR part 60.
 - (2) 14 CFR part 61.
 - (3) 14 CFR part 63.
 - (4) 14 CFR part 119.(5) 14 CFR part 121.
 - (6) 14 CFR part 121.
 - (7) 14 CFR part 135.
 - (8) 14 CFR part 141.
 - (9) 14 CFR part 142.
- (10) AC 120-28, as amended, Criteria for Approval of Category III Landing Weather Minima.
- (11) AC 120-29, as amended, Criteria for Approving Category I and Category II Landing Minima for part 121 operators.
- (12) AC 120-35, as amended, Flightcrew Member, Line Operational Simulations: Line-Oriented Flight Training, Special Purpose Operational Training, Line Operational Evaluation.
- $\left(13\right)$ AC 120–40, as amended, Airplane Simulator Qualification.
- (14) AC 120-41, as amended, Criteria for Operational Approval of Airborne Wind Shear Alerting and Flight Guidance Systems.
- (15) AC 120-57, as amended, Surface Movement Guidance and Control System (SMGCS).
- $(16)~\mathrm{AC}~150/5300\text{--}13,$ as amended, Airport Design.
- (17) AC 150/5340-1, as amended, Standards for Airport Markings.

- (18) AC 150/5340-4, as amended, Installation Details for Runway Centerline Touchdown Zone Lighting Systems.
- (19) AC 150/5340-19, as amended, Taxiway Centerline Lighting System.
- (20) AC 150/5340-24, as amended, Runway and Taxiway Edge Lighting System.
- (21) AC 150/5345-28, as amended, Precision Approach Path Indicator (PAPI) Systems.
- (22) International Air Transport Association document, "Flight Simulation Training Device Design and Performance Data Requirements," as amended.
- (23) AC 25-7, as amended, Flight Test Guide for Certification of Transport Category Airplanes.
- (24) AC 23–8, as amended, Flight Test Guide for Certification of Part 23 Airplanes.
- (25) International Civil Aviation Organization (ICAO) Manual of Criteria for the Qualification of Flight Simulation Training Devices, as amended.
- (26) Aeroplane Flight Simulation Training Device Evaluation Handbook, Volume I, as amended and Volume II, as amended, The Royal Aeronautical Society, London, UK.
- (27) FAA Airman Certification Standards and Practical Test Standards for Airline Transport Pilot, Type Ratings, Commercial Pilot. and Instrument Ratings
- (28) The FAA Aeronautical Information Manual (AIM). An electronic version of the AIM is on the Internet at http://www.faa.gov/atpubs.
- (29) Aeronautical Radio, Inc. (ARINC) document number 436, titled *Guidelines For Electronic Qualification Test Guide* (as amended).
- (30) Aeronautical Radio, Inc. (ARINC) document 610, Guidance for Design and Integration of Aircraft Avionics Equipment in Simulators (as amended).

END INFORMATION

2. Applicability (§§ 60.1 and 60.2)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.1, Applicability, or to §60.2, Applicability of sponsor rules to persons who are not sponsors and who are engaged in certain unauthorized activities.

END INFORMATION

3. Definitions ($\S60.3$)

BEGIN INFORMATION

See Appendix F of this part for a list of definitions and abbreviations from part 1 and

Pt. 60, App. A

part 60, including the appropriate appendices of part 60.

END INFORMATION

4. QUALIFICATION PERFORMANCE STANDARDS (§ 60.4)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.4, Qualification Performance Standards.

END INFORMATION

5. Quality Management System (§60.5)

BEGIN INFORMATION

See Appendix E of this part for additional regulatory and informational material regarding Quality Management Systems.

END INFORMATION

6. Sponsor Qualification Requirements $(\S 60.7)$

BEGIN INFORMATION

- a. The intent of the language in §60.7(b) is to have a specific FFS, identified by the sponsor, used at least once in an FAA-approved flight training program for the airplane simulated during the 12-month period described. The identification of the specific FFS may change from one 12-month period to the next 12-month period as long as the sponsor sponsors and uses at least one FFS at least once during the prescribed period. No minimum number of hours or minimum FFS periods are required.
- b. The following examples describe acceptable operational practices:
 - (1) Example One.
- (a) A sponsor is sponsoring a single, specific FFS for its own use, in its own facility or elsewhere—this single FFS forms the basis for the sponsorship. The sponsor uses that FFS at least once in each 12-month period in the sponsor's FAA-approved flight training program for the airplane simulated. This 12-month period is established according to the following schedule:
- (i) If the FFS was qualified prior to May 30, 2008, the 12-month period begins on the date of the first continuing qualification evaluation conducted in accordance with \$60.19 after May 30, 2008, and continues for each subsequent 12-month period;

- (ii) A device qualified on or after May 30, 2008, will be required to undergo an initial or upgrade evaluation in accordance with \$60.15. Once the initial or upgrade evaluation is complete, the first continuing qualification evaluation will be conducted within 6 months. The 12-month continuing qualification evaluation cycle begins on that date and continues for each subsequent 12-month period.
- (b) There is no minimum number of hours of FFS use required.
- (c) The identification of the specific FFS may change from one 12-month period to the next 12-month period as long as the sponsor sponsors and uses at least one FFS at least once during the prescribed period.
 - (2) Example Two.
- (a) A sponsor sponsors an additional number of FFSs, in its facility or elsewhere. Each additionally sponsored FFS must be—
- (i) Used by the sponsor in the sponsor's FAA-approved flight training program for the airplane simulated (as described in §60.7(d)(1));

OR

(ii) Used by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the airplane simulated (as described in §60.7(d)(1)). This 12-month period is established in the same manner as in example one;

OR

- (iii) Provided a statement each year from a qualified pilot (after having flown the airplane, not the subject FFS or another FFS, during the preceding 12-month period), stating that the subject FFS's performance and handling qualities represent the airplane (as described in §60.7(d)(2)). This statement is provided at least once in each 12-month period established in the same manner as in example one.
- (b) No minimum number of hours of FFS use is required.
- (3) Example Three.
- (a) A sponsor in New York (in this example, a Part 142 certificate holder) establishes "satellite" training centers in Chicago and Moscow.
- (b) The satellite function means that the Chicago and Moscow centers must operate under the New York center's certificate (in accordance with all of the New York center's practices, procedures, and policies; e.g., instructor and/or technician training/checking requirements, record keeping, QMS program).
- (c) All of the FFSs in the Chicago and Moscow centers could be dry-leased (i.e., the certificate holder does not have and use FAA-approved flight training programs for the FFSs in the Chicago and Moscow centers) because—
- (i) Each FFS in the Chicago center and each FFS in the Moscow center is used at least once each 12-month period by another

Federal Aviation Administration, DOT

FAA certificate holder in that other certificate holder's FAA-approved flight training program for the airplane (as described in §60.7(d)(1));

OR.

(ii) A statement is obtained from a qualified pilot (having flown the airplane, not the subject FFS or another FFS, during the preceding 12-month period) stating that the performance and handling qualities of each FFS in the Chicago and Moscow centers represents the airplane (as described in §60.7(d)(2)).

END INFORMATION

7. Additional Responsibilities of the Sponsor (§ 60.9)

BEGIN INFORMATION

The phrase "as soon as practicable" in §60.9(a) means without unnecessarily disrupting or delaying beyond a reasonable time the training, evaluation, or experience being conducted in the FFS.

END INFORMATION

8. FFS USE (§ 60.11)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.11, Simulator Use.

END INFORMATION

9. FFS OBJECTIVE DATA REQUIREMENTS (§ 60.13)

BEGIN QPS REQUIREMENTS

- a. Flight test data used to validate FFS performance and handling qualities must have been gathered in accordance with a flight test program containing the following:
 - (1) A flight test plan consisting of:
- (a) The maneuvers and procedures required for aircraft certification and simulation programming and validation.
- (b) For each maneuver or procedure—
- (i) The procedures and control input the flight test pilot and/or engineer used.
- (ii) The atmospheric and environmental conditions.
- (iii) The initial flight conditions.
- (iv) The airplane configuration, including weight and center of gravity. $\,$
 - (v) The data to be gathered.

- (vi) All other information necessary to recreate the flight test conditions in the FFS.
- (2) Appropriately qualified flight test personnel.
- (3) An understanding of the accuracy of the data to be gathered using appropriate alternative data sources, procedures, and instrumentation that is traceable to a recognized standard as described in Attachment 2, Table A2E of this appendix.
- (4) Appropriate and sufficient data acquisition equipment or system(s), including appropriate data reduction and analysis methods and techniques, as would be acceptable to the FAA's Aircraft Certification Service.
- b. The data, regardless of source, must be presented as follows:
- (1) In a format that supports the FFS validation process.
- (2) In a manner that is clearly readable and annotated correctly and completely.
- (3) With resolution sufficient to determine compliance with the tolerances set forth in Attachment 2, Table A2A of this appendix.
- (4) With any necessary instructions or other details provided, such as yaw damper or throttle position.
- (5) Without alteration, adjustments, or bias. Data may be corrected to address known data calibration errors provided that an explanation of the methods used to correct the errors appears in the QTG. The corrected data may be re-scaled, digitized, or otherwise manipulated to fit the desired presentation.
- c. After completion of any additional flight test, a flight test report must be submitted in support of the validation data. The report must contain sufficient data and rationale to support qualification of the FFS at the level requested.
- d. As required by §60.13(f), the sponsor must notify the responsible Flight Standards office when it becomes aware that an addition to, an amendment to, or a revision of data that may relate to FFS performance or handling characteristics is available. The data referred to in this paragraph is data used to validate the performance, handling qualities, or other characteristics of the aircraft, including data related to any relevant changes occurring after the type certificate was issued. The sponsor must—
- (1) Within 10 calendar days, notify the responsible Flight Standards office of the existence of this data; and
- (2) Within 45 calendar days, notify the responsible Flight Standards office of—
- (a) The schedule to incorporate this data into the FFS: or
- (b) The reason for not incorporating this data into the FFS.
- e. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot tests" results in lieu of a time-history result, the sponsor or other

Pt. 60, App. A

data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snapshot.

END QPS REQUIREMENTS

BEGIN INFORMATION

f. The FFS sponsor is encouraged to maintain a liaison with the manufacturer of the aircraft being simulated (or with the holder of the aircraft type certificate for the aircraft being simulated if the manufacturer is no longer in business), and, if appropriate, with the person having supplied the aircraft data package for the FFS in order to facilitate the notification required by §60.13(f).

g. It is the intent of the responsible Flight Standards office that for new aircraft entering service, at a point well in advance of preparation of the Qualification Test Guide (QTG), the sponsor should submit to the responsible Flight Standards office for approval, a descriptive document (see Table A2C. Sample Validation Data Roadman for Airplanes) containing the plan for acquiring the validation data, including data sources. This document should clearly identify sources of data for all required tests, a description of the validity of these data for a specific engine type and thrust rating configuration, and the revision levels of all avionics affecting the performance or flying qualities of the aircraft. Additionally, this document should provide other information, such as the rationale or explanation for cases where data or data parameters are missing, instances where engineering simulation data are used or where flight test methods require further explanations. It should also provide a brief narrative describing the cause and effect of any deviation from data requirements. The aircraft manufacturer may provide this document.

h. There is no requirement for any flight test data supplier to submit a flight test plan or program prior to gathering flight test data. However, the responsible Flight Standards office notes that inexperienced data gatherers often provide data that is irrelevant, improperly marked, or lacking adequate justification for selection. Other problems include inadequate information regarding initial conditions or test maneuvers. The responsible Flight Standards office has been forced to refuse these data submissions as validation data for an FFS evaluation. It is for this reason that the responsible Flight Standards office recommends that any data supplier not previously experienced in this area review the data necessary for programming and for validating the performance of the FFS, and discuss the flight test plan anticipated for acquiring such data with the responsible Flight Standards office well in advance of commencing the flight tests.

i. The responsible Flight Standards office will consider, on a case-by-case basis, whether to approve supplemental validation data derived from flight data recording systems, such as a Quick Access Recorder or Flight Data Recorder.

END INFORMATION

10. SPECIAL EQUIPMENT AND PERSONNEL REQUIREMENTS FOR QUALIFICATION OF THE FFSs (§ 60.14)

BEGIN INFORMATION

a. In the event that the responsible Flight Standards office determines that special equipment or specifically qualified persons will be required to conduct an evaluation, the responsible Flight Standards office will make every attempt to notify the sponsor at least one (1) week, but in no case less than 72 hours, in advance of the evaluation. Examples of special equipment include spot photometers, flight control measurement devices, and sound analyzers. Examples of specially qualified personnel include individuals specifically qualified to install or use any special equipment when its use is required.

b. Examples of a special evaluation include an evaluation conducted after an FFS is moved, at the request of the TPAA, or as a result of comments received from users of the FFS that raise questions about the continued qualification or use of the FFS.

END INFORMATION

11. Initial (and Upgrade) Qualification Requirements (§ 60.15)

BEGIN QPS REQUIREMENTS

- a. In order to be qualified at a particular qualification level, the ${\tt FFS}$ must:
- (1) Meet the general requirements listed in Attachment 1 of this appendix;
- (2) Meet the objective testing requirements listed in Attachment 2 of this appendix; and
- (3) Satisfactorily accomplish the subjective tests listed in Attachment 3 of this appendix.
- b. The request described in §60.15(a) must include all of the following:
- (1) A statement that the FFS meets all of the applicable provisions of this part and all applicable provisions of the QPS.
- (2) Unless otherwise authorized through prior coordination with the responsible Flight Standards office, a confirmation that

Federal Aviation Administration, DOT

the sponsor will forward to the responsible Flight Standards office the statement described in §60.15(b) in such time as to be received no later than 5 business days prior to the scheduled evaluation and may be forwarded to the responsible Flight Standards office via traditional or electronic means.

- (3) A QTG, acceptable to the responsible Flight Standards office, that includes all of the following:
- (a) Objective data obtained from traditional aircraft testing or another approved source
- (b) Correlating objective test results obtained from the performance of the FFS as prescribed in the appropriate QPS.
- (c) The result of FFS subjective tests prescribed in the appropriate QPS.
- (d) A description of the equipment necessary to perform the evaluation for initial qualification and the continuing qualification evaluations.
- c. The QTG described in paragraph (a)(3) of this section, must provide the documented proof of compliance with the simulator objective tests in Attachment 2, Table A2A of this appendix.
- d. The QTG is prepared and submitted by the sponsor, or the sponsor's agent on behalf of the sponsor, to the responsible Flight Standards office for review and approval, and must include, for each objective test:
- (1) Parameters, tolerances, and flight conditions;
- (2) Pertinent and complete instructions for the conduct of automatic and manual tests;
- (3) A means of comparing the FFS test results to the objective data;
- (4) Any other information as necessary, to assist in the evaluation of the test results;
- (5) Other information appropriate to the qualification level of the FFS.
- e. The QTG described in paragraphs (a)(3) and (b) of this section, must include the following:
- (1) A QTG cover page with sponsor and FAA approval signature blocks (see Attachment 4, Figure A4C, of this appendix for a sample QTG cover page).
 - (2) [Reserved]
- (3) An FFS information page that provides the information listed in this paragraph (see Attachment 4, Figure A4B, of this appendix for a sample FFS information page). For convertible FFSs, the sponsor must submit a separate page for each configuration of the FFS.
- (a) The sponsor's FFS identification number or code.
- (b) The airplane model and series being simulated.
- (c) The aerodynamic data revision number or reference.
- (d) The source of the basic aerodynamic model and the aerodynamic coefficient data used to modify the basic model.

- (e) The engine model(s) and its data revision number or reference.
- (f) The flight control data revision number or reference.
- (g) The flight management system identification and revision level.
 - (h) The FFS model and manufacturer.
 - (i) The date of FFS manufacture.
- (j) The FFS computer identification.
- (k) The visual system model and manufacturer, including display type.
- (1) The motion system type and manufacturer, including degrees of freedom.
 - (4) A Table of Contents.
- (5) A log of revisions and a list of effective pages.
 - (6) A list of all relevant data references.
- (7) A glossary of terms and symbols used (including sign conventions and units).
- (8) Statements of Compliance and Capability (SOCs) with certain requirements.
- (9) Recording procedures or equipment required to accomplish the objective tests.
- (10) The following information for each objective test designated in Attachment 2, Table A2A, of this appendix as applicable to the qualification level sought:
 - (a) Name of the test.
 - (b) Objective of the test.
 - (c) Initial conditions.
- (d) Manual test procedures.
- (e) Automatic test procedures (if applicable).
- $(\hat{\boldsymbol{f}})$ Method for evaluating FFS objective test results.
- (g) List of all relevant parameters driven or constrained during the automatically conducted test(s).
- (h) List of all relevant parameters driven or constrained during the manually conducted test(s).
 - (i) Tolerances for relevant parameters.
- (j) Source of Validation Data (document and page number).
- (k) Copy of the Validation Data (if located in a separate binder, a cross reference for the identification and page number for pertinent data location must be provided).
- (1) Simulator Objective Test Results as obtained by the sponsor. Each test result must reflect the date completed and must be clearly labeled as a product of the device being tested.
- f. A convertible FFS is addressed as a separate FFS for each model and series airplane to which it will be converted and for the FAA qualification level sought. If a sponsor seeks qualification for two or more models of an airplane type using a convertible FFS, the sponsor must submit a QTG for each airplane model, or a QTG for the first airplane model and a supplement to that QTG for each additional airplane model. The responsible Flight Standards office will conduct evaluations for each airplane model.
- g. Form and manner of presentation of objective test results in the QTG:

Pt. 60, App. A

- (1) The sponsor's FFS test results must be recorded in a manner acceptable to the responsible Flight Standards office, that allows easy comparison of the FFS test results to the validation data (e.g., use of a multichannel recorder, line printer, cross plotting, overlays, transparencies).
- (2) FFS results must be labeled using terminology common to airplane parameters as opposed to computer software identifications.
- (3) Validation data documents included in a QTG may be photographically reduced only if such reduction will not alter the graphic scaling or cause difficulties in scale interpretation or resolution.
- (4) Scaling on graphical presentations must provide the resolution necessary to evaluate the parameters shown in Attachment 2, Table A2A of this appendix.
- (5) Tests involving time histories, data sheets (or transparencies thereof) and FFS test results must be clearly marked with appropriate reference points to ensure an accurate comparison between the FFS and the airplane with respect to time. Time histories recorded via a line printer are to be clearly identified for cross plotting on the airplane data. Over-plots must not obscure the reference data.
- h. The sponsor may elect to complete the QTG objective and subjective tests at the manufacturer's facility or at the sponsor's training facility (or other sponsor designated location where training will take place). If the tests are conducted at the manufacturer's facility, the sponsor must repeat at least one-third of the tests at the sponsor's training facility in order to substantiate FFS performance. The QTG must be clearly annotated to indicate when and where each test was accomplished. Tests conducted at the manufacturer's facility and at the sponsor's designated training facility must be conducted after the FFS is assembled with systems and sub-systems functional and operating in an interactive manner. The test results must be submitted to the responsible Flight Standards office.
- i. The sponsor must maintain a copy of the MQTG at the FFS location.
- j. All FFSs for which the initial qualification is conducted after May 30, 2014, must have an electronic MQTG (eMQTG) including all objective data obtained from airplane testing, or another approved source (reformatted or digitized), together with correlating objective test results obtained from the performance of the FFS (reformatted or digitized) as prescribed in this appendix. The eMQTG must also contain the general FFS performance or demonstration results (reformatted or digitized) prescribed in this appendix, and a description of the equipment necessary to perform the initial qualification evaluation and the continuing qualification evaluations. The eMQTG must include the

original validation data used to validate FFS performance and handling qualities in either the original digitized format from the data supplier or an electronic scan of the original time-history plots that were provided by the data supplier. A copy of the eMQTG must be provided to the responsible Flight Standards office.

- k. All other FFSs not covered in subparagraph "j" must have an electronic copy of the MQTG by May 30, 2014. An electronic copy of the MQTG must be provided to the responsible Flight Standards office. This may be provided by an electronic scan presented in a Portable Document File (PDF), or similar format acceptable to the responsible Flight Standards office.
- 1. During the initial (or upgrade) qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person who is a user of the device (e.g., a qualified pilot or instructor pilot with flight time experience in that aircraft) and knowledgeable about the operation of the aircraft and the operation of the FFS.

END QPS REQUIREMENTS

BEGIN INFORMATION

- m. Only those FFSs that are sponsored by a certificate holder as defined in Appendix F of this part will be evaluated by the responsible Flight Standards office. However, other FFS evaluations may be conducted on a case-by-case basis as the Administrator deems appropriate, but only in accordance with applicable agreements.
- n. The responsible Flight Standards office will conduct an evaluation for each configuration, and each FFS must be evaluated as completely as possible. To ensure a thorough and uniform evaluation, each FFS is subjected to the general simulator requirements in Attachment 1 of this appendix, the objective tests listed in Attachment 2 of this appendix, and the subjective tests listed in Attachment 3 of this appendix. The evaluations described herein will include, but not necessarily be limited to the following:
- (1) Airplane responses, including longitudinal and lateral-directional control responses (see Attachment 2 of this appendix);
- (2) Performance in authorized portions of the simulated airplane's operating envelope, to include tasks evaluated by the responsible Flight Standards office in the areas of surface operations, takeoff, climb, cruise, descent, approach, and landing as well as abnormal and emergency operations (see Attachment 2 of this appendix);
- (3) Control checks (see Attachment 1 and Attachment 2 of this appendix);
- (4) Flight deck configuration (see Attachment 1 of this appendix);

- (5) Pilot, flight engineer, and instructor station functions checks (see Attachment 1 and Attachment 3 of this appendix);
- (6) Airplane systems and sub-systems (as appropriate) as compared to the airplane simulated (see Attachment 1 and Attachment 3 of this appendix):
- (7) FFS systems and sub-systems, including force cueing (motion), visual, and aural (sound) systems, as appropriate (see Attachment 1 and Attachment 2 of this appendix); and
- (8) Certain additional requirements, depending upon the qualification level sought, including equipment or circumstances that may become hazardous to the occupants. The sponsor may be subject to Occupational Safety and Health Administration requirements.
- o. The responsible Flight Standards office administers the objective and subjective tests, which includes an examination of functions. The tests include a qualitative assessment of the FFS by a pilot from the responsible Flight Standards office. The evaluation team leader may assign other qualified personnel to assist in accomplishing the functions examination and/or the objective and subjective tests performed during an evaluation when required.
- (1) Objective tests provide a basis for measuring and evaluating FFS performance and determining compliance with the requirements of this part.
 - (2) Subjective tests provide a basis for:
- (a) Evaluating the capability of the FFS to perform over a typical utilization period;
- (b) Determining that the FFS satisfactorily simulates each required task;
- (c) Verifying correct operation of the FFS controls, instruments, and systems; and
- (d) Demonstrating compliance with the requirements of this part.
- p. The tolerances for the test parameters listed in Attachment 2 of this appendix reflect the range of tolerances acceptable to the responsible Flight Standards office for FFS validation and are not to be confused with design tolerances specified for FFS manufacture. In making decisions regarding tests and test results, the responsible Flight Standards office relies on the use of operational and engineering judgment in the application of data (including consideration of the way in which the flight test was flown and the way the data was gathered and applied), data presentations, and the applicable tolerances for each test.
- q. In addition to the scheduled continuing qualification evaluation, each FFS is subject to evaluations conducted by the responsible Flight Standards office at any time without prior notification to the sponsor. Such evaluations would be accomplished in a normal manner (i.e., requiring exclusive use of the FFS for the conduct of objective and subjective tests and an examination of functions) if

- the FFS is not being used for flight crewmember training, testing, or checking. However, if the FFS were being used, the evaluation would be conducted in a non-exclusive manner. This non-exclusive evaluation will be conducted by the FFS evaluator accompanying the check airman, instructor, Aircrew Program Designee (APD), or FAA inspector aboard the FFS along with the student(s) and observing the operation of the FFS during the training, testing, or checking activities.
- r. Problems with objective test results are handled as follows:
- (1) If a problem with an objective test result is detected by the evaluation team during an evaluation, the test may be repeated or the OTG may be amended.
- (2) If it is determined that the results of an objective test do not support the level requested but do support a lower level, the responsible Flight Standards office may qualify the FFS at that lower level. For example, if a Level D evaluation is requested and the FFS fails to meet sound test tolerances, it could be qualified at Level C.
- s. After an FFS is successfully evaluated, the responsible Flight Standards office issues a Statement of Qualification (SOQ) to the sponsor. The responsible Flight Standards office recommends the FFS to the TPAA, who will approve the FFS for use in a flight training program. The SOQ will be issued at the satisfactory conclusion of the initial or continuing qualification evaluation and will list the tasks for which the FFS is qualified, referencing the tasks described in Table A1B in Attachment 1 of this appendix. However, it is the sponsor's responsibility to obtain TPAA approval prior to using the FFS in an FAA-approved flight training program.
- t. Under normal circumstances, the responsible Flight Standards office establishes a date for the initial or upgrade evaluation within ten (10) working days after determining that a complete QTG is acceptable. Unusual circumstances may warrant establishing an evaluation date before this determination is made. A sponsor may schedule an evaluation date as early as 6 months in advance. However, there may be a delay of 45 days or more in rescheduling and completing the evaluation if the sponsor is unable to meet the scheduled date. See Attachment 4 of this appendix, Figure A4A, Sample Request for Initial, Upgrade, or Reinstatement Evaluation
- u. The numbering system used for objective test results in the QTG should closely follow the numbering system set out in Attachment 2 of this appendix, FFS Objective Tests, Table A2A.
- v. Contact the responsible Flight Standards office for additional information regarding the preferred qualifications of pilots used to meet the requirements of \$60.15(d).

Pt. 60, App. A

w. Examples of the exclusions for which the FFS might not have been subjectively tested by the sponsor or the responsible Flight Standards office and for which qualification might not be sought or granted, as described in §60.15(g)(6), include windshear training and circling approaches.

END INFORMATION

12. ADDITIONAL QUALIFICATIONS FOR A CURRENTLY QUALIFIED FFS (§60.16)

BEGIN INFORMATION

No additional regulatory or informational material applies to \$60.16, Additional Qualifications for a Currently Qualified FFS.

END INFORMATION

13. Previously Qualified FFSs (§60.17)

BEGIN QPS REQUIREMENTS

- a. In instances where a sponsor plans to remove an FFS from active status for a period of less than two years, the following procedures apply:
- (1) The responsible Flight Standards office must be notified in writing and the notification must include an estimate of the period that the FFS will be inactive;
- (2) Continuing Qualification evaluations will not be scheduled during the inactive period:
- (3) The responsible Flight Standards office will remove the FFS from the list of qualified FSTDs on a mutually established date not later than the date on which the first missed continuing qualification evaluation would have been scheduled;
- (4) Before the FFS is restored to qualified status, it must be evaluated by the responsible Flight Standards office. The evaluation content and the time required to accomplish the evaluation is based on the number of continuing qualification evaluations and sponsor-conducted quarterly inspections missed during the period of inactivity.
- (5) The sponsor must notify the responsible Flight Standards office of any changes to the original scheduled time out of service;
- b. Simulators qualified prior to May 31, 2016, are not required to meet the general simulation requirements, the objective test requirements or the subjective test requirements of attachments 1, 2, and 3 of this appendix as long as the simulator continues to meet the test requirements contained in the MQTG developed under the original qualification basis.

- c. After May 30, 2009, each visual scene or airport model beyond the minimum required for the FFS qualification level that is installed in and available for use in a qualified FFFS must meet the requirements described in attachment 3 of this appendix.
- d. Simulators qualified prior to May 31, 2016, may be updated. If an evaluation is deemed appropriate or necessary by the responsible Flight Standards office after such an update, the evaluation will not require an evaluation to standards beyond those against which the simulator was originally qualified.
- e. Other certificate holders or persons desiring to use an FFS may contract with FFS sponsors to use FFSs previously qualified at a particular level for an airplane type and approved for use within an FAA-approved flight training program. Such FFSs are not required to undergo an additional qualification process, except as described in §60.16.
- f. Each FFS user must obtain approval from the appropriate TPAA to use any FFS in an FAA-approved flight training program.
- g. The intent of the requirement listed in §60.17(b), for each FFS to have a SOQ within 6 years, is to have the availability of that statement (including the configuration list and the limitations to authorizations) to provide a complete picture of the FFS inventory regulated by the FAA. The issuance of the statement will not require any additional evaluation or require any adjustment to the evaluation basis for the FFS.
- h. Downgrading of an FFS is a permanent change in qualification level and will necessitate the issuance of a revised SOQ to reflect the revised qualification level, as appropriate. If a temporary restriction is placed on an FFS because of a missing, malfunctioning, or inoperative component or ongoing repairs, the restriction is not a permanent change in qualification level. Instead, the restriction is temporary and is removed when the reason for the restriction has been resolved.
- i. The responsible Flight Standards office will determine the evaluation criteria for an FFS that has been removed from active status. The criteria will be based on the number of continuing qualification evaluations and quarterly inspections missed during the period of inactivity. For example, if the FFS were out of service for a 1 year period, it would be necessary to complete the entire QTG, since all of the quarterly evaluations would have been missed. The responsible Flight Standards office will also consider how the FFS was stored, whether parts were removed from the FFS and whether the FFS was disassembled.
- j. The FFS will normally be requalified using the FAA-approved MQTG and the criteria that was in effect prior to its removal from qualification. However, inactive periods

Federal Aviation Administration, DOT

Pt. 60, App. A

of 2 years or more will require requalification under the standards in effect and current at the time of requalification.

END INFORMATION

 INSPECTION, CONTINUING QUALIFICATION EVALUATION, AND MAINTENANCE REQUIRE-MENTS (§ 60.19)

BEGIN QPS REQUIREMENTS

- a. The sponsor must conduct a minimum of four evenly spaced inspections throughout the year. The objective test sequence and content of each inspection must be developed by the sponsor and must be acceptable to the responsible Flight Standards office.
- b. The description of the functional preflight check must be contained in the sponsor's QMS.
- c. Record "functional preflight" in the FFS discrepancy log book or other acceptable location, including any item found to be missing, malfunctioning, or inoperative.
- d. During the continuing qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FFS.
- e. The responsible Flight Standards office will conduct continuing qualification evaluations every 12 months unless:
- (1) The responsible Flight Standards office becomes aware of discrepancies or performance problems with the device that warrants more frequent evaluations; or
- (2) The sponsor implements a QMS that justifies less frequent evaluations. However, in no case shall the frequency of a continuing qualification evaluation exceed 36 months.

END QPS REQUIREMENTS

BEGIN INFORMATION

- f. The sponsor's test sequence and the content of each quarterly inspection required in $\S 60.19(a)(1)$ should include a balance and a mix from the objective test requirement areas listed as follows:
 - (1) Performance.
 - (2) Handling qualities.
 - (3) Motion system (where appropriate).
 - (4) Visual system (where appropriate).
 - (5) Sound system (where appropriate).
 - (6) Other FFS systems.
- g. If the evaluator plans to accomplish specific tests during a normal continuing qualification evaluation that requires the use of special equipment or technicians, the sponsor will be notified as far in advance of the evaluation as practical; but not less than 72

hours. Examples of such tests include latencies, control dynamics, sounds and vibrations, motion, and/or some visual system tests.

- h. The continuing qualification evaluations, described in §60.19(b), will normally require 4 hours of FFS time. However, flexibility is necessary to address abnormal situations or situations involving aircraft with additional levels of complexity (e.g., computer controlled aircraft). The sponsor should anticipate that some tests may require additional time. The continuing qualification evaluations will consist of the following:
- (1) Review of the results of the quarterly inspections conducted by the sponsor since the last scheduled continuing qualification evaluation
- (2) A selection of approximately 8 to 15 objective tests from the MQTG that provide an adequate opportunity to evaluate the performance of the FFS. The tests chosen will be performed either automatically or manually and should be able to be conducted within approximately one-third (1/2) of the allotted FFS time.
- (3) A subjective evaluation of the FFS to perform a representative sampling of the tasks set out in attachment 3 of this appendix. This portion of the evaluation should take approximately two-thirds (%) of the allotted FFS time
- (4) An examination of the functions of the FFS may include the motion system, visual system, sound system, instructor operating station, and the normal functions and simulated malfunctions of the airplane systems. This examination is normally accomplished simultaneously with the subjective evaluation requirements.

END INFORMATION

15. Logging FFS Discrepancies (§60.20)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.20. Logging FFS Discrepancies.

END INFORMATION

16. INTERIM QUALIFICATION OF FFSs FOR NEW AIRPLANE TYPES OR MODELS (\$60.21)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.21, Interim Qualification of FFSs for New Airplane Types or Models.

Pt. 60, App. A

END INFORMATION

17. Modifications to FFSs (§60.23)

BEGIN QPS REQUIREMENTS

a. The notification described in §60.23(c)(2) must include a complete description of the planned modification, with a description of the operational and engineering effect the proposed modification will have on the operation of the FFS and the results that are expected with the modification incorporated.

b. Prior to using the modified FFS:

(1) All the applicable objective tests completed with the modification incorporated, including any necessary updates to the MQTG (e.g., accomplishment of FSTD Directives) must be acceptable to the responsible Flight Standards office; and

(2) The sponsor must provide the responsible Flight Standards office with a statement signed by the MR that the factors listed in §60.15(b) are addressed by the appropriate personnel as described in that section.

END QPS REQUIREMENTS

BEGIN INFORMATION

FSTD Directives are considered modifications of an FFS. See Attachment 4 of this appendix for a sample index of effective FSTD Directives. See Attachment 6 of this appendix for a list of all effective FSTD Directives applicable to Airplane FFSs.

END INFORMATION

18. OPERATION WITH MISSING, MALFUNC-TIONING, OR INOPERATIVE COMPONENTS (§60.25)

BEGIN INFORMATION

a. The sponsor's responsibility with respect to $\S60.25(a)$ is satisfied when the sponsor fairly and accurately advises the user of the current status of an FFS, including any missing, malfunctioning, or inoperative (MMI) component(s).

b. It is the responsibility of the instructor, check airman, or representative of the administrator conducting training, testing, or checking to exercise reasonable and prudent judgment to determine if any MMI component is necessary for the satisfactory completion of a specific maneuver, procedure, or task

c. If the 29th or 30th day of the 30-day period described in §60.25(b) is on a Saturday, a Sunday, or a holiday, the FAA will extend the deadline until the next business day.

d. In accordance with the authorization described in §60.25(b), the sponsor may develop a discrepancy prioritizing system to accom-

14 CFR Ch. I (1-1-24 Edition)

plish repairs based on the level of impact on the capability of the FFS. Repairs having a larger impact on FFS capability to provide the required training, evaluation, or flight experience will have a higher priority for repair or replacement.

END INFORMATION

19. Automatic Loss of Qualification and Procedures for Restoration of Qualification (§ 60.27)

BEGIN INFORMATION

If the sponsor provides a plan for how the FFS will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FFS is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing required for requalification.

END INFORMATION

20. Other Losses of Qualification and Procedures for Restoration of Qualification (§ 60.29)

BEGIN INFORMATION

If the sponsor provides a plan for how the FFS will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FFS is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing required for requalification.

END INFORMATION

21. RECORDKEEPING AND REPORTING (§ 60.31)

BEGIN QPS REQUIREMENTS

a. FFS modifications can include hardware or software changes. For FFS modifications involving software programming changes, the record required by \$60.31(a)(2) must consist of the name of the aircraft system software, aerodynamic model, or engine model change, the date of the change, a summary of the change, and the reason for the change.

Federal Aviation Administration, DOT

b. If a coded form for record keeping is used, it must provide for the preservation and retrieval of information with appropriate security or controls to prevent the inappropriate alteration of such records after the fact.

END QPS REQUIREMENTS

22. APPLICATIONS, LOGBOOKS, REPORTS, AND RECORDS: FRAUD, FALSIFICATION, OR INCORRECT STATEMENTS (§ 60.33)

BEGIN INFORMATION

No additional regulatory or informational material applies to \$60.33, Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements.

23. Specific FFS Compliance Requirements (§ 60.35)

No additional regulatory or informational material applies to §60.35, Specific FFS Compliance Requirements.

24. [Reserved]

25. FFS QUALIFICATION ON THE BASIS OF A BI-LATERAL AVIATION SAFETY AGREEMENT (BASA) (§ 60.37)

No additional regulatory or informational material applies to §60.37, FFS Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA).

END INFORMATION

ATTACHMENT 1 TO APPENDIX A TO PART 60—GENERAL SIMULATOR REQUIREMENTS

BEGIN QPS REQUIREMENTS

1. Requirements

a. Certain requirements included in this appendix must be supported with an SOC as defined in Appendix F, which may include objective and subjective tests. The requirements for SOCs are indicated in the "General Simulator Requirements" column in Table A1A of this appendix.

Pt. 60, App. A

b. Table A1A describes the requirements for the indicated level of FFS. Many devices include operational systems or functions that exceed the requirements outlined in this section. However, all systems will be tested and evaluated in accordance with this appendix to ensure proper operation.

END QPS REQUIREMENTS

BEGIN INFORMATION

2. Discussion

- a. This attachment describes the general simulator requirements for qualifying an airplane FFS. The sponsor should also consult the objective tests in Attachment 2 of this appendix and the examination of functions and subjective tests listed in Attachment 3 of this appendix to determine the complete requirements for a specific level simulator.
- b. The material contained in this attachment is divided into the following categories:
 - (1) General flight deck configuration.
- (2) Simulator programming.
- (3) Equipment operation.
- (4) Equipment and facilities for instructor/evaluator functions.
- (5) Motion system.
- (6) Visual system.
- (7) Sound system.
- c. Table A1A provides the standards for the General Simulator Requirements.
- d. Table A1B provides the tasks that the sponsor will examine to determine whether the FFS satisfactorily meets the requirements for flight crew training, testing, and experience, and provides the tasks for which the simulator may be qualified.
- e. Table A1C provides the functions that an instructor/check airman must be able to control in the simulator.
- f. It is not required that all of the tasks that appear on the List of Qualified Tasks (part of the SOQ) be accomplished during the initial or continuing qualification evaluation.

END INFORMATION

	INFORMATION	Notes
nts		Simulator Levels A B C D
Table A1A – Minimum Simulator Requireme	QPS REQUIREMENTS	General Simulator Requirements
		Entry Number

Number	General Simulator Requirements	Levels	Levels		Notes	
		1	2	2		_
1. General	1. General Flight Deck Configuration.					_
1.a.	The simulator must have a flight deck that is a replica of the airplane	XXXX	×		For simulator purposes, the	
	simulated with controls, equipment, observable flight deck indicators, circuit				flight deck consists of all that	
	breakers, and bulkheads properly located, functionally accurate and				space forward of a cross	
	replicating the airplane. The direction of movement of controls and switches				section of the flight deck at the	
	must be identical to the airplane. Pilot seats must allow the occupant to				most extreme aft setting of the	
	achieve the design "eye position" established for the airplane being simulated.				pilots' seats, including	
	Equipment for the operation of the flight deck windows must be included, but				additional required	
	the actual windows need not be operable. Additional equipment such as fire				crewmember duty stations and	
	axes, extinguishers, and spare light bulbs must be available in the FFS but				those required bulkheads aft of	
	may be relocated to a suitable location as near as practical to the original				the pilot seats. For	
	position. Fire axes, landing gear pins, and any similar purpose instruments				clarification, bulkheads	
	need only be represented in silhouette.				containing only items such as	
					landing gear pin storage	
	The use of electronically displayed images with physical overlay or masking				compartments, fire axes and	
	for simulator instruments and/or instrument panels is acceptable provided:				extinguishers, spare light	
	(1) All instruments and instrument panel layouts are dimensionally				bulbs, and aircraft document	
	correct with differences, if any, being imperceptible to the pilot;				pouches are not considered	
	(2) Instruments replicate those of the airplane including full instrument				essential and may be omitted.	
	functionality and embedded logic;					
	(3) Instruments displayed are free of quantization (stepping);					
	(4) Instrument display characteristics replicate those of the airplane					
	including: resolution, colors, luminance, brightness, fonts, fill					
	patterns, line styles and symbology;					
	(5) Overlay or masking, including bezels and bugs, as applicable,					
	replicates the airplane panel(s);					
	(6) Instrument controls and switches replicate and operate with the same					
	technique, effort, travel and in the same direction as those in the					
	airplane;					
		_		_		_

	(7) Instrument lighting replicates that of the airplane and is operated from the FSTD control for that lighting and, if applicable, is at a level commensurate with other lighting operated by that same control; and (8) As applicable, instruments must have faceplates that replicate those in the airplane; and		×	×	
	Level C and Level D only; (1) The display image of any three dimensional instrument, such as an electro-mechanical instrument, should appear to have the same three dimensional depth as the replicated instrument. The appearance of the simulated instrument, when viewed from the principle operator's angle, should replicate that of the actual airplane instrument. Any instrument reading inaccuracy due to viewing angle and parallax present in the actual airplane instrument should be duplicated in the				
	simulated instrument display image. Viewing angle error and parallax must be minimized on shared instruments such and engine displays and standby indicators.				
1.b.	Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate.	X	×	X	
2. Programming.	nming.				
2.a.	A flight dynamics model that accounts for various combinations of drag and thrust normally encountered in flight must correspond to actual flight	×	×	×	The SOC should include a range of tabulated target values
	conditions, including the effect of change in airplane attitude, thrust, drag, altitude, temperature, gross weight, moments of inertia, center of gravity location, and configuration.				to enable a demonstration of the mass properties model to be conducted from the
	An SOC is required.				instructor's station. The data at a minimum should contain 3
	For Level C and Level D simulators, the effects of pitch attitude and of fuel slosh on the aircraft center of gravity must be simulated.		×	×	weight conditions including zero fuel weight and maximum taxi weight with a least 2
					different combinations of zero fuel weight, fuel weight and payload for each condition.
2.b.	The simulator must have the computer capacity, accuracy, resolution, and dynamic response needed to meet the qualification level sought.	×	×	×	
	An SOC is required.				

14 CFR Ch. I (1-1-24 Edition)

2.c.	Surface operations must be represented to the extent that allows turns within the confines of the runway and adequate controls on the landing and roll-out from a crosswind approach to a landing.	×				
2.d.	Ground handling and aerodynamic programming must include the following:					
2.d.1.	Ground effect.		×	X X X		Ground effect includes
					1	modeling that accounts for
						roundout, flare, touchdown,
					_	lift, drag, pitching moment,
						trim, and power while in
2.4.2.	Ground reaction	+	<u> </u>	<u> </u>	×	ground effect. Ground reaction includes
		•				modeling that accounts for
	Ground reaction modeling must produce the appropriate effects during				92	strut deflections, tire friction,
	bounced or skipped landings, including the effects and indications of ground					and side forces. This is the
	contact due to landing in an abnormal aircraft attitude (e.g. tailstrike or				1	reaction of the airplane upon
	nosewheel contact). An SOC is required.					contact with the runway during
					_	landing, and may differ with
					_	changes in factors such as
					OIJ	gross weight, airspeed, or rate
		\dashv	\dashv			of descent on touchdown.
2.d.3.	Ground handling characteristics, including aerodynamic and ground reaction	_	$\frac{\sim}{\times}$	$\frac{\sim}{\times}$	$\frac{1}{x}$	In developing gust models for
	modeling including steering inputs, operations with crosswind, braking, thrust				_	use in training, the FSTD
	reversing, deceleration, and turning radius.				9 2 +	sponsor should coordinate with
	Aerodynamic and ground reaction modeling to support training in crosswinds		_	${\times}$	×	the gust models do not exceed
	and gusting crosswinds up to the aircraft's maximum demonstrated crosswind		1			the capabilities of the
	component. Realistic gusting crosswind profiles must be available to the					aerodynamic and ground
	instructors that have been tuned in intensity and variation to require pilot					models.
	intervention to avoid runway departure during takeoff or landing roll.					
	An SOC is required describing source data used to construct gusting					
	crosswind profiles.		\dashv	-		
2.e.	If the aircraft being simulated is one of the aircraft listed in § 121.358, Low-		-	$\frac{\sim}{\times}$	$\frac{-}{\times}$	If desired, Level A and B
	altitude windshear system equipment requirements, the simulator must				J	simulators may qualify for
	employ windshear models that provide training for recognition of windshear				+	Windshear training by meeting
		+	+	\dashv	7	mese standards, see

Federal Aviation Administration, DOT

	phenomena and the execution of recovery procedures. Models must be available to the instructor/evaluator for the following critical phases of flight:			Attachment 5 of this appendix. Windshear models may consist
	(1) Prior to takeoff rotation; (2) At liftoff;			of independent variable winds in multiple simultaneous
	(3) During initial climb; and (4) On final annewach below 500 ft AGI			components. The FAA
	(+) On third approach, below 500 it AOL.			presents one acceptable means
	The QTG must reference the FAA Windshear Training Aid or present			of compliance with simulator
	alternate airplane related data, including the implementation method(s) used.			wind model requirements.
	If the alternate method is selected, wind models from the Royal Aerospace			
	Establishment (RAE), the Joint Airport Weather Studies (JAWS) Project and			The simulator should employ a
	other recognized sources may be implemented, but must be supported and			method to ensure the required
	property referenced in the QTO. Only mose similators incerning meser requirements may be used to satisfy the training requirements of part 121			windshear scenarios are
	pertaining to a certificate holder's approved low-altitude windshear flight			repeatable in the training
	uanning program as described in § 121.409.			environinent.
	The addition of realistic levels of turbulence associated with each required			
	windshear profile must be available and selectable to the instructor.			
	In addition to the four basic windshear models required for qualification, at			
	least two additional "complex" windshear models must be available to the instructor which represent the complexity of actual windshear encounters			
	These models must be available in the takeoff and landing configurations and			
	must consist of independent variable winds in multiple simultaneous			
	components. The Windshear Training Aid provides two such example "compley" windshear models that may be used to satisfy this requirement			
2.f.	The simulator must provide for manual and automatic testing of simulator	X	×	Automatic "flagging" of out-
	hardware and software programming to determine compliance with simulator			of-tolerance situations is
	objective tests as prescribed in Attachment 2 of this appendix.			encouraged.
	An SOC is required.			
2.g.	Relative responses of the motion system, visual system, and flight deck			The intent is to verify that the
	instruments, measured by latency tests or transport delay tests. Motion onset			simulator provides instrument,
	should occur before the start of the visual scene change (the start of the scan			motion, and visual cues that
	the end of the connot that video field Instrument reconnecement occur.			are, within the stated time
	prior to motion onset. Test results must be within the following limits:			responses. For airplane
		1		

14 CFR Ch. I (1-1-24 Edition)

					response, acceleration in the appropriate, corresponding rotational axis is preferred.
2.g.1.	300 milliseconds of the airplane response.	X			
2.g.2.	100 milliseconds of the airplane response (motion and instrument cues) 120 milliseconds of the airplane response (visual system cues)		×	×	
2.h.	The simulator must accurately reproduce the following runway conditions: (1) Dry; (2) Wet; (3) Icy; (4) Patchy Wet; (5) Patchy Icy; and (6) Wet on Rubber Residue in Touchdown Zone. An SOC is required.		×	×	
2.i.	The simulator must simulate: (1) brake and tire failure dynamics, including antiskid failure; and (2) decreased brake efficiency due to high brake temperatures, if applicable. An SOC is required.		×	×	Simulator pitch, side loading, and directional control characteristics should be representative of the airplane.
2.j.	Engine and Airframe Icing Modeling that includes the effects of icing, where appropriate, on the airframe, aerodynamics, and the engine(s). Icing models must simulate the aerodynamic degradation effects of ice accretion on the airplane lifting surfaces including loss of lift, decrease in stall angle of attack, change in pitching moment, decrease in control effectiveness, and changes in control forces in addition to any overall increase in drag. Aircraft systems (such as the stall protection system and autoflight system) must respond properly to ice accretion consistent with the simulated aircraft. Aircraft OEM data or other acceptable analytical methods must be utilized to develop ice accretion models. Acceptable analytical methods may include wind tunnel analysis and/or engineering analysis of the aerodynamic effects of icing on the lifting surfaces coupled with tuning and supplemental subjective assessment by a subject matter expert pilot.		×	×	SOC should be provided describing the effects which provide training in the specific skills required for recognition of icing phenomena and execution of recovery. The SOC should describe the source data and any analytical methods used to develop ice accretion models including verification that these effects have been tested. Icing effects simulation models are only required for those

	SOC and tests required. See objective testing requirements (Attachment 2, test 2.i.).				airplanes authorized for operations in icing conditions.
					See Attachment 7 of this Appendix for further guidance material.
2.k.	The aerodynamic modeling in the simulator must include:			×	See Attachment 2 of this
	(1) Low-altitude level-flight ground effect; (2) Mach effect at high altitude:				appendix, paragraph 5, for further information on ground
	(2) Normal and reverse dynamic thrust effect on control surfaces;				effect.
	(4) Aeroelastic representations; and				
	(5) Nonlinearities due to sideslip.				
	An SOC is required and must include references to computations of				
	aeroeiasuc representations and of nonlineartites due to sidestip.			1	
2.I.	The simulator must have aerodynamic and ground reaction modeling for the	×	×	×	
	effects of reverse thrust on directional control, if applicable.				
	An SOC is required.				
2.m.	High Angle of Attack Modeling		×	×	The requirements in this
	Aerodynamic stall modeling that includes degradation in static/dynamic				section only apply to those
	lateral-directional stability, degradation in control response (pitch, roll, and				FSTDs that are qualified for
	yaw), uncommanded roll response or roll-off requiring significant control				full stall training tasks.
	deflection to counter, apparent randomness or non-repeatability, changes in				Sponsors may elect to not
	pitch stability, Mach effects, and stall buffet, as appropriate to the aircraft				qualify an FSTD for full stall
	type.				training tasks; however, the
					FSTD's qualification will be
	The aerodynamic model must incorporate an angle of attack and sideslip				restricted to approach to stall
	Tange to support the training tasks. At a minimum, the motern must support an anole of attack rance to ten degrees beyond the stall identification angle of				the activation of the stall
	angre of attack tanger to be a section of offertook in defined on the noise trabes the				ure activities of the state of
	anack. The stail identification angle of anack is defined as the point where the behavior of the airplane gives the pilot a clear and distinctive indication				warning system.
	through the inherent flight characteristics or the characteristics resulting from				Specific guidance should be
	the operation of a stall identification device (e.g., a stick pusher) that the				available to the instructor
	airplane has stalled.				which clearly communicates
					the flight configurations and
			\dashv		stall maneuvers that have been

14 CFR Ch. I (1-1-24 Edition)

ft upset;	
l aircraf	
ss leve	
, wings l	
nose-high	

- A nose-high, wings level aircraft
 A nose-low aircraft upset; and
 A high bank angle aircraft upset.

guidance to the instructor concerning the method used to drive the FSTD into drive an airplane upset is generally not acceptable unless used purely as a tool an upset condition, including any malfunction or degradation in the FSTD's simulator functionality (such as degrading flight control effectiveness) to functionality required to initiate the upset. The unrealistic degradation of Upset Scenarios: IOS selectable dynamic airplane upsets must provide for repositioning the FSTD with the pilot out of the loop.

mechanism in place to notify the instructor/evaluator when the simulator's exceeded during an upset recovery training task. This feedback mechanism Instructor Operating System (IOS): The simulator must have a feedback validated aerodynamic envelope and aircraft operating limits have been must include:

envelopes must provide the instructor real-time feedback on the "confidence level" of the aerodynamic model depending on the degree of flight validation or source of predictive methods The simulation during a maneuver. There must be a minimum of a (1) FSTD validation envelope. This must be in the form of an alpha/beta envelope (or equivalent method) depicting the flaps up and flaps down envelope available;

(2) Flight control inputs. This must enable the instructor to assess the pilot's flight control displacements and forces (including fly-bywire as appropriate); and

Consideration should be taken with flight envelope protected

positioning the airplane to a

specified attitude may

airplanes as artificially

incorrectly initialize flight

Statement of Compliance (SOC): An SOC is required that defines the source instructor station and the associated training maneuver has been evaluated data used to construct the FSTD validation envelope. The SOC must also verify that each upset prevention and recovery feature programmed at the a suitably qualified pilot using methods described in this section. The (3) Airplane operational limits. This must display the aircraft operating limits during the maneuver as applicable for the configuration of the airplane.

statement must confirm that the recovery maneuver can be performed such

ER09DE22.007</GPH>

Bank angle greater than than 10 degrees, nose Pitch attitude greater down

Flight at airspeeds inappropriate for 45 degrees conditions.

must meet the requirements for high angle of attack modeling recovery maneuvers at angles FSTDs used to conduct upset as described in section 2.m. warning system activation of attack above the stal

should be placed on tuning out Special consideration should be given to the motion system maneuvers. Notwithstanding the limitations of simulator motion, specific emphasis motion system responses. prevention and recovery response during upset

Appendix for further guidance See Attachment 7 of this control laws.

14 CFR Ch. I (1-1-24 Edition)

	that the FSTD does not exceed the FSTD validation envelope, or when exceeded, that it is within the realm of confidence in the simulation accuracy.				
3. Equipm	3. Equipment Operation.	-	-		
3.a.	All relevant instrument indications involved in the simulation of the airplane must automatically respond to control movement or external disturbances to the simulated airplane; e.g., turbulence or windshear. Numerical values must be presented in the appropriate units. For Level C and Level D simulators, instrument indications must also respond to effects resulting from icing.		X		
3.b.	Communications, navigation, caution, and warning equipment must be installed and operate within the tolerances applicable for the airplane. Instructor control of internal and external navigational aids. Navigation aids must be usable within range or line-of-sight without restriction, as applicable to the geographic area.	X	×	Х	See Attachment 3 of this appendix for further information regarding longrange navigation equipment.
3.b.1.	Complete navigation database for at least 3 airports with corresponding precision and non-precision approach procedures, including navigational database updates.		X	X	
3.b.2.	Complete navigation database for at least 1 airport with corresponding precision and non-precision approach procedures, including navigational database updates.	X			
3.c.	Simulated airplane systems must operate as the airplane systems operate under normal, abnormal, and emergency operating conditions on the ground and in flight. Once activated, proper systems operation must result from system management by the crew member and not require any further input from the instructor's controls.	×	X	×	Airplane system operation should be predicated on, and traceable to, the system data supplied by the airplane manufacturer or alternative approved data for the airplane system or component. At a minimum, alternate approved data should validate the operation of all normal, abnormal, and emergency operating procedures and

3.4. The simulator must provide pilot controls with control forces and control in the same manner as in the aimplane under the same fight conditions. In the same manner as in the same plane under the same fight conditions. In the same manner as in the same plane under the same fight conditions. X<						training tasks the FSTD is qualified to conduct.
Simulator control feel dynamics must replicate the airplane. This must be determined by comparing a recording of the control feel dynamics of the simulator to airplane measurements. For initial and upgrade qualification evaluations, the control dynamic characteristics must be measured and recorded directly from the flight deck controls, and must be accomplished in takeoff, cruise, and landing flight deck controls, and must be accomplished in takeoff, cruise, and landing flight conditions and configurations. For aircraft equipped with a stick pusher system, control forces, displacement, and surface position must correspond to that of the airplane being simulated. A Statement of Compliance (SOC) is required verifying that the stick pusher system has been modeled, programmed, and validated using the aircraft manufacturer's design data or other acceptable data source. The SOC must address, at a minimum, stick pusher activation and cancellation logic as well as system dynamics, control displacement and forces as a result of the stick pusher activation. Tests required. In addition to the flight crewmember stations, the simulator must have at least two suitable seats for the instructor/check airman and FAA inspector. These seats must provide adequately secured to the floor and equipped with similar positive restraint devices. The simulator must bave controls that enable the instructor/evaluator to control all required system variables and insert all abnormal or emergency conditions into the simulated airplane systems as described in the sponsor's	3.d.	The simulator must provide pilot controls with control forces and control travel that correspond to the simulated airplane. The simulator must also react in the same manner as in the airplane under the same flight conditions. Control systems must replicate airplane operation for the normal and any nonnormal modes including back-up systems and should reflect failures of associated systems. Appropriate cockpit indications and messages must be replicated.			×	
For aircraft equipped with a stick pusher system, control forces, displacement, and surface position must correspond to that of the airplane being simulated. A Statement of Compliance (SOC) is required verifying that the stick pusher system has been modeled, programmed, and validated using the aircraft manufacturer's design data or other acceptable data source. The SOC must address, at a minimum, stick pusher activation and cancellation logic as well as system dynamics, control displacement and forces as a result of the stick pusher activation. Tests required. Tests required. In addition to the flight crewmember stations, the simulator must have at least two suitable seats for the instructor/check airman and FAA inspector. These seats must be adequately secured to the floor and equipped with similar positive restraint devices. The simulator must have controls that enable the instructor/evaluator to control all required system variables and insert all abnormal or emergency control all required system variables as a described in the sponsor's	3.e.	Simulator control feel dynamics must replicate the airplane. This must be determined by comparing a recording of the control feel dynamics of the simulator to airplane measurements. For initial and upgrade qualification evaluations, the control dynamic characteristics must be measured and recorded directly from the flight deck controls, and must be accomplished in takeoff, cruise, and landing flight conditions and configurations.		X	X	
The simulator must have controls that enable the instructor/evaluator to X X X control all required system variables and insert all abnormal or emergency conditions into the simulated airplane systems as described in the sponsor's	3.f. 4. Instruc 4.a.	For aircraft equipped with a stick pusher system, control forces, displacement, and surface position must correspond to that of the airplane being simulated. A Statement of Compliance (SOC) is required verifying that the stick pusher system has been modeled, programmed, and validated using the aircraft manufacturer's design data or other acceptable data source. The SOC must address, at a minimum, stick pusher activation and cancellation logic as well as system dynamics, control displacement and forces as a result of the stick pusher activation. Tests required. Tests required. To or Evaluator Facilities. In addition to the flight crewmember stations, the simulator must have at least two suitable seats for the instructor/check airman and FAA inspector. These seats must provide adequate vision to the pilot's panel and forward windows. All seats other than flight crew seats need not represent those found in the airplane, but must be adequately secured to the floor and equipped with similar positive restraint devices.	×	×	×	See Appendix A, Table A2A, test 2.a.10 (stick pusher system force calibration) for objective testing requirements. The requirements in this section only apply to those FSTDs that are qualified for full stall training tasks. The responsible Flight Standards office will consider alternatives to this standard for additional seats based on unique flight deck configurations.
	4.b.	The simulator must have controls that enable the instructor/evaluator to control all required system variables and insert all abnormal or emergency conditions into the simulated airplane systems as described in the sponsor's			×	

14 CFR Ch. I (1-1-24 Edition)

4.c. The simulator must have instructed expected to be available at the IO precipitation, temperature, storm intermediate and high altitude win a precipitation, temperature, storm intermediate and high altitude win a precipitation. The simulator must provide the in ground and air hazards. 5. Motion System. 5.a. The simulator must have a motion three degrees of freedom (at least hare a motion three degrees of freedom (at least equivalent to those of a six-motion system (i.e., pitch, roll, yamotion system) system (i.e., pitch, r	manual as appropriate. The simulator must have instructor controls for all environmental effects X expected to be available at the IOS; e.g., clouds, visibility, icing,	_	_		
tion S	l effects		_	1	
tions	precipitation, temperature, storm cells and microbursts, turbulence, and intermediate and high altitude wind speed and direction.		×	×	
tion S	The simulator must provide the instructor or evaluator the ability to present ground and air hazards.		P	×	For example, another airplane crossing the active runway or converging airborne traffic.
		ł	1	-	
	The simulator must have motion (force) cues perceptible to the pilot that are representative of the motion in an airplane.		×	×	For example, touchdown cues should be a function of the rate of descent (RoD) of the simulated airplane.
	The simulator must have a motion (force cueing) system with a minimum of three degrees of freedom (at least pitch, roll, and heave). An SOC is required.		×		
	The simulator must have a motion (force cueing) system that produces cues at least equivalent to those of a six-degrees-of-freedom, synergistic platform motion system (i.e., pitch, roll, yaw, heave, sway, and surge). An SOC is required.			×	
	The simulator must provide for the recording of the motion system response time. An SOC is required.		×	×	
	The simulator must provide motion effects programming to include:				
(4) Bumps associate (5) Buffet during ex (6) Buffet in the air. (7) Approach-to-stal	 (1) Thrust effect with brakes set; (2) Runway rumble, oleo deflections, effects of ground speed, uneven runway, centerline lights, and taxiway characteristics; (3) Buffets on the ground due to spoiler/speedbrake extension and thrust reversal; (4) Bumps associated with the landing gear; (5) Buffet during extension and retraction of landing gear; (6) Buffet in the air due to flap and spoiler/speedbrake extension; (7) Approach-to-stall buffet and stall buffet (where applicable); 		×	X	If there are known flight conditions where buffet is the first indication of the stall, or where no stall buffet occurs, this characteristic should be included in the model.

	 (8) Representative touchdown cues for main and nose gear; (9) Nosewheel scuffing, if applicable; (10) Mach and maneuver buffet; (11) Engine failures, malfunctions, and engine damage (12) Tail and nod strike; 					
5.e.2.	(13) Taxiing effects such as lateral and directional cues resulting from steering and braking inputs; (14) Buffet due to atmospheric disturbances (e.g. buffets due to turbulence, gusting winds, storm cells, windshear, etc.) in three linear axes (isotropic); (15) Tire failure dynamics; and (16) Other significant vibrations, buffets and bumps that are not mentioned above (e.g. RAT), or checklist items such as motion effects due to pre-flight flight control inputs.		,	X		
5.f.	The simulator must provide characteristic motion vibrations that result from operation of the airplane if the vibration marks an event or airplane state that can be sensed in the flight deck.			×	The simulator should be programmed and instrumented in such a manner that the characteristic buffet modes can be measured and compared to airplane data.	ented es can ed to
6. Visual System.	ystem. The simulator must have a visual system providing an out-of-the-flight deck	×	×	X		
1,9	View. The circulator want manufactor constitutions collimated field of views of st long					
d o	In the simulator must provide a continuous continuous to the sumulator must provide a continuous continuous to the number of degrees necessary to meet the visual ground segment requirement, whichever is greater. Both pilot seat visual systems must be operable simultaneously. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. An SOC is required and must explain the system geometry measurements	<u>, </u>			Additional field-of-view capability may be added at the sponsor's discretion provided the minimum fields of view are retained.	at the ided ew are
	including system linearity and field-of-view.			+		
6.d.	The simulator must provide a continuous collimated visual field-of-view of at least 176° horizontally and 36° vertically or the number of degrees necessary to meet the visual ground segment requirement, whichever is greater. The minimum horizontal field-of-view coverage must be plus and minimum sone-half	+		×	The horizontal field-of-view is traditionally described as a 180° field-of-view. However, the field-of-view is tochnically	iew is a sver, ically
	IIIIIIIIIIIIIII HOLIZOIIIAI HEID-OI-VIEW COVETAGE IIIUSI DE DIUS AND IIIIIUUS ONE-HAII	1	\dashv	\dashv	THE HEIG-OI-VIEW IS RECITIVE	Icany

	(½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage.				no less than 176°. Additional field-of-view capability may be added at the sponsor's
	An SOC is required and must explain the system geometry measurements including system linearity and field-of-view.				discretion provided the minimum fields of view are retained.
6.e.	The visual system must be free from optical discontinuities and artifacts that create non-realistic cues.	×	×	×	Non-realistic cues might include image "swimming" and image "roll-off," that may lead a pilot to make incorrect assessments of speed, acceleration, or situational awareness.
6.f.	The simulator must have operational landing lights for night scenes. Where used, dusk (or twilight) scenes require operational landing lights.	X	×	×	
6.8.	The simulator must have instructor controls for the following:	X	×	×	
	 Visibility in statute miles (km) and runway visual range (RVR) in ft.(m); Airport selection; and Airport lighting. 				
6.h.	The simulator must provide visual system compatibility with dynamic response programming.	X	×	×	
6.i.	The simulator must show that the segment of the ground visible from the simulator flight deck is the same as from the airplane flight deck (within established tolerances) when at the correct airspeed, in the landing configuration, at the appropriate height above the touchdown zone, and with appropriate visibility.	X	X 1	X	This will show the modeling accuracy of RVR, glideslope, and localizer for a given weight, configuration, and speed within the airplane's operational envelope for a normal approach and landing.
6.j.	The simulator must provide visual cues necessary to assess sink rates (provide depth perception) during takeoffs and landings, to include: (1) Surface on runways, taxiways, and ramps; and (2) Terrain features.	×	X	×	
6.k.	The simulator must provide for accurate portrayal of the visual environment relating to the simulator attitude.	XX	X	X	Visual attitude vs. simulator attitude is a comparison of pitch and roll of the horizon as displayed in the visual scene
		Ì	١	١	

					compared to the display on the attitude indicator.
6.I.	The simulator must provide for quick confirmation of visual system color, RVR, focus, and intensity.		X	X	
	An SOC is required.	+	-	-	
0.III.	The simulator must be capable of producing at least 10 levels of occurring.	_	<	<	
6.n.	Night Visual Scenes. When used in training, testing, or checking activities, the simulator must provide night visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights.	×	×	×	
· · ·	Dusk (or Twilight) Visual Scenes. When used in training, testing, or checking activities, the simulator must provide dusk (or twilight) visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Dusk (or twilight) scenes, as a minimum, must provide full color presentations of reduced ambient intensity, sufficient surfaces with appropriate textural cues that include self-illuminated objects such as road networks, ramp lighting and airport signage, to conduct a visual approach, landing and airport movement (taxi). Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights. If provided, directional horizon lighting must have correct orientation and be consistent with surface shading effects. Total night or dusk (twilight) scene content must be comparable in detail to that produced by 10,000 visible textured surfaces and 15,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects.		×	×	
6.p.	Daylight Visual Scenes. The simulator must provide daylight visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Any ambient lighting must not "washout" the displayed visual scene. Total daylight scene content must be		×	×	

	X For example: short runways, landing approaches over water, uphill or downhill runways, rising terrain on the approach path, unique topographic features.	X X	X X	X	X Scud effects are low, detached, and irregular clouds below a defined cloud layer.	Atmospheric model should support representative effects of wake turbulence and	mountain waves as needed to enhance UPRT training.	The mountain wave model should support the atmospheric climb, descent, and roll rates which can be encountered in
comparable in detail to that produced by 10,000 visible textured surfaces and 6,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects. The visual display must be free of apparent and distracting quantization and other distracting visual effects while the simulator is in motion. An SOC is required.	The simulator must provide operational visual scenes that portray physical relationships known to cause landing illusions to pilots.	The simulator must provide special weather representations of light, medium, and heavy precipitation near a thunderstorm on takeoff and during approach and landing. Representations need only be presented at and below an altitude of 2,000 ft. (610 m) above the airport surface and within 10 miles (16 km) of the airport.	The simulator must present visual scenes of wet and snow-covered runways, including runway lighting reflections for wet conditions, partially obscured lights for snow conditions, or suitable alternative effects.	The simulator must present realistic color and directionality of all airport lighting.	The following weather effects as observed on the visual system must be simulated and respective instructor controls provided. (1) Multiple cloud layers with adjustable bases, tops, sky coverage and send effect:		(4) Effects on ownship external lighting;(5) Effects on airport lighting (including variable intensity and fog effects);	 (6) Surface contaminants (including wind blowing effect); (7) Variable precipitation effects (rain, hail, snow); (8) In-cloud airspeed effect; and (9) Gradual visibility changes entering and breaking out of cloud.
	6.q.	6.r.	e.s.	6.t.	6.и.			

7. The simulator must provide visual efficulty of the simulator must provide visual efficulty of the simulator must provide flight decliphts are seen, 7. Sound System. 7. Sound System. The simulator must provide flight declipht correspond to those that occur int meets all qualification requirements.						ı
The that The mee					mountain wave and rotor conditions.	_
S punc	The simulator must provide visual effects for: (1) Light poles; (2) Raised edge lights as appropriate; and (3) Glow associated with approach lights in low visibility before physical lights are seen,		X	×	Visual effects for light poles and raised edge lights are for the purpose of providing additional depth perception during takeoff, landing, and taxi training tasks. Three dimensional modeling of the actual poles and stanchions is not required.	
						_
	The simulator must provide flight deck sounds that result from pilot actions X that correspond to those that occur in the airplane.	×	×	×		
	The volume control must have an indication of sound level setting which meets all qualification requirements.	×	X	X	For Level D simulators, this indication should be readily available to the instructor on or about the IOS and is the sound level setting required to meet the objective testing requirements as described in Table A2A of this Appendix. For all other simulator levels, this indication is the sound level setting as evaluated during the simulator's initial evaluation.	
The simulator must accurately simulate the wipers, and other significant airplane nois normal and abnormal operations, and incl simulator is landed in an unusual attitude limitations); normal engine and thrust reve gear, and spoiler extension and retraction. Sounds must be directionally representative.	The simulator must accurately simulate the sound of precipitation, windshield wipers, and other significant airplane noises perceptible to the pilot during normal and abnormal operations, and include the sound of a crash (when the simulator is landed in an unusual attitude or in excess of the structural gear limitations); normal engine and thrust reversal sounds; and the sounds of flap, gear, and spoiler extension and retraction. Sounds must be directionally representative.		×	×	For simulators qualified for full stall training tasks, sounds associated with stall buffet should be replicated if significant in the airplane.	1

	A SOC is required.		
7.d.	The simulator must provide realistic amplitude and frequency of flight deck		×
	noises and sounds. Simulator performance must be recorded, compared to		
	amplitude and frequency of the same sounds recorded in the airplane, and be		
	mode a nort of the OTG		

TABLE A1B—TABLE OF TASKS VS. SIMULATOR LEVEL

	QPS requirements					Information
Entry No.	Subjective requirements In order to be qualified at the simulator qualification level indicated, the simulator must be able to perform at least the		nulat			Notes
	tasks associated with that level of qualification.	Α	В	С	D	
1. Preflight I	Procedures					I
1.a	Preflight Inspection (flight deck only)	Х	Х	Х	Х	
1.b	Engine Start	Х	х	х	х	
1.c	Taxiing		R	х	х	
1.d	Pre-takeoff Checks	Х	х	х	х	
2. Takeoff a	nd Departure Phase					
2.a	Normal and Crosswind Takeoff		R	х	х	
2.b	Instrument Takeoff	х	х	х	х	
2.c	Engine Failure During Takeoff	Α	х	х	х	
2.d	Rejected Takeoff	Х	х	х	х	
2.e	Departure Procedure	Х	х	х	х	
3. Inflight Ma	aneuvers					
3.a	Steep Turns	Х	х	х	х	
3.b. High Angle of Attack Maneu- vers						
3.b.1 3.b.2	Approaches to Stall	X	X	X	X	Stall maneuvers at angles of attack above the activation of the stall warning system. Required only for FSTDs qualified to conduct full stall training tasks as indicated on the Statement of Qualification.
3.c	Engine Failure—Multiengine Airplane	х	x	x	х	ilcation.
3.d	Engine Failure—Single-Engine Airplane	Х	х	х	х	
3.e	Specific Flight Characteristics incorporated into the user's FAA approved flight training program.	Α	Α	Α	Α	
3.f	Recovery From Unusual Attitudes	Х	x	x	х	Within the normal flight enve- lope supported by applicable simulation validation data.
3.g	Upset Prevention and Recovery Training (UPRT)			x	x	Upset recovery or unusual atti tude training maneuvers within the FSTD's validation envelope that are intended to exceed pitch attitudes greater than 25 degrees nose up; pitch attitudes greater than 10 degrees nose down, and bank angles greater than 45 degrees.
4. Instrumer	nt Procedures					
4.a	Standard Terminal Arrival/Flight Management System Arrivals Procedures.	х	х	х	Х	

TABLE A1B—TABLE OF TASKS VS. SIMULATOR LEVEL—Continued

	TABLE ATD TABLE OF TAGING VG. GINIOLA					
	QPS requirements					Information
Entry No.	Subjective requirements In order to be qualified at the simulator qualification level indicated, the simulator must be able to perform at least the tasks associated with that level of qualification.	Sir	nulat	or lev	els	Notes
4.b	Holding	Х	X	Х	X	
4.c	Precision Instrument.					
4.c.1	All Engines Operating	Х	х	х	Х	e.g., Autopilot, Manual (Flt. Dir. Assisted), Manual (Raw Data).
4.c.2	One Engine Inoperative	х	х	х	х	e.g., Manual (Flt. Dir. Assisted), Manual (Raw Data).
4.d	Non-Precision Instrument Approach	x	х	х	х	e.g., NDB, VOR, VOR/DME, VOR/TAC, RNAV, LOC, LOC/BC, ADF, and SDF.
4.e	Circling Approach	х	х	х	х	Specific authorization required
4.f	Missed Approach.					
4.f.1	Normal	х	х	Х	Х	
4.f.2	One Engine Inoperative	х	х	Х	Х	
5. Landings	and Approaches to Landings					
5.a	Normal and Crosswind Approaches and Landings		R	Х	Х	
5.b	Landing From a Precision/Non-Precision Approach		R	Х	Х	
5.c	Approach and Landing with (Simulated) Engine Failure—Multiengine Airplane.		R	х	х	
5.d	Landing From Circling Approach		R	Х	х	
5.e	Rejected Landing	Х	х	х	Х	
5.f	Landing From a No Flap or a Nonstandard Flap Configuration Approach.		R	х	х	
6. Normal a	nd Abnormal Procedures					
6.a	Engine (including shutdown and restart)	Х	х	х	Х	
6.b	Fuel System	х	х	Х	Х	
6.c	Electrical System	Х	х	х	Х	
6.d	Hydraulic System	Х	х	х	Х	
6.e	Environmental and Pressurization Systems	Х	х	х	Х	
6.f	Fire Detection and Extinguisher Systems	х	х	х	х	
6.g	Navigation and Avionics Systems	Х	х	х	Х	
6.h	Automatic Flight Control System, Electronic Flight Instrument System, and Related Subsystems.	х	х	х	х	
6.i	Flight Control Systems	х	х	х	х	
6.j	Anti-ice and Deice Systems	х	х	х	х	
6.k	Aircraft and Personal Emergency Equipment	Х	х	х	Х	
7. Emergen	cy Procedures					
7.a	Emergency Descent (Max. Rate)	Х	х	Х	Х	
	I.					

TABLE A1B—TABLE OF TASKS VS. SIMULATOR LEVEL—Continued

	QPS requirements					Information
Entry No.	Subjective requirements In order to be qualified at the simulator qualification level indicated, the simulator must be able to perform at least the	Sir	nulate	or lev	els	Notes
	tasks associated with that level of qualification.	Α	В	С	D	
7.b	Inflight Fire and Smoke Removal	Х	Х	х	х	
7.c	Rapid Decompression	Χ	х	х	х	
7.d	Emergency Evacuation	Х	х	х	х	
8. Postflight	Procedures					
8.a	After-Landing Procedures	Х	Х	х	х	
8.b	Parking and Securing	Х	х	х	х	

[&]quot;A"—indicates that the system, task, or procedure may be examined if the appropriate aircraft system or control is simulated in the FSTD and is working properly.

"R"—indicates that the simulator may be qualified for this task for continuing qualification training.

"X"—indicates that the simulator must be able to perform this task for this level of qualification.

TABLE A1C—TABLE OF SIMULATOR SYSTEM TASKS

	QPS requirements					Information
Entry No.	Subjective requirements In order to be qualified at the simulator qualification level indi-	Sir	nulate	or lev	els	Notes
	cated, the simulator must be able to perform at least the tasks associated with that level of qualification.	Α	В	С	D	
1. Instructor	Operating Station (IOS), as appropriate					
1.a	Power switch(es)	Х	х	Х	х	
1.b	Airplane conditions	Х	Х	х	х	e.g., GW, CG, Fuel loading and Systems.
1.c	Airports/Runways	Х	Х	х	х	e.g., Selection, Surface, Presets, Lighting controls.
1.d	Environmental controls	Х	х	x	х	e.g., Clouds, Visibility, RVR, Temp, Wind, Ice, Snow, Rain, and Windshear.
1.e	Airplane system malfunctions (Insertion/deletion)	Х	х	х	х	
1.f	Locks, Freezes, and Repositioning	Х	х	х	х	
2. Sound Co	ontrols					
2.a	On/off/adjustment	Х	х	х	х	
3. Motion/Co	ontrol Loading System					
3.a	On/off/emergency stop	Х	х	Х	х	
4. Observer	Seats/Stations					
4.a	Position/Adjustment/Positive restraint system	Х	х	Х	х	
			-		-	

49

ATTACHMENT 2 TO APPENDIX A TO PART 60— FFS OBJECTIVE TESTS

TABLE OF CONTENTS

Paragraph No.	Title
1	Introduction.
2	Test Requirements.

TABLE OF CONTENTS—Continued

Paragraph No.	Title
	Table A2A, Objective Tests.
3	General.
4	Control Dynamics.

Pt. 60, App. A

TABLE OF CONTENTS—Continued

Paragraph No.	Title
5	Ground Effect.
6	Motion System.
7	Sound System.
8	Additional Information About Flight Simulator Qualification for New or Derivative Airplanes.
9	Engineering Simulator—Validation Data.
10	[Reserved]
11	Validation Test Tolerances.
12	Validation Data Roadmap.
13	Acceptance Guidelines for Alternative Engines Data.
14	Acceptance Guidelines for Alternative Avionics (Flight-Related Computers and Controllers).
15	Transport Delay Testing.
16	Continuing Qualification Evaluations—Validation Test Data Presentation.
17	Alternative Data Sources, Procedures, and Instrumentation: Level A and Level B Simulators Only.

BEGIN INFORMATION

1. Introduction

- a. For the purposes of this attachment, the flight conditions specified in the Flight Conditions Column of Table A2A of this appendix, are defined as follows:
- $(\dot{1})$ Ground—on ground, independent of airplane configuration;
- (2) Take-off—gear down with flaps/slats in any certified takeoff position;
- (3) First segment climb—gear down with flaps/slats in any certified takeoff position (normally not above 50 ft AGL);
- (4) Second segment climb—gear up with flaps/slats in any certified takeoff position (normally between 50 ft and 400 ft AGL);
- (5) Clean—flaps/slats retracted and gear up; (6) Cruise—clean configuration at cruise
- altitude and airspeed;
 (7) Approach—gear up or down with flaps/slats at any normal approach position as recommended by the airplane manufacturer;
- (8) Landing—gear down with flaps/slats in any certified landing position.
- b. The format for numbering the objective tests in Appendix A, Attachment 2, Table A2A, and the objective tests in Appendix B, Attachment 2, Table B2A, is identical. However, each test required for FFSs is not necessarily required for FTDs. Also, each test

required for FTDs is not necessarily required for FFSs. Therefore, when a test number (or series of numbers) is not required, the term "Reserved" is used in the table at that location. Following this numbering format provides a degree of commonality between the two tables and substantially reduces the potential for confusion when referring to objective test numbers for either FFSs or FTDs.

- c. The reader is encouraged to review the Airplane Flight Simulator Evaluation Handbook, Volumes I and II, published by the Royal Aeronautical Society, London, UK, and AC 25-7, as amended, Flight Test Guide for Certification of Transport Category Airplanes, and AC 23-8, as amended, Flight Test Guide for Certification of Part 23 Airplanes, for references and examples regarding flight testing requirements and techniques.
- d. If relevant winds are present in the objective data, the wind vector should be clearly noted as part of the data presentation, expressed in conventional terminology, and related to the runway being used for the test.

END INFORMATION

BEGIN QPS REQUIREMENTS

2. Test Requirements

- a. The ground and flight tests required for qualification are listed in Table A2A, FFS Objective Tests. Computer generated simulator test results must be provided for each test except where an alternative test is specifically authorized by the responsible Flight Standards office. If a flight condition or operating condition is required for the test but does not apply to the airplane being simulated or to the qualification level sought, it may be disregarded (e.g., an engine out missed approach for a single-engine airplane or a maneuver using reverse thrust for an airplane without reverse thrust capability). Each test result is compared against the validation data described in §60.13 and in this appendix. Although use of a driver program designed to automatically accomplish the tests is encouraged for all simulators and required for Level C and Level D simulators, it must be possible to conduct each test manually while recording all appropriate parameters. The results must be produced on an appropriate recording device acceptable to the responsible Flight Standards office and must include simulator number, date, time, conditions, tolerances, and appropriate dependent variables portraved in comparison to the validation data. Time histories are required unless otherwise indicated in Table A2A. All results must be labeled using the tolerances and units given.
- b. Table A2A in this attachment sets out the test results required, including the parameters, tolerances, and flight conditions

for simulator validation. Tolerances are provided for the listed tests because mathematical modeling and acquisition and development of reference data are often inexact. All tolerances listed in the following tables are applied to simulator performance. When two tolerance values are given for a parameter, the less restrictive may be used unless otherwise indicated. In those cases where a tolerance is expressed only as a percentage, the tolerance percentage applies to the maximum value of that parameter within its normal operating range as measured from the neutral or zero position unless otherwise indicated.

- c. Certain tests included in this attachment must be supported with an SOC. In Table A2A, requirements for SOCs are indicated in the "Test Details" column.
- d. When operational or engineering judgment is used in making assessments for light test data applications for simulator validity, such judgment must not be limited to a single parameter. For example, data that exhibit rapid variations of the measured parameters may require interpolations or a "best fit" data selection. All relevant parameters related to a given maneuver or flight condition must be provided to allow overall interpretation. When it is difficult or impossible to match simulator to airplane data throughout a time history, differences must be justified by providing a comparison of other related variables for the condition being assessed.
- e. It is not acceptable to program the FFS so that the mathematical modeling is correct only at the validation test points. Unless otherwise noted, simulator tests must represent airplane performance and handling qualities at operating weights and centers of gravity (CG) typical of normal operation. Simulator tests at extreme weight or CG conditions may be acceptable where required for concurrent aircraft certification testing. Tests of handling qualities must include validation of augmentation devices.
- f. When comparing the parameters listed to those of the airplane, sufficient data must also be provided to verify the correct flight condition and airplane configuration changes. For example, to show that control force is within the parameters for a static stability test, data to show the correct airspeed, power, thrust or torque, airplane configuration, altitude, and other appropriate datum identification parameters must also be given. If comparing short period dynamics, normal acceleration may be used to establish a match to the airplane, but airspeed. altitude, control input, airplane configuration, and other appropriate data must also be given. If comparing landing gear change dynamics, pitch, airspeed, and altitude may be used to establish a match to the airplane. but landing gear position must also be provided. All airspeed values must be properly

annotated (e.g., indicated versus calibrated). In addition, the same variables must be used for comparison (e.g., compare inches to inches rather than inches to centimeters).

- g. The QTG provided by the sponsor must clearly describe how the simulator will be set up and operated for each test. Each simulator subsystem may be tested independently, but overall integrated testing of the simulator must be accomplished to assure that the total simulator system meets the prescribed standards. A manual test procedure with explicit and detailed steps for completing each test must also be provided.
- h. For previously qualified simulators, the tests and tolerances of this attachment may be used in subsequent continuing qualification evaluations for any given test if the sponsor has submitted a proposed MQTG revision to the responsible Flight Standards office and has received responsible Flight Standards office approval.
- i. Simulators are evaluated and qualified with an engine model simulating the airplane data supplier's flight test engine. For qualification of alternative engine models (either variations of the flight test engines or other manufacturer's engines) additional tests with the alternative engine models may be required. This attachment contains guidelines for alternative engines.
- j. For testing Computer Controlled Aircraft (CCA) simulators, or other highly augmented airplane simulators, flight test data is required for the Normal (N) and/or Nonnormal (NN) control states, as indicated in this attachment. Where test results are independent of control state, Normal or Non-normal control data may be used. All tests in Table A2A require test results in the Normal control state unless specifically noted otherwise in the Test Details section following the CCA designation. The responsible Flight Standards office will determine what tests are appropriate for airplane simulation data. When making this determination, the responsible Flight Standards office may require other levels of control state degradation for specific airplane tests. Where Nonnormal control states are required, test data must be provided for one or more Non-normal control states, and must include the least augmented state. Where applicable. flight test data must record Normal and Non-normal states for:
- (1) Pilot controller deflections or electronically generated inputs, including location of input; and
- (2) Flight control surface positions unless test results are not affected by, or are independent of, surface positions.
- k. Tests of handling qualities must include validation of augmentation devices. FFSs for highly augmented airplanes will be validated both in the unaugmented configuration (or failure state with the maximum permitted degradation in handling qualities) and the

Pt. 60, App. A

augmented configuration. Where various levels of handling qualities result from failure states, validation of the effect of the failure is necessary. Requirements for testing will be mutually agreed to between the sponsor and the responsible Flight Standards office on a case-by-case basis.

1. Some tests will not be required for airplanes using airplane hardware in the simulator flight deck (e.g., "side stick controller"). These exceptions are noted in Section 2 "Handling Qualities" in Table A2A of this attachment. However, in these cases, the sponsor must provide a statement that the airplane hardware meets the appropriate manufacturer's specifications and the sponsor must have supporting information to that fact available for responsible Flight Standards office review.

m. For objective test purposes, see Appendix F of this part for the definitions of "Near maximum," "Light," and "Medium" gross weight.

14 CFR Ch. I (1-1-24 Edition)

END QPS REQUIREMENTS

BEGIN INFORMATION

n. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot tests" results in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition should exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.

o. For references on basic operating weight, see AC 120-27, "Aircraft Weight and Balance;" and FAA-H-8083-1, "Aircraft Weight and Balance Handbook."

END INFORMATION

DI ADBHEHEI 3 with DISTILLED

	INFORMATION	Notes	1,000
		Simulator Level	A B C D
Table A2A - Full Flight Simulator (FFS) Objective Tests	NTS	Test	Details
le A2A - Full Flight S	QPS REQUIREMENTS	Flight	Conditions
Tab		Toloronco	TOTAL STATE OF THE
		Test	Title
			Entry Number

					-	}	$\frac{1}{2}$	
. Performance.	nance.							
.а.	Taxi.							
.a.1	Minimum radius turn.	±0.9 m (3 ft) or ±20% of airplane turn radius.	Ground.	Plot both main and nose gear loci and key engine parameter(a). Data for no bakes and the minimum thrust required to maintain a steady turn except for airplanes requiring asymmetric thrust or braking to achieve the minimum radius turn.	×	×	×	
.a.2	Rate of turn versus nosewheel steering angle (NWA).	±10% or ±2°/s of turn rate.	Ground.	Record for a minimum of two speeds, greater than minimum turning radius speed with one at a typical taxi speed, and with a spread of at least 5 kt.	×	×	×	
.b.	Takeoff.			Note—All airplane manufacturer commonly- used ecrificated take-diff flap settings must be demonstrated at least once either in minimum unstick speed (1, b.3), normal take-off (1, b.4), critical engine failure on take-off (1, b.5) or crossward take-off (1, b.6).				
.b.1	Ground acceleration time and distance.	±1.5 s or ±5% of time; and ±6 Im (200 ft) or ±5% of distance.	Takeoff.	Acceleration time and distance must be recorded X for a minimum of 80% of the total time from brake release to Y. Preliminary aircraft certification data may be used.	X	×	X × c c c c c c c c c c c c c c c c c c	May be combined with normal takeoff (1.b.4.) or rejected takeoff (1.b.7.). Plotted data should be shown using appropriate scales for each portion of the maneuver.
.b.2	psped, ground (V _{mep}) sped, ground (V _{mep}) using acrodynamic controls only per applicable airworthiness requirement or adlemative engine inoperative test to demonistrate ground characteristics.	#25% of maximum airplane lateral devatation reached or ±1.5 m (5 ft). For airplanes with reversible flight control systems: #2.2 daN (5 lbf) or ±10% of rudder pedal force.	Takoff.	Engine failure speed must be within ±1 kt of a surplane engine failure speed. Engine thrist decay must be that resulting from the mathematical model for the engine applicable to the FSTD under test. If the modeled engine is not the same as the airplane manufacturer's flight test engine, a further test may be run with the same initial conditions using the thrust from the flight test data as the driving parameter.	×	×	X Heddyddogn Hogod	If a V _{may} test is not available, an acceptable alternative is a flight test snap engine deceleration to diet at a speed deceleration to diet at a speed deceleration to diet at a speed between V ₁ and V ₁ -10 kt, followed by control of the deading using actordynamic control only and recovery should be achieved with the main geat on the ground. To ensure only aerodynamic control, noswheel steering should be disabled (i.e. asstored) or the nosewheel held slightly off the ground.

V _{mm} is defined as the minimum speed at which the last main landing gear leaves the ground. Main landing gear leaves struct compression or equivalent air/ground signal should be recorded. If a V _{mm} test is not available, alternative acceptable flight tests are a constant high—alternative acceptable flight tests are a constant high—alternative lakeoff run through main gear lift-off or an early rotation takeof. If either of these alternative solutions is selected, alt body contact/tail strike protection fluctionally in present on the airplane, slound be active.		
×	×	×
×	×	×
×	×	×
×	×	×
Record time history data from 10 knots before start of rotation until at least 5 seconds after the occurrence of main gear lift-off.	Data required for near maximum certificated takeoff weight at mid center of gravity location and light takeoff weight at an aft center of gravity location. If the airplane has more than one certificated takeoff configuration, a different configuration must be used for each weight. Record takeoff profile from brake release to at least 61 m (200 ft) AGL.	Record takeoff profile to at least 61 m (200 ft) AGL. Engine failure speed must be within ±3 kt of airplane data. Test at near maximum takeoff weight.
Takeoff.	Takeoff.	Takeoff.
±3. kt airspeed. ±1.5° pitch angle.	±1.3° pitch angle. ±1.3° AOA. ±6 m (20 ft) height. For airplanes with reversible flight control systems: ±2 dan (51 ft) or ±1.0% of column force.	±3 kt airspeed. ±1.5° pitch angle. ±1.5° AOA. ±6 m (20 ft) height. ±2° roll angle. ±2° side-slip angle. ±2° beading angle. For airplanes with For airplanes with systems: ±2.2 daN (5 lbf) or ±10% of volumn force; ±1.3 daN (3 lbf) or ±10% of wheel force; and
Minimum unstick speed (Vm) or speed (Vm) or equivalent test to demonstrate early rotation take-off characteristics.	Normal take-off.	Ortical engine failure on take-off.
1.b.3	1.b.4	1.6.5

		_												_		
												Airplane should be configured with all anti-ice and de-ice systems operating normally, gear up and goaround flap.	All icing accountability considerations, in accordance with the airplane performance data for an approach in icing conditions, should be amplied.			
			×			×				×		X			×	
			×			×				×		X			×	
			×			×						×			×	
			×			×						×			×	
Record hands-off from 5 s before engine failure to +5 s or 30° roll angle, whichever occurs first.	CCA: Test in Normal and Non-normal control state.		Flight test data are preferred; however, airplane performance manual data are an acceptable alternative.	Record at nominal climb speed and mid initial climb altitude.	FSTD performance is to be recorded over an interval of at least 300 m (1 000 ft).	Flight test data is preferred; however, airplane performance manual data is an acceptable alternative.	Record at nominal climb speed.	FSTD performance is to be recorded over an interval of at least 300 m (1,000 ft).	Test at WAT (weight, altitude or temperature) limiting condition.	Flight test data or airplane performance manual data may be used.	Test for at least a 1,550 m (5,000 ft) segment.	Flight test data or airplane performance manual data may be used. FSTD performance to be recorded over an interval of at least 300 m (1,000 ft).	Test near maximum certificated landing weight as may be applicable to an approach in icing conditions.		Time required to increase airspeed a minimum of 50 kt, using maximum continuous thrust rating or equivalent.	For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.
			Clean.			2nd segment climb.				Clean		Approach			Cruise	
			±3 kt airspeed. ±0.5 m/s (100 ft/ min) or ±5% of rate of elimb			±3 kt airspeed. ±0.5 m/s (100 ft/ min)	or ±5% of rate of climb, but not less than airulane nerformance	data requirements.		±10% time, ±10% distance, ±10% fuel used		±3 kt airspeed. ±0.5 m/s (100 ft/ min) or ±5% rate of climb, but not less than airplane performance	data.		±5% Time	
		Climb.	Normal Climb, all engines operating.			One-engine- inoperative 2nd segment climb.				One Engine Inoperative En route Climb.		One Engine Inoperative Approach Climb for airplanes with icing accountability if provided in the	airplane performance data for this phase of flight.	Cruise / Descent.	Level flight acceleration	
		1.c.	1.e.1.			1.c.2.				1.c.3.		1.c.4.		1.d.	1.d.1.	

				See Appendix F of this part for definitions of T ₁ , and T ₁ .	See Appendix F of this part for definitions of T _i , and T _i .				ould e e m ne ne D, a	Test results should be validated with in-flight data	from tests such as longitudinal static stability, stalls, etc.			Test results should be validated with in-flight data from tests such as engine-out	trims, steady state side-slips, etc.				Test results should be validated with in-flight data from tests such as engine-out
	×			×	×		t		ixtures ation conting the defort by the cutoffine cutoffine the cutoffine cutoffine the cutoffine cutoffin	×				×					×
	×			×	×				test fi menta onducc oe use, ing eq ing eq ing eq ing ed cted c	×				×					×
				×	×				ternal hile c ould t easur ed wi ressu	×				×					×
				×	×				of exititis is this is ent within control in the mind in the pact pact process.	×				×					×
runway braking coefficients, are an acceptable alternative.	Either flight test or manufacturer's performance manual data must be used, where available.	Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway baking coefficients, are an acceptable alternative.		Total response is the incremental change in the critical engine parameter from idle power to goaround power.	Total response is the incremental change in the critical engine parameter from maximum takeoff power to idle power.	to the bound			Note 2 — Peting of position wereasts force is no applicable (f) forces are generated solely by use of cirplane hadrone in the 1871D. Note 2 — Petit, roll and you controller position reveats force or time should be measured at the control. An alternative method in least of external tests fixtures at the flight controls would be to have recording and measuring instrumentation built into the FSTD. The force and position data from this instrumentation could be used by the contacting the state of the employer of the test provided the instrumentation was verified by using external measuring instrumentation or the state control closeds of the instrumentation could be used for both state control closeds, or equivalent means, and that evidence of the suspiciony comparison is method in the MQTs, the maximentation could be used for both should be repeated if major mediteriors of the measuring applications and or repairs are made to the control closeds. Perfection of the instrumentation by using external measuring the expected may time being lost for the installation could be used without any time being lost for the installation of external devices. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures as the Note 3 — FSTD static control testing from the data provider if a single set of data is applicable to both sides. If controls are not mechanically interconnected on the FSTD, a standard is required from the data provider if a single set of data is applicable to both sides. If controls are not mechanically interconnected on the size best of the vest sufficient.	Record results for an uninterrupted control sweep to the stops.				Record results for an uninterrupted control sweep to the stops.					Record results for an uninterrupted control sweep to the stops.
	Landing.			Approach or landing	Ground				ticable fly overs are general sus force or time should be the measuring instrumentatio at Provided the instrument at Provided the instrument of the general properties only a made to the court of and dynamic flight con dise and dynamic flight con dist are of pilot controls is on tr ff a single set of data is a	Ground.				Ground.					Ground.
	±61 m (200 ft) or ±10% of distance.			±10% Ti or ±0.25 s; and ±10% Tt or ±0.25 s.	±10% Ti or ±0.25 s; and	±10% 11 0f ±0.23 s.			uition versus force is not app that you controller position ver advantage of the artificial of a marched to the artificial that of the artificial of the application and or re- action of external devices. St policies from the secon outrol testing from the secon quiron of praying from the secon intend from the data provide triving from the data provide	±0.9 daN (2 lbf) breakout.	±2.2 daN (5 lbf) or ±10% of force.	±2° elevator angle.		±0.9 daN (2 lbf) breakout.	±1.3 daN (3 lbf) or ±10% of force.	±2° aileron angle.	±3° spoiler angle.		±2.2 daN (5 lbf) breakout.
	Stopping distance, wheel brakes, icy	гипмау.	Engines.	Acceleration.	Deceleration.		2. Handling Qualities.	Static Control Tests.	Note 2 — Festing of position werst art the flight controls would be to I be directly recorded and matched be directly recorded and matched static control cheeks, or equivalent static control cheeks, or equivalent should be repeated if major modified being lost for the installation of excludition daw where applicable. Association daw where applicable. Note 3 — FSTD static control tests and restrict is wifficient where we fortest is wifficient.	Pitch controller position versus force	and surface position calibration.		(Reserved)	Roll controller position versus force and surface position	calibration.			(Reserved)	Rudder pedal position versus force and surface position calibration
	1.e.4.		J.1	1.f.1.	1.f2.		2. Handlin	2.a.		2.a.1.a.			2.a.1.b.	2.a.2.a.				2.a.2.b.	2.a.3.a.

	±2.2 daN (5 lbf) or ±10% of force.				trims, steady state side-slips, etc.
_	±2° rudder angle.				
	±0.9 daN (2 lbf) breakout.	Ground.	Record results of an uninterrupted control sweep to X X the stops.	×	×
	±1.3 daN (3 lbf) or ±10% of force.				
_	±2° NWA. ±2° NWA.	Ground.	Record results of an uninterrupted control sweep to X X	×	×
	±0.5° trim angle.	Ground.	* *	×	The purpose of the test is to compare FSTD surface position and indicator against the flight control model computed value.
	±10% of trim rate (°/s) or or ±0.1°/s trim rate.	Ground and approach.	Trim rate to be cheeked at pilot primary induced X X trim rate (ground) and autoplict or pilot primary trim rate in-flight at go-around flight conditions. For CCA, representative flight test conditions must be used.	×	×
	When matching engine parameters: ±5° of TLA. #5° of TLA. When matching detents: ±3% N to ±.03 EPR or ±33% to reque, or equivalent. Where the levers do not have angular travel, a tolerance of ±2, cm eloterance of ±2, cm eloterance of ±2, cm eloterance of ±2, cm eloterance of ±2, cm	Ground.	Simultaneous recording for all engines. The X tolerances apply against airplane data. For airplanes with throttle detents, all detents to be presented and at least one position between detents' endpoints (where practical). For airplanes without detents, end points and at least three other positions are to be presented.	×	Data from a test airplane or equinecting test bench are acceptable, provided the correct engine controller (both hardware and software) is used. In the case of propeller-driven airplanes, if an additional lever, usually referred to as the propeller lever, is present, it should also be checked. This test may be a series of snapshot tests.
	±2.2 daN (5 lbf) or ±10% of force. ±1.0 MPa (150 psi) or ±10% of brake system pressure.	Ground.	Reture the by drautic system pressure to pedal position in a ground static test. Both left and right pedals must be checked.	×	FFS computer output results may be used to show compliance.
	±10% or ±5 lb (2.2 daN)) Stick/Column force	Ground or Flight	Test is intended to validate the stick/column transient fores as a result of a sick pusher system activation. This test may be conducted in an on-ground condition through stimulation of the stall	×	A ricraft manufacturer design data may be utilized as validation data as determined acceptable by the responsible Flight Standards office.

				protection system in a manner that generates a stick pusher response that is representative of an in-flight condition.		Test requirement may be met through column force validation testing in validation testing in conjunction with the Stall Characteristics test (2,c,8,a.). This test is required only for
						FSTDs qualified to conduct full stall training tasks.
2.b.	Dynamic Control Tests.	ts.				
	Note.— Tests 2.b.1, 2.b.2 and 2 airplane controller unit installe paragraph 4 of this attachment.	.2 and 2.b.3 are not applicab tinstalled in the FSTD, Power chment.	le for FSTDs where the con r setting may be that requir	Note.— Tests B. b. 1, 2 b. 2 and 2 b.3 are not applicable for FXTDs where the courtof forces are completely generated within the airplane controller unit installed in the FSTD. Power setting may be that required for level flight unless otherwise specified. See paragraph 4 of this autochment.		
2.b.1.	Pitch Control.	For underdamped systems:	Takeoff, Cruise, and Landing.	Data must be for normal control displacements in both directions (approximately 25% to 50% of full throw or approximately 25% to 50% of	X	X n = the sequential period of a full oscillation.
		$T(P_0) \pm 10\%$ of P_0 or ± 0.05 s.		maximum allowable pitch controller deflection for flight conditions limited by the maneuvering		Refer to paragraph 4 of this Attachment.
		$T(P_1) \pm 20\%$ of P_1 or ± 0.05 s.		Tolerances apply against the absolute values of		For overdamped and critically damped systems, see Figure A2B of Anneadix A for an
		$T(P_2) \pm 30\%$ of P_2 or ± 0.05 s.		each period (considered independently).		illustration of the reference measurement.
		$T(P_n) \pm 10^*(n+1)\%$ of P_n or ± 0.05 s.				
		$T(A_{\rm in}) \pm 10\%$ of $A_{\rm max}$, where $A_{\rm max}$ is the largest amplitude or $\pm 0.5\%$ of the total control travel (stop to stop).				
		$T(A_d) \pm 5\%$ of $A_d =$ residual band or $\pm 0.5\%$ of the maximum control travel = residual band.				
		±1 significant overshoots (minimum of 1 significant overshoot).				
		Steady state position within residual band.				
		Note 1.— Tolerances should not be applied on period or amplitude after the last significant overshoot.				

	Refer to paragraph 4 of this Attachment. For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.			
	×	×	×	×
	×	×	×	×
	Data must be for normal control displacement (approximately 25% to 50% of full throw or approximately 25% to 50% of funstimum allowable roll controller deflection for flight conditions limited by the maneuvering load envelope).	Data must be for normal control displacement (approximately 23% to 50% of full throw).	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2% pitch rate). Test in both directions. Show time history data from 5 s before until at least 5 s after initiation of control input. If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction. CCA: Test in normal and non-normal control state.	Control inputs must be typical of minor corrections made while established on an 11.5 approach (approximately 0.5 to 2% stoll rate). Test in one direction. For airplanes that exhibit non-symmetrical behavior, test in both directions. Show time history data from 5 s before until at least 5 s after initiation of control input.
	Takeoff, Cruise, and Landing.	Takeoff, Cruise, and Landing.	Approach or Landing.	Approach or landing.
None 2.— Oscillations within the residual band are not considered asygnificant and are not subject to tolerances. For overlamped and critically damped systems only, the following tolerance applies: [Robos of the control of the critically damped and critically damped and critically damped applies. [Robos of the critical of the cri	Same as 2.b.1.	Same as 2.b.1.	±0.15% body prich rate or ±20.7% of peak body prich rate prich rate prich rate prich rate prick	±0.15% body roll rate or ±20% or peak body roll rate applied throughout the time history.
	Roll Control.	Yaw Control.	Small Control Inputs – Pitch.	Small Control Inputs - Roll.
	2.b.2.	2.b.3.	2.b.4.	2.b.5.

		×							×			×			×				
		X							×			×			×				_
									×			×			×				_
If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.	CCA: Test in normal and non-normal control state.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s yaw rate).	Test in both directions.	Show time history data from 5 s before until at least 5 s after initiation of control input.	If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.	CCA: Test in normal and non-normal control state.			Power change from thrust for approach or level flight to maximum continuous or go-around power.	Time history of uncontrolled free response for a time increment equal to at least 5 s before initiation of the power change to the completion of the power change + 15 s.	CCA: Test in normal and non-normal control mode	Time history of uncontrolled free response for a X time increment equal to at least 5 s before	initiation of the reconfiguration change to the completion of the reconfiguration change + 15 s.	CCA: Test in normal and non-normal control mode	Time history of uncontrolled free response for a	initiation of the configuration change to the	comprehension of the companion change 113 s.	Results required for both extension and retraction.	
		Approach or landing.						otherwise specified.	Approach.			Takeoff through initial flap retraction, and	approach to landing.		Cruise.				
		±0.15°/s body yaw rate or ±20% of peak body yaw rate applied throughout the time	history.				Tests.	Power setting is that required for level flight unless otherwise specified	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch	, , , , , , , , , , , , , , , , , , ,		±3 kt airspeed.	±30 m (100 ft) altitude.	$\pm 1.5^{\circ}$ or $\pm 20\%$ of pitch angle.	±3 kt airspeed.	±30 m (100 ft) altitude.	±1.5° or ±20% of pitch	angle.	
		Small Control Inputs - Yaw.					Longitudinal Control Tests	Power setting is that rec	Power Change Dynamics.			Flap/Slat Change Dynamics.			Spoiler/Speedbrake	Cinango Ly namics.			
		2.b.6.					2.c.		2.c.1.			2.c.2.			2.c.3.				

				CCA: Test in normal and non-normal control mode		
2.c.4.	Gear Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Takeoff (retraction), and Approach (extension).	Time history of uncontrolled free response for a X X time increment equal to at least 5 s before initiation of the configuration change to the completion of the configuration change + 15 s. CCA: Test in normal and non-normal control mode.	×	×
2.e.5.	Longitudinal Trim.	±1° elevator angle. =0.5° stabilizer or trim surface angle. ±1° pitch angle. =5% of net thrust or courvalent.	Cruise, Approach, and Landing.	Steady-state wings level trim with thrust for level X X flight. This test may be a series of snapshot tests. CCA: Test in normal or non-normal control mode, as applicable.	×	×
2.c.6.	Longitudinal Maneuvering Stability (Stick Force/g).	±2.2 daN (5 lbf) or ±10% of pitch controller force. Alternative method: ±1° or±10% of the change of elevator angle.	Cruise, Approach, and Landing.	Continuous time history data or a series of snapshot tests may be used. Test up to approximately 30° of roll angle for approach and landing configurations. Test up to approach and landing configuration. Test up to approximately 45° of roll angle for the cruise configuration. Force tolerance not applicable if forces are generated solely by the use of airplane hardware in the FSTD. Alternative method applies to airplanes which do not exhibit stick-force-per-g characteristics. CCA: Test in normal or non-normal control mode	×	×
2.c.7.	Longitudinal Static Stability.	±2.2 daN (5 lbf) or ±10% of pitch controller free. Alternative method: ±1° or ±10% of the change of elevator angle.	Approach.	Data for at least two speeds above and two speeds X and two speeds above and two speeds afterwards will feight to demonstrate stick force versus speed characteristics. This test may be a series of snapshot tests. Force tolerame is not applicable if forces are generated solely by the use of airplane hardware in the FSTD. Alternative method applies to airplanes which do not exhibit speed stability characteristics. CCA: Test in normal or non-normal control mode, as applicable.	×	×

Control displacements and flight control surfaces must be plotted and demonstrate correct rend and magnitude.			Approach to stall entry in turning flight of at least 3.5 what waged (accelerated stall) Approach to stall entry in a power-on condition (required only for propeller driven aircraft) The cruise flight condition must be conducted in all annewn (clean) configuration. The second				Tolerances on stall buffer are not applicable where the first indication of the stall is the activation of the stall warning system (i.e. stick shaker).
±2.0° pitch angle; ±2.0° angle of attack; and ±2.0° bank angle			ar insp-sup (cean) configuration. In escend segment climb flight condition must use a different flap setting than the approach or landing flight condition.				
Additionally, for those administry with reversible light control systems: ±10% or ±5 lb (2.2 daN)) Stick/Column force			CCA: Test in Normal and Non-normal control states. For CCA aircraft with stall envelope protection systems, the normal mode testing is only required to an angle of attack ranges morecessary to demonstrate the correct operation of the system. These tests may be used to satisfy the required dangle of aircack Juliah memouver and envelope protection tests (test 2.16.6).				
±10% of period. Cruise.	-≌	e.	that	x	×	×	
±10% of time to one half or double amplitude or ±0.02 of damning ratio.			necessary to determine time to one half or double amplitude, whichever is less.				
±1.5° pitch angle or Cruise. ±2°/s pitch rate.	uise.		ntrol	×	×	×	
±0.1 g normal acceleration							
Lateral Directional Tests.							
ight unless or	wise	specified.					
±3 kt airspeed. Takeoff. (whichev critical ii	keoff, hichev ical ii	Takeoff or Landing (whichever is most critical in the airplane).	Takeoff thrust must be set on the operating engine(s). Time history or snapshot data may be used.	×	×	X	Minimum speed may be defined by a performance or control limit which prevents demonstration of V _{mea} or V _{mel} in the conventional manner.
			CCA: Test in normal or non-normal control state, as applicable.				
±2% or ±10% of roll Cruise, a rate.	uise, a nding.	Cruise, and Approach or Landing.	Test with normal roll control displacement (approximately one-third of maximum roll controller travel).	×	×	×	
ror arpaanes with reversible flight control systems:			This test may be combined with step input of flight deck roll controller test 2.d.3.				
±1.3 daN (3 lbf) or ±10% of wheel force.							
±2° or ±10% of roll Approac	proac	Approach or Landing.	This test may be combined with roll response (rate) test 2.d.2.	×	×	×	With wings level, apply a step roll control input using

				CCA: Test in normal and non-normal control mode			approxi the roll When ro 20° to 3 return th neutral approxi airplane	approximately one-third of the roll controller travel. When reaching approximately 20° to 30° of bank, abruptly return the roll controller to neutral and allow approximately 10 seconds of
2.d.4.	Spiral Stability.	Correct trend and ±2° or ±10% of relul angle in 20 s. If alternate test is used: correct trend and ±2° aileron angle.	Cruise, and Approach or Landing.	Airplanc data averaged from multiple tests may be used. Test for both directions. Test for both directions. As an alternative test, show lateral control argue for maintain as steady turn with a roll angle of approximately 30°. CCA: Test in non-normal control mode.	×	×	×	
2.d.5.	Engine Inoperative Trim.	±1° nudder angle or ±1° tab angle or equivalent rudder pedal. ±2° side-slip angle.	Second Segment Climb, and Approach or Landing.	This test may consist of snapshot tests.	×	×	Test she manner which a manner which a an enging an enging should 1 Approashould 1 flight.	Test should be performed in a manner similar to that for which a plot is trained to trim an engine failure condition. 2nd segment climb test should be at takeoff firmst. Approach or landing test should be at thrust for level flight.
2.d.6.	Rudder Response.	±2% or ±10% of yaw rate.	Approach or Landing.	Test with stability augmentation on and off. Test with a step input at approximately 25% of full rudder pedal throw. CCA: Test in normal and non-normal control	×	×	×	
2.d.7.	Dutch Roll	±0.5 s or ±10% of period. ±10% of time to one half or double amplitude ratio. ±1 s or ±20% of time difference between peaks of roll angle and side-slip angle.	Cruise, and Approach or Landing.	Test for at least six cycles with stability augmentation off. CCA: Test in non-normal control mode.	×	×	*	
2.d.8.	Steady State Sideslip.	For a given rudder position: ±2° roll angle;	Approach or Landing.	This test may be a series of snapshot tests using X at least two rudder positions (in each direction for propeller-driven airplanes), one of which must be near maximum allowable rudder.	×	×	×	

		Two tests should be shown, including wo normal landing flaps (if applicable) one of which should be near maximum certificated landing mass, the other at light or medium mass.
		× ×
		× ×
		×
		Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown. CCA: Test in normal and non-normal control mode, if applicable. Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown. Test at near maximum certificated landing weight.
		Landing. Minimum Certified Landing Flap Configuration.
±1° side-slip angle; ±2° or ±10% of ailcron angle; and ±5° or ±10% of spoiler or equivalent toll force. For airplanes with reversible flight control systems: ±1.3 daN (3 lbf) or ±10% of vwheel force. ±2.2 daN (5 lbf) or ±10% of rudder pedal force.		±3. kt airspeed. ±1.5° pitch angle. ±1.5° AOA. ±3 m (10 ft) or ±10% of height. For airplanes with reversible flight control systems. ±2.2 daN (5 lbf) or ±10% of column force. ±3. kt airspeed. ±1.5° pitch angle. ±1.5° AOA. ±3. m (10 ft) or ±10% of height. For airplanes with reversible flight control systems.
	Landings.	Normal Landing. Minimum Flap Landing.
	2.e.	2.6.2.

	In those situations where a maximum crosswind or a maximum demonstrated	crosswind is not known,	Standards office.																See Appendix F of this part for definition of T _c .	
	×											x							×	
	×											×							×	
	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown	speed.	Test data is required, including wind profile, for a crosswind component of at least 60% of airplane	performance data value measured at 10 m (33 ft) above the runway.	Wind components must be provided as headwind and crosswind values with respect to the runway.							Test from a minimum of 61 m (200 ft) AGL to a	speed.						If autopilot provides roll-out guidance, record lateral deviation from touchdown to a 50% decrease in main landing gear touchdown speed.	Time of autopilot flare mode engage and main gear touchdown must be noted.
	Landing.											Landing.							Landing.	
±2.2 daN (5 lbf) or ±10% of column force.	±3 kt airspeed.	±1.5" pitch angle.	±1.5° AOA.	±3 m (10 ft) or ±10% of height.	±2° roll angle.	±2° side-slip angle.	±3° heading angle.	For airplanes with reversible flight control systems:	±2.2 daN (5 lbf) or ±10% of column force.	±1.3 daN (3 lbf) or ±10% of wheel force.	±2.2 daN (5 lbf) or ±10% of rudder pedal force.	±3 kt airspeed.	±1.5° pitch angle.	±1.5° AOA.	±3 m (10 ft) or ±10% of height.	±2° roll angle.	±2° side-slip angle.	±3° heading angle.	±1.5 m (5 ft) flare height.	±0.5 s or ± 10% of Tf.
	Crosswind Landing.											One Engine Inconstative Landing	moperative transmig.						Autopilot landing (if applicable).	
	2.e.3.											2.e.4.							2.e.5.	

		±0.7 m/s (140 ft/min) rate of descent at touchdown.			
		±3 m (10 ft) lateral deviation during roll- out.			
2.e.6.	All-engine autopilot	±3 kt airspeed.	As per airplane	Normal all-engine autopilot go-around must be X X X X demonstrated (if annicable) at medium weight	
		±1.5° pitch angle.		demonstrated (1 apprendix) at medium weight.	
		±1.5° AOA.			
2.e.7.	One engine	±3 kt airspeed.	As per airplane	Engine inoperative go-around required near X X X	
	around.	±1.5° pitch angle.		critical engine inoperative.	
		±1.5° AOA.		Provide one test with autopilot (if applicable) and	
		±2° roll angle.		one without autophiot.	
		±2° side-slip angle.		C.C.A. Non-autophiot test to be conducted in non- normal mode.	
2.e.8.	Directional control (rudder effectiveness)	±5 kt airspeed.	Landing.	Apply rudder pedal input in both directions using X X X full reverse thrust until reaching full thrust	
	with symmetric reverse thrust.	±2°/s yaw rate.		reverser minimum operating speed.	
2.e.9.	Directional control	±5 kt airspeed.	Landing.	With full reverse thrust on the operating X X X X enrine(s) maintain heading with rudder nedal	
	with asymmetric reverse thrust.	±3° heading angle.		input utili maximum rudder pedal input or thrust reverser minimum operation speed is reached.	
2.f.	Ground Effect.				
	Test to demonstrate Ground Effect.	±1° elevator angle.	Landing.	A rationale must be provided with justification of X X X X results.	See paragraph 5 of this Attachment for additional
		±0.5° stabilizer angle.		OCA, Toot is accessed on non-non-non-non-non-non-non-non-non-	information.
		±5% of net thrust or equivalent.		mode, as applicable.	
		±1° AOA.			
		±1.5 m (5 ft) or ±10% of height.			
		±3 kt airspeed.			
		±1° pitch angle.			
2.g.	Windshear.				
	Four tests, two takeoff and two landing, with one of each conducted in etill oir and the other	See Attachment 5 of this appendix.	Takeoff and Landing.	Requires windshear models that provide training in the specific skills needed to recognize windshear phenomena and to execute recovery procedures 26e Attachment 3 of this appendix for rests releases to and necondures.	See Attachment 5 of this appendix for information related to Level A and B simulators.
	Still all and the other			TOT tools, total and coordines.	

	with windshear active							
	to demonstrate windshear models.							
2.h.	Flight Maneuver and	Flight Maneuver and Envelope Protection Functions.	ions.					
	Note. — The requireme inputs during entry into different) are required.	Note. — The requirements of 2.h are only applicable to computer-controlled airplanes. inputs during entry into each envelope protection function (i.e. with normal and egged different may are required. Set thin tast as required to reach the envelope protection function different.	le to computer-controlled ai mction (i.e. with normal and ich the envelope protection f	Note. — The requirements of 2.h are only applicable to computer-controlled airplanes. Time history results of response to control raping starting earny into each envelope protection function its arrival model air and legended control states if their function its different are required. Set thrust as reaaired to reach the envelope protection function.				
2.h.1.	Overspeed.	±5 kt airspeed.	Cruise.		×	X		
2.h.2.	Minimum Speed.	±3 kt airspeed.	Takeoff, Cruise, and Approach or Landing.		-	-		
2.h.3.	Load Factor.	±0.1g normal load factor	Takeoff, Cruise.		×	X		
2.h.4.	Pitch Angle.	±1.5° pitch angle	Cruise, Approach.		X	X		
2.h.5.	Bank Angle.	±2° or ±10% bank angle	Approach.		×	X		
2.h.6.	Angle of Attack.	±1.5° angle of attack	Second Segment Climb, and Approach or Landing.		×	×		
2.i.	Engine and Airframe Icing Effects	Icing Effects						
2.i.	Fnoine and Airframe	D	Takeoff or Annroach or	Time history of a full stall and initiation of the	ľ	>	Tests will be evaluated for	T,
	leing Effects Demonstration (High Angle of Attack)		Landing [One flight condition – two tests (ice on and off)]	recovery, Tests are intended to demonstrate representative acrodynamic effects caused by infight ice accretion. Fight test validation data is not required. Two tests are required to demonstrate engine and aritimate sing effects. One test will demonstrate the FSTDs baseline performance without ice accretion, and the second test will demonstrate the acredynamic effects of ice accretion relative to the baseline test. The test must utilize the icing model(s) as described in the required Statement of Compliance in Table ALI, section 2, Test must include rationale that describes the icing effects basing demonstrated. Leing effects may include. But are not limited to, the following effects as applicable to the particular ariplane type: Decrease in stall bufflet characteristics and threshold of perception Thanges in control effectiveness Change in stall bufflet characteristics and threshold of perception Engine effects (power reduction account) effects the effects the effects the effects the effects of the percent on the aricraft in the ice accretion scenario				on stall
3 Motion System	Suctions			oenig tested)				
3. MOHOL	System.					+		
3.а.	Frequency response.					_		

			of this		em oom oom lis		dished urer a a		s for ould f is of this	
See paragraph 6 of this Attachment.		See paragraph 6 of this Attachment.	Refer to Attachment 3 of this Appendix on subjective testing.		Ensure that motion system hardware and software (in normal FSTD operating mode) continue to perform as originally qualified. Performance changes from the original baseline can be readily identified with this information. See paragraph 6.c., of this Attachment.		Testing may be accomplished by the FSTD manufacturer and results provided as a statement of compliance.		The recorded test results for characteristic buffers should allow the comparison of relative amplitude versus frequency. See also paragraph 6.e. of this Attachment.	
graph 6 ent.		graph 6 ent.	Attachr c on sul		and so and so STD of ntinue / qualifications on.		nay be. TD mats ts prov.		rded tes istic bu comps mplitue //	
se parag ttachm		See paragrap Attachment.	Refer to Appendic	,	Ensure that motion in hardware and softwomen ESTD opera monde) continue to p originally qualified. Performance change the original baseline readily identified with formation.		esting r r the FS nd resul atemen		The recorde characteristic characteristic characteristic allow the confidence amplified unit frequency. See also par Attachment.	
× ×		š <	X X < 3		X HHHHHHHHHH SA		× + 7. = 2	+	X S A A S A	×
×		×	×		×		×	t		
×		×	×		×					
×		×	×		×					
Appropriate test to demonstrate required frequency response.		Appropriate test to demonstrate required smooth turn-around.					For the motion system as applied during training, record the combined modulus and plase of the motion cueing algorithm and motion platform over the frequency range appropriate to the characteristics of the simulated aircraft. This test is only required for initial FSTD	quamication.		Test must be conducted at maximum possible thrust with brakes set.
Not applicable.		Not applicable.			Лопе.		Ground and flight.		Ground and flight.	Ground.
As specified by the sponsor for FSTD qualification.		As specified by the sponsor for FSTD qualification.		ability.	=0.05 g actual platform linear accelerations.		As specified by the FSTD manufacturer for initial qualification.		None.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of
	Turn-around check.		Motion effects.	Motion system repeatability.	Motion system repeatability	Motion cueing fidelity	Motion cueing fidelity – Frequency- domain criterion.	Reserved	Characteristic motion vibrations. The following tests with recorded results and an SOC are required for required for characteristic motion vibrations, which can be sensed at the flight deck where applicable by	Thrust effect with brakes set.
	3.b.		3.c	3.d.		3.e.	3.e.l.	3.e.2.	3.5	3.f.l.

5	Dr. Cot with landing	being present within ± 2 Hz of the airplane data.	Dlight		
3.1.2.	Buffet with landing gear extended.	In the FS1 Uses results must exhibit the overall appearance and trends of the airphane data, with at least three (3) of the predominant frequency, "spikes" being present within ± 2 Hz of the airphane data.	Flight.	speed and not at the gear limiting speed.	
3.f.3.	Buffer with flaps extended.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" frequency "spikes" to 7 the airplane data.	Flight.	Test condition must be at a normal operational speed and not at the flap limiting speed.	
3.f.4.	Buffer with speedbrakes deployed.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes" frequency "spikes" Lt of the airplane data.	Flight.	Test condition must be at a typical speed for a representative buffet.	
3,15,	Stall buffer	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the bredominant frequency "spikes," the breing present within ± 2. Hz of the airplane data.	Cruise (High Altinude), Second Segment Climb, and Approach or Landing	Tests must be conducted for an angle of attack trange between the buffet threshold of perception to the plot and the stall angle of attack. Post stall characteristics are not required. Characteristics are not required. Test required or perception and the stall angle of attack a variable, but a small characteristics are not required. Test required or FSTDs qualified and the stall training tast attack. Test required or FSTDs qualified stall fraining tast attack. Test required or perception and those aircraft with a stall fraining tast attack.	If stabilized flight data between buffet inseshold of perception and the stall angle of attack are not available. PSD analysis should be conducted for a time span between initial buffet and the stall angle of attack. Test required only for FSTDs qualified for full stall tanging tasks or for forest attack as all training tasks or for those aircraft which exhibit stall buffet before the activation of the stall and system.
3.f.6.	Buffer at high airspeeds or high Mach.	The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency 'spikes' being present within ± 2. Hz of the airplane data	Flight.	X Test com he to the total control of the total con	Test condition should be for high-speed maneuver buffev, mid-une or alternatively. Mach buffet.

Test should be conducted to be representative of in-flight vibrations for propeller-driven airplanes.			Field of view should be measured using a visual test pattern filling the entire visual scene (all channels) consisting of a matrix of black and white 5° squares. Installed alignment should be confirmed in an SOC (this would generally consist of results from acceptance testing).	A vertical field-of-view of 30 may be insufficient to meet visual ground segment requirements.	The purpose of this test is to displayed linearity of the displayed image at either pilot eye point. System geometry should be measured using a should be measured using a visual test partern filling the entire visual sevene (all channels) with a matrix of baback and white 3° squares with light points at the intersections. For continuing qualification testing, the use of an optical elecking device is encouraged. This device is encouraged. This device is encouraged. This device should typically consist of a hand-held gloon go gauge to check that the relative positioning is maintained.
×			×		×
			×		×
				×	×
				×	×
			Required as part of MQTG but not required as part of continuing evaluations.	Required as part of MQTG but not required as part of continuing evaluations.	The angular spacing of any chosen 3° square and the relative spacing of adjacent squares must be within the stated folerances.
Flight (clean configuration).			Not applicable.	Not applicable.	Not applicable.
The FSTD test results must exhibit the overall appearance and trends of the airplane data, with at least three (3) of the predominant frequency "spikes;" being present within ± 2 Hz of the airplane data.			Cross-cockpit, collmander visual display providing each pilot with a minimum of 176 horizontal and 36° 176 horizontal and 36° ortical continuous field of view.	Continuous collimated field-of-view providing at least 45° horizontal and 30° vertical field-of-view for each pilot seat. Both pilot seat usual systems must be operable simultaneously.	\$° even angular spacing within ±1° as measured from either pilot eye point and within 1.5° for adjacent squares.
In-flight vibrations for propeller driven airplanes.	ystem.	Visual scene quality	Continuous cochimated cross-cochimated cross-view.	Continuous collimated cross- cockpit visual field of view.	System geometry
3.f.7.	4. Visual System.	4.a.	4.a.1.		4.n.2.

Resolution will be demonstrated by a test of objects shown to occupy the required visual angle in each visual display used on a scene from the pilot's eyepoint. The object will subtend 2 are minutes to the eye. This may be demonstrated uning threshold bars for a horizontal test. A vertical test.	Light point size should be measured using a test pattern consisting of a centrally located single row of white light points displayed as both a horizontal and vertical row. It should be possible to move the light points relative to the eyepoint in all axes. At a point where modulation is just discernible in each visual channel, a calculation should be made to determine the light spacing.	Surface contrast ratio should drawn test pattern filling the entire visual scene (all chiamble). The test pattern should consist of black and white square, with a white square in the center of each channel. Measurement should be made on the center bright square for the call of the contrast of the contrast of the center bright square for each channel using a 1° spot photometer. This value should have a minimum brightness of 7 cd/m² (2 ft. lamberts), Measure any adjacent dark squares.
×	×	×
×	x	x
An SOC is required and must include the relevant calculations and an explanation of those eaculations. This requirement is applicable to any level of simulator equipped with a daylight visual system.	An SOC is required and must include the relevant calculations and an explanation of those calculations. This requirement is applicable to any level of simulator equipped with a day light visual system.	This requirement is applicable to any level of simulator equipped with a day light visual system.
Not applicable.	Not applicable.	Not applicable.
Not greater than 2 arc minutes.	Not greater than 5 arc minutes.	Not less than 5:1.
Surface resolution (object detection).	Light point size.	Raster surface contrast ratio.
4.a.3	4.a.4	4.a.S

The contrast ratio is the bright square value divided by the dark square value. Note 1. — During contrast ratio testing; STID appears ratio testing; STID appears and flight deck ambient light levels should be as low as possible. Note 2. — Measurements should be taken at the conter of squares to avoid light key still into the measurement device.	Light point contrast ratio should be measured using a test pattern deamonstrating an area of greater than 1º area filled with white light points and should be compared to the adjacent background. Note. — Light point modulation should be just discernible on calligraphic systems but will not be discernible on reaster systems. Measurements of the background should be just discernible on reaster systems. Measurements of the background should be taken just out of the light meter FOV. Note. — During contrast ratio results, FSTD affectable and filght deck ambient light levels should be as low as prrecised.		X Light points should be displayed as a matrix creating a square.	On calligraphic systems the light points should just merge.	On raster systems the light points should overlap such that the square is continuous
	×		×		
		×			
		×			
	An SOC is required and must include the relevant calculations.				
	Not applicable.	Not applicable.	Not applicable.		
	Not less than 25.1.	Not less than 10:1.	Not less than 20 cd/m ² (5.8 ft-lamberts).		
	Light point contrast ratio.	Light point contrast ratio.	Light point brightness.		
	4.86		4.a.7		

							(individual light points will not be visible).
4.a.8	Surface brightness.	Not less than 20 cd/m ² (5.8 ft-lamberts) on the display.	Not applicable.	This requirement is applicable to any level of simulator equipped with a daylight visual system.	×	×	Surface brightness should be measured on a white raster, measuring the brightness using the 1° spot photometer. Light points are not acceptable. Use of calligraphic eapabilities to enhance raster eapabilities to enhance raster brightness is acceptable.
4 a.9	Black level and sequential confrast.	Black intensity: Background brightness Backpound brightness (2015 duffness (2014 lamberts). Sequential contrast: Maximum brightness – (Background brightness Black polygon brightness) > 2,000:1.	Not applicable.	×	× ×	×	All projectors should be turned of fand the cockpit environment made as dark as possible. A background reading should be taken of the remaining ambient light on the sercen. The projectors should then be turned on and a black polygon the sercen and a black polygon the sercen and the black polygon displayed. A second reading should then be taken and the difference between this and the ambient level recorded. A full brightness white polygon should then be measured for the sequential contrast test. This test is generally only required for the trying required for the sequential contrast test.
4.a.10	Motion blur.	When a pattern is rotated about the eyepoint at 10%, the smallest detectable gap must be 4 arc min or less.	Not applicable.	×	×	×	A test pattern consists of an array of 5 peak white squares with black gaps between them of decreasing width. The range of black gap widths should at least extend above and below the required detectable gap, and be in steps of I are min. The pattern is rotated at the required rate. The pattern is rotated at the required rate. Two arrays of squares should be provided, one rotating in

heading and the other in pitch, to provide testing in both axes.	A series of stationary numbers identifies the gap number.	Note.— This test can be limited by the display technology. Where this is the case the responsible Flight Standards affice should be consulted on the limitations.	This test is generally only required for light valve projectors.	This test is generally only required for laser projectors.		Alignment requirement applies to any HUD system in use or both simultaneously if	they are used simultaneously for training.		A statement of the system capabilities should be provided and the capabilities demonstrated			Note.— The effects of the alignment tolerance in 4.b. I should be taken into account.	Infra-red scene representative of both 350 m (1,200 ft), and 1,609 m (1 sm) RVR.
				X		X			×	×		×	×
				X		×			×	×		×	×
				X									
				X									
				An SOC is required describing the test method.									
				Not applicable.		N/A			N/A	Flight.		Takeoff point and on approach at 200 ft.	Flight.
				Speckle contrast must be $< 10\%$.		Static alignment with displayed image.	HUD bore sight must align with the center of the displayed image	spherical pattern.	All functionality in all flight modes must be demonstrated.	Pitch and roll align with aircraft instruments.		Alignment between EFVS display and out of the window image must represent the alignment typical of the aircraft and system type.	The scene represents the EFVS view at 350 m (1,200 ft) and 1,609 m
				Speckle test.	Head-Up Display (HUD)	Static Alignment.			System display.	HUD attitude versus FSTD attitude indicator (pitch and roll of horizon).	Enhanced Flight Vision System (EFVS)	Registration test.	EFVS RVR and visibility calibration.
				4.a.11	4.b	4.b.1			4.b.2	4.b.3	4.c	4.c.1	4.c.2

14 CFR Ch. I (1-1-24 Edition)

		(1 sm) RVR including correct light intensity.						Visual scene may be removed.
4.c.3	Thermal crossover.	Demonstrate thermal crossover effects during day to night transition.	Day and night.			X	×	The scene will correctly represent the thermal characteristics of the scene during a day to night transition.
4.d	Visual ground segment	-						
4441	Visual ground segment (VGS).	Near end: the correct number of approach ingints within the computed VGS must be visible. Far end: ±20% of the computed VGS. The threshold lights computed to be visible must be visible in the FSTD.	Trimmed in the landing configuration at 30 m (100 ft) wheel height above touchdown zone on gilde slope at an RVR setting of 300 m (1,200 ft),	This test is designed to assess items impacting the accuracy of the Visibal scene presented to a pilot. These items include: 1) RVR/Visibility; 2) glides slope (GS) and localizer modeling accuracy (location and slope) for an ILS; 3) for a given weight, configuration and speed representative of a point within the airplane's operational envelope for a normal approach and landing, and 4) Radio altimeter. Anne—If non-homogeneous fog is used, the vertical variation in horizontal visibility should be described and included in the stant range visibility calculation used in the VGS	×	×	×	
4.e	Visual System Capacity							
4.e. l	System capacity – Day mode.	Not less than: 10,000 visible textured surfaces, 6,000 light points, 16 moving models.	Not applicable.			×	×	Demonstrated through use of a visual scene randered with the same image generator modes used to produce scenes for training. The required surfaces, light points, and moving models silvalid be displayed simulated solishi
4.c.2	System capacity – Twilight/night mode.	Not less than: 10,000 visible textured avarfaces, 15,000 light points, 16 moving models.	Not applicable.			×	×	Demonstrated through use of a visual seave tradected with the same image generator modes used to produce scenes for training. The required surfaces, light populs, and moving models should be displayed simultaneously.

	All tests in this section should be presented using an unweighted 1/3-octave band formar from at least hand 17 to 42 (50 Hz to 16 kHz).	A measurement of minimum 20 s should be taken at the location corresponding to the approved data set.	The approved data set and FSTD results should be produced using comparable data analysis techniques.	Refer to paragraph 7 of this Attachment	re primitale variantarion, it is acceptable to have some 1/3 courve bands out of ± 6 dB courve bands out of ± 6 dB courve bands out of ± 6 dB out are consecutive and in any case within ± 7 dB from any covered the coverall trend is correct. Where initial evaluation employs approved subjective tuning to develop the approved reference standard, cerurent evaluation tolerances should be used during recurrent evaluation. For initial evaluation, it is acceptable to have some 1/3 caccus band sout of ± 5 dB finderance but not more than 5.	that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct.
					× ×	
5. Sound System. The sponsor will mot be required to repeat the airplane tests (i.e., tests 5.a.l. through 5.a.8 (or 5.b.l. through 5.b.9) and 5.c., as appropriately during continuing qualification evaluations if frequency response and background noise test results are within tolerance when compared to the initial qualification evaluation results, and the sponsor shows that no software changes have occurred that will affect the airplane tests results in the frequency response to proflow and test and to show the results are repeated during continuing qualification evaluations, the results may be compared against initial qualification evaluation results or airplane master data. All tests in this section must be presented using an unweighted 17-occurs band format from the 17-occurs bear on must be presented using an unweighted the airplane tests to sufficient to secure at the location corresponding to the airplane data set. The airplane and flight simulator results must be produced using comparable data analysis techniques.					Normal condition prior to engine start. The APU should be on if appropriate. Normal condition prior to takeoff.	
tests S.a.l. through 5.a.8. It no software changes ha t no software changes ha t no software changes ha t on may elect to fix the fix are repeated during cont ne master data. All tests i minimum 20 second ave minimum 20 second ave minimum 20 second ave					Ground, Ground,	
untions if frequency response autions if frequency response s, and the sponsor shows than se chosen and fails, the sponsor me tests. If the airphane tests to evaluation results or airphan for the property of the property of the frequency of the property of the property of the frequency of the property of the property of the property of the frequency of the property of the propert					Initial evaluation: Bard Bort 1/3 octave band. Recurrent evaluation: cannot exceed ± dB difference on three consecutive bands when conpared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed ± dB. Initial evaluation: E dB per 1/3 octave band.	Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial
em. Il not be required to π il not be required to π ing qualification evalu tition results to results to response test method is lect to repeat the airpla nst initial qualification deformat from band 17 deformat from band 17 at set. The airplane ans ast. The airplane ans ast.	Turbo-jet airplanes.				Start. All engines at idle.	
5. Sound System. The sponsor will reduring continuing initial qualification the frequency responsor may elect compared against 1/3-octave band ft the airplane data set.	5.a.				5.a.1.	

14 CFR Ch. I (1-1-24 Edition)

Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB octave bands octave bands of ± 5 dB octave bands oct	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB octave band in any case within ± 7 dB from approved reference data, providing that the overall trend is correct. Where initial evaluation employs approved subjective timing to develop the approved reference standard, recurrent evaluation recurrent evaluation recurrent evaluations.	For initial evaluation, it is coerphable to have some 1/3 octave bands out of ± 5 dB tolerance but not more than 2 that are consecutive and in any case within ± 10 fB from approved reference data, providing that the overall trend is correct.
	×	×	×
	Normal condition prior to takeoff.	Medium altitude.	Normal cruiss configuration.
	Ground.	En-route climb.	Cruise.
evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	hirital evaluation: ± 5 dB per 1/3 octave band. Recurrent evaluation: cannot exceed ±5 dB difference on three compacturive bands when compacted to initial when evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	linital evaluation: # 5 dB per 1/3 octave band. Recurrent evaluation: cannot exceed ±5 dB difference on three compacturive bands when compacted to initial when evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Linital evaluation: ± 5.4B per 1/3 octave band. Recurrent evaluation: cannot exceed ±5.4B difference on three consecutive bands when compared to initial evaluation and the
	All engines at maximum	Climb	Спіšе
	5.a.3.	5.a.4.	5.a.5.

Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation toderance standard during recurrent evaluations.	X For initial evaluation, it is acceptable to have some 1/3 octave bands out of ±5 dB octave bands out of ±5 dB octave bands out of ±5 dB to the are consecutive and in any case within ±7 dB tron approved reference data, providing that the overall trends is correct. Where initial evaluation employs approved subjective furning to develop the approved reference stander, recurrent evaluation complexes and the approved reference stander, recurrent evaluation to develop the approved reference stander, recurrent evaluation to develop the approved reference stander, recurrent evaluation to develop the approved reference stander.	X For initial evaluation, it is acceptable to have some 1/3 octave bands out of ±5 dB octave bands out of ±5 dB octave bands out of ±5 dB to the are consecutive and in any case within ±7 dB from approved reference data, providing that the overall trends is correct. Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation comploys approved subjective tuning to develop the approved reference standard, recurrent evaluation to develop the approved reference standard, recurrent evaluation to develop the approved reference standard, recurrent evaluation to develop the approved reference standard, required to the approved reference standard required to the approved reference standard required to the approved reference standard required to the approved reference standard.	X For initial evaluation, it is acceptable to have some 1/3 careb bands out of ±5 dB cotave bands out of ±5 dB cotave bands out of ±5 dB tolerance but not more than 2 that are consecution on any ease within ±7 dB from any ease within ±7 dB from any peroved reference data, providing that the overall trend is correct.
	Normal and constant speed brake deflection for descent at a constant airspeed and power setting.	Constant airspeed, gent up, flaps/slats as appropriate.	Constant airspeed, gear down, landing configuration flaps.
	Cruise.	Approach.	Landing.
average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	15 dB per 1/3 octave band, and a feet	± 5 dB per 1/3 octave band, Beurrent evaluation: earnot exceed ±5 dB difference on three comscentive bands when compared to initial average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	1 and the state of
	Speed speed speed as a ppropriate).	Initial approach.	Find approach.
	5.a.6.	5.a.7	5.a.8

14 CFR Ch. I (1-1-24 Edition)

		initial and recurrent evaluation results cannot exceed 2 dB.			Where initial evaluation cmploys approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.
5.6	Propeller-driven airplanes	rplanes			All tests in this section should be presented using an unweighted 1/3-cotave band format from at least band 17 to 42 (50 Hz to 16 kHz). A measurement of minimum 20 s should be taken at the location corresponding to the approved data set. The approved data set. The approved data set and FS/TD results should be produced using comparable data analysis techniques.
5.b.1.	Ready for engine start.	Initial evaluation: # 5 dB per 1/3 octave band. Recurrent evaluation: Genamot exceed 45 dB difference on three compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Ground.	Normal condition prior to engine start. The APU should be on if appropriate.	A roperator. Rot initial evaluation, it is acceptable to have some 1/3 occare banks out of ± 50 occare banks out of ± 50 occare banks out of ± 50 occare bank of that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct. Where initial evaluation employs approved reference subjective tuning to develop the approved reference standard, recurrent evaluation recurrent evaluation recurrent evaluations.
5.b.2	All propellers feathered, if applicable.	1 Initial evaluation: ± 5 dB per 1/3 octave band. Recurrent evaluation: camon eveced ±5 dB difference on three consecutive bands when	Ground.	Normal condition prior to takeoff.	For initial evaluation, it is acceptable to have some 1/3 octave banks out of ±5 dB tolerance but not more than 2 that are consecutive and in any case within ±7 dB from approved reference data.

	,		
providing that the overall trend is correct. Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation folloamoes should be used during recurrent evaluations.	For initial evaluation, it is acceptable to have some 13 octave bands out of ± 6 db tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, approved reference data, providing that the overall trend is correct. Where initial evaluation employs approved subjective tuning to eve clot the approved reference sandar, reming to eve clot the approved reference sandar, recurrent evaluation.	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ±5 dB cotave bands out of ±5 dB cotave bands out of ±5 dB cotave but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct. Where initial evaluation employs approved adjoctive unitial evaluation employs approved adjoctive tuning to develop the approved reference standard, recurrent evaluation foreigness should be used furning recurrent evaluation foreigness should be used.	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ±5 dB tolerance but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data,
	×	×	×
	Normal condition prior to takeoff.	Normal condition prior to takeoff.	Normal condition prior to takeoff.
	Ground.	Ground.	Ground.
compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	hirital evaluation: ± 6.4B per 1/3 octave band. Recurrent evaluation: emmot exceed ±5.6B difference on three compared to initial when compared to initial when evaluation and the average of the absolute differences between initial and recurrent evaluation results camnot exceed 2.4B.	Initial evaluation: 45 dB per 1/3 octave band, band, Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the evaluation and the initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: ± 5 dB per 1/3 octave band. Recurrent evaluation: cannot exceed ± 5 dB difference on three consecutive bands when compared to initial
	Ground idle or equivalent.	Flight idle or equivalent.	All engines at maximum allowable power with brakes set.
	5.6.3.	5,b,4	5.b.5

14 CFR Ch. I (1-1-24 Edition)

		evaluation and the average of the absolute				providing that the overall trend is correct.
		differences between initial and recurrent				Where initial evaluation
		evaluation results cannot exceed 2 dB.				employs approved subjective tuning to develop the
						approved reference standard,
						tolerances should be used
					-	during recurrent evaluations.
5.b.6	Climb.	Initial evaluation:	En-route climb.	Medium altitude.	×	For initial evaluation, it is
		± 5 dB per 1/3 octave				acceptable to have some 1/3
		Dallu.				tolerance but not more than 2
		Recurrent evaluation:				that are consecutive and in
		cannot exceed ±5 dB				any case within ± 7 dB from
		difference on three				approved reference data,
		consecutive bands when				providing that the overall
		evaluation and the				trend is correct.
		average of the absolute				Where initial evaluation
		initial and recurrent				employs approved subjective
		evaluation results				tuning to develop the
		cannot exceed 2 dB.				approved reference standard,
						tolerances should be used
						during recurrent evaluations.
5.b.7	Cruise	Initial evaluation:	Cruise.	Normal cruise configuration.	×	For initial evaluation, it is
		\pm 5 dB per 1/3 octave				acceptable to have some 1/3
		band.				octave bands out of \pm 5 dB
						tolerance but not more than 2
		Recurrent evaluation:				that are consecutive and in
		difference on three				any case within ± 7 dB from
		consecutive hands when				approved reference data,
		compared to initial				providing that the overall
		evaluation and the				trend is correct.
		average of the absolute				Where initial evaluation
		differences between				employs approved subjective
		evaluation results				tuning to develop the
		cannot exceed 2 dB.				approved reference standard,
						recurrent evaluation
						during recurrent evaluations
5.b.8	Initial approach.	Initial evaluation:	Approach.	Constant airspeed,	×	For initial evaluation, it is
		± 5 dB per 1/3 octave		gear up,		acceptable to have some 1/3
		band.		flaps extended as appropriate,		octave bands out of \pm 5 dB
				RPM as per operating manual.		tolerance but not more than 2
		Recurrent evaluation:				that are consecutive and in
		difference on three				any case within ± / dB from
		consecutive bands when				providing that the overall
		compared to initial				trend is correct.
		cyananon and me			_	

Where initial evaluation employs approved subjective tuning to develop the approved reference standard, recurrent evaluation tolerances should be used during recurrent evaluations.	For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB octave but not more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct. Where in finite evaluation employs approved subjective tuning to develop the tuning to develop the contract of the contrac	This applies to special steady- state cases identified as particularly significant to the pilot, important in training, or unique to a specific airplane type or model. For initial evaluation, it is acceptable to have some 1/3 octave bands out of ± 5 dB tolerance but nor more than 2 that are consecutive and in any case within ± 7 dB from approved reference data, providing that the overall trend is correct. Where initial evaluation employs approved subjective tuning to develop the approved reference stander, recurrent evaluation	X The simulated sound will be evaluated to ensure that the background noise does not interfere with training.
	Constant airspeed, gear down, landing configuration flaps, RPM as per operating manual.		Results of the background noise at initial qualification must be included in the QTG document and approved by the responsible Flight Standards office. The measurements are to be
	Landings.	As appropriate.	
average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: ± 5 dB per 1/3 octave band, band, common exceed ±5 dB difference on three compared to initial evaluation and the evaluation and the evaluation and the initial and recurrent differences between initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: ± 5 dB per 1/3 octave band. Recurrent evaluation: Recurrent evaluation: eompared to initial evaluation and the evaluation and the initial and recurrent initial and recurrent entranged of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: background noise levels must fall below the sound levels described
	Final approach.	Special cases.	FSTD background noise
	\$.b.9	ن بر	5.d

BEGIN INFORMATION

3. General

a. If relevant winds are present in the objective data, the wind vector should be clearly noted as part of the data presentation, expressed in conventional terminology, and re-

lated to the runway being used for test near the ground.

b. The reader is encouraged to review the Airplane Flight Simulator Evaluation Handbook, Volumes I and II, published by the Royal Aeronautical Society, London, UK, and AC 25–7, as amended, Flight Test Guide for Certification of Transport Category Airplanes, and AC 23–8, as amended, Flight Test

ER09DE22.050</GPH>

Guide for Certification of Part 23 Airplanes, for references and examples regarding flight testing requirements and techniques.

4. Control Dynamics

a. General. The characteristics of an airplane flight control system have a major effect on handling qualities. A significant consideration in pilot acceptability of an airplane is the "feel" provided through the flight controls. Considerable effort is expended on airplane feel system design so that pilots will be comfortable and will consider the airplane desirable to fly. In order for an FFS to be representative, it should "feel" like the airplane being simulated. Compliance with this requirement is determined by comparing a recording of the control feel dynamics of the FFS to actual airplane measurements in the takeoff, cruise and landing configurations.

(1) Recordings such as free response to an impulse or step function are classically used to estimate the dynamic properties of electromechanical systems. In any case, it is only possible to estimate the dynamic properties as a result of being able to estimate true inputs and responses. Therefore, it is imperative that the best possible data be collected since close matching of the FFS control loading system to the airplane system is essential. The required dynamic control tests are described in Table A2A of this attachment.

(2) For initial and upgrade evaluations, the QPS requires that control dynamics characteristics be measured and recorded directly from the flight controls (Handling Qualities—Table A2A). This procedure is usually accomplished by measuring the free response of the controls using a step or impulse input to excite the system. The procedure should be accomplished in the takeoff, cruise and landing flight conditions and configurations.

(3) For airplanes with irreversible control systems, measurements may be obtained on the ground if proper pitot-static inputs are provided to represent airspeeds typical of those encountered in flight. Likewise, it may be shown that for some airplanes, takeoff, cruise, and landing configurations have like effects. Thus, one may suffice for another. In either case, engineering validation or airplane manufacturer rationale should be submitted as justification for ground tests or for eliminating a configuration. For FFSs requiring static and dynamic tests at the controls, special test fixtures will not be required during initial and upgrade evaluations if the QTG shows both test fixture results and the results of an alternate anproach (e.g., computer plots that were produced concurrently and show satisfactory agreement). Repeat of the alternate method during the initial evaluation satisfies this test requirement.

b Control Dynamics Evaluation. The dynamic properties of control systems are often stated in terms of frequency, damping and a number of other classical measurements. In order to establish a consistent means of validating test results for FFS control loading, criteria are needed that will clearly define the measurement interpretation and the applied tolerances. Criteria are needed for underdamped, critically damped and overdamped systems. In the case of an underdamped system with very light damping, the system may be quantified in terms of frequency and damping. In critically damped or overdamped systems, the frequency and damping are not readily measured from a response time history. Therefore, the following suggested measurements may be used:

(1) For Level C and D simulators. Tests to verify that control feel dynamics represent the airplane should show that the dynamic damping cycles (free response of the controls) match those of the airplane within specified tolerances. The Flight Standards Service recognizes that several different testing methods may be used to verify the control feel dynamic response. The responsible Flight Standards office will consider the merits of testing methods based on reliability and consistency. One acceptable method of evaluating the response and the tolerance to be applied is described below for the underdamped and critically damped cases. A sponsor using this method to comply with the QPS requirements should perform the tests as follows:

(a) Underdamped response. Two measurements are required for the period, the time to first zero crossing (in case a rate limit is present) and the subsequent frequency of oscillation. It is necessary to measure cycles on an individual basis in case there are nonuniform periods in the response. Each period will be independently compared to the respective period of the airplane control system and, consequently, will enjoy the full tolerance specified for that period. The damping tolerance will be applied to overshoots on an individual basis. Care should be taken when applying the tolerance to small overshoots since the significance of such overshoots becomes questionable. Only those overshoots larger than 5 per cent of the total initial displacement should be considered. The residual band, labeled T(A_d) on Figure A2A is ±5 percent of the initial displacement amplitude A_d from the steady state value of the oscillation. Only oscillations outside the residual band are considered significant. When comparing FFS data to airplane data, the process should begin by overlaying or aligning the FFS and airplane steady state values and then comparing amplitudes of oscillation peaks, the time of the first zero crossing and individual periods of oscillation. The FFS should show the same number

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. A

of significant overshoots to within one when compared against the airplane data. The procedure for evaluating the response is illustrated in Figure A2A.

- (b) Critically damped and overdamped response. Due to the nature of critically damped and overdamped responses (no overshoots), the time to reach 90 percent of the steady state (neutral point) value should be the same as the airplane within ± 10 percent. Figure A2B illustrates the procedure.
- (c) Special considerations. Control systems that exhibit characteristics other than classical overdamped or underdamped responses should meet specified tolerances. In addition, special consideration should be given to ensure that significant trends are maintained.
 - (2) Tolerances.
- (a) The following table summarizes the tolerances, T, for underdamped systems, and "n" is the sequential period of a full cycle of oscillation. See Figure A2A of this attachment for an illustration of the referenced measurements.

$T(P_0)$	$\pm 10\%$ of P ₀ .
$T(P_1)$	$\pm 20\%$ of P_1 .
$T(P_2)$	$\pm 30\%$ of P ₂ .
$T(P_n)$	$\pm 10(n + 1)\%$ of P_n
$T(A_n)$	$\pm 10\%$ of A ₁ .

 $T(A_n)$ $\pm 10\%$ of A_1 . $T(A_d)$ $\pm 5\%$ of A_d = residual band.

Significant overshoots, First overshoot and ± 1 subsequent overshoots.

(b) The following tolerance applies to critically damped and overdamped systems only. See Figure A2B for an illustration of the reference measurements:

 $T(P_0)$ $\pm 10\%$ of P_0

END INFORMATION

BEGIN QPS REQUIREMENT

c. Alternative method for control dynamics evaluation.

- (1) An alternative means for validating control dynamics for aircraft with hydraulically powered flight controls and artificial feel systems is by the measurement of control force and rate of movement. For each axis of pitch, roll, and yaw, the control must be forced to its maximum extreme position for the following distinct rates. These tests are conducted under normal flight and ground conditions.
- (a) Static test—Slowly move the control so that a full sweep is achieved within 95 to 105 seconds. A full sweep is defined as movement of the controller from neutral to the stop, usually aft or right stop, then to the opposite stop, then to the neutral position.
- (b) Slow dynamic test—Achieve a full sweep within 8–12 seconds.
- (c) Fast dynamic test—Achieve a full sweep within 3–5 seconds.

NOTE: Dynamic sweeps may be limited to forces not exceeding 100 lbs. (44.5 daN).

- (d) Tolerances
- (i) Static test; see Table A2A, FFS Objective Tests, Entries 2.a.1., 2.a.2., and 2.a.3.
- (ii) Dynamic test— ± 2 lbs (0.9 daN) or $\pm 10\%$ on dynamic increment above static test.

END QPS REQUIREMENT

BEGIN INFORMATION

d. The FAA is open to alternative means such as the one described above. The alternatives should be justified and appropriate to the application. For example, the method described here may not apply to all manufacturers' systems and certainly not to aircraft with reversible control systems. Each case is considered on its own merit on an ad hoc basis. If the FAA finds that alternative methods do not result in satisfactory performance, more conventionally accepted methods will have to be used.

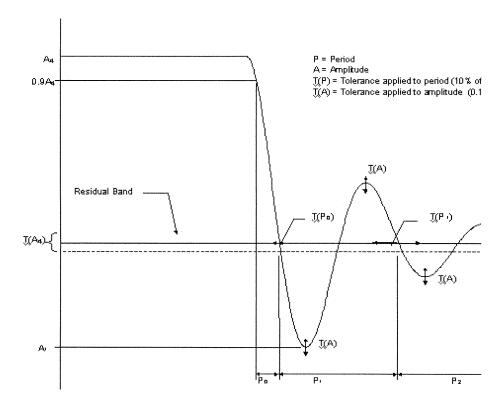


Figure A2A **Underdamped Step Response**

14 CFR Ch. I (1-1-24 Edition)

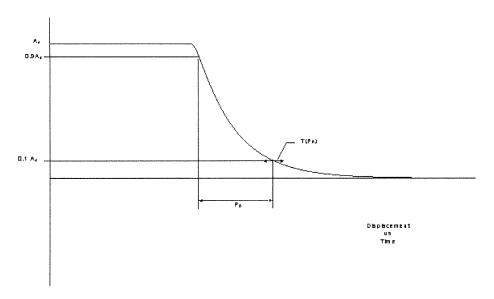


Figure A2B Critically and Overdamped Step Response

5. GROUND EFFECT

- a. For an FFS to be used for take-off and landing (not applicable to Level A simulators in that the landing maneuver may not be credited in a Level A simulator) it should reproduce the aerodynamic changes that occur in ground effect. The parameters chosen for FFS validation should indicate these changes.
- (1) A dedicated test should be provided that will validate the aerodynamic ground effect characteristics.
- (2) The organization performing the flight tests may select appropriate test methods and procedures to validate ground effect. However, the flight tests should be performed with enough duration near the ground to sufficiently validate the ground-effect model.
- b. The responsible Flight Standards office will consider the merits of testing methods based on reliability and consistency. Acceptable methods of validating ground effect are described below. If other methods are proposed, rationale should be provided to conclude that the tests performed validate the ground-effect model. A sponsor using the

- methods described below to comply with the QPS requirements should perform the tests as follows:
- (1) Level fly-bys. The level fly-bys should be conducted at a minimum of three altitudes within the ground effect, including one at no more than 10% of the wingspan above the ground, one each at approximately 30% and 50% of the wingspan where height refers to main gear tire above the ground. In addition, one level-flight trim condition should be conducted out of ground effect (e.g., at 150% of wingspan).
- (2) Shallow approach landing. The shallow approach landing should be performed at a glide slope of approximately one degree with negligible pilot activity until flare.
- c. The lateral-directional characteristics are also altered by ground effect. For example, because of changes in lift, roll damping is affected. The change in roll damping will affect other dynamic modes usually evaluated for FFS validation. In fact, Dutch roll dynamics, spiral stability, and roll-rate for a given lateral control input are altered by ground effect. Steady heading sideslips will also be affected. These effects should be accounted for in the FFS modeling. Several

tests such as crosswind landing, one engine inoperative landing, and engine failure on take-off serve to validate lateral-directional ground effect since portions of these tests are accomplished as the aircraft is descending through heights above the runway at which ground effect is an important factor.

6. MOTION SYSTEM

a. General.

(1) Pilots use continuous information signals to regulate the state of the airplane. In concert with the instruments and outsideworld visual information, whole-body motion feedback is essential in assisting the pilot to control the airplane dynamics, particularly in the presence of external disturbances. The motion system should meet basic objective performance criteria, and should be subjectively tuned at the pilot's seat position to represent the linear and angular accelerations of the airplane during a prescribed minimum set of maneuvers and conditions. The response of the motion cueing system should also be repeatable.

(2) The Motion System tests in Section 3 of Table A2A are intended to qualify the FFS motion cueing system from a mechanical performance standpoint. Additionally, the list of motion effects provides a representative sample of dynamic conditions that should be present in the flight simulator. An additional list of representative, trainingcritical maneuvers, selected from Section 1 (Performance tests), and Section 2 (Handling Qualities tests), in Table A2A, that should be recorded during initial qualification (but without tolerance) to indicate the flight simulator motion cueing performance signature have been identified (reference Section 3.e). These tests are intended to help improve the overall standard of FFS motion cueing.

b. Motion System Checks. The intent of test 3a, Frequency Response, and test 3b, Turn-Around Check, as described in the Table of Objective Tests, are to demonstrate the performance of the motion system hardware, and to check the integrity of the motion set-up with regard to calibration and wear. These tests are independent of the motion cueing software and should be considered robotic tests.

c. Motion System Repeatability. The intent of this test is to ensure that the motion system software and motion system hardware have not degraded or changed over time. This diagnostic test should be completed during continuing qualification checks in lieu of the robotic tests. This will allow an improved ability to determine changes in the software or determine degradation in the hardware. The following information delineates the methodology that should be used for this test.

(1) Input: The inputs should be such that rotational accelerations, rotational rates, and linear accelerations are inserted before

the transfer from airplane center of gravity to pilot reference point with a minimum amplitude of 5 deg/sec/sec, 10 deg/sec and 0.3 g, respectively, to provide adequate analysis of the output.

(2) Recommended output:

(a) Actual platform linear accelerations; the output will comprise accelerations due to both the linear and rotational motion acceleration:

(b) Motion actuators position.

d. Objective Motion Cueing Test—Frequency Domain

(1) Background. This test quantifies the response of the motion cueing system from the output of the flight model to the motion platform response. Other motion tests, such as the motion system frequency response, concentrate on the mechanical performance of the motion system hardware alone. The intent of this test is to provide quantitative frequency response records of the entire motion system for specified degree-of-freedom transfer relationships over a range of frequencies. This range should be representative of the manual control range for that particular aircraft type and the simulator as set up during qualification. The measurements of this test should include the combined influence of the motion cueing algorithm, the motion platform dynamics, and the transport delay associated with the motion cueing and control system implementation. Specified frequency responses describing the ability of the FSTD to reproduce aircraft translations and rotations, as well as the cross-coupling relations, are required as part of these measurements. When simulating forward aircraft acceleration, the simulator is accelerated momentarily in the forward direction to provide the onset cueing. This is considered the direct transfer relation. The simulator is simultaneously tilted nose-up due to the low-pass filter in order to generate a sustained specific force. The tilt associated with the generation of the sustained specific force, and the angular rates and angular accelerations associated with the initiation of the sustained specific force, are considered cross-coupling relations. The specific force is required for the perception of the aircraft sustained specific force, while the angular rates and accelerations do not occur in the aircraft and should be minimized.

(2) Frequency response test. This test requires the frequency response to be measured for the motion cueing system. Reference sinusoidal signals are inserted at the pilot reference position prior to the motion cueing computations. The response of the motion platform in the corresponding degree-of-freedom (the direct transfer relations), as well as the motions resulting from cross-coupling (the cross-coupling relations), are recorded. These are the tests that are important to

pilot motion cueing and are general tests applicable to all types of airplanes.

(3) This test is only required to be run once for the initial qualification of the FSTD and will not be required for continuing qualification purposes. The FAA will accept test results provided by the FSTD manufacturer as part of a Statement of Compliance confirming that the objective motion cueing tests were used to assist in the tuning of the FSTD's motion cueing algorithms.

e. Motion Vibrations.

(1) Presentation of results. The characteristic motion vibrations may be used to verify that the flight simulator can reproduce the frequency content of the airplane when flown in specific conditions. The test results should be presented as a Power Spectral Density (PSD) plot with frequencies on the horizontal axis and amplitude on the vertical axis. The airplane data and flight simulator data should be presented in the same format with the same scaling. The algorithms used for generating the flight simulator data should be the same as those used for the airplane data. If they are not the same then the algorithms used for the flight simulator data should be proven to be sufficiently comparable. As a minimum, the results along the dominant axes should be presented and a rationale for not presenting the other axes should be provided.

(2) Interpretation of results. The overall trend of the PSD plot should be considered while focusing on the dominant frequencies. Less emphasis should be placed on the differences at the high frequency and low amplitude portions of the PSD plot. During the analysis, certain structural components of the flight simulator have resonant frequencies that are filtered and may not appear in the PSD plot. If filtering is required, the notch filter bandwidth should be limited to 1 Hz to ensure that the buffet feel is not adversely affected. In addition, a rationale should be provided to explain that the characteristic motion vibration is not being adversely affected by the filtering. The amplitude should match airplane data as described below. However, if the PSD plot was altered for subjective reasons, a rationale should be provided to justify the change. If the plot is on a logarithmic scale, it may be difficult to interpret the amplitude of the buffet in terms of acceleration. For example, a $1 \times$ 10⁻³ g-rms²/Hz would describe a heavy buffet and may be seen in the deep stall regime. Alternatively, a 1×10^{-6} g-rms²/Hz buffet is almost not perceivable; but may represent a flap buffet at low speed. The previous two examples differ in magnitude by 1000. On a PSD plot this represents three decades (one decade is a change in order of magnitude of 10: and two decades is a change in order of magnitude of 100).

NOTE: In the example, "g-rms2 is the mathematical expression for "g's root mean squared."

7. SOUND SYSTEM

a. General. The total sound environment in the airplane is very complex, and changes with atmospheric conditions, airplane configuration, airspeed, altitude, and power settings. Flight deck sounds are an important component of the flight deck operational environment and provide valuable information to the flight crew. These aural cues can either assist the crew (as an indication of an abnormal situation), or hinder the crew (as a distraction or nuisance). For effective training, the flight simulator should provide flight deck sounds that are perceptible to the pilot during normal and abnormal operations, and comparable to those of the airplane. The flight simulator operator should carefully evaluate background noises in the location where the device will be installed. To demonstrate compliance with the sound requirements, the objective or validation tests in this attachment were selected to provide a representative sample of normal static conditions typically experienced by a pilot.

b. Alternate propulsion. For FFS with multiple propulsion configurations, any condition listed in Table A2A of this attachment should be presented for evaluation as part of the QTG if identified by the airplane manufacturer or other data supplier as significantly different due to a change in propulsion system (engine or propeller).

c. Data and Data Collection System.

- (1) Information provided to the flight simulator manufacturer should be presented in the format suggested by the International Air Transport Association (IATA) "Flight Simulator Design and Performance Data Requirements," as amended. This information should contain calibration and frequency response data.
- (2) The system used to perform the tests listed in Table A2A should comply with the following standards:
- (a) The specifications for octave, half octave, and third octave band filter sets may be found in American National Standards Institute (ANSI) S1.11–1986;
- (b) Measurement microphones should be type WS2 or better, as described in International Electrotechnical Commission (IEC) 1094–4-1995.
- (3) Headsets. If headsets are used during normal operation of the airplane they should also be used during the flight simulator evaluation
- (4) Playback equipment. Playback equipment and recordings of the QTG conditions should be provided during initial evaluations.
- (5) Background noise.

- (a) Background noise is the noise in the flight simulator that is not associated with the airplane, but is caused by the flight simulator's cooling and hydraulic systems and extraneous noise from other locations in the building. Background noise can seriously impact the correct simulation of airplane sounds and should be kept below the airplane sounds. In some cases, the sound level of the simulation can be increased to compensate for the background noise. However, this approach is limited by the specified tolerances and by the subjective acceptability of the sound environment to the evaluation pilot.
- (b) The acceptability of the background noise levels is dependent upon the normal sound levels in the airplane being represented. Background noise levels that fall below the lines defined by the following points, may be acceptable:
 - (i) 70 dB @ 50 Hz;
 - (ii) 55 dB @ 1000 Hz;
 - (iii) 30 dB @ 16 kHz
- (Note: These limits are for unweighted ½ octave band sound levels. Meeting these limits for background noise does not ensure an acceptable flight simulator. Airplane sounds that fall below this limit require careful review and may require lower limits on background noise.)
- (6) Validation testing. Deficiencies in airplane recordings should be considered when applying the specified tolerances to ensure that the simulation is representative of the airplane. Examples of typical deficiencies are:
 - (a) Variation of data between tail numbers;
 - (b) Frequency response of microphones;
 - (c) Repeatability of the measurements.

TABLE A2B—EXAMPLE OF CONTINUING QUALIFICATION FREQUENCY RESPONSE TEST TOLERANCE

Band center frequency	Initial results (dBSPL)	Continuing qualification results (dBSPL)	Absolute difference
50	75.0	73.8	1.2
63	75.9	75.6	0.3
80	77.1	76.5	0.6
100	78.0	78.3	0.3
125	81.9	81.3	0.6
160	79.8	80.1	0.3
200	83.1	84.9	1.8
250	78.6	78.9	0.3
315	79.5	78.3	1.2
400	80.1	79.5	0.6
500	80.7	79.8	0.9
630	81.9	80.4	1.5
800	73.2	74.1	0.9
1000	79.2	80.1	0.9
1250	80.7	82.8	2.1
1600	81.6	78.6	3.0
2000	76.2	74.4	1.8
2500	79.5	80.7	1.2
3150	80.1	77.1	3.0
4000	78.9	78.6	0.3
5000	80.1	77.1	3.0

TABLE A2B—EXAMPLE OF CONTINUING QUALIFICATION FREQUENCY RESPONSE TEST TOLERANCE—Continued

Band center frequency	Initial results (dBSPL)	Continuing qualification results (dBSPL)	Absolute difference
6300	80.7	80.4	0.3
8000	84.3	85.5	1.2
10000	81.3	79.8	1.5
12500	80.7	80.1	0.6
16000	71.1	71.1	0.0
Average			1.1

- 8. Additional Information About Flight SIMULATOR QUALIFICATION FOR NEW OR DE-RIVATIVE AIRPLANES
- a. Typically, an airplane manufacturer's approved final data for performance, handling qualities, systems or avionics is not available until well after a new or derivative airplane has entered service. However, flight crew training and certification often begins several months prior to the entry of the first airplane into service. Consequently, it may be necessary to use preliminary data provided by the airplane manufacturer for interim qualification of flight simulators.
- b. In these cases, the responsible Flight Standards office may accept certain partially validated preliminary airplane and systems data, and early release ("red label") avionics data in order to permit the necessary program schedule for training, certification, and service introduction.
- c. Simulator sponsors seeking qualification based on preliminary data should consult the responsible Flight Standards office to make special arrangements for using preliminary data for flight simulator qualification. The sponsor should also consult the airplane and flight simulator manufacturers to develop a data plan and flight simulator qualification plan.
- d. The procedure to be followed to gain the responsible Flight Standards office acceptance of preliminary data will vary from case to case and between airplane manufacturers. Each airplane manufacturer's new airplane development and test program is designed to suit the needs of the particular project and may not contain the same events or sequence of events as another manufacturer's program, or even the same manufacturer's program for a different airplane. Therefore, there cannot be a prescribed invariable procedure for acceptance of preliminary data, but instead there should be a statement describing the final sequence of events, data sources, and validation procedures agreed by the simulator sponsor, the airplane manufacturer, the flight simulator manufacturer. and the responsible Flight Standards office.

NOTE: A description of airplane manufacturer-provided data needed for flight simulator modeling and validation is to be found in the IATA Document "Flight Simulator Design and Performance Data Requirements," as amended.

- e. The preliminary data should be the manufacturer's best representation of the airplane, with assurance that the final data will not significantly deviate from the preliminary estimates. Data derived from these predictive or preliminary techniques should be validated against available sources including, at least, the following:
- (1) Manufacturer's engineering report. The report should explain the predictive method used and illustrate past success of the method on similar projects. For example, the manufacturer could show the application of the method to an earlier airplane model or predict the characteristics of an earlier model and compare the results to final data for that model.
- (2) Early flight test results. This data is often derived from airplane certification tests, and should be used to maximum advantage for early flight simulator validation. Certain critical tests that would normally be done early in the airplane certification program should be included to validate essential pilot training and certification maneuvers. These include cases where a pilot is expected to cope with an airplane failure mode or an engine failure. Flight test data that will be available early in the flight test program will depend on the airplane manufacturer's flight test program design and may not be the same in each case. The flight test program of the airplane manufacturer should include provisions for generation of very early flight test results for flight simulator validation.
- f. The use of preliminary data is not indefinite. The airplane manufacturer's final data should be available within 12 months after the airplane's first entry into service or as agreed by the responsible Flight Standards office, the simulator sponsor, and the airplane manufacturer. When applying for interim qualification using preliminary data, the simulator sponsor and the responsible Flight Standards office should agree on the update program. This includes specifying that the final data update will be installed in the flight simulator within a period of 12 months following the final data release, unless special conditions exist and a different schedule is acceptable. The flight simulator performance and handling validation would then be based on data derived from flight tests or from other approved sources. Initial airplane systems data should be updated after engineering tests. Final airplane systems data should also be used for flight simulator programming and validation.
- g. Flight simulator avionics should stay essentially in step with airplane avionics

(hardware and software) updates. The permitted time lapse between airplane and flight simulator updates should be minimal. It may depend on the magnitude of the update and whether the QTG and pilot training and certification are affected. Differences in airplane and flight simulator avionics versions and the resulting effects on flight simulator qualification should be agreed between the simulator sponsor and the responsible Flight Standards office. Consultation with the flight simulator manufacturer is desirable throughout the qualification process.

- h. The following describes an example of the design data and sources that might be used in the development of an interim qualification plan.
- (1) The plan should consist of the development of a QTG based upon a mix of flight test and engineering simulation data. For data collected from specific airplane flight tests or other flights, the required design model or data changes necessary to support an acceptable Proof of Match (POM) should be generated by the airplane manufacturer.
- (2) For proper validation of the two sets of data, the airplane manufacturer should compare their simulation model responses against the flight test data, when driven by the same control inputs and subjected to the same atmospheric conditions as recorded in the flight test. The model responses should result from a simulation where the following systems are run in an integrated fashion and are consistent with the design data released to the flight simulator manufacturer:
 - (a) Propulsion;
 - (b) Aerodynamics;
 - (c) Mass properties;(d) Flight controls;
 - (e) Stability augmentation; and
 - (f) Brakes/landing gear.
- i. A qualified test pilot should be used to assess handling qualities and performance evaluations for the qualification of flight simulators of new airplane types.

END INFORMATION

BEGIN QPS REQUIREMENT

9. Engineering Simulator—Validation Data

a. When a fully validated simulation (i.e., validated with flight test results) is modified due to changes to the simulated airplane configuration, the airplane manufacturer or other acceptable data supplier must coordinate with the responsible Flight Standards office if they propose to supply validation data from an "audited" engineering simulator/simulation to selectively supplement flight test data. The responsible Flight Standards office must be provided an opportunity to audit the engineering simulation

or the engineering simulator used to generate the validation data. Validation data from an audited engineering simulation may be used for changes that are incremental in nature. Manufacturers or other data suppliers must be able to demonstrate that the predicted changes in aircraft performance are based on acceptable aeronautical principles with proven success history and valid outcomes. This must include comparisons of predicted and flight test validated data.

- b. Airplane manufacturers or other acceptable data suppliers seeking to use an engineering simulator for simulation validation data as an alternative to flight-test derived validation data, must contact the responsible Flight Standards office and provide the following:
- (1) A description of the proposed aircraft changes, a description of the proposed simulation model changes, and the use of an integral configuration management process, including a description of the actual simulation model modifications that includes a step-by-step description leading from the original model(s) to the current model(s).
- (2) A schedule for review by the responsible Flight Standards office of the proposed plan and the subsequent validation data to establish acceptability of the proposal.
- (3) Validation data from an audited engineering simulator/simulation to supplement specific segments of the flight test data.
- c. To be qualified to supply engineering simulator validation data, for aerodynamic, engine, flight control, or ground handling models, an airplane manufacturer or other acceptable data supplier must:
- (1) Be able to verify their ability able to:
- (a) Develop and implement high fidelity simulation models; and
- (b) Predict the handling and performance characteristics of an airplane with sufficient accuracy to avoid additional flight test activities for those handling and performance characteristics.
 - (2) Have an engineering simulator that:
- (a) Is a physical entity, complete with a flight deck representative of the simulated class of airplane;
- (b) Has controls sufficient for manual flight;
- (c) Has models that run in an integrated manner;
- (d) Has fully flight-test validated simulation models as the original or baseline simulation models;
- (e) Has an out-of-the-flight deck visual system;
- (f) Has actual avionics boxes interchangeable with the equivalent software simulations to support validation of released software:
- (g) Uses the same models as released to the training community (which are also used to produce stand-alone proof-of-match and checkout documents);

- (h) Is used to support airplane development and certification; and
- (i) Has been found to be a high fidelity representation of the airplane by the manufacturer's pilots (or other acceptable data supplier), certificate holders, and the responsible Flight Standards office.
- (3) Use the engineering simulator/simulation to produce a representative set of integrated proof-of-match cases.
- (4) Use a configuration control system covering hardware and software for the operating components of the engineering simulator/simulation.
- (5) Demonstrate that the predicted effects of the change(s) are within the provisions of sub-paragraph "a" of this section, and confirm that additional flight test data are not required.
- d. Additional Requirements for Validation Data
- (1) When used to provide validation data, an engineering simulator must meet the simulator standards currently applicable to training simulators except for the data package
- (2) The data package used must be:
- (a) Comprised of the engineering predictions derived from the airplane design, development, or certification process;
- (b) Based on acceptable aeronautical principles with proven success history and valid outcomes for aerodynamics, engine operations, avionics operations, flight control applications, or ground handling;
- (c) Verified with existing flight-test data; and
- (d) Applicable to the configuration of a production airplane, as opposed to a flight-test airplane.
- (3) Where engineering simulator data are used as part of a QTG, an essential match must exist between the training simulator and the validation data.
- (4) Training flight simulator(s) using these baseline and modified simulation models must be qualified to at least internationally recognized standards, such as contained in the ICAO Document 9625, the "Manual of Criteria for the Qualification of Flight Simulators."

END QPS REQUIREMENT

10. [Reserved]

11. VALIDATION TEST TOLERANCES

BEGIN INFORMATION

- a. Non-Flight-Test Tolerances
- (1) If engineering simulator data or other non-flight-test data are used as an allowable

form of reference validation data for the objective tests listed in Table A2A of this attachment, the data provider must supply a well-documented mathematical model and testing procedure that enables a replication of the engineering simulation results within 40% of the corresponding flight test tolerances.

- b. Background
- (1) The tolerances listed in Table A2A of this attachment are designed to measure the quality of the match using flight-test data as a reference.
- (2) Good engineering judgment should be applied to all tolerances in any test. A test is failed when the results clearly fall outside of the prescribed tolerance(s).
- (3) Engineering simulator data are acceptable because the same simulation models used to produce the reference data are also used to test the flight training simulator (i.e., the two sets of results should be "essentially" similar).
- (4) The results from the two sources may differ for the following reasons:
- (a) Hardware (avionics units and flight controls);
 - (b) Iteration rates;
 - (c) Execution order;
 - (d) Integration methods:
 - (e) Processor architecture:
 - (f) Digital drift, including:
 - (i) Interpolation methods;
 - (ii) Data handling differences; and
 - (iii) Auto-test trim tolerances.
- (5) The tolerance limit between the reference data and the flight simulator results is generally 40 percent of the corresponding 'flight-test' tolerances. However, there may be cases where the simulator models used are of higher fidelity, or the manner in which they are cascaded in the integrated testing loop have the effect of a higher fidelity, than those supplied by the data provider. Under these circumstances, it is possible that an error greater than 40 percent may be generated. An error greater than 40 percent may be acceptable if simulator sponsor can provide an adequate explanation.
- (6) Guidelines are needed for the application of tolerances to engineering-simulatorgenerated validation data because:
- (a) Flight-test data are often not available due to technical reasons;
- (b) Alternative technical solutions are being advanced; and
 - (c) High costs.

12. VALIDATION DATA ROADMAP

- a. Airplane manufacturers or other data suppliers should supply a validation data roadmap (VDR) document as part of the data package. A VDR document contains guidance material from the airplane validation data supplier recommending the best possible sources of data to be used as validation data in the QTG. A VDR is of special value when requesting interim qualification, qualification of simulators for airplanes certificated prior to 1992, and qualification of alternate engine or avionics fits. A sponsor seeking to have a device qualified in accordance with the standards contained in this QPS appendix should submit a VDR to the responsible Flight Standards office as early as possible in the planning stages. The responsible Flight Standards office is the final authority to approve the data to be used as validation material for the QTG.
- b. The VDR should identify (in matrix format) sources of data for all required tests. It should also provide guidance regarding the validity of these data for a specific engine type, thrust rating configuration, and the revision levels of all avionics affecting airplane handling qualities and performance. The VDR should include rationale or explanation in cases where data or parameters are missing, engineering simulation data are to be used, flight test methods require explanation, or there is any deviation from data requirements. Additionally, the document should refer to other appropriate sources of validation data (e.g., sound and vibration data documents).
- c. The Sample Validation Data Roadmap (VDR) for airplanes, shown in Table A2C, depicts a generic roadmap matrix identifying sources of validation data for an abbreviated list of tests. This document is merely a sample and does not provide actual data. A complete matrix should address all test conditions and provide actual data and data sources.
- d. Two examples of rationale pages are presented in Appendix F of the IATA "Flight Simulator Design and Performance Data Requirements." These illustrate the type of airplane and avionics configuration information and descriptive engineering rationale used to describe data anomalies or provide an acceptable basis for using alternative data for QTG validation requirements.

END INFORMATION

Table A2C - Sample Validation Data Roadmap for Airplanes

Comments	Legend: D71 = Engine Type (Thrust Rating of 71.5K) D73 = Engine Type (Thrust Rating of 73K) Bold upper case = primary validation source. Lower case, within parentheses = alternative validation source. R = Rationale included in the data package Appendix.			Primary data contained in IPOM.	See engineering rationale for test data in VDR.		Primary data contained in IPOM.	Alternative engine thrust rating flight test data in VDR.	Alternative engine thrust rating flight test data in VDR.	Test procedure anomaly; see rationale.	No flight test data available; see rationale.	Primary data contained in IPOM.	Alternative engine thrust rating flight test data in VDR.	AFM data available (73K).		Eng sim data w/ modified EEC accel rate in VDR.	Eng sim data w/ modified EEC accel rate in VDR.		No flight test data available; see rationale.					No flight test data available; see rationale.	
	Appendix to this VDR Doc. #xxx987, NEW		-	<u>a</u>	D73 S		-	D73 A	$\mathbf{D73} \mid \frac{A}{V}$	R	D73 N	P	D73 A	D73 A		D73 E	D73 E		(d73) N	(d73)	(d73)		(d73)	D73 N	
ent	Integrated POM Doc. #xxx654, Rev. A		-	D73			D73					D71													
Docum	Propulsion POM Doc. #321, Rev. C		T				1															1			
Validation Document	Ground Handling POM Doc. B. XXX789, Rev. B	D71	D71	(d73)										-											
Š	Flight Controls POM Doc.#xxx456, NEW																								
	Aerodynamics POM Doc.#xxx123, Rev. A				(d71)	D71	(d73)	(d71)	(d71)	D71		(d71)	(d71)	(d71)	D71	(d73)	(d73)	D71	D71	D7.1	D71		D71	(d71)	
Validation Source	Engineering Simulator Data (DEF- 73 Engines)				Х						Х					×	X		×	(x)	(X)		(x)	x	
Valid Sou	Aircraft Flight Test Data	×	×	×	(x)	×	×	×	Х	×		X	X	×	X	×	(x)	×		×	×		×		
	CCA Mode																								
Test Description	Notes: 1. Only one page is shown; and some test conditions were deleted for brevity. 2. Relevant regulatory material should be consulted and all applicable tests addressed. all applicable tests addressed. Asolidation source, document and comments provided herein are for reference only and do not constitute approval for use. A CA mode must be described for each test condition. 5. If more than one aircraft type (e.g., derivative and baseline) are used as validation data more columns	Minimum Radius Turn	Rate of Turn vs. Nosewheel Angle (2 speeds).	Ground Acceleration Time and Distance.	Minimum Control Speed, Ground (Vmcg).	Minimum Unstick Speed (Vmu).	Normal Takeoff.	Critical Engine Failure on Takeoff.	Crosswind Takeoff.	Rejected Takeoff.	Dynamic Engine Failure After Takeoff.	Normal Climb – All Engines.	Climb - Engine-out, Second Segment.	Climb - Engine-out, Enroute.	Engine-out, Approach Climb.	Level Flight Acceleration.	Level Flight Deceleration.	Cruise Performance.	Stopping Time & Distance (Wheel brakes / Light weight).	Stopping Time & Distance (Wheel brakes/ Med. weight).	Stopping Time & Distance	(Wheel brakes / Heavy weight).	Stopping Time & Distance (Reverse thrust / Light weight).	Stopping Time & Distance (Reverse thrust / Med. Weight).	
ICAO or IATA#	Notes: 1. Only one page i deleted for brevity. 2. Retevant regular all applicable tests 3. Validation sour approval for use. approval for use. CA mode mu condition. 5. If more than on baseline are used baseline are used	1.a.1.	1.a.2.	1.b.1.	1.b.2.	1.b.3.	1.b.4.	1.b.5.	1.b.6.	1.b.7.	1.b.8.	1.c.1.	1.c.2.	1.c.3.	1.c.4.	1.c.5.a.	1.c.5.b.	1.d.1.	1.e.1.a.	1.e.1.b.	1.e.1.c.		I.e.2.a.	1.e.2.b.	

BEGIN INFORMATION

13. ACCEPTANCE GUIDELINES FOR ALTERNATIVE ENGINES DATA.

a. Background

- (1) For a new airplane type, the majority of flight validation data are collected on the first airplane configuration with a "baseline" engine type. These data are then used to validate all flight simulators representing that airplane type.
- (2) Additional flight test validation data may be needed for flight simulators representing an airplane with engines of a different type than the baseline, or for engines with thrust rating that is different from previously validated configurations.
- (3) When a flight simulator with alternate engines is to be qualified, the QTG should contain tests against flight test validation data for selected cases where engine differences are expected to be significant.

b. Approval Guidelines For Validating Alternate Engine Applications

- (1) The following guidelines apply to flight simulators representing airplanes with alternate engine applications or with more than one engine type or thrust rating.
- (2) Validation tests can be segmented into two groups, those that are dependent on engine type or thrust rating and those that are not
- (3) For tests that are independent of engine type or thrust rating, the QTG can be based on validation data from any engine application. Tests in this category should be designated as independent of engine type or thrust rating.
- (4) For tests that are affected by engine type, the QTG should contain selected engine-specific flight test data sufficient to validate that particular airplane-engine configuration. These effects may be due to engine dynamic characteristics, thrust levels or engine-related airplane configuration changes. This category is primarily characterized by variations between different engine manufacturers' products, but also includes differences due to significant engine design changes from a previously flight-validated configuration within a single engine type, See Table A2D, Alternate Engine Validation Flight Tests in this section for a list of acceptable tests.
- (5) Alternate engine validation data should be based on flight test data, except as noted in sub-paragraphs 13.c.(1) and (2), or where other data are specifically allowed (e.g., engineering simulator/simulation data). If certification of the flight characteristics of the airplane with a new thrust rating (regardless of percentage change) does require certification flight testing with a comprehensive

stability and control flight instrumentation package, then the conditions described in Table A2D in this section should be obtained from flight testing and presented in the QTG. Flight test data, other than throttle calibration data, are not required if the new thrust rating is certified on the airplane without need for a comprehensive stability and control flight instrumentation package.

- (6) As a supplement to the engine-specific flight tests listed in Table A2D and baseline engine-independent tests, additional engine-specific engineering validation data should be provided in the QTG, as appropriate, to facilitate running the entire QTG with the alternate engine configuration. The sponsor and the responsible Flight Standards office should agree in advance on the specific validation tests to be supported by engineering simulation data.
- (7) A matrix or VDR should be provided with the QTG indicating the appropriate validation data source for each test.
- (8) The flight test conditions in Table A2D are appropriate and should be sufficient to validate implementation of alternate engines in a flight simulator.

END INFORMATION

BEGIN QPS REQUIREMENT

c. Test Requirements

- (1) The QTG must contain selected enginespecific flight test data sufficient to validate the alternative thrust level when:
- (a) the engine type is the same, but the thrust rating exceeds that of a previously flight-test validated configuration by five percent (5%) or more; or
- (b) the engine type is the same, but the thrust rating is less than the lowest previously flight-test validated rating by fifteen percent (15%) or more. See Table A2D for a list of acceptable tests.
- (2) Flight test data is not required if the thrust increase is greater than 5%, but flight tests have confirmed that the thrust increase does not change the airplane's flight characteristics.
- (3) Throttle calibration data (i.e., commanded power setting parameter versus throttle position) must be provided to validate all alternate engine types and engine thrust ratings that are higher or lower than a previously validated engine. Data from a test airplane or engineering test bench with the correct engine controller (both hardware and software) are required.

END QPS REQUIREMENT

BEGIN QPS REQUIREMENT

Entry No.	Test description		Alternative engine type	Alternative thrust rating ²
1.b.1., 1.b.4	Normal take-off/ground acceleration time and di	stance	Х	Х
1.b.2	$V_{\rm mcg},$ if performed for airplane certification		Х	Х
1.b.5	Engine-out take-off Dynamic engine failure after take-off.	Either test may be performed.	x	
1.b.7. 1.d.1. 1.f.1, 1.f.2. 2.a.7. 2.c.1. 2.d.1. 2.d.1. 2.d.5. 2.e.1.	Rejected take-off if performed for airplane certification can be considered as a consideration and deceleration. Throttle calibration 1 Power change dynamics (acceleration) V _{max} if performed for airplane certification Engine inoperative trim Normal landing	cation	X X X X X X	X X X X

¹ Must be provided for all changes in engine type or thrust rating; see paragraph 13.c.(3). ² See paragraphs 13.c.(1) through 13.c.(3), for a definition of applicable thrust ratings.

END QPS REQUIREMENT

BEGIN INFORMATION

14. ACCEPTANCE GUIDELINES FOR ALTERNATIVE AVIONICS (FLIGHT-RELATED COMPUTERS AND CONTROLLERS)

a. Background

- (1) For a new airplane type, the majority of flight validation data are collected on the first airplane configuration with a "baseline" flight-related avionics ship-set; (see subparagraph b.(2) of this section). These data are then used to validate all flight simulators representing that airplane type.
- (2) Additional validation data may be required for flight simulators representing an airplane with avionics of a different hardware design than the baseline, or a different software revision than previously validated configurations.
- (3) When a flight simulator with additional or alternate avionics configurations is to be qualified, the QTG should contain tests against validation data for selected cases where avionics differences are expected to be significant.

b. Approval Guidelines for Validating Alternate Avionics

- (1) The following guidelines apply to flight simulators representing airplanes with a revised avionics configuration, or more than one avionics configuration.
- (2) The baseline validation data should be based on flight test data, except where other data are specifically allowed (e.g., engineering flight simulator data).
- (3) The airplane avionics can be segmented into two groups, systems or components whose functional behavior contributes to the aircraft response presented in the QTG re-

- sults, and systems that do not. The following avionics are examples of contributory systems for which hardware design changes or software revisions may lead to significant differences in the aircraft response relative to the baseline avionics configuration: Flight control computers and controllers for engines, autopilot, braking system, nosewheel steering system, and high lift system. Related avionics such as stall warning and augmentation systems should also be considered.
- (4) The acceptability of validation data used in the QTG for an alternative avionics fit should be determined as follows:
- (a) For changes to an avionics system or component that do not affect QTG validation test response, the QTG test can be based on validation data from the previously validated avionics configuration.
- (b) For an avionics change to a contributory system, where a specific test is not affected by the change (e.g., the avionics change is a Built In Test Equipment (BITE) update or a modification in a different flight phase), the QTG test can be based on validation data from the previously-validated avionics configuration. The QTG should include authoritative justification (e.g., from the airplane manufacturer or system supplier) that this avionics change does not affect the test.
- (c) For an avionics change to a contributory system, the QTG may be based on validation data from the previously-validated avionics configuration if no new functionality is added and the impact of the avionics change on the airplane response is small and based on acceptable aeronautical principles with proven success history and valid outcomes. This should be supplemented with avionics-specific validation data from the airplane manufacturer's engineering

simulation, generated with the revised avionics configuration. The QTG should also include an explanation of the nature of the change and its effect on the airplane response.

- (d) For an avionics change to a contributory system that significantly affects some tests in the QTG or where new functionality is added, the QTG should be based on validation data from the previously validated avionics configuration and supplemental avionics-specific flight test data sufficient to validate the alternate avionics revision. Additional flight test validation data may not be needed if the avionics changes were certified without the need for testing with a comprehensive flight instrumentation package. The airplane manufacturer should coordinate flight simulator data requirements, in advance with the responsible Flight Standards office.
- (5) A matrix or "roadmap" should be provided with the QTG indicating the appropriate validation data source for each test. The roadmap should include identification of the revision state of those contributory avionics systems that could affect specific test responses if changed.

15. Transport Delay Testing

- a. This paragraph explains how to determine the introduced transport delay through the flight simulator system so that it does not exceed a specific time delay. The transport delay should be measured from control inputs through the interface, through each of the host computer modules and back through the interface to motion, flight instrument, and visual systems. The transport delay should not exceed the maximum allowable interval.
- b. Four specific examples of transport delay are:
- (1) Simulation of classic non-computer controlled aircraft;
- (2) Simulation of computer controlled aircraft using real airplane black boxes;
- (3) Simulation of computer controlled aircraft using software emulation of airplane boxes;
- (4) Simulation using software avionics or re-hosted instruments.
- c. Figure A2C illustrates the total transport delay for a non-computer-controlled airplane or the classic transport delay test. Since there are no airplane-induced delays for this case, the total transport delay is equivalent to the introduced delay.
- d. Figure A2D illustrates the transport delay testing method using the real airplane controller system.
- e. To obtain the induced transport delay for the motion, instrument and visual signal, the delay induced by the airplane controller should be subtracted from the total transport delay. This difference represents the in-

troduced delay and should not exceed the standards prescribed in Table A1A.

- f. Introduced transport delay is measured from the flight deck control input to the reaction of the instruments and motion and visual systems (See Figure A2C).
- g. The control input may also be introduced after the airplane controller system and the introduced transport delay measured directly from the control input to the reaction of the instruments, and simulator motion and visual systems (See Figure A2D).
- h. Figure A2E illustrates the transport delay testing method used on a flight simulator that uses a software emulated airplane controller system.
- i. It is not possible to measure the introduced transport delay using the simulated airplane controller system architecture for the pitch, roll and yaw axes. Therefore, the signal should be measured directly from the pilot controller. The flight simulator manufacturer should measure the total transport delay and subtract the inherent delay of the actual airplane components because the real airplane controller system has an inherent delay provided by the airplane manufacturer. The flight simulator manufacturer should ensure that the introduced delay does not exceed the standards prescribed in Table AlA.
- j. Special measurements for instrument signals for flight simulators using a real airplane instrument display system instead of a simulated or re-hosted display. For flight instrument systems, the total transport delay should be measured and the inherent delay of the actual airplane components subtracted to ensure that the introduced delay does not exceed the standards prescribed in Table A1A.
- (1) Figure A2FA illustrates the transport delay procedure without airplane display simulation. The introduced delay consists of the delay between the control movement and the instrument change on the data bus.
- (2) Figure A2FB illustrates the modified testing method required to measure introduced delay due to software avionics or rehosted instruments. The total simulated instrument transport delay is measured and the airplane delay should be subtracted from this total. This difference represents the introduced delay and should not exceed the standards prescribed in Table A1A. The inherent delay of the airplane between the data bus and the displays indicated in figure A2FA. The display manufacturer should provide this delay time.
- k. Recorded signals. The signals recorded to conduct the transport delay calculations should be explained on a schematic block diagram. The flight simulator manufacturer should also provide an explanation of why each signal was selected and how they relate to the above descriptions.
- 1. Interpretation of results. Flight simulator results vary over time from test to test

Pt. 60, App. A

due to "sampling uncertainty." All flight simulators run at a specific rate where all modules are executed sequentially in the host computer. The flight controls input can occur at any time in the iteration, but these data will not be processed before the start of the new iteration. For example, a flight simulator running at 60 Hz may have a difference of as much as 16.67 msec between test results. This does not mean that the test has failed. Instead, the difference is attributed to variations in input processing. In some con-

ditions, the host simulator and the visual system do not run at the same iteration rate, so the output of the host computer to the visual system will not always be synchronized.

m. The transport delay test should account for both daylight and night modes of operation of the visual system. In both cases, the tolerances prescribed in Table A1A must be met and the motion response should occur before the end of the first video scan containing new information.

14 CFR Ch. I (1-1-24 Edition)

Figure A2C

Transport Delay for simulation of classic non-computer controlled aircraft.

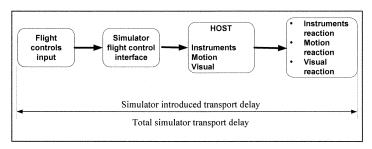


Figure A2D

Transport Delay for simulation of computer controlled aircraft using real airplane black

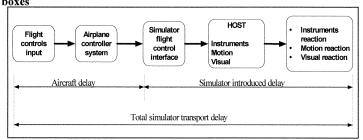


Figure A2E

Transport Delay for simulation of computer controlled aircraft using software emulation of airplane boxes

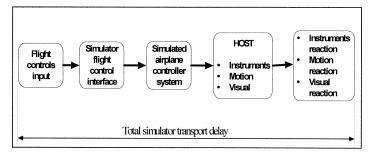
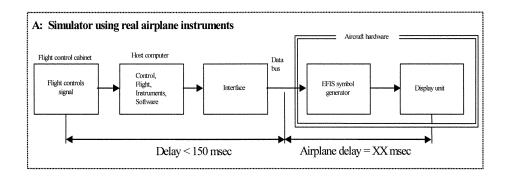
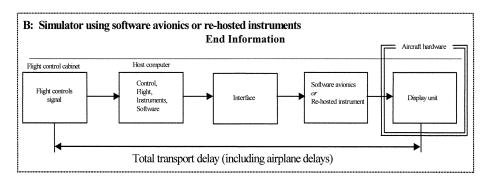


Figure A2FA and A2FB

Transport delay for simulation of airplanes using real or re-hosted instrument drivers





BEGIN INFORMATION

16. CONTINUING QUALIFICATION EVALUATIONS— VALIDATION TEST DATA PRESENTATION

a. Background

- (1) The MQTG is created during the initial evaluation of a flight simulator. This is the master document, as amended, to which flight simulator continuing qualification evaluation test results are compared.
- (2) The currently accepted method of presenting continuing qualification evaluation test results is to provide flight simulator results over-plotted with reference data. Test results are carefully reviewed to determine if the test is within the specified tolerances. This can be a time consuming process, particularly when reference data exhibits rapid variations or an apparent anomaly requiring engineering judgment in the application of the tolerances. In these cases, the solution is to compare the results to the MQTG. The continuing qualification results are com-

pared to the results in the MQTG for acceptance. The flight simulator operator and the responsible Flight Standards office should look for any change in the flight simulator performance since initial qualification.

b. Continuing Qualification Evaluation Test Results Presentation

- (1) Flight simulator operators are encouraged to over-plot continuing qualification validation test results with MQTG flight simulator results recorded during the initial evaluation and as amended. Any change in a validation test will be readily apparent. In addition to plotting continuing qualification validation test and MQTG results, operators may elect to plot reference data as well.
- (2) There are no suggested tolerances between flight simulator continuing qualification and MQTG validation test results. Investigation of any discrepancy between the MQTG and continuing qualification flight simulator performance is left to the discretion of the flight simulator operator and the responsible Flight Standards office.

- (3) Differences between the two sets of results, other than variations attributable to repeatability issues that cannot be explained, should be investigated.
- (4) The flight simulator should retain the ability to over-plot both automatic and manual validation test results with reference data.

END INFORMATION

BEGIN OPS REQUIREMENTS

- 17. ALTERNATIVE DATA SOURCES, PROCE-DURES, AND INSTRUMENTATION: LEVEL A AND LEVEL B SIMULATORS ONLY
- a. Sponsors are not required to use the alternative data sources, procedures, and instrumentation. However, a sponsor may choose to use one or more of the alternative sources, procedures, and instrumentation described in Table A2E.

END QPS REQUIREMENTS

BEGIN INFORMATION

- b. It has become standard practice for experienced simulator manufacturers to use modeling techniques to establish data bases for new simulator configurations while awaiting the availability of actual flight test data. The data generated from the aerodynamic modeling techniques is then compared to the flight test data when it becomes available. The results of such comparisons have become increasingly consistent, indicating that these techniques, applied with the appropriate experience, are dependable and accurate for the development of aerodynamic models for use in Level A and Level B simulators.
- c. Based on this history of successful comparisons, the responsible Flight Standards office has concluded that those who are experienced in the development of aerodynamic models may use modeling techniques to alter the method for acquiring flight test data for Level A or Level B simulators.
- d. The information in Table A2E (Alternative Data Sources, Procedures, and Instrumentation) is presented to describe an acceptable alternative to data sources for simulator modeling and validation and an acceptable alternative to the procedures and instrumentation traditionally used to gather such modeling and validation data.
- (1) Alternative data sources that may be used for part or all of a data requirement are the Airplane Maintenance Manual, the Airplane Flight Manual (AFM), Airplane Design Data, the Type Inspection Report (TIR), Certification Data or acceptable supplemental flight test data.

- (2) The sponsor should coordinate with the responsible Flight Standards office prior to using alternative data sources in a flight test or data gathering effort.
- e. The responsible Flight Standards office position regarding the use of these alternative data sources, procedures, and instrumentation is based on the following presumptions:
- (1) Data gathered through the alternative means does not require angle of attack (AOA) measurements or control surface position measurements for any flight test. However, AOA can be sufficiently derived if the flight test program ensures the collection of acceptable level, unaccelerated, trimmed flight data. All of the simulator time history tests that begin in level, unaccelerated, and trimmed flight, including the three basic trim tests and "fly-by" trims, can be a successful validation of angle of attack by comparison with flight test pitch angle. (Note: Due to the criticality of angle of attack in the development of the ground effects model, particularly critical for normal landings and landings involving cross-control input applicable to Level B simulators, stable "fly-by" trim data will be the acceptable norm for normal and cross-control input landing objective data for these applications.)
- (2) The use of a rigorously defined and fully mature simulation controls system model that includes accurate gearing and cable stretch characteristics (where applicable), determined from actual aircraft measurements. Such a model does not require control surface position measurements in the flight test objective data in these limited applications.
- f. The sponsor is urged to contact the responsible Flight Standards office for clarification of any issue regarding airplanes with reversible control systems. Table A2E is not applicable to Computer Controlled Aircraft FFSs.
- g. Utilization of these alternate data sources, procedures, and instrumentation (Table A2E) does not relieve the sponsor from compliance with the balance of the information contained in this document relative to Level A or Level B FFSs.
- h. The term "inertial measurement system" is used in the following table to include the use of a functional global positioning system (GPS).
- i. Synchronized video for the use of alternative data sources, procedures, and instrumentation should have:
- (1) Sufficient resolution to allow magnification of the display to make appropriate measurement and comparisons; and
- (2) Sufficient size and incremental marking to allow similar measurement and comparison. The detail provided by the video should provide sufficient clarity and accuracy to measure the necessary parameter(s) to at least ½ of the tolerance authorized for

Pt. 60, App. A

the specific test being conducted and allow an integration of the parameter(s) in question to obtain a rate of change.

END INFORMATION

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION

The standards in this table are re			EMENTS a gathering methods described in paragraph	Information
Table of objective tests	Sim	level	Alternative data sources, procedures, and	Notes
Test entry number and title	Α	В	instrumentation	
1.a.1. Performance. Taxi. Min- imum Radius turn.	х	x	TIR, AFM, or Design data may be used.	
A.2. Performance. Taxi Rate of Turn vs. Nosewheel Steering Angle.		X	Data may be acquired by using a constant tiller position, measured with a protractor or full rudder pedal application for steady state turn, and synchronized video of heading indicator. If less than full rudder pedal is used, pedal position must be recorded	A single procedure may not be adequate for all airplane steering systems, therefore appropriate measurement procedures must be devised and proposed for the responsible Flight Standards office concurrence.
Derformance. Takeoff. Ground Acceleration Time and Distance.	х	x	Preliminary certification data may be used. Data may be acquired by using a stop watch, calibrated airspeed, and runway markers during a takeoff with power set before brake release. Power settings may be hand recorded. If an inertial measurement system is installed, speed and distance may be derived from acceleration measurements.	
1.b.2. Performance. Takeoff. Minimum Control Speed— ground (V _{meg}) using aero- dynamic controls only (per ap- plicable airworthiness stand- ard) or low speed, engine in- operative ground control char- acteristics.	х	X	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	Rapid throttle reductions at speeds near $V_{\rm mcg}$ may be used while recording appropriate parameters. The nosewheel must be free to caster, or equivalently freed of sideforce generation.
1.b.3. Performance. Takeoff. Minimum Unstick Speed (V _{mu}) or equivalent test to demonstrate early rotation takeoff characteristics.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and the force/position measurements of flight deck controls.	
1.b.4. Performance. Takeoff. Normal Takeoff.	Х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. AOA can be calculated from pitch attitude and flight path.	
Derformance. Takeoff. Critical Engine Failure during Takeoff.	Х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	Record airplane dynamic response to engine failure and control inputs required to correct flight path.
1.b.6. Performance. Takeoff. Crosswind Takeoff.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	The "1:7 law" to 100 feet (30 meters) is an acceptable wind profile.

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued

The standards in this table are re	quired if	the data	EMENTS a gathering methods described in paragraph —	Information	
	Append	9 of ix A are	not used.		
Table of objective tests	Sim	level	Alternative data sources, procedures, and	Notes	
Test entry number and title	А В		instrumentation		
1.b.7. Performance. Takeoff. Rejected Takeoff.	x	Х	Data may be acquired with a syn- chronized video of calibrated airplane instruments, thrust lever position, en- gine parameters, and distance (e.g., runway markers). A stop watch is re- quired		
.c. 1. Performance. Climb. Normal Climb all engines operating	Х	х	Data may be acquired with a syn- chronized video of calibrated airplane instruments and engine power through- out the climb range.		
.c.2. Performance. Climb. One engine Inoperative Climb.	Х	Х	Data may be acquired with a syn- chronized video of calibrated airplane instruments and engine power through- out the climb range.		
I.c.4. Performance. Climb. One Engine Inoperative Approach Climb (if operations in icing conditions are authorized).	х	х	Data may be acquired with a syn- chronized video of calibrated airplane instruments and engine power through- out the climb range.		
1.d.1. Cruise/Descent. Level flight acceleration	Х	х	Data may be acquired with a syn- chronized video of calibrated airplane instruments, thrust lever position, en- gine parameters, and elapsed time.		
1.d.2. Cruise/Descent. Level flight deceleration 1.d.4. Cruise/Descent. Idle descent.	x	x	Data may be acquired with a synchronized video of calibrated airplane instruments, thrust lever position, engine parameters, and elapsed time. Data may be acquired with a synchronized video of calibrated airplane instruments, thrust lever position, engine parameters, and elapsed time.		
1.d.5. Cruise/Descent. Emergency Descent.	х	Х	Data may be acquired with a syn- chronized video of calibrated airplane instruments, thrust lever position, en- gine parameters, and elapsed time.		
I.e.1. Performance. Stopping. Deceleration time and distance, using manual application of wheel brakes and no reverse thrust on a dry runway.	X	Х	Data may be acquired during landing tests using a stop watch, runway markers, and a synchronized video of calibrated airplane instruments, thrust lever position and the pertinent parameters of engine power.		
1.e.2. Performance. Ground. Deceleration Time and Distance, using reverse thrust and no wheel brakes.	х	х	Data may be acquired during landing tests using a stop watch, runway markers, and a synchronized video of calibrated airplane instruments, thrust lever position and pertinent parameters of engine power.		
1.f.1. Performance. Engines. Acceleration.	х	Х	Data may be acquired with a syn- chronized video recording of engine in- struments and throttle position.		
1.f.2. Performance. Engines. Deceleration.	Х	Х	Data may be acquired with a syn- chronized video recording of engine in- struments and throttle position.		

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued

The standards in this table are re	QPS F quired if	the data	EMENTS a gathering methods described in paragraph	Information		
	Append	9 of ix A are	not used.			
Table of objective tests	Sim	level	Alternative data sources, procedures, and	Notes		
Test entry number and title	Α	В	instrumentation			
2.a.1.a.Handling Qualities. Static Control Checks. Pitch Controller Position vs. Force and Surface Position Calibration.	x	X	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant column positions (encompassing significant column position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same column position data points.	For airplanes with reversible control systems, surface position data acquisition should be accomplished with winds less than 5 kts.		
2.a.2.a. Handling Qualities. Static Control Checks. Roll Controller Position vs. Force and Surface Position Calibration.	X	X	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant wheel positions (encompassing significant wheel position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same wheel position data points	For airplanes with reversible control systems, surface position data acquisition should be accomplished with winds less than 5 kts.		
2.a.3.a.Handling Qualities. Static Control Checks. Rudder Pedal Position vs. Force and Surface Position Calibration.	X	X	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant rudder pedal positions (encompassing significant rudder pedal position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same rudder pedal position data points.	For airplanes with reversible control systems, surface position data acquisition should be accomplished with winds less than 5 kts.		
2.a.4. Handling Qualities. Static Control Checks. Nosewheel Steering Controller Force and Position.	Х	X	Breakout data may be acquired with a hand held force gauge. The remainder of the force to the stops may be calculated if the force gauge and a protractor are used to measure force after breakout for at least 25% of the total displacement capability.			
2.a.5. Handling Qualities. Static Control Checks. Rudder Pedal Steering Calibration.	X	х	Data may be acquired through the use of force pads on the rudder pedals and a pedal position measurement device, together with design data for nosewheel position.			
2.a.6. Handling Qualities. Static Control Checks. Pitch Trim In- dicator vs. Surface Position Calibration.	Х	х	Data may be acquired through calculations.			
2.a.7. Handling qualities. Static control tests. Pitch trim rate.	Х	х	Data may be acquired by using a syn- chronized video of pitch trim indication and elapsed time through range of trim indication.			
2.a.8. Handling Qualities. Static Control tests. Alignment of Flight deck Throttle Lever Angle vs. Selected engine pa- rameter.	Х	х	Data may be acquired through the use of a temporary throttle quadrant scale to document throttle position. Use a synchronized video to record steady state instrument readings or hand-record steady state engine performance readings.			

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued

The standards in this table are re		the data	EMENTS a gathering methods described in paragraph	Information		
	Append	9 of ix A are	not used.			
Table of objective tests	Sim	level	Alternative data sources, procedures, and	Notes		
Test entry number and title	Α	В	instrumentation			
2.a.9. Handling qualities. Static control tests. Brake pedal position vs. force and brake system pressure calibration.	x	X	Use of design or predicted data is acceptable. Data may be acquired by measuring deflection at "zero" and "maximum" and calculating deflections between the extremes using the airplane design data curve.			
c.c.1. Handling qualities. Longitudinal control tests. Power change dynamics.	х	Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and throttle position.			
c.2. Handling qualities. Longitudinal control tests. Flap/slat change dynamics.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and flap/slat position.			
2.c.3. Handling qualities. Longitudinal control tests. Spoiler/ speedbrake change dynamics.	x	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and spoiler/speedbrake position.			
2.c.4. Handling qualities. Longitudinal control tests. Gear change dynamics.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and gear position.			
2.c.5. Handling qualities. Longitudinal control tests. Longitudinal trim.	x	Х	Data may be acquired through use of an inertial measurement system and a synchronized video of flight deck controls position (previously calibrated to show related surface position) and the engine instrument readings.			
c.c.6. Handling qualities. Longitudinal control tests. Longitudinal maneuvering stability (stick force/g).	X	X	Data may be acquired through the use of an inertial measurement system and a synchronized video of calibrated airplane instruments; a temporary, high resolution bank angle scale affixed to the attitude indicator; and a wheel and column force measurement indication.			
.c.7. Handling qualities. Longitudinal control tests. Longitudinal static stability.	Х	х	Data may be acquired through the use of a synchronized video of airplane flight instruments and a hand held force gauge.			
.c.8. Handling qualities. Longitudinal control tests. Stall characteristics.	х	х	Data may be acquired through a synchronized video recording of a stop watch and calibrated airplane airspeed indicator. Hand-record the flight conditions and airplane configuration.	Airspeeds may be cross checked with those in the TIR and AFM.		
.c.9. Handling qualities. Longitudinal control tests. Phugoid dynamics.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.			
c.c.10. Handling qualities. Lon- gitudinal control tests. Short period dynamics.		х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.			

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued

The standards in this table are re		the data	EMENTS a gathering methods described in paragraph	Information
	Append	9 of lix A are	not used.	
Table of objective tests	Sim	level	Alternative data sources, procedures, and	Notes
Test entry number and title	Α	В	instrumentation	
$2.d.1.$ Handling qualities. Lateral directional tests. Minimum control speed, air ($V_{\rm mca}$ or $V_{\rm mci}$), per applicable airworthiness standard or Low speed engine inoperative handling characteristics in the air.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	
 Handling qualities. Lateral directional tests. Roll re- sponse (rate). 	x	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck lateral controls.	May be combined with step input of flight deck roll controller test, 2.d.3.
A.3. Handling qualities. Lateral directional tests. Roll response to flight deck roll controller step input.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck lateral controls.	
2.d.4. Handling qualities. Lateral directional tests. Spiral stability.	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments; force/position measurements of flight deck controls; and a stop watch.	
2.d.5. Handling qualities. Lateral directional tests. Engine inop- erative trim.	х	х	Data may be hand recorded in-flight using high resolution scales affixed to trim controls that have been calibrated on the ground using protractors on the control/trim surfaces with winds less than 5 kts.OR Data may be acquired during second segment climb (with proper pilot control input for an engine-out condition) by using a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	Trimming during second seg- ment climb is not a certifi- cation task and should not be conducted until a safe alti- tude is reached.
2.d.6. Handling qualities. Lateral directional tests. Rudder response.	х	Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of rudder pedals.	
2.d.7. Handling qualities. Lateral directional tests. Dutch roll, (yaw damper OFF).	х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	
A.8. Handling qualities. Lateral directional tests. Steady state sideslip.	Х	х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. Ground track and wind corrected heading may be used for sideslip angle.	
2.e.1. Handling qualities. Landings. Normal landing.		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.	

TABLE A2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued

The standards in this table are r	Information					
	Appendi	9 of x A are	not used.			
Table of objective tests	Sim	Alternative data sources, procedures, and	Notes			
Test entry number and title	Α	В	instrumentation			
2.e.3. Handling qualities. Land- ings. Crosswind landing.		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.			
2.e.4. Handling qualities. Land- ings. One engine inoperative landing.		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and the force/position measurements of flight deck controls. Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
2.e.5. Handling qualities. Land- ings. Autopilot landing (if ap- plicable).		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
 2.e.6. Handling qualities. Land- ings. All engines operating, autopilot, go around. 		X	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
2.e.7. Handling qualities. Land- ings. One engine inoperative go around.		X	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
2.e.8. Handling qualities. Land- ings. Directional control (rud- der effectiveness with sym- metric thrust).		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
 2.e.9. Handling qualities. Landings. Directional control (rudder effectiveness with asymmetric reverse thrust). 		Х	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls. Normal and lateral accelerations may be recorded in lieu of AOA and sideslip.			
2.f. Handling qualities. Ground effect. Test to demonstrate ground effect.		Х	Data may be acquired by using calibrated airplane instruments, an inertial measurement system, and a synchronized video of calibrated airplane instruments and force/position measurements of flight deck controls.			

ATTACHMENT 3 TO APPENDIX A TO PART 60-SIMULATOR SUBJECTIVE EVALUATION

BEGIN QPS REQUIREMENTS

1. Requirements

- a. Except for special use airport models, described as Class III, all airport models required by this part must be representations of real-world, operational airports or representations of fictional airports and must meet the requirements set out in Tables A3B or A3C of this attachment, as appropriate.
- b. If fictional airports are used, the sponsor must ensure that navigational aids and all appropriate maps, charts, and other navigational reference material for the fictional airports (and surrounding areas as necessary) are compatible, complete, and accurate with respect to the visual presentation of the airport model of this fictional airport. An SOC must be submitted that addresses navigation aid installation and performance and other criteria (including obstruction clearance protection) for all instrument approaches to the fictional airports that are available in the simulator. The SOC must reference and account for information in the terminal instrument procedures manual and the construction and availability of the required maps, charts, and other navigational material. This material must be clearly marked "for training purposes only."
- c. When the simulator is being used by an instructor or evaluator for purposes of training, checking, or testing under this chapter, only airport models classified as Class I, Class II, or Class III may be used by the instructor or evaluator. Detailed descriptions/definitions of these classifications are found in Appendix F of this part.
- d. When a person sponsors an FFS maintained by a person other than a U.S. certificate holder, the sponsor is accountable for that FFS originally meeting, and continuing to meet, the criteria under which it was originally qualified and the appropriate Part 60 criteria, including the airport models that may be used by instructors or evaluators for purposes of training, checking, or testing under this chapter.
- e. Neither Class II nor Class III airport visual models are required to appear on the SOQ, and the method used for keeping instructors and evaluators apprised of the airport models that meet Class II or Class III requirements on any given simulator is at the option of the sponsor, but the method used must be available for review by the TPAA.
- f. When an airport model represents a real world airport and a permanent change is

made to that real world airport (e.g., a new runway, an extended taxiway, a new lighting system, a runway closure) without a written extension grant from the responsible Flight Standards office (described in paragraph 1.g. of this section), an update to that airport model must be made in accordance with the following time limits:

- (1) For a new airport runway, a runway extension, a new airport taxiway, a taxiway extension, or a runway/taxiway closure—within 90 days of the opening for use of the new airport runway, runway extension, new airport taxiway, or taxiway extension; or within 90 days of the closure of the runway or taxiway.
- (2) For a new or modified approach light system—within 45 days of the activation of the new or modified approach light system.
- (3) For other facility or structural changes on the airport (e.g., new terminal, relocation of Air Traffic Control Tower)—within 180 days of the opening of the new or changed facility or structure.
- g. If a sponsor desires an extension to the time limit for an update to a visual scene or airport model or has an objection to what must be updated in the specific airport model requirement, the sponsor must provide a written extension request to the responsible Flight Standards office stating the reason for the update delay and a proposed completion date, or explain why the update is not necessary (i.e., why the identified airport change will not have an impact on flight training, testing, or checking). A copy of this request or objection must also be sent to the POI/TCPM. The responsible Flight Standards office will send the official response to the sponsor and a copy to the POI/ TCPM. If there is an objection, after consultation with the appropriate POI/TCPM regarding the training, testing, or checking impact, the responsible Flight Standards office will send the official response to the sponsor and a copy to the POI/TCPM.

END QPS REQUIREMENTS

BEGIN INFORMATION

2. Discussion

a. The subjective tests provide a basis for evaluating the capability of the simulator to perform over a typical utilization period; determining that the simulator accurately simulates each required maneuver, procedure, or task; and verifying correct operation of the simulator controls, instruments, and systems. The items listed in the following Tables are for simulator evaluation purposes only. They may not be used to limit or exceed the authorizations for use of a given level of simulator, as described on the SOQ, or as approved by the TPAA.

- b. The tests in Table A3A, Operations Tasks, in this attachment, address pilot functions, including maneuvers and procedures (called flight tasks), and are divided by flight phases. The performance of these tasks by the responsible Flight Standards office includes an operational examination of the visual system and special effects. There are flight tasks included to address some features of advanced technology airplanes and innovative training programs. For example, "high angle-of-attack maneuvering" is included to provide a required alternative to "approach to stalls" for airplanes employing flight envelope protection functions.
- c. The tests in Table A3A, Operations Tasks, and Table A3G, Instructor Operating Station of this attachment, address the overall function and control of the simulator including the various simulated environmental conditions; simulated airplane system operations (normal, abnormal, and emergency); visual system displays; and special effects necessary to meet flight crew training, evaluation, or flight experience requirements.
- d. All simulated airplane systems functions will be assessed for normal and, where appropriate, alternate operations. Normal, abnormal, and emergency operations associated with a flight phase will be assessed during the evaluation of flight tasks or events within that flight phase. Simulated airplane systems are listed separately under Flight Phase" to ensure appropriate attention to systems checks. Operational navigation systems (including inertial navigation systems, global positioning systems, or other long-range systems) and the associated electronic display systems will be evaluated if installed. The pilot will include in his report to the TPAA, the effect of the system operation and any system limitation.
- e. Simulators demonstrating a satisfactory circling approach will be qualified for the circling approach maneuver and may be approved for such use by the TPAA in the sponsor's FAA-approved flight training program. To be considered satisfactory, the circling approach will be flown at maximum gross weight for landing, with minimum visibility for the airplane approach category, and must allow proper alignment with a landing runway at least 90° different from the instrument approach course while allowing the pilot to keep an identifiable portion of the airport in sight throughout the maneuver (reference—14 CFR 91.175(e)).
- f. At the request of the TPAA, the responsible Flight Standards office may assess a device to determine if it is capable of simulating certain training activities in a sponsor's training program, such as a portion of a Line Oriented Flight Training (LOFT) scenario. Unless directly related to a requirement for the qualification level, the results of such an evaluation would not affect the qualification level of the simulator. How-

- ever, if the responsible Flight Standards office determines that the simulator does not accurately simulate that training activity, the simulator would not be approved for that training activity.
- g. The FAA intends to allow the use of Class III airport models when the sponsor provides the TPAA (or other regulatory authority) an appropriate analysis of the skills, knowledge, and abilities (SKAs) necessary for competent performance of the tasks in which this particular media element is used. The analysis should describe the ability of the FFS/visual media to provide an adequate environment in which the required SKAs are satisfactorily performed and learned. The analysis should also include the specific media element, such as the airport model.
- h. The TPAA may accept Class III airport models without individual observation provided the sponsor provides the TPAA with an acceptable description of the process for determining the acceptability of a specific airport model, outlines the conditions under which such an airport model may be used, and adequately describes what restrictions will be applied to each resulting airport or landing area model. Examples of situations that may warrant Class_III model designation by the TPAA include the following:
- (a) Training, testing, or checking on very low visibility operations, including SMGCS operations.
- (b) Instrument operations training (including instrument takeoff, departure, arrival, approach, and missed approach training, testing, or checking) using—
- (i) A specific model that has been geographically "moved" to a different location and aligned with an instrument procedure for another airport.
- (ii) A model that does not match changes made at the real-world airport (or landing area for helicopters) being modeled.
- (iii) A model generated with an "off-board" or an "on-board" model development tool (by providing proper latitude/longitude reference; correct runway or landing area orientation, length, width, marking, and lighting information; and appropriate adjacent taxiway location) to generate a facsimile of a real world airport or landing area.
- i. Previously qualified simulators with certain early generation Computer Generated Image (CGI) visual systems, are limited by the capability of the Image Generator or the display system used. These systems are:
- (1) Early CGI visual systems that are excepted from the requirement of including runway numbers as a part of the specific runway marking requirements are:
 - (a) Link NVS and DNVS.
 - (b) Novoview 2500 and 6000.
- (c) FlightSafety VITAL series up to, and including, VITAL III, but not beyond.
 - (d) Redifusion SP1, SP1T, and SP2.

Pt. 60, App. A

(2) Early CGI visual systems are excepted from the requirement of including runway numbers unless the runways are used for LOFT training sessions. These LOFT airport models require runway numbers but only for the specific runway end (one direction) used in the LOFT session. The systems required to display runway numbers only for LOFT scenes are:

- (a) FlightSafety VITAL IV.
- (b) Redifusion SP3 and SP3T.
- (c) Link-Miles Image II.
- (3) The following list of previously qualified CGI and display systems are incapable of

generating blue lights. These systems are not required to have accurate taxi-way edge lighting:

- (a) Redifusion SP1.
- (b) FlightSafety Vital IV.
- (c) Link-Miles Image II and Image IIT
- (d) XKD displays (even though the XKD image generator is capable of generating blue colored lights, the display cannot accommodate that color).

END INFORMATION

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks	Sin	mulat B	or Le	vel D
	Tasks in this table are subject to evaluation if appropriate for the			_	
1.	indicated in the SOQ Configuration List or the level of simulator Items not installed or not functional on the simulator and, therefor SOQ Configuration List, are not required to be listed as exception Preparation For Flight	qualifi re, not is on th	cation appea ne SOO	involvring or Q.	ed.
1.a.	Pre-flight. Accomplish a functions check of all switches, indi- equipment at all crew members' and instructors' station				
1.a.1	The flight deck design and functions are identical to that of the airplane being simulated.	X	X	X	X
1.a.2	Reserved				
1.a.3	Reserved				
2.	Surface Operations (pre-flight).				
2.a.	Engine Start	w	10	W	W
2.a.1.	Normal start	X	X	X	X
2.a.2. 2.a.3.	Alternate start procedures Abnormal starts and shutdowns (e.g., hot/hung start, tail pipe fire)	X	X	X	X
2.b.	Taxi				
2.b.1	Pushback/powerback		X	X	X
2.b.2.	Thrust response	X	X	X	X
2.b.3.	Power lever friction	X	X	X	X
2.b.4.	Ground handling	X	X	X	X
2.b.5.	Nosewheel scuffing			X	X
2.b.6.	Taxi aids (e.g. taxi camera, moving map)			X	X
2.b.7.	Low visibility (taxi route, signage, lighting, markings, etc.)			X	X
2.c.	Brake Operation				
2.c.1.	Brake operation (normal and alternate/emergency)	X	X	X	X
2.c.2.	Brake fade (if applicable)	X	X	X	X
2.d	Other				
3.	Take-off.				
3.a.	Normal Aimlang/anging narrameter relationshing including run un	107	18.7	16.7	1 27
3.a.1. 3.a.2.	Airplane/engine parameter relationships, including run-up Nosewheel and rudder steering	X	X	X	X
3.a.2. 3.a.3.a	Crosswind (maximum demonstrated)	X	X	X	X
3.a.3.b	Gusting crosswind	A	A	X	X
3.a.3.b 3.a.4.	Special performance			A	Λ
3.a.4.a	Reduced V ₁	X	X	X	X
3.a.4.b	Maximum engine de-rate	X	X	X	X
3.a.4.c	Soft surface	- /1		X	X
3.a.4.d	Short field/short take-off and landing (STOL) operations	X	X	X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks	Sin	mula:	tor Le	vel
3.a.4.e	Obstacle (performance over visual obstacle)	1 1		X	X
3.a.5.	Low visibility take-off	X	X	X	X
3.a.6.	Landing gear, wing flap leading edge device operation	X	X	X	X
3.a.7.	Contaminated runway operation			X	X
3.a.8.	Other				
3.b.	Abnormal/emergency	-			
3.b.1.	Rejected Take-off	X	X	X	X
3.b.2.	Rejected special performance (e.g., reduced V ₁ , max de-rate, short field operations)	X	X	X	X
3.b.3.	Rejected take-off with contaminated runway			X	X
3.b.4.	Takeoff with a propulsion system malfunction (allowing an analysis of causes, symptoms, recognition, and the effects on aircraft performance and handling) at the following points: (i) Prior to V1 decision speed; (ii) Between V1 and Vr (rotation speed); and (iii)Between Vr and 500 feet above ground level.	X	X	X	X
3.b.5.	Flight control system failures, reconfiguration modes, manual reversion and associated handling.	X	X	X	X
3.b.6.	Other				
4.	Climb.				
4.a.	Normal.	X	X	X	X
4.b.	One or more engines inoperative.	X	X	X	X
4.c.	Approach climb in icing (for airplanes with icing accountability).	X	X	X	X
4.d.	Other				
5.	Cruise.				
5.a.	Performance characteristics (speed vs. power, configuration,			1	
5.a.1.	Straight and level flight.	X	X	X	X
5.a.2.	Change of airspeed.	X	X	X	X
5.a.3.	High altitude handling.	X	X	X	X
5.a.4.	High Mach number handling (Mach tuck, Mach buffet) and recovery (trim change).	X	X	X	X
5.a.5.	Overspeed warning (in excess of V _{mo} or M _{mo}).	X	X	X	X
5.a.6.	High IAS handling.	X	X	X	X
5.a.7.	Other				
5.b.	Maneuvers				
5.b.1.	High Angle of Attack			,	
5.b.1.a	High angle of attack, approach to stalls, stall warning, and stall buffet (take-off, cruise, approach, and landing configuration) including reaction of the autoflight system and stall protection system.	X	X		
5.b.1.b	High angle of attack, approach to stalls, stall warning, stall buffet, and stall (take-off, cruise, approach, and landing			X	X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks		mulat B	or Le	vel
	configuration) including reaction of the autoflight system and	A	В		ע
	stall protection system.				
5.b.2.	Slow flight			X	X
5.b.3.	Upset prevention and recovery maneuvers within the FSTD's validation envelope.			X	X
5.b.4.	Flight envelope protection (high angle of attack, bank limit, overspeed, etc.)	X	X	X	X
5.b.5.	Turns with/without speedbrake/spoilers deployed	X	X	X	X
5.b.6.	Normal and standard rate turns	X	X	X	X
5.b.7.	Steep turns	X	X	X	X
5.b.8.	Performance turn			X	X
5.b.9.	In flight engine shutdown and restart (assisted and windmill)	X	X	X	X
5.b.10.	Maneuvering with one or more engines inoperative, as appropriate	X	X	X	X
5.b.11.	Specific flight characteristics (e.g. direct lift control)	X	X	X	X
5.b.12.	Flight control system failures, reconfiguration modes, manual reversion and associated handling	X	X	X	X
5.b.13	Gliding to a forced landing			X	X
5.b.14	Visual resolution and FSTD handling and performance for the fo	llowing	g (whe	re	
	applicable by aircraft type and training program):	1			
5.b.14.a	Terrain accuracy for forced landing area selection;			X	X
5.b.14.b	Terrain accuracy for VFR Navigation;			X	X
5.b.14.c	Eights on pylons (visual resolution);	-		X	X
5.b.14.d	Turns about a point; and			X	X
5.b.14.e	S-turns about a road or section line.			X	X
5.b.15	Other.				
6.	Descent. Normal	v	w	W	w
6.a. 6.b.		X	X	X	X
6.c.	Maximum rate/emergency (clean and with speedbrake, etc.). With autopilot.	X	X	X	X
6.d.	Flight control system failures, reconfiguration modes, manual	X	X	X	X
	reversion and associated handling.	1			-
6.e.	Other				
7.	Instrument Approaches And Landing. Those instrument approach and landing tests relevant to the simu selected from the following list. Some tests are made with limiti under windshear conditions, and with relevant system failures, in the Flight Director. If Standard Operating Procedures allow use precision approaches, evaluation of the autopilot will be included are not authorized to credit the landing maneuver.	ng win cluding autopil	d velog the factor	cities, ailure (non-	of
7.a.	Precision approach				
7.a. 7.a.1	CAT I published approaches.	T			
7.a.1.a	Manual approach with/without flight director including	X	X	X	X
/.a.1.a	ivianuai approach with without fight uncettor including	Λ	Λ	Λ	Λ

	Table A3A - Functions And Subjective Tests							
	QPS REQUIREMENTS							
Entry Number	Operations Tasks	Simulator			vel			
Z		A	В	C	D			
	landing.							
7.a.1.b	Autopilot/autothrottle coupled approach and manual landing.	X	X	X	X			
7.a.1.c	Autopilot/autothrottle coupled approach, engine(s) inoperative.	X	X	X	X			
7.a.1.d	Manual approach, engine(s) inoperative.	X	X	X	X			
7.a.1.e	HUD/EFVS			X	X			
7.a.2	CAT II published approaches.							
7.a.2.a	Autopilot/autothrottle coupled approach to DH and landing (manual and autoland).	X	X	X	X			
7.a.2.b	Autopilot/autothrottle coupled approach with one-engine- inoperative approach to DH and go-around (manual and autopilot).	X	X	X	X			
7.a.2.c	HUD/EFVS			X	X			
7.a.3	CAT III published approaches.							
7.a.3.a	Autopilot/autothrottle coupled approach to landing and roll- out (if applicable) guidance (manual and autoland).	X	X	X	X			
7.a.3.b	Autopilot/autothrottle coupled approach to DH and go- around (manual and autopilot).	X	X	X	X			
7.a.3.c	Autopilot/autothrottle coupled approach to land and roll-out (if applicable) guidance with one engine inoperative (manual and autoland).	X	X	X	X			
7.a.3.d	Autopilot/autothrottle coupled approach to DH and go- around with one engine inoperative (manual and autopilot).	X	X	X	X			
7.a.3.e	HUD/EFVS			X	X			
7.a.4	Autopilot/autothrottle coupled approach (to a landing or to a go- around):							
7.a.4.a	With generator failure;	X	X	X	X			
7.a.4.b.1	With maximum tail wind component certified or authorized;			X	X			
7.a.4.b.2	With 10 knot tail wind;	X	X					
7.a.4.c.1	With maximum crosswind component demonstrated or authorized; and			X	X			
7.a.4.c.2	With 10 knot crosswind.	X	X					
7.a.5	PAR approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X			
7.a.6	MLS, GBAS, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X			
7.b.	Non-precision approach.			l				
7.b.1	Surveillance radar approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X			
7.b.2	NDB approach, all engine(s) operating and with one or more engine(s) inoperative	X	X	X	X			

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks		Simulator I		
7.b.3	VOR, VOR/DME, TACAN approach, all engines(s) operating	X	X	X	D X
7.50.0	and with one or more engine(s) inoperative	1.	1.	1.	1.
7.b.4	RNAV / RNP / GNSS (RNP at nominal and minimum	X	X	X	X
	authorized temperatures) approach, all engine(s) operating and				
	with one or more engine(s) inoperative				
7.b.5	ILS LLZ (LOC), LLZ back course (or LOC-BC) approach, all	X	X	X	X
	engine(s) operating and with one or more engine(s) inoperative				
7.b.6	ILS offset localizer approach, all engine(s) operating and with	X	X	X	X
	one or more engine(s) inoperative				
7.c	Approach procedures with vertical guidance (APV), e.g.				
	SBAS, flight path vector				
7.c.1	APV/baro-VNAV approach, all engine(s) operating and with			X	X
	one or more engine(s) inoperative				
7.c.2	Area navigation (RNAV) approach procedures based on SBAS,			X	X
	all engine(s) operating and with one or more engine(s)				
8.	inoperative Visual Approaches (Visual Segment) And Landings.				
		oveu	or that	t partic	cular
	approach procedure.				
8.a.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance	X	or that	t partic	x
8.a. 8.b.	Maneuvering, normal approach and landing, all engines				
	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance	X	X	X	X
8.b. 8.c.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal	X	X	X X X	X
8.b. 8.c.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind	X X X	X X X	X X X	X X X
8.b. 8.c.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures,	X X X	X X X	X X X	X X X
8.b. 8.c. 8.d.1 8.d.2	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated	X X X	X X X	X X X	X X X
8.b. 8.c. 8.d.1 8.d.2 8.e.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable)	X X X	X X X	X X X X X	X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions	X X X	X X X	X X X X X	X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction	X X X X	X X X X	X X X X X	X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction	X X X X X X	X X X X X X	X X X X X X	X X X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power	X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X	X X X X X X X X X	X X X X X X X X X X X X X X X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach)	X X X X X X	X X X X X X	X X X X X X	X X X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a 8.e.1.b	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach) Approach and landing from visual traffic pattern	X X X X X X X X X X X X X	X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e.1. 8.e.1.a 8.e.1.b 8.f. 8.g.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach) Approach and landing from visual traffic pattern Approach and landing from non-precision approach	X X X X X X X X X X X X X X	X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X X
8.b. 8.c. 8.d.1 8.d.2 8.e. 8.e.1. 8.e.1.a 8.e.1.b 8.f. 8.g.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance Approach and landing with one or more engines inoperative Operation of landing gear, flap/slats and speedbrakes (normal and abnormal) Approach and landing with crosswind (max. demonstrated) Approach and landing with gusting crosswind Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable) Approach and landing with trim malfunctions Longitudinal trim malfunction Lateral-directional trim malfunction Approach and landing with standby (minimum) electrical/hydraulic power Approach and landing from circling conditions (circling approach) Approach and landing from visual traffic pattern	X X X X X X X X X X X X X	X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X X

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks	Simulate		or Le	vel D
9.	Missed Approach.				
9.a.	All engines, manual and autopilot.	X	X	X	X
9.b.	Engine(s) inoperative, manual and autopilot.	X	X	X	X
9.c.	Rejected landing			X	X
9.d.	With flight control system failures, reconfiguration modes, manual reversion and associated handling	X	X	X	X
9.e.	Bounced landing recovery			X	X
10.	Surface Operations (landing, after-landing and post-flight).				
10.a	Landing roll and taxi				
10.a.1	HUD/EFVS			X	X
10.a.2.	Spoiler operation	X	X	X	X
10.a.3.	Reverse thrust operation	X	X	X	X
10.a.4.	Directional control and ground handling, both with and without reverse thrust		X	X	X
10.a.5.	Reduction of rudder effectiveness with increased reverse thrust (rear pod-mounted engines)		X	X	X
10.a.6.	Brake and anti-skid operation				
10.a.6.a	Brake and anti-skid operation with dry, patchy wet, wet on			X	X
	rubber residue, and patchy icy conditions				
10.a.6.b	Reserved				
10.a.6.c	Brake operation	X	X		
10.a.6.d	Auto-braking system operation	X	X	X	X
10.a.7	Other				
10.b	Engine shutdown and parking	**		**	**
10.b.1	Engine and systems operation	X	X	X	X
10.b.2	Parking brake operation	X	X	X	X
10.b.3	Other A FILL AND				
11.	Any Flight Phase.				
11.a.	Airplane and engine systems operation (where fitted) Air conditioning and pressurization (ECS)	v	v	v	v
11.a.1. 11.a.2.	De-icing/anti-icing	X	X	X	X
11.a.2. 11.a.3.	Auxiliary power unit (APU).	X	X	X	X
11.a.3. 11.a.4.	Communications	X	X	X	X
11.a.4. 11.a.5.	Electrical	X	X	X	X
11.a.s. 11.a.6.	Fire and smoke detection and suppression	X	X	X	X
11.a.o. 11.a.7.	Flight controls (primary and secondary)	X	X	X	X
11.a./. 11.a.8.	Fuel and oil	X	X	X	X
11.a.9.	Hydraulic	X	X	X	X
11.a.10.	Pneumatic	X	X	X	X
11.a.10. 11.a.11.	Landing gear	X	X	X	X
11.a.12.	Oxygen	X	X	X	X
11.a.13.	Engine	X	X	X	X
11.4.15.		∠ 1	∠ x	∠ x	∡1.

14 CFR Ch. I (1-1-24 Edition)

	Table A3A - Functions And Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	Operations Tasks			Simulator Lev	
11.a.14.	Airborne radar	X	X	X	D X
11.a.15.	Autopilot and Flight Director	X	X	X	X
11.a.16.	Terrain awareness warning systems and collision avoidance systems (e.g. EGPWS, GPWS, TCAS)	X	X	X	X
11.a.17.	Flight control computers including stability and control augmentation	X	X	X	X
11.a.18.	Flight display systems	X	X	X	X
11.a.19.	Flight management computers	X	X	X	X
11.a.20.	Head-up displays (including EFVS, if appropriate)	X	X	X	X
11.a.21.	Navigation systems	X	X	X	X
11.a.22.	Stall warning/avoidance	X	X	X	X
11.a.23.	Wind shear avoidance/recovery guidance equipment	X	X	X	X
11.a.24.	Flight envelope protections	X	X	X	X
11.a.25.	Electronic flight bag			X	X
11.a.26.	Automatic checklists (normal, abnormal and emergency procedures)			X	X
11.a.27.	Runway alerting and advisory system			X	X
11.a.28.	Other				
11.b.	Airborne procedures				
11.b.1.	Holding	X	X	X	X
11.b.2.	Air hazard avoidance (traffic, weather, including visual correlation)			X	X
11.b.3.	Windshear				
11.b.3.a	Prior to take-off rotation			X	X
11.b.3.b	At lift-off			X	X
11.b.3.c	During initial climb			X	X
11.b.3.d	On final approach, below 150 m (500 ft) AGL			X	X
11.b.4.	Effects of airframe ice			X	X

	Table A3B - Functions and Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level	Siı	mulat	or Le	vel
E N	Class I Airport Models	A	В	C	D
indicated leve	cifies the minimum airport model content and functionality to qualif- il. This table applies only to the airport models required for simulato for Level A and Level B simulators; three airport models for Level C	r qual	ificatio	n; i.e.	
	Begin QPS Requirements				
1.	Functional test content requirements for Level A and Level B s The following is the minimum airport model content requirement to capability tests, and provides suitable visual cues to allow completi subjective tests described in this attachment for simulators at Level	o satis on of	fy visu all fun		and
1.a.	A minimum of one (1) representative airport model. This model identification must be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.	X	X		
1.b.	The fidelity of the airport model must be sufficient for the aircrew to visually identify the airport; determine the position of the simulated airplane within a night visual scene; successfully accomplish take-offs, approaches, and landings; and maneuver around the airport on the ground as necessary.	X	X		
1.c.	Runways:	X	X		
1.c.1.	Visible runway number.	X	X		
1.c.2.	Runway threshold elevations and locations must be modeled to provide sufficient correlation with airplane systems (e.g., altimeter).	X	X		
1.c.3.	Runway surface and markings.	X	X		
1.c.4.	Lighting for the runway in use including runway edge and centerline.	X	X		
1.c.5.	Lighting, visual approach aid and approach lighting of appropriate colors.	X	X		
1.c.6.	Representative taxiway lights.	X	X		
2.a.	Additional functional test content requirements				
2.a.1	Airport scenes				
2.a.1.a	A minimum of three (3) real-world airport models to be consistent with published data used for airplane operations and capable of demonstrating all the visual system features below. Each model should be in a different visual scene to permit assessment of FSTD automatic visual scene changes. The model identifications must be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.			X	X
2.a.1.b	Reserved				
2.a.1.c	Reserved				
2.a.1.d	Airport model content. For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intended landing. If all runways in an airport model used to meet the requirements of this	X	X	X	X

	Table A3B - Functions and Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level	Simulat		or Le	vel
E N	Class I Airport Models	A	В	C	D
	attachment are not designated as "in use," then the "in use" runways must be listed on the SOQ (e.g., KORD, Rwys 9R, 14L, 22R). Models of airports with more than one runway must have all significant runways not "in-use" visually depicted for airport and runway recognition purposes. The use of white or off white light strings that identify the runway threshold, edges, and ends for twilight and night scenes are acceptable for this requirement. Rectangular surface depictions are acceptable for daylight scenes. A visual system's capabilities must be balanced between providing airport models with an accurate representation of the airport and a realistic representation of the surrounding environment. Airport model detail must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that such models contain details that are beyond the design capability of the currently qualified visual system. Only one "primary" taxi route from parking to the runway end will be required for each "in-use"				
2.a.2	runway. Visual scene fidelity.				
2.a.2.a	The visual scene must correctly represent the parts of the airport	X	X	X	X
2 - 2 h	and its surroundings used in the training program. Reserved				
2.a.2.b 2.a.2.c	Reserved				
2.a.2.c 2.a.3	Runways and taxiways.				
2.a.3.a	Airport specific runways and taxiways.	X	X	X	X
2.a.3.a 2.a.3.b	Reserved	A	Λ	Λ	Λ
2.a.3.c	Reserved				
2.a.4	If appropriate to the airport, two parallel runways and one crossing runway displayed simultaneously; at least two runways must be capable of being lit simultaneously.			X	X
2.a.5	Runway threshold elevations and locations must be modeled to provide correlation with airplane systems (e.g. HUD, GPS, compass, altimeter).			X	X
2.a.6	Slopes in runways, taxiways, and ramp areas must not cause distracting or unrealistic effects, including pilot eye-point height variation.			X	X
2.a.7	Runway surface and markings for each "in-use" runway must if appropriate:	includ	le the	follow	ing,
2.a.7.a	Threshold markings.	X	X	X	X
2.a.7.b	Runway numbers.	X	X	X	X
2.a.7.c	Touchdown zone markings.	X	X	X	X
2.a.7.d	Fixed distance markings.	X	X	X	X

Table A3B - Functions and Subjective Tests					
	QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level		Simulator 1		
ΞŽ	Class I Airport Models	A	В	C	D
2.a.7.e	Edge markings.	X	X	X	X
2.a.7.f	Center line markings.	X	X	X	X
2.a.7.g	Distance remaining signs.	X	X	X	X
2.a.7.h	Signs at intersecting runways and taxiways.	X	X	X	X
2.a.7.i	Windsock that gives appropriate wind cues.			X	X
2.a.8	Runway lighting of appropriate colors, directionality, behavior	and s	pacing	g for t	he
	"in-use" runway including the following:				
2.a.8.a	Threshold lights.	X	X	X	X
2.a.8.b	Edge lights.	X	X	X	X
2.a.8.c	End lights.	X	X	X	X
2.a.8.d	Center line lights.	X	X	X	X
2.a.8.e	Touchdown zone lights.	X	X	X	X
2.a.8.f	Lead-off lights.	X	X	X	X
2.a.8.g	Appropriate visual landing aid(s) for that runway.	X	X	X	X
2.a.8.h	Appropriate approach lighting system for that runway.	X	X	X	X
2.a.9	Taxiway surface and markings (associated with each "in-use" r	unwa	y):		
2.a.9.a	Edge markings	X	X	X	X
2.a.9.b	Center line markings.	X	X	X	X
2.a.9.c	Runway holding position markings.	X	X	X	X
2.a.9.d	ILS critical area markings.	X	X	X	X
2.a.9.e	All taxiway markings, lighting, and signage to taxi, as a minimum, from a designated parking position to a designated runway and return, after landing on the designated runway, to a designated parking position; a low visibility taxi route (e.g. surface movement guidance control system, follow-me truck, daylight taxi lights) must also be demonstrated at one airport model for those operations authorized in low visibilities. The				X
	designated runway and taxi routing must be consistent with that airport for operations in low visibilities. The qualification of surface movement guidance control systems (SMGCS) is optional at the request of the FSTD sponsor. For the qualification of SMGCS, a demonstration model must be provided for evaluation.				
2.a.10	Taxiway lighting of appropriate colors, directionality, behavior (associated with each "in-use" runway):	and s	pacin	g	
2.a.10.a	Edge lights.	X	X	X	X
2.a.10.b	Center line lights.	X	X	X	X
2.a.10.c	Runway holding position and ILS critical area lights.	X	X	X	X
2.a.11	Required visual model correlation with other aspects of the air	port e			
	simulation.				
2.a.11.a	The airport model must be properly aligned with the navigational aids that are associated with operations at the runway "in-use".	X	X	X	X

	Table A3B - Functions and Subjective Tests OPS REQUIREMENTS					
Entry Number	For Qualification At The Stated Level Simul			lator Level		
E S	Class I Airport Models	A	В	С	D	
2.a.11.b	The simulation of runway contaminants must be correlated with the displayed runway surface and lighting.				X	
2.a.12	Airport buildings, structures and lighting.					
2.a.12.a	Buildings, structures and lighting:					
2.a.12.a.1	Airport specific buildings, structures and lighting.			X	X	
2.a.12.a.2	Reserved					
2.a.12.a.3	Reserved					
2.a.12.b	At least one useable gate, set at the appropriate height (required only for those airplanes that typically operate from terminal gates).			X	X	
2.a.12.c	Representative moving and static airport clutter (e.g. other airplanes, power carts, tugs, fuel trucks, additional gates).			X	X	
2.a.12.d	Gate/apron markings (e.g. hazard markings, lead-in lines, gate numbering), lighting and gate docking aids or a marshaller.			X	X	
2.a.13	Terrain and obstacles.					
2.a.13.a	Terrain and obstacles within 46 km (25 NM) of the reference airport.			X	X	
2.a.13.b	Reserved					
2.a.14	Significant, identifiable natural and cultural features and movi	ng air	borne	traffi	c.	
2.a.14.a	Significant, identifiable natural and cultural features within 46 km (25 NM) of the reference airport. Note.— This refers to natural and cultural features that are typically used for pilot orientation in flight. Outlying airports not intended for landing need only provide a reasonable facsimile of runway orientation.			X	X	
2.a.14.b	Reserved					
2.a.14.c	Representative moving airborne traffic (including the capability to present air hazards – e.g. airborne traffic on a possible collision course).			X	X	
2.b	Visual scene management.					
2.b.1	All airport runway, approach and taxiway lighting and cultural lighting intensity for any approach must be capable of being set to six (6) different intensities (0 to 5); all visual scene light points should fade into view appropriately.			X	X	
2.b.2	Airport runway, approach and taxiway lighting and cultural lighting intensity for any approach must be set at an intensity representative of that used in training for the visibility set; all visual scene light points should fade into view appropriately.	X	X			
2.b.3	The directionality of strobe lights, approach lights, runway edge lights, visual landing aids, runway center line lights, threshold lights, and touchdown zone lights on the runway of intended landing must be realistically replicated.	X	X	X	X	
2.c	Visual feature recognition.					

	Table A3B - Functions and Subjective Tests					
	QPS REQUIREMENTS					
Entry	For Qualification At The Stated Level	Simulator			vel	
" ž	Class I Airport Models	A	В	C	D	
	Note.— The following are the minimum distances at which runway	,				
	visible. Distances are measured from runway threshold to an airple		0		ıe	
	runway on an extended 3-degree glide slope in suitable simulated r				. 1	
	conditions. For circling approaches, all tests below apply both to the	he run	way u	sed for	* the	
2 . 1	initial approach and to the runway of intended landing.	X	v	v	v	
2.c.1	Runway definition, strobe lights, approach lights, and runway edge white lights from 8 km (5 sm) of the runway threshold.	Α	X	X	X	
2.c.2	Visual approach aids lights.					
2.c.2.a	Visual approach aids lights from 8 km (5 sm) of the runway			X	X	
2.C.2.a	threshold.			Λ	A	
2.c.2.b	Visual approach aids lights from 4.8 km (3 sm) of the runway	X	X			
2.0.2.0	threshold.	71	1			
2.c.3	Runway center line lights and taxiway definition from 4.8 km	X	X	X	X	
	(3 sm).					
2.c.4	Threshold lights and touchdown zone lights from 3.2 km (2 sm).	X	X	X	X	
2.c.5	Runway markings within range of landing lights for night scenes;	X	X	X	X	
	as required by the surface resolution test on day scenes.					
2.c.6	For circling approaches, the runway of intended landing and	X	X	X	X	
	associated lighting must fade into view in a non-distracting					
	manner.					
2.d	Selectable airport visual scene capability for:					
2.d.1	Night.	X	X	X	X	
2.d.2	Twilight.			X	X	
2.d.3	Day.			X	X	
2.d.4	Dynamic effects — the capability to present multiple ground and			X	X	
	air hazards such as another airplane crossing the active runway or					
	converging airborne traffic; hazards should be selectable via					
2.15	controls at the instructor station.				*7	
2.d.5	Illusions — operational visual scenes which portray				X	
	representative physical relationships known to cause landing illusions, for example short runways, landing approaches over					
	water, uphill or downhill runways, rising terrain on the approach					
	path and unique topographic features.					
	Note.— Illusions may be demonstrated at a generic airport or at					
	a specific airport.					
2.e	Correlation with airplane and associated equipment.					
2.e.1	Visual cues to relate to actual airplane responses.	X	X	X	X	
2.e.2	Visual cues during take-off, approach and landing.					
2.e.2.a	Visual cues to assess sink rate and depth perception during		X	X	X	
	landings.				$oxed{oxed}$	
2.e.2.b	Visual cueing sufficient to support changes in approach path by	X	X	X	X	
	using runway perspective. Changes in visual cues during take-off,					
	approach and landing should not distract the pilot.					

	Table A3B - Functions and Subjective Tests				
	QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level	Sir	nulat	or Le	vel
E S	Class I Airport Models	A	В	C	D
2.e.3	Accurate portrayal of environment relating to airplane attitudes.	X	X	X	X
2.e.4	The visual scene must correlate with integrated airplane systems, where fitted (e.g. terrain, traffic and weather avoidance systems and HUD/EFVS).			X	X
2.e.5	The effect of rain removal devices must be provided.			X	X
2.f	Scene quality.				
2.f.1	Quantization.				
2.f.1.a	Surfaces and textural cues must be free from apparent quantization (aliasing).			X	X
2.f.1.b	Surfaces and textural cues must not create distracting quantization (aliasing).	X	X		
2.f.2	System capable of portraying full color realistic textural cues.			X	X
2.f.3	The system light points must be free from distracting jitter, smearing or streaking.	X	X	X	X
2.f.4	System capable of providing representative focus effects that simulate rain (e.g. reduced visibility and object resolution in the out the window view as a result of rain).			X	X
2.f.5	System capable of providing light point perspective growth (e.g. relative size of runway and taxiway edge lights increase as the lights are approached).			X	X
2.g	Environmental effects.				
2.g.1	The displayed scene must correspond to the appropriate surface contaminants and include runway lighting reflections for wet, partially obscured lights for snow, or suitable alternative effects.			X	X
2.g.2	Special weather representations which include the sound, motion and visual effects of light, medium and heavy precipitation near a thunderstorm on take-off, approach and landings at and below an altitude of 600 m (2 000 ft) above the airport surface and within a radius of 16 km (10 sm) from the airport.			X	X
2.g.3	One airport with a snow scene to include terrain snow and snow-covered taxiways and runways.			X	X
2.g.4	In-cloud effects such as variable cloud density, speed cues and ambient changes should be provided.			X	X
2.g.5	The effect of multiple cloud layers representing few, scattered, broken and overcast conditions giving partial or complete obstruction of the ground scene.			X	X
2.g.6	Gradual break-out to ambient visibility/RVR, defined as up to 10% of the respective cloud base or top, 20 ft ≤ transition layer ≤ 200 ft; cloud effects should be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport. Transition effects should be complete when the IOS cloud base or top is reached when exiting and start when entering the cloud, i.e. transition effects should occur			X	X

	Table A3B - Functions and Subjective Tests QPS REQUIREMENTS				
Entry Number	For Qualification At The Stated Level	Sin	nulat	or Le	vel
E S	Class I Airport Models	A	В	C	D
	within the IOS defined cloud layer.				
2.g.7	Visibility and RVR measured in terms of distance. Visibility/RVR must be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport.	X	X	X	X
2.g.8	Patchy fog (sometimes referred to as patchy RVR) giving the effect of variable RVR. The lowest RVR should be that selected on the IOS, ie. variability is only greater than the IOS RVR.			X	X
2.g.9	Effects of fog on airport lighting such as halos and defocus.			X	X
2.g.10	Effect of ownship lighting in reduced visibility, such as reflected glare, to include landing lights, strobes, and beacons.			X	X
2.g.11	Wind cues to provide the effect of blowing snow or sand across a dry runway or taxiway should be selectable from the instructor station.			X	X
	End QPS Requirement				
	Begin Information				
3.	An example of being able to "combine two airport models to achieve two "in-use" runways: One runway designated as the "in use" runway in the first model of the airport, and the second runway designated as the "in use" runway in the second model of the same airport. For example, the clearance is for the ILS approach to Runway 27, Circle to Land on Runway 18 right. Two airport visual models might be used: the first with Runway 27 designated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right designated as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may change to the second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pilot would make a visual approach and landing. This process is acceptable to the FAA as long as the temporary interruption due to the visual model change is not distracting to the pilot, does not cause changes in navigational radio frequencies, and does not cause undue instructor/evaluator time.				
4.	Sponsors are not required to provide every detail of a runway, but the detail that is provided should be correct within the capabilities of the system. End Information				

TABLE A3C—FUNCTIONS AND SUBJECTIVE TESTS

	Additional airport models beyond minimum required for qualification—Class II airport mod-	Sin	nulat	or lev	/el				
Entry No.	els	Α	В	С	D				
library, beyon	fies the minimum airport model content and functionality necessary to add airport models to a d those necessary for qualification at the stated level, without the necessity of further involvem- andards office or TPAA.								
	Begin QPS Requirements								
1	Airport model management. The following is the minimum airport model management require tors at Levels A, B, C, and D.	men	ts for	simu	ıla-				
1.a	The direction of strobe lights, approach lights, runway edge lights, visual landing aids, runway centerline lights, threshold lights, and touchdown zone lights on the "in-use" runway must be replicated.	x	х	Х	х				
2	Visual feature recognition. The following are the minimum distances at which runway features for simulators at Levels A, B, C, and D. Distances are measured from runway threshold to ar with the runway on an extended 3° glide-slope in simulated meteorological conditions that rec imum distances for visibility. For circling approaches, all requirements of this section apply to for the initial approach and to the runway of intended landing.								
2.a	Runway definition, strobe lights, approach lights, and runway edge white lights from 5 sm (8 km) from the runway threshold.	Х	Х	Х	х				
2.b	Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) from the runway threshold			Х	Х				
2.c	Visual Approach Aid lights (VASI or PAPI) from 3 sm (5 km) from the runway threshold	х	х						
2.d	Runway centerline lights and taxiway definition from 3 sm (5 km) from the runway threshold.	Х	Х	Х	х				
2.e	Threshold lights and touchdown zone lights from 2 sm (3 km) from the runway threshold	х	х	Х	Х				
2.f	Runway markings within range of landing lights for night scenes and as required by the surface resolution requirements on day scenes.	Х	х	Х	х				
2.g	For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-distracting manner.	х	х	Х	Х				
_									
3	Airport model content. The following prescribes the minimum requirements for what must be port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construend maps, or other similar data, or developed in accordance with published regulatory materiates not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intitial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway.	that inctionation that including the contraction that includin	mode o drav owev curre ay us	I for vings er, the ently ed fo	sim- s nis or				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construent maps, or other similar data, or developed in accordance with published regulatory materidoes not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the the initial approach and to the runway of intended landing. Only one "primary" taxi route from	that inctionation that including the contraction that includin	mode o drav owev curre ay us	I for vings er, the ently ed fo	sim- s nis or				
	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construent and maps, or other similar data, or developed in accordance with published regulatory material does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the the initial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway.	that inctionation that including the contraction that includin	mode o drav owev curre ay us	I for vings er, the ently ed fo	sim- s nis or				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory mater does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intitial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway:	that in that in that in that in the interval i	mode n drav owev curre ay us king	I for wings er, the ently ed for to the	sim-				
3.a 3.a.1.	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory mater does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intended approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings	that in uction ial; he fither runwan parl	mode n drav owev curre ay us king	I for wings er, the ently sed for the	sim-				
3.a 3.a.1. 3.a.2.	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construent and maps, or other similar data, or developed in accordance with published regulatory materidoes not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the the initial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings Runway numbers	that in uction ial; he fither runward part	mode n draw owev curre ay us king	I for wings er, thently sed for the	sim-sinis				
3.a 3.a.1. 3.a.2. 3.a.3.	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory materia does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intential approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway: The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings	that in uction ial; he of the runwan part	moden draw owev curre ay us king	I for wings er, thently sed for the X	sim- sinis or				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory mater does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intended landing approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings Fixed distance markings	that i uction that i uction ial; he feet the runwar n parl	mode n draw owev curre ay us king t	I for wings er, the entry ed for the XXXXX	sim-sinis				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construent and maps, or other similar data, or developed in accordance with published regulatory material does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the the initial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings Edge markings	that i th	mode n dravowev curre ay us king h	I for wingser, the entity ed for o the	sim- sinis or X X				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, content and maps, or other similar data, or developed in accordance with published regulatory material does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intential approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings Edge markings Centerline stripes	that i th	mode n dravowev curre ay us king h	I for wingser, the entity ed for o the	sim- sinis or X X				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory mater does not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the the initial approach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway: The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings Edge markings Centerline stripes The lighting for each "in-use" runway	that i uction ial; he for the runward of the runwar	mode of draw owev curred ay use king to the curred ay use king to the curred ay use	I for wings er, the hold of the last of th	sim-simis or X X X X				
3.a	port model and identifies other aspects of the airport environment that must correspond with ulators at Levels A, B, C, and D. The detail must be developed using airport pictures, construand maps, or other similar data, or developed in accordance with published regulatory materioes not require that airport models contain details that are beyond the designed capability of qualified visual system. For circling approaches, all requirements of this section apply to the intermedial papproach and to the runway of intended landing. Only one "primary" taxi route from runway end will be required for each "in-use" runway. The surface and markings for each "in-use" runway: Threshold markings Runway numbers Touchdown zone markings Edge markings Edge markings Centerline stripes The lighting for each "in-use" runway Threshold lights	that i uction ial; he for the runwar n parl	x x x x x x x x x x x x x x x x x x x	I for wings er, the entity ed for the transfer of the transfer	sim- sim- sinis or X X X X				

	QPS requirements				
Entry No.	Additional airport models beyond minimum required for qualification—Class II airport mod-	Sir	nulate	or lev	el
	els	Α	В	С	D
3.b.5.	Touchdown zone lights, if appropriate	Х	Х	Χ	Х
3.b.6.	Leadoff lights, if appropriate	Х	х	Х	Х
3.b.7.	Appropriate visual landing aid(s) for that runway	х	х	Х	Х
3.b.8.	Appropriate approach lighting system for that runway	х	х	Х	Х
3.c	The taxiway surface and markings associated with each "in-use" runway:				
3.c.1.	Edge	х	х	Х	х
3.c.2.	Centerline	х	х	х	х
3.c.3.	Runway hold lines	х	х	Х	Х
3.c.4.	ILS critical area markings	х	х	Х	Х
3.d	The taxiway lighting associated with each "in-use" runway:				
3.d.1.	Edge			х	Х
3.d.2.	Centerline	х	х	Х	Х
3.d.3.	Runway hold and ILS critical area lights	х	х	Х	Х
4	Required model correlation with other aspects of the airport environment simulation The following are the minimum model correlation tests that must be conducted for simulators at Levels A, B, C, and D.				
4.a	The airport model must be properly aligned with the navigational aids that are associated with operations at the "in-use" runway.	х	х	Х	х
4.b	Slopes in runways, taxiways, and ramp areas, if depicted in the visual scene, must not cause distracting or unrealistic effects.	х	Х	Х	х
5	Correlation with airplane and associated equipment. The following are the minimum correlation that must be made for simulators at Levels A, B, C, and D.	on co	mpar	isons	;
5.a	Visual system compatibility with aerodynamic programming	х	х	Х	х
5.b	Accurate portrayal of environment relating to flight simulator attitudes	х	х	Х	Х
5.c	Visual cues to assess sink rate and depth perception during landings		х	Х	Х
5.d	Visual effects for each visible, own-ship, airplane external light(s)		х	Х	Х
6	Scene quality. The following are the minimum scene quality tests that must be conducted for els A, B, C, and D.	simu	ulator	s at L	.ev-
6.a	Surfaces and textural cues must be free of apparent and distracting quantization (aliasing)			Х	Х
6.b	Correct color and realistic textural cues			Х	Х
6.c	Light points free from distracting jitter, smearing or streaking	х	х	Х	Х
7	Instructor controls of the following: The following are the minimum instructor controls that mu simulators at Levels A, B, C, and D.	st be	avai	lable	in
7.a	Environmental effects, e.g., cloud base (if used), cloud effects, cloud density, visibility in statute miles/kilometers and RVR in feet/meters.	х	Х	Х	х
7.b	Airport selection	х	х	Х	х
7.c	Airport lighting including variable intensity	х	Х	Х	х
7.d	Dynamic effects including ground and flight traffic			Х	х

14 CFR Ch. I (1-1-24 Edition)

TABLE A3C—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS requirements									
Fata Na	Additional airport models beyond minimum required for qualification—Class II airport mod-	Sir	nulat	or lev	el					
Entry No.	els				D					
	End QPS Requirements									
	Begin Information									
Sponsors are not required to provide every detail of a runway, but the detail that is pro- X X X X X X X X X X X X X X X X X X X										
	End Information									

	INFORMATION		Notes							
		ivel	Q		X		×		X	
70		Simulator Level	C		X		×		×	
Test		mula	В		X		×		×	
ctive		Si	₹		X		×		×	
Table A3D - Functions and Subjective Tests	QPS REQUIREMENTS		Motion System Effects	decelerate the simulated airplane. Do not use wheel braking so that only the buffet due to the ground spoilers and thrust reversers is felt.	Bumps associated with the landing gear:	Procedure: Perform a normal take-off paying special attention to the bumps that could be perceptible due to maximum oleo extension after lift-off. When the landing gear is extended or retracted, motion bumps can be felt when the gear locks into position.	Buffet during extension and retraction of landing gear:	Procedure: Operate the landing gear. Check that the motion cues of the buffet experienced represent the actual airplane.	Buffet in the air due to flap and spoiler/speedbrake extension:	Procedure: Perform an approach and extend the flaps and slats with airspeeds deliberately in excess of the normal approach speeds. In cruise configuration, verify the buffets associated with the spoiler/speedbrake extension. The above effects can also be verified with different combinations of spoiler/speedbrake, flap, and landing gear settings to assess the interaction effects.
		J	Entry Vumber		4.		છં		9.	

	Table A3D - Functions and Subjective Tests ODS BEOTHREMENTS	tive	Tests			INFORMATION
		Sin	1 1 1 1 1	Simulator Level	ē	NOTE THE PARTY OF
Entry Vumber	Motion System Effects	4	B	ာ	Q	Notes
7.	Buffet due to atmospheric disturbances (e.g. buffet due to turbulence, windshear, proximity to thunderstorms, gusting winds, etc.).			×	×	
8.	Approach to stall buffet and stall buffet (where applicable):	×	×	×	×	For FSTDs qualified for full stall training tasks modeling
	Procedure: Conduct an approach-to-stall with engines at idle and a deceleration of 1 knot/second. Check that the motion cues of the buffet, including the level of buffet increase with decreasing sneed are representative of the actual airmlane.					that accounts for any increase in buffet amplitude from initial buffet threshold of perception to critical angle of attack or
						deterrent buffet as a function of angle of attack. The stall buffet modeling should
						include effects of Nz, as well as Nx and Ny if relevant.
9.	Touchdown cues for main and nose gear:	×	×	×	×	
	Procedure: Conduct several normal approaches with various rates of descent. Check that the motion cues for the touchdown bumps for each descent rate are representative of the actual airplane.					
10.	Nosewheel scuffing:		×	×	×	
	Procedure: Taxi at various ground speeds and manipulate the nosewheel steering to cause yaw rates to develop that cause the					

	Table A3D - Functions and Subjective Tests	tive	Test			
	QPS REQUIREMENTS					INFORMATION
J		Sir	nula	Simulator Level	vel	
Entry Vumber	Motion System Effects	A	æ	C	D	Notes
	nosewheel to vibrate against the ground ("scuffing"). Evaluate the speed/nosewheel combination needed to produce scuffing and check that the resultant vibrations are representative of the actual airplane.					
11.	Thrust effect with brakes set:	×	×	×	×	This effect is most discernible with wing-mounted engines.
	Procedure: Set the brakes on at the take-off point and increase the engine power until buffet is experienced. Evaluate its characteristics. Confirm that the buffet increases appropriately with increasing engine thrust.					
12.	Mach and maneuver buffet:		×	×	×	
	Procedure: With the simulated airplane trimmed in 1 g flight while at high altitude, increase the engine power so that the Mach number exceeds the documented value at which Mach buffet is experienced. Check that the buffet begins at the same Mach number as it does in the airplane (for the same configuration) and that buffet levels are representative of the actual airplane. For certain airplanes, maneuver buffet can also be verified for the same effects. Maneuver buffet can occur during turning flight at conditions greater than 1 g, particularly at higher altitudes.					
13.	Tire failure dynamics:			×	×	The pilot may notice some yawing with a multiple tire

	Table A3D - Functions and Subjective Tests	tive	Fests			INCID FRANCIA
	QPS KEQUIKEMENTS					INFORMATION
ı		Sin	ulat	Simulator Level	,el	
Entry Numbe	Motion System Effects	4	В	C	Ω	Notes
	Procedure: Simulate a single tire failure and a multiple tire failure.					failure selected on the same side. This should require the use of the rudder to maintain control of the airplane. Dependent on airplane type, a single tire failure may not be noticed by the pilot and should not have any special motion effect. Sound or vibration may be associated with the actual tire losing pressure.
14.	Engine failures, malfunction, engine, and airframe structural damage:		×	×	×	
	Procedure: The characteristics of an engine malfunction as stipulated in the malfunction definition document for the particular flight simulator must describe the special motion effects felt by the pilot. Note the associated engine instruments varying according to the nature of the malfunction and note the replication of the effects of the airframe vibration.					
15.	Tail strikes, engine pod/propeller, wing strikes:		×	×	×	The motion effect should be felt as a noticeable bump. If
	Procedure: Tail-strikes can be checked by over-rotation of the airplane at a speed below V _r while performing a takeoff. The					the tail strike affects the airplane angular rates, the

	INFORMATION		Notes	cueing provided by the motion	system should have an associated effect.
		evel	D		
s		tor L	C		
Lest		Simulator Level	A B C		
ctive		Si	A		
Table A3D - Functions and Subjective Tests	QPS REQUIREMENTS		Motion System Effects	effects can also be verified during a landing.	Excessive banking of the airplane during its take-off/landing roll can cause a pod strike.
			Entry		

Pt. 60, App. A

TABLE A3E—FUNCTIONS AND SUBJECTIVE TESTS

	QPS Requirements				
Fata Na	O constant	Sir	nulate	or lev	el
Entry No.	Sound system	Α	В	С	D
	The following checks are performed during a normal flight profile with motion system ON.				
1	Precipitation			х	Х
2	Rain removal equipment.			Х	Х
3	Significant airplane noises perceptible to the pilot during normal operations			Х	Х
4	Abnormal operations for which there are associated sound cues including, engine malfunctions, landing gear/tire malfunctions, tail and engine pod strike and pressurization malfunction.			х	Х
5	Sound of a crash when the flight simulator is landed in excess of limitations	х	Х		

	<u> </u>	۵		X						×													
	or Lev	၁	evel.	X						×													
	Simulator Level	В	lator l																				
	.S.	A	l simu																				
Table A3F - Functions and Subjective Tests OPS REQUIREMENTS	ds		This table specifies the minimum special effects necessary for the specified simulator level.	Braking Dynamics:	Representations of the dynamics of brake failure (flight simulator pirch side-loading and directional control characteristics	representative of the airplane), including antiskid and decreased	brake efficiency due to high brake temperatures (based on airplane	related data), sufficient to enable pilot identification of the problem	and implementation of appropriate procedures.	Effects of Airframe and Engine Icing:	Required only for those airplanes authorized for operations in	known icing conditions.	Procedure: With the simulator airborne, autopilot on and auto-	throttles off, engine and airfoil anti-ice/de-ice systems deactivated;	activate icing conditions at a rate that allows monitoring of simulator	and systems response. Icing recognition will typically include	airspeed decay, change in simulator pitch attitude, change in engine	performance indications (other than due to airspeed changes), and	change in data from pitot/static system. Activate heating, anti-ice, or	de-ice systems independently. Recognition will include proper	effects of these systems, eventually returning the simulated airplane	to normal flight. See Table A1A, section 2.j. and Attachment 7 for	additional requirements.
	Entry Entry	1		1.						7.													

TABLE A3G—FUNCTIONS AND SUBJECTIVE TESTS

	QPS Requirements				
Entry No.	Special effects	Sir	nulat	or lev	el
		Α	В	С	D
Functions in	n this table are subject to evaluation only if appropriate for the airplane and/or the system is install simulator.	led o	n the	spec	ific
1	Simulator Power Switch(es)	х	Х	Х	Х
2	Airplane conditions				
2.a	Gross weight, center of gravity, fuel loading and allocation	х	х	Х	Х
2.b	Airplane systems status	х	Х	Х	Х
2.c	Ground crew functions (e.g., ext. power, push back)	х	х	Х	х
3	Airports				
3.a	Number and selection	х	Х	Х	х
3.b	Runway selection	х	х	Х	х
3.c	Runway surface condition (e.g., rough, smooth, icy, wet)	х	х		
3.d	Preset positions (e.g., ramp, gate, #1 for takeoff, takeoff position, over FAF)	х	Х	Х	х
3.e	Lighting controls	х	х	Х	х
4	Environmental controls				
4.a	Visibility (statute miles (kilometers))	х	Х	Х	х
4.b	Runway visual range (in feet (meters))	х	х	Х	х
4.c	Temperature	х	х	Х	х
4.d	Climate conditions (e.g., ice, snow, rain)	х	Х	Х	х
4.e	Wind speed and direction	х	Х	Х	Х
4.f	Windshear	х	х		
4.g	Clouds (base and tops)	х	Х	Х	Х
5	Airplane system malfunctions (Inserting and deleting malfunctions into the simulator)	х	х	Х	х
6	Locks, Freezes, and Repositioning				
6.a	Problem (all) freeze/release	х	х	Х	Х
6.b	Position (geographic) freeze/release	х	х	Х	х
6.c	Repositioning (locations, freezes, and releases)	х	х	Х	Х
6.d	Ground speed control	х	Х	Х	х
7	Remote IOS	х	х	х	х
8	Sound Controls. On/off/adjustment	х	х	х	х
9	Motion/Control Loading System				
9.a	On/off/emergency stop	х	х	х	х
10	Observer Seats/Stations. Position/Adjustment/Positive restraint system	х	х	Х	х

BEGIN INFORMATION

1. Introduction

a. The following is an example test schedule for an Initial/Upgrade evaluation that covers the majority of the requirements set out in the Functions and Subjective test requirements. It is not intended that the schedule be followed line by line, rather, the example should be used as a guide for preparing a schedule that is tailored to the airplane, sponsor, and training task.

b. Functions and subjective tests should be planned. This information has been organized as a reference document with the considerations, methods, and evaluation notes for each individual aspect of the simulator task presented as an individual item. In this way the evaluator can design his or her own test plan, using the appropriate sections to provide guidance on method and evaluation criteria. Two aspects should be present in any test plan structure:

(1) An evaluation of the simulator to determine that it replicates the aircraft and performs reliably for an uninterrupted period equivalent to the length of a typical training session.

(2) The simulator should be capable of operating reliably after the use of training device functions such as repositions or malfunctions.

c. A detailed understanding of the training task will naturally lead to a list of objectives that the simulator should meet. This list will form the basis of the test plan. Additionally, once the test plan has been formulated, the initial conditions and the evaluation criteria should be established. The evaluator should consider all factors that may have an influence on the characteristics observed during particular training tasks in order to make the test plan successful.

2. Events

a. Initial Conditions

- (1) Airport.
- (2) QNH.
- (3) Temperature.
- (4) Wind/Crosswind.
- (5) Zero Fuel Weight /Fuel/Gross Weight Center of Gravity.

b. Initial Checks

- (1) Documentation of Simulator.
- (a) Simulator Acceptance Test Manuals.
- (b) Simulator Approval Test Guide.
- (c) Technical Logbook Open Item List. (d) Daily Functional Pre-flight Check.
- (2) Documentation of User/Carrier Flight
- Logs
- (a) Simulator Operating/Instructor Manual.
 - (b) Difference List (Aircraft/Simulator).

- (c) Flight Crew Operating Manuals.
- (d) Performance Data for Different Fields.
- (e) Crew Training Manual.
- (f) Normal/Abnormal/Emergency Checklists.
 - (3) Simulator External Checks.
 - (a) Appearance and Cleanliness.
 - (b) Stairway/Access Bridge.
- (c) Emergency Rope Ladders.(d) "Motion On"/"Flight in Progress" Lights.
 - (4) Simulator Internal Checks
- (a) Cleaning/Disinfecting Towels (for cleaning oxygen masks).
- (b) Flight deck Layout (compare with difference list).
 - (5) Equipment.
- (a) Quick Donning Oxygen Masks.
- (b) Head Sets.
- (c) Smoke Goggles.
- (d) Sun Visors.
- (e) Escape Rope.
- (f) Chart Holders. (g) Flashlights.
- (h) Fire Extinguisher (inspection date).
- (i) Crash Axe.
- (i) Gear Pins.

c. Power Supply and APU Start Checks

- (1) Batteries and Static Inverter.
- (2) APU Start with Battery.
- (3) APU Shutdown using Fire Handle.
- (4) External Power Connection.
- (5) APU Start with External Power. (6) Abnormal APU Start/Operation.

d. Flight deck Checks

- (1) Flight deck Preparation Checks.
- (2) FMC Programming.
- (3) Communications and Navigational Aids

e. Engine Start

- (1) Before Start Checks.
- (2) Battery start with Ground Air Supply Unit
 - (3) Engine Crossbleed Start.
- (4) Normal Engine Start.
- (5) Abnormal Engine Starts.
- (6) Engine Idle Readings.
- (7) After Start Checks.

f. Taxi Checks

- (1) Pushback/Powerback.
- (2) Taxi Checks
- (3) Ground Handling Check:
- (a) Power required to initiate ground roll.
- (b) Thrust response.
- (c) Nosewheel and Pedal Steering.
- (d) Nosewheel Scuffing.
- (e) Perform 180 degree turns.
- (f) Brakes Response and Differential Braking using Normal, Alternate and Emergency.
- (g) Brake Systems.

140

- (h) Eye height and fore/aft position.
- (4) Runway Roughness.

- g. Visual Scene—Ground Assessment. Select 3 different airport models and perform the following checks with Day, Dusk and Night selected, as appropriate:
 - (1) Visual Controls.
 - (a) Daylight, Dusk, Night Scene Controls.
- (b) Flight deck "Daylight" ambient lighting.
 - (c) Environment Light Controls.
 - (d) Runway Light Controls.
- (e) Taxiway Light Controls.
- (2) Airport Model Content.
- (a) Ramp area for buildings, gates, airbridges, maintenance ground equipment, parked aircraft.
- (b) Daylight shadows, night time light pools.
- (c) Taxiways for correct markings, taxiway/runway, marker boards, CAT I and II/III hold points, taxiway shape/grass areas, taxiway light (positions and colors).
- (d) Runways for correct markings, lead-off lights, boards, runway slope, runway light positions, and colors, directionality of runway lights.
- (e) Airport environment for correct terrain and significant features.
- (f) Visual scene quantization (aliasing), color, and occulting levels.
 - (3) Ground Traffic Selection.
 - (4) Environment Effects.
 - (a) Low cloud scene.
- (i) Rain:
- (A) Runway surface scene.
- (B) Windshield wiper—operation and sound.
- (ii) Hail:
- (A) Runway surface scene.
- (B) Windshield wiper—operation and sound.
- (b) Lightning/thunder.
- (c) Snow/ice runway surface scene.
- (d) Fog.
- h. Takeoff. Select one or several of the following test cases:
 - ${\rm (1)}\ T/O\ Configuration\ Warnings.$
 - (2) Engine Takeoff Readings.
- (3) Rejected Takeoff (Dry/Wet/Icy Runway) and check the following:
 - (a) Autobrake function.
 - (b) Anti-skid operation.
- (c) Motion/visual effects during deceleration.
- (d) Record stopping distance (use runway plot or runway lights remaining).
- Continue taxiing along the runway while applying brakes and check the following:
- (e) Center line lights alternating red/white for 2000 feet/600 meters.
- (f) Center line lights all red for 1000 feet/300 meters.
 - (g) Runway end, red stop bars.
- (h) Braking fade effect.
- (i) Brake temperature indications.
- (4) Engine Failure between VI and V2.
- (5) Normal Takeoff:
- (a) During ground roll check the following:
- (i) Runway rumble.
- (ii) Acceleration cues.

- (iii) Groundspeed effects.
- (iv) Engine sounds.
- (v) Nosewheel and rudder pedal steering.
- (b) During and after rotation, check the following:
 - (i) Rotation characteristics.
 - (ii) Column force during rotation.
- (iii) Gear uplock sounds/bumps.
- (iv) Effect of slat/flap retraction during climbout.
- (6) Crosswind Takeoff (check the following):
- (a) Tendency to turn into or out of the wind.
- (b) Tendency to lift upwind wing as air-speed increases.
- (7) Windshear during Takeoff (check the following):
- (a) Controllable during windshear encounter.
- (b) Performance adequate when using correct techniques.
- (c) Windshear Indications satisfactory.
 (d) Motion cues satisfactory (particularly turbulence).
- (8) Normal Takeoff with Control Malfunction
- (9) Low Visibility T/O (check the following):
 - (a) Visual cues.
 - (b) Flying by reference to instruments.
 - (c) SID Guidance on LNAV.
- i. Climb Performance. Select one or several of the following test cases:
- (1) Normal Climb—Climb while maintaining recommended speed profile and note fuel, distance and time.
- (2) Single Engine Climb—Trim aircraft in a zero wheel climb at V2.

Note: Up to 5° bank towards the operating engine(s) is permissible. Climb for 3 minutes and note fuel, distance, and time. Increase speed toward en route climb speed and retract flaps. Climb for 3 minutes and note fuel, distance, and time.

- j. Systems Operation During Climb.
- Check normal operation and malfunctions as appropriate for the following systems:
- (1) Air conditioning/Pressurization/Ventilation.
 - (2) Autoflight.
 - (3) Communications.
 - (4) Electrical.
 - (5) Fuel.

141

- (6) Icing Systems.
- (7) Indicating and Recording Systems.
- (8) Navigation/FMS.
- (9) Pneumatics.
- k. Cruise Checks. Select one or several of the following test cases:
- (1) Cruise Performance.
- (2) High Speed/High Altitude Handling (check the following):
- (a) Overspeed warning.
- (b) High Speed buffet.
- $\hbox{(c) Aircraft control satisfactory.}\\$

(d) Envelope limiting functions on Computer Controlled Aircraft.

Reduce airspeed to below level flight buffet onset speed, start a turn, and check the following:

(e) High Speed buffet increases with Gloading.

Reduce throttles to idle and start descent, deploy the speedbrake, and check the following:

- (f) Speedbrake indications.
- (g) Symmetrical deployment.
- (h) Airframe buffet.
- (i) Aircraft response hands off.
- (3) Yaw Damper Operation. Switch off yaw dampers and autopilot. Initiate a Dutch roll and check the following:
 - (a) Aircraft dynamics.
 - (b) Simulator motion effects.

Switch on yaw dampers, re-initiate a Dutch roll and check the following:

- (c) Damped aircraft dynamics.
- (4) APU Operation.
- (5) Engine Gravity Feed.
- (6) Engine Shutdown and Driftdown Check: FMC operation Aircraft performance.
 - (7) Engine Relight.
- *l. Descent.* Select one of the following test cases:
- (1) Normal Descent. Descend while maintaining recommended speed profile and note fuel, distance and time.
- (2) Cabin Depressurization/Emergency Descent.
- m. Medium Altitude Checks. Select one or several of the following test cases:
- (1) High Angle of Attack/Stall. Trim the aircraft at 1.4 Vs, establish 1 kt/sec² deceleration rate, and check the following—
 - (a) System displays/operation satisfactory.
 - (b) Handling characteristics satisfactory.
 - (c) Stall and Stick shaker speed.
 - (d) Buffet characteristics and onset speed.
- (e) Envelope limiting functions on Computer Controlled Aircraft.

Recover to straight and level flight and check the following:

- $(f) \ Handling \ characteristics \ satisfactory.$
- (2) Turning Flight. Roll aircraft to left, establish a 30° to 45° bank angle, and check the following:
 - (a) Stick force required, satisfactory.
- (b) Wheel requirement to maintain bank angle.
 - (c) Slip ball response, satisfactory.
 - (d) Time to turn 180°.
- Roll aircraft from 45° bank one way to 45° bank the opposite direction while maintaining altitude and airspeed—check the following:
- (e) Controllability during maneuver.
- (3) Degraded flight controls.
- (4) Holding Procedure (check the following:)
 - (a) FMC operation.
 - (b) Autopilot auto thrust performance.
 - (5) Storm Selection (check the following:)

- (a) Weather radar controls.
- (b) Weather radar operation.
- (c) Visual scene corresponds with WXR pattern.
- (Fly through storm center, and check the following:)
 - (d) Aircraft enters cloud.
- (e) Aircraft encounters representative turbulence.
 - (f) Rain/hail sound effects evident.
- As aircraft leaves storm area, check the following:
 - (g) Storm effects disappear.
 - (6) TCAS (check the following:)
 - (a) Traffic appears on visual display.
- (b) Traffic appears on TCAS display(s).

As conflicting traffic approaches, take relevant avoiding action, and check the following:

- (c) Visual and TCAS system displays.
- n. Approach and Landing. Select one or several of the following test cases while monitoring flight control and hydraulic systems for normal operation and with malfunctions selected:
- (1) Flaps/Gear Normal Operation. Check the following:
 - (a) Time for extension/retraction.
 - (b) Buffet characteristics.
 - (2) Normal Visual Approach and Landing.

Fly a normal visual approach and landing—check the following:

- (a) Aircraft handling.
- (b) Spoiler operation.
- (c) Reverse thrust operation.
- (d) Directional control on the ground.
- (e) Touchdown cues for main and nosewheel.
 - (f) Visual cues.
 - (g) Motion cues.
 - (h) Sound cues.
 - (i) Brake and anti-skid operation.
- (3) Flaps/Gear Abnormal Operation or with hydraulic malfunctions.
- (4) Abnormal Wing Flaps/Slats Landing.
- (5) Manual Landing with Control Malfunction.
- (a) Aircraft handling.
- (b) Radio aids and instruments.
- (c) Airport model content and cues.
- (d) Motion cues.
- (e) Sound cues.
- (6) Non-precision Approach—All Engines Operating.
 - (a) Aircraft handling.
 - (b) Radio Aids and instruments.
 - (c) Airport model content and cues.
 - (d) Motion cues.
 - (e) Sound cues.
 - (7) Circling Approach.
- (a) Aircraft handling.
- (c) Radio Aids and instruments.(d) Airport model content and cues.
- (d) Airport model con (e) Motion cues.
- (f) Sound cues.
- (8) Non-precision Approach—One Engine Inoperative.

- (a) Aircraft handling.
- (b) Radio Aids and instruments.
- (c) Airport model content and cues.
- (d) Motion cues.
- (e) Sound cues.
- (9) One Engine Inoperative Go-around.
- (a) Aircraft handling.
- (b) Radio Aids and instruments.
- (c) Airport model content and cues.
- (d) Motion cues.
- (e) Sound cues.
- (10) CAT I Approach and Landing with raw-data ILS.
 - (a) Aircraft handling.
 - (b) Radio Aids and instruments.
 - (c) Airport model content and cues.
 - (d) Motion cues.
 - (e) Sound cues.
- (11) CAT I Approach and Landing with Limiting Crosswind.
 - (a) Aircraft handling.
 - (b) Radio Aids and instruments.
 - (c) Airport model content and cues.
 - (d) Motion cues.
 - (e) Sound cues.
- (12) CAT I Approach with Windshear. Check the following:
- (a) Controllable during windshear encounter.
- (b) Performance adequate when using correct techniques.
 - (c) Windshear indications/warnings.
 - (d) Motion cues (particularly turbulence).
- (13) CAT II Approach and Automatic Go-Around.
- (14) CAT III Approach and Landing—System Malfunctions.
- (15) CAT III Approach and Landing—1 Engine Inoperative.
 - (16) GPWS evaluation.
 - $o.\ Visual\ Scene{--In-Flight}\ Assessment.$

Select three (3) different visual models and perform the following checks with "day," "dusk," and "night" (as appropriate) selected. Reposition the aircraft at or below 2000 feet within 10 nm of the airfield. Fly the aircraft around the airport environment and assess control of the visual system and evaluate the Airport model content as described below:

- (1) Visual Controls.
- (a) Daylight, Dusk, Night Scene Controls.
- (b) Environment Light Controls.
- (c) Runway Light Controls.
- (d) Taxiway Light Controls.(e) Approach Light Controls.
- (2) Airport model Content.
- (a) Airport environment for correct terrain and significant features.
- (b) Runways for correct markings, runway slope, directionality of runway lights.
- (c) Visual scene for quantization (aliasing), color, and occulting.

Reposition the aircraft to a long, final approach for an "ILS runway." Select flight freeze when the aircraft is 5-statute miles

(sm)/8-kilometers (km) out and on the glide slope. Check the following:

- (3) Airport model content.
- (a) Airfield features.
- (b) Approach lights.
- (c) Runway definition.
- (d) Runway definition.
- (e) Runway edge lights and VASI lights.
- (f) Strobe lights.

Release flight freeze. Continue flying the approach with NP engaged. Select flight freeze when aircraft is 3 sm/5 km out and on the glide slope. Check the following:

- (4) Airport model Content.
- (a) Runway centerline light.
- (b) Taxiway definition and lights.

Release flight freeze and continue flying the approach with A/P engaged. Select flight freeze when aircraft is 2 sm/3 km out and on the glide slope. Check the following:

- (5) Airport model content.
- (a) Runway threshold lights.
- (b) Touchdown zone lights.
- At 200 ft radio altitude and still on glide slope, select Flight Freeze. Check the following:
 - (6) Airport model content.
 - (a) Runway markings.
- Set the weather to Category I conditions and check the following:
 - (7) Airport model content.
 - (a) Visual ground segment.

Set the weather to Category II conditions, release Flight Freeze, re-select Flight Freeze at 100 feet radio altitude, and check the following:

- (8) Airport model content.
- (a) Visual ground segment.

Select night/dusk (twilight) conditions and check the following:

- (9) Airport model content.
- (a) Runway markings visible within landing light lobes.

Set the weather to Category III conditions, release Flight Freeze, re-select Flight Freeze at 50 feet radio altitude and check the following:

- (10) Airport model content.
- (a) Visual ground segment.

Set WX to a typical "missed approach? weather condition, release Flight Freeze, reselect Flight Freeze at 15 feet radio altitude, and check the following:

- (11) Airport model content.
- (a) Visual ground segment.
- When on the ground, stop the aircraft. Set 0 feet RVR, ensure strobe/beacon tights are switched on and check the following:
 - (12) Airport model content.
 - (a) Visual effect of strobe and beacon.

Reposition to final approach, set weather to "Clear," continue approach for an automatic landing, and check the following:

(13) Airport model content.

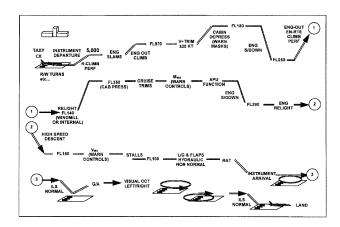
143

(a) Visual cues during flare to assess sink rate.

14 CFR Ch. I (1-1-24 Edition)

- (b) Visual cues during flare to assess Depth perception.
 - (c) Flight deck height above ground.
 - After Landing Operations.
 - (1) After Landing Checks.
 - (2) Taxi back to gate. Check the following:
 (a) Visual model satisfactory.
- (b) Parking brake operation satisfactory.
- (3) Shutdown Checks.
- q. Crash Function.
- (1) Gear-up Crash.
- (2) Excessive rate of descent Crash.
- (3) Excessive bank angle Crash.

Typical Subjective Continuing Qualification Evaluation Profile (2 hours)



End Information

Attachment 4 to Appendix A to Part 60--

SAMPLE DOCUMENTS

Table of Contents

Title of Sample

Figure A4F

Figure A4A S	Sample Letter, Request for Initial, Upgrade, or Rein	statement Evaluation.
--------------	--	-----------------------

Figure A4B Attachment: FFS Information Form

Figure A4C Sample Letter of Compliance

Figure A4D Sample Qualification Test Guide Cover Page

Sample Statement of Qualification - Certificate Figure A4E

Sample Statement of Qualification - List of Qualified Tasks

Figure A4H Sample Continuing Qualification Evaluation Requirements Page

Sample Statement of Qualification - Configuration List

Figure A4I Sample MQTG Index of Effective FFS Directives

Pt. 60, App. A

Attachment 4 to Appendix A to Part 60-Figure A4B - Sample Letter, Request for Initial, Upgrade, or Reinstatement Évaluation **Attachment: FSTD Information Form**

INFORMATION

Date:					
	Section 1. FS7	TD Informat	tion and Character	ristics	
Sponsor Name:			FSTD Location:		
Address:			Physical Address:		
City:			City:		
State:			State:		
Country:			Country:		
ZIP:			ZIP:		
Manager					
Sponsor ID No: (Four Letter FAA Designator)	1		Nearest Airport: (Airport Designator)	<u> </u>	
Type of Evaluation Requeste			al 🔲 Upgrade 🔲 Contin	-i OUEU	- De
Type of Evaluation Requeste	:a:		ai □ Opgrade □ Contin istatement	uing Quanticatio	n 🗀 Speciai
Aircraft Make/model/series:					
Initial Qualification: (If Applicable)	Date: Level	I	Manufacturer's Identification or Serial Number		
Upgrade Qualification: (If Applicable)	Date:Leve		□ eMQTG		
Qualification Basis:	A	□В	☐ Interim C	□ c	□ D
	□6	□ 7	Provisiona	l Status	
Other Technical Information	1:				
FAA FSTD ID No: (If Applicable)			FSTD Manufacturer:		
Convertible FSTD:	□Yes:		Date of Manufacture:	MM/DD/YYYY	-
Related FAA ID No. (If Applicable)			Sponsor FSTD ID No:		
Engine model(s) and data rev	vision:		Source of aerodynamic	model:	
FMS identification and revis	ion level:		Source of aerodynamic	coefficient data:	
Visual system manufacturer/	model:		Aerodynamic data revi	sion number:	
Flight control data revision:			Visual system display:		
Mot ion system manufacture	r/type:		FSTD computer(s) idea	ntification:	
National Aviation Authority (NAA):					
(If Applicable) NAA FSTD ID No:			Last NAA Evaluation	T	
			Date:		
NAA Qualification Level:					
NAA Qualification Basis:					
				1	
Visual System Manufacturer and Type:		FSTD Seats Available:	Motion System Mar and Type:	nufacturer	:

Attachment 4 to Appendix A to Part 60-Figure A4B – Sample Letter , Request for Initial, Upgrade, or Reinstatement Évaluation

Attachment: FSTD Information Form

		e(s):	☐ EFIS ☐ TCAS ☐ GPS ☐ WX Rada	HUI GPV FMS	VS 🔲 Plai Type:	n Vi		Engine Instrumentation: EICAS FADEC Other:
								1
Airport Models:		3.6.1 Airport Des	signator	3.6	.2 Airport D	esig	nator	3.6.3 Airport Designator
Circle to Land:		3. 7.1 Airport Des		3.	7.2			3. 7.3 Landing Runway
Visual Ground Segment		3.8.1 Airport De		3.8	.2Approx			3. 8.3 Landing Runway
		THI POST 25	voignavot		търго			
		Section 2	. Suppleme					
FAA Training Program	Approval Au	thority:			POI 🗌 T	CPN	И 🗌 Other:	
Name:				Of	fice:			
Tel:				Fa	x:			
Email:								
FSTD Scheduling Person	1:							
Name:								
Address 1:				Ad	dress 2			Antonomonomonomonomonomonomon
City:				Sta	ite:			
ZIP:		***************************************	***************************************	En	nail:			
Tel:				Fa	x:			
FSTD Technical Contac	t:						***************************************	
Name:								
Address 1:				Add	iress 2			
City:				Stat	te:			
ZIP:				Em	ail:			
Tel:				Fax	;			
Area/Function/Maneuve		3. Training	g, Testing a	nd (Checkin Requeste		onsidera Remarks	tions
Private Pilot - Training	Checks: (142	2)						
Commercial Pilot - Train	ning /Checks:	(142)						4
Multi-Engine Rating - T	raining / Che	cks (142)						-
Instrument Rating -Trai	ning / Checks	i (142)						_
Type Rating - Training	/ Checks (135	/121/142)						_
Proficiency Checks (135/	(121/142)							

Pt. 60, App. A

Attachment 4 to Appendix A to Part 60— Figure A4B – Sample Letter , Request for Initial, Upgrade, or Reinstatement Évaluation

Attachment: FSTD Information Form

INFORMATION	
CAT I: (RVR 2400/1800 ft. DH200 ft)	
CAT II: (RVR 1200 ft. DH 100 ft)	
CAT III * (lowest minimum) RVR ft.	
* State CAT III (≤ 700 ft.), CAT IIIb (≤ 150 ft.), or CAT IIIc (0 ft.)	dichalaning sandan sure sana sandar
Circling Approach	
Windshear Training:	
Windshear Training IAW 121.409(d) (121 Turbojets Only)	
Generic Unusual Attitudes and Recoveries within the Normal Flight Envelope	
Specific Unusual Attitudes Recoveries	
Auto-coupled Approach/Auto Go Around	
Auto-land / Roll Out Guidance	
TCAS/ACAS I / II	
WX-Radar	
HUD	
HGS	
EFVS	
Future Air Navigation Systems	
GPWS / EGPWS	
ETOPS Capability	
GPS	
SMGCS	
Helicopter Slope Landings	
Helicopter External Load Operations	
Helicopter Pinnacle Approach to Landings	
Helicopter Night Vision Maneuvers	
Helicopter Category A Takeoffs	

Date	to I
RE: Request for Initial/Upgrade Evaluation Date	1
This is to advise you of our intent to request an (initial or upgrade) evaluation of our (FFS Manufacturer),	<u>ق</u>
(Aircraft Type/Level) Full Flight Simulator (FFS), (FAA ID Number, if previously qualified), located in (City,	
State) at the (Facility) on (Proposed Evaluation Date). (The proposed evaluation date shall not be more than	
180 days following the date of this letter.) The FFS will be sponsored by (Name of Training Center/Air	
Carrier), FAA Designator (4 Letter Code). The FFS will be sponsored as follows: (Select One)	

Attachment Appendix A Figure A4C Letter of

For QTG tests run at the factory, not later, than 45 days prior to the proposed evaluation date with the additional "1/3 on-site" tests provided not later than 14 days prior to the proposed evaluation date. We agree to provide the formal request for the evaluation to your staff as follows: (check one) The FFS will be used for dry lease only.

☐ For QTG tests run on-site, not later than 30 days prior to the proposed evaluation date.

We understand that the formal request will contain the following documents:

- Sponsor's Letter of Request (Company Compliance Letter).
- Principal Operations Inspector (POI) or Training Center Program Manager's (TCPM) endorsement. Sponsor's Letter o
 Principal Operation
 Complete QTG.

If we are unable to meet the above requirements, we understand this may result in a significant delay, perhaps 45 days or more, in rescheduling and completing the evaluation. (The sponsor should add additional comments as necessary).

Please contact (Name Telephone and Fax Number of Sponsor's Contact) to confirm the date for this initial evaluation. We understand a member of your National Simulator Program staff will respond to this request

A copy of this letter of intent has been provided to (Name), the Principal Operations Inspector (POI) and/or Fraining Center Program Manager (TCPM).

Sincerely.

Attachment: FFS Information Form cc: POI/TCPM

ER09DE22.054</GPH>

INFORMATION

Name of responsible Flight Standards office

(Date)

(City/State/Zip) <u>Address</u>)

Letter of Compliance

been established. Our Pilot(s), (Name(s)), who are qualified on (Aircraft Type) aircraft have assessed the FFS and have found that it conforms to the (<u>Operator/Sponsor</u>) (<u>Aircraft Type</u>) flight deck configuration and that the simulated systems and subsystems function equivalently to those in the aircraft. The above named pilot(s) have also assessed the performance and the Name/Model) system is fully defined on the FFS Information page of the accompanying Qualification Test Guide (QTG). We have completed the tests of the FFS and certify that it meets all applicable requirements of FAR parts 121, 125, or 135), and the guidance of (AC 120-40B)or 14 CFR Part 60). Appropriate hardware and software configuration control procedures have (Operator Sponsor Name) requests evaluation of our (Aircraft Type) FFS for Level flying qualities of the FFS and find that it represents the respective aircraft.

(Added Comments may be placed here)

(Sponsor Representative)

ATTACHMENT 4 TO APPENDIX A TO PART 60-FIGURE A4D—SAMPLE QUALIFICATION TEST GUIDE COVER PAGE

Dear Mr. (Name of TPAA):

INFORMATION

Date:

Date:

(Sponsor)

FAA

SPONSOR NAME SPONSOR ADDRESS

FAA QUALIFICATION TEST GUIDE (SPECIFIC AIRPLANE MODEL)

for example Stratos BA797-320A

(Simulator Identification Including Manufacturer, Serial Number, Visual System Used) (Type of Simulator)

(Qualification Performance Standard Used) (Simulator Level)

(Simulator Location)

FAA Initial Evaluation Date:

Pt. 60, App. A

ATTACHMENT 4 TO APPENDIX A TO PART 60—FIGURE A4E—SAMPLE STATEMENT OF QUALIFICATION—CERTIFICATE

INFORMATION

And pursuant to 14 CFR Part 60 found it to meet its original qualification basis, AC 120-40B (MM/DD/YY)

The Master Qualification Test Guide and the attached

Configuration List and Restrictions List

Provide the Qualification Basis for this device to operate at

B. Williamson

March 15, 2009

Until April 30, 2010 Unless sooner rescinded or extended by the FAA

(for the FAA)

Federal Aviation Administration

Certificate of Qualification

This is to certify that representatives of the FAA Completed an evaluation of the

Go-Fast Airlines

Farnsworth Z-100 Full Flight Simulator

FAA Identification Number 999

VerDate Sep<11>2014 14:00 Mar 14, 2024 Jkt 262047 PO 00000 Frm 00161 Fmt 8010 Sfmt 8006 Q:\14\14V2.TXT PC31

Attachment 4 to Appendix A to Part 60-Figure A4F - Sample Statement of Qualification; Configuration List INFORMATION

STATEMENT OF QUALIFICATION **CONFIGURATION LIST**

Date:		
	Section 1. FSTD	Information and Characteristics
Sponsor Name:		FSTD Location:
Address:		Physical Address:
City:		City:
State:		State:
Country:		Country:
ZIP:		ZIP:
Manager		
Sponsor ID No: (Four Letter FAA Designator)		Nearest Airport: (Airport Designator)
Type of Evaluation Requeste	ed:	☐ Initial ☐ Upgrade ☐ Continuing Qualification ☐ Special ☐ Reinstatement
Aircraft Make/model/series:		
Initial Qualification: (If Applicable)	Date: Level MM/DD/YYYY	Manufacturer's Identification or Serial Number
Upgrade Qualification: (If Applicable)	Date:Level MM/DD/YYYY	eMQTG
Qualification Basis:	□ A □ 6	□ B □ Interim C □ C □ D □ 7 □ Provisional Status
	101	
Other Technical Information	n:	
Other Technical Information FAA FSTD ID No: (If Applicable)	n:	FSTD Manufacturer:
	n:	Date of Manufacture:
FAA FSTD ID No: (If Applicable)		
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No.		Date of Manufacture: MM//DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable)	Yes:	Date of Manufacture: MM/DD/YYYY Sponsor FSTD ID No:
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev	Vision:	Date of Manufacture: MM/DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis	Yes: vision: ion level: /model:	Date of Manufacture: MM/DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis Visual system manufacturer/	Yes: vision: ion level:	Date of Manufacture: MM//DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis Visual system manufacturer/ Flight control data revision:	Yes: vision: ion level:	Date of Manufacture: MM//DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis Visual system manufacturer/ Flight control data revision:	Vision: ion level: /model:	Date of Manufacture: MM//DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis Visual system manufacturer/ Flight control data revision: Mot ion system manufacture National Aviation Authority (NAA):	Vision: ion level: /model:	Date of Manufacture: MM//DD/YYYY
FAA FSTD ID No: (If Applicable) Convertible FSTD: Related FAA ID No. (If Applicable) Engine model(s) and data rev FMS identification and revis Visual system manufacturer/ Flight control data revision: Mot ion system manufacture National Aviation Authority (If Applicable)	Vision: ion level: /model:	Date of Manufacture: MM/DD/YYYY

Attachment 4 to Appendix A to Part 60— Figure A4F – Sample Statement of Qualification; Configuration List INFORMATION

and Type:	turer		Available:		and Type:	stem Manutae	cturer	
Aircraft Equipment:	Engine Typ	e(s):	Flight Instru] HUD] GPW] FMS	D ☐ HGS VS ☐ Plair S Type:			ine Instrumentation: CICAS FADEC Other:
Airport Models:		3.6.1 Airport De	signator	3.6	.2 Airport De	signator	3.6.3 Ai	rport Designator
Circle to Land:		3. 7.1 Airport De		3. 1	7.2 Approa		3. 7.3	
Visual Ground Segmen	t	3.8.1 Airport D		3.8			3. 8.3	
		Section 2	. Supplem	enta	rv Infor	mation		
FAA Training Progran	ı Approval Aı					CPM DOthe	r:	
Name:				Of	fice:			
Tel:				Fa	x:			A. Land
Email:								
FSTD Scheduling Person	on:							
Name:	T							
Address 1:				Ad	dress 2		T	
City:		*		Sta	ite:	***************************************	_	
ZIP:				En	nail:		-	
Tel:		-		Fa	x:			
FSTD Technical Conta	ct:							
Name:		-						
Address 1:		_		Add	iress 2			
City:				Stat				
ZIP:			***************************************	Em:				
Tel:		n.		Fax	:		<u> </u>	
		3. Trainin	g, Testing	and (ations	
Area/Function/Maneuv					Requested	i Remarks		
Private Pilot - Training	g / Checks: (14	2)						
Commercial Pilot - Tra	ining /Checks	:(142)						
Multi-Engine Rating -	Training / Ch	ecks (142)						
Instrument Rating -Tr	aining / Check	s (142)	***************************************					
Type Rating - Training	g / Checks (13	5/121/142)						
L								

Attachment 4 to Appendix A to Part 60— Figure A4F – Sample Statement of Qualification; Configuration List INFORMATION

INFORMATION		
Proficiency Checks (135/121/142)		
CAT I: (RVR 2400/1800 ft. DH200 ft)		
CAT II: (RVR 1200 ft. DH 100 ft)		
CAT III * (lowest minimum) RVR ft. * State CAT III (< 700 ft.), CAT IIIb (< 150 ft.), or CAT IIIc (0 ft.)		
Circling Approach	10	
Windshear Training:		
Windshear Training IAW 121.409(d) (121 Turbojets Only)		
Generic Unusual Attitudes and Recoveries within the Normal Flight Envelope		
Specific Unusual Attitudes Recoveries		
Auto-coupled Approach/Auto Go Around		
Auto-land / Roll Out Guidance		
TCAS/ACAS I / II	П	
WX-Radar		
HUD		
HGS		
EFVS		
Future Air Navigation Systems		
GPWS / EGPWS		
ETOPS Capability		
GPS		
SMGCS		
Helicopter Slope Landings		
Helicopter External Load Operations		
Helicopter Pinnacle Approach to Landings		
Helicopter Night Vision Maneuvers		
Helicopter Category A Takeoffs		

Attachment 4 to Appendix A to Part 60— Figure A4G – Sample Statement of Qualification – List of Qualified Tasks INFORMATION

STATEMENT of QUALIFICATION List of Qualified Tasks

Go Fast Airline Training -- Farnsworth Z-100 -- Level D -- FAA ID# 999

The FFS is qualified to perform all of the Maneuvers, Procedures, Tasks, and Functions Listed in Appendix A, Attachment 1, Table A1B, Minimum FFS Requirements In Effect on [mm/dd/yyyy] except for the following listed Tasks or Functions.

Qualified for all tasks in Table A1B, for which the sponsor has requested qualification, except for the following:

3.e(1)(i) NDB approach

3.f. Recovery from Unusual Attitudes

4.3. Circling Approach

Additional tasks for which this FFS is qualified (i.e., in addition to the list in Table A1B)

- 1. Enhanced Visual System
- 2. Windshear Training IAW Section 121.409(d).

The airport visual models evaluated for qualification at this level are:

- 1. Atlanta Hartsfield International Airport (KATL)
- 2. Miami International Airport (KMIA)
- 3. Dallas/Ft. Worth Regional Airport (KDFW)

ATTACHMENT 4 TO APPENDIX A TO PART 60—FIGURE A4H [RESERVED]

Attachment 4 to Appendix A to Part 60— Figure A4I – Sample MQTG Index of Effective FFS Directives INFORMATION

		fective FSTD Directives ed in this Section	
Number	Effective Date	Date of Notification	Details

Continue as Necessary....

ATTACHMENT 5 TO APPENDIX A TO PART 60—SIMULATOR QUALIFICATION REQUIREMENTS FOR WINDSHEAR TRAINING PROGRAM USE

BEGIN QPS REQUIREMENTS

1. Applicability

This attachment applies to all simulators, regardless of qualification level, that are used to satisfy the training requirements of an FAA-approved low-altitude windshear flight training program, or any FAA-approved training program that addresses windshear encounters.

2. STATEMENT OF COMPLIANCE AND CAPABILITY (SOC)

a. The sponsor must submit an SOC confirming that the aerodynamic model is based on flight test data supplied by the airplane manufacturer or other approved data provider. The SOC must also confirm that any change to environmental wind parameters, including variances in those parameters for windshear conditions, once inserted for computation, result in the correct simulated performance. This statement must also include examples of environmental wind parameters currently evaluated in the simulator (such as crosswind takeoffs, crosswind approaches, and crosswind landings).

b. For simulators without windshear warning, caution, or guidance hardware in the original equipment, the SOC must also state that the simulation of the added hardware and/or software, including associated flight deck displays and annunciations, replicates the system(s) installed in the airplane. The statement must be accompanied by a block diagram depicting the input and output signal flow, and comparing the signal flow to the equipment installed in the airplane.

3. Models

The windshear models installed in the simulator software used for the qualification evaluation must do the following:

- a. Provide cues necessary for recognizing windshear onset and potential performance degradation requiring a pilot to initiate recovery procedures. The cues must include all of the following, as appropriate for the portion of the flight envelope:
- (1) Rapid airspeed change of at least ± 15 knots (kts).
- (2) Stagnation of airspeed during the take-off roll.
- (3) Rapid vertical speed change of at least ±500 feet per minute (fpm).
- (4) Rapid pitch change of at least $\pm 5^{\circ}$.
- b. Be adjustable in intensity (or other parameter to achieve an intensity effect) to at

least two (2) levels so that upon encountering the windshear the pilot may identify its presence and apply the recommended procedures for escape from such a windshear.

- (1) If the intensity is lesser, the performance capability of the simulated airplane in the windshear permits the pilot to maintain a satisfactory flightpath; and
- (2) If the intensity is greater, the performance capability of the simulated airplane in the windshear does not permit the pilot to maintain a satisfactory flightpath (crash). Note: The means used to accomplish the "nonsurvivable" scenario of paragraph 3.b.(2) of this attachment, that involve operational elements of the simulated airplane, must reflect the dispatch limitations of the airplane.
- c. Be available for use in the FAA-approved windshear flight training program.

4. Demonstrations

- a. The sponsor must identify one survivable takeoff windshear training model and one survivable approach windshear training model. The wind components of the survivable models must be presented in graphical format so that all components of the windshear are shown, including initiation point, variance in magnitude, and time or distance correlations. The simulator must be operated at the same gross weight, airplane configuration, and initial airspeed during the takeoff demonstration (through calm air and through the first selected survivable windshear), and at the same gross weight, airplane configuration, and initial airspeed during the approach demonstration (through calm air and through the second selected survivable windshear).
- b. In each of these four situations, at an "initiation point" (i.e., where windshear onset is or should be recognized), the recommended procedures for windshear recovery are applied and the results are recorded as specified in paragraph 5 of this attachment.
- c. These recordings are made without inserting programmed random turbulence. Turbulence that results from the windshear model is to be expected, and no attempt may be made to neutralize turbulence from this source.
- d. The definition of the models and the results of the demonstrations of all four?(4) cases described in paragraph 4.a of this attachment, must be made a part of the MQTG.

5. RECORDING PARAMETERS

- a. In each of the four MQTG cases, an electronic recording (time history) must be made of the following parameters:
 - (1) Indicated or calibrated airspeed.
 - (2) Indicated vertical speed.
 - (3) Pitch attitude.

- (4) Indicated or radio altitude.
- (5) Angle of attack.
- (6) Elevator position.
- (7) Engine data (thrust, N1, or throttle position).
- (8) Wind magnitudes (simple windshear model assumed).
- b. These recordings must be initiated at least 10 seconds prior to the initiation point, and continued until recovery is complete or ground contact is made.

6. EQUIPMENT INSTALLATION AND OPERATION

All windshear warning, caution, or guidance hardware installed in the simulator must operate as it operates in the airplane. For example, if a rapidly changing wind speed and/or direction would have caused a windshear warning in the airplane, the simulator must respond equivalently without instructor/evaluator intervention.

7. QUALIFICATION TEST GUIDE

- a. All QTG material must be forwarded to the responsible Flight Standards office.
- b. A simulator windshear evaluation will be scheduled in accordance with normal procedures. Continuing qualification evaluation schedules will be used to the maximum extent possible.
- c. During the on-site evaluation, the evaluator will ask the operator to run the performance tests and record the results. The results of these on-site tests will be compared to those results previously approved and placed in the QTG or MQTG, as appropriate.
- d. QTGs for new (or MQTGs for upgraded) simulators must contain or reference the information described in paragraphs 2, 3, 4, and 5 of this attachment.

END QPS REQUIREMENTS

BEGIN INFORMATION

8. Subjective Evaluation

The responsible Flight Standards office will fly the simulator in at least two of the available windshear scenarios to subjectively evaluate simulator performance as it encounters the programmed windshear conditions.

- a. One scenario will include parameters that enable the pilot to maintain a satisfactory flightpath.
- b. One scenario will include parameters that will not enable the pilot to maintain a satisfactory flightpath (crash).
- c. Other scenarios may be examined at the responsible Flight Standards office's discretion.

9. QUALIFICATION BASIS

The addition of windshear programming to a simulator in order to comply with the qualification for required windshear training does not change the original qualification basis of the simulator.

10. Demonstration Repeatability

For the purposes of demonstration repeatability, it is recommended that the simulator be flown by means of the simulator's autodrive function (for those simulators that have autodrive capability) during the demonstrations.

END INFORMATION

ATTACHMENT 6 TO APPENDIX A TO PART 60— FSTD DIRECTIVES APPLICABLE TO AIRPLANE FLIGHT SIMULATORS

FLIGHT SIMULATION TRAINING DEVICE (FSTD) DIRECTIVE

FSTD Directive 1. Applicable to all Full Flight Simulators (FFS), regardless of the original qualification basis and qualification date (original or upgrade), having Class II or Class III airport models available.

Agency: Federal Aviation Administration (FAA), DOT.

Action: This is a retroactive requirement to have all Class II or Class III airport models meet current requirements.

Summary: Notwithstanding the authorization listed in paragraph 13b in Appendices A and C of this part, this FSTD Directive requires each certificate holder to ensure that by May 30, 2009, except for the airport model(s) used to qualify the simulator at the designated level, each airport model used by the certificate holder's instructors or evaluators for training, checking, or testing under this chapter in an FFS, meets the definition of a Class II or Class III airport model as defined in 14CFR part 60. The completion of this requirement will not require a report. and the method used for keeping instructors and evaluators apprised of the airport models that meet Class II or Class III requirements on any given simulator is at the ontion of the certificate holder whose employees are using the FFS, but the method used must be available for review by the TPAA for that certificate holder.

Dates: FSTD Directive 1 becomes effective on May 30, 2008.

SPECIFIC REQUIREMENTS:

- 1. Part 60 requires that each FSTD be:
- a. Sponsored by a person holding or applying for an FAA operating certificate under Part 119, Part 141, or Part 142, or holding or applying for an FAA-approved training pro-

gram under Part 63, Appendix C, for flight engineers, and

- b. Evaluated and issued an SOQ for a specific FSTD level.
- 2. FFSs also require the installation of a visual system that is capable of providing an out-of-the-flight-deck view of airport models. However, historically these airport models were not routinely evaluated or required to meet any standardized criteria. This has led to qualified simulators containing airport models being used to meet FAA-approved training, testing, or checking requirements with potentially incorrect or inappropriate visual references.
- 3. To prevent this from occurring in the future, by May 30, 2009, except for the airport model(s) used to qualify the simulator at the designated level, each certificate holder must assure that each airport model used for training, testing, or checking under this chapter in a qualified FFS meets the definition of a Class II or Class III airport model as defined in Appendix F of this part.
- 4. These references describe the requirements for visual scene management and the minimum distances from which runway or landing area features must be visible for all levels of simulator. The airport model must provide, for each "in-use runway" or "in-use landing area," runway or landing area surface and markings, runway or landing area lighting, taxiway surface and markings, and taxiway lighting. Additional requirements include correlation of the v airport models with other aspects of the airport environment, correlation of the aircraft and associated equipment, scene quality assessment features, and the control of these models the instructor must be able to exercise.
- 5. For circling approaches, all requirements of this section apply to the runway used for the initial approach and to the runway of intended landing.
- 6. The details in these models must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material. However, this FSTD DIRECTIVE 1 does not require that airport models contain details that are beyond the initially designed capability of the visual system, as currently qualified. The recognized limitations to visual systems are as follows:
- a. Visual systems not required to have runway numbers as a part of the specific runway marking requirements are:
 - (1) Link NVS and DNVS.
 - (2) Novoview 2500 and 6000.
- (3) FlightSafety VITAL series up to, and including, VITAL III, but not beyond.
 - (4) Redifusion SP1, SP1T, and SP2.
- b. Visual systems required to display runway numbers only for LOFT scenes are:
 - (1) FlightSafety VITAL IV
- (2) Redifusion SP3 and SP3T.
- (3) Link-Miles Image II.

- c. Visual systems not required to have accurate taxiway edge lighting are:
 - (1) Redifusion SP1.
 - (2) FlightSafety Vital IV.
 - (3) Link-Miles Image II and Image IIT
- (4) XKD displays (even though the XKD image generator is capable of generating blue colored lights, the display cannot accommodate that color).
- 7. A copy of this Directive must be filed in the MQTG in the designated FSTD Directive Section, and its inclusion must be annotated on the Index of Effective FSTD Directives chart. See Attachment 4, Appendices A through D for a sample MQTG Index of Effective FSTD Directives chart.

FLIGHT SIMULATION TRAINING DEVICE (FSTD) DIRECTIVE

FSTD Directive 2. Applicable to all airplane Full Flight Simulators (FFS), regardless of the original qualification basis and qualification date (original or upgrade), used to conduct full stall training, upset recovery training, airborne icing training, and other flight training tasks as described in this Directive.

Agency: Federal Aviation Administration (FAA), DOT.

Action: This is a retroactive requirement for any FSTD being used to obtain training, testing, or checking credit in an FAA approved flight training program for the specific training maneuvers as defined in this Directive.

Summary: Notwithstanding the authorization listed in paragraph 13b in Appendix A of this Part, this FSTD Directive requires that each FSTD sponsor conduct additional subjective and objective testing, conduct required modifications, and apply for additional FSTD qualification under §60.16 to support continued qualification of the following flight training tasks where training, testing, or checking credit is being sought in a selected FSTD being used in an FAA approved flight training program:

- a. Recognition of and Recovery from a Full Stall
- b. Upset Prevention and Recovery
- c. Engine and Airframe Icing
- d. Takeoff and Landing with Gusting Crosswinds
- e. Recovery from a Bounced Landing

The FSTD sponsor may elect to apply for additional qualification for any, all, or none of the above defined training tasks for a particular FSTD. After March 12, 2019, any FSTD used to conduct the above training tasks must be evaluated and issued additional qualification by the responsible Flight Standards office as defined in this Directive.

Dates: FSTD Directive No. 2 becomes effective on May 31, 2016.

SPECIFIC REQUIREMENTS

- 1. Part 60 requires that each FSTD be:
- a. Sponsored by a person holding or applying for an FAA operating certificate under Part 119, Part 141, or Part 142, or holding or applying for an FAA-approved training program under Part 63, Appendix C, for flight engineers, and
- b. Evaluated and issued a Statement of Qualification (SOQ) for a specific FSTD
- 2. The evaluation criteria contained in this Directive is intended to address specific training tasks that require additional evaluation to ensure adequate FSTD fidelity.
- 3. The requirements described in this Directive define additional qualification criteria for specific training tasks that are applicable only to those FSTDs that will be utilized to obtain training, testing, or checking credit in an FAA approved flight training program. In order to obtain additional qualification for the tasks described in this Directive, FSTD sponsors must request additional qualification in accordance with §60.16 and the requirements of this Directive. FSTDs that are found to meet the requirements of this Directive will have their Statement of Qualification (SOQ) amended to reflect the additional training tasks that the FSTD has been qualified to conduct. The additional qualification requirements as defined in this Directive are divided into the following training tasks:
- a. Section I—Additional Qualification Requirements for Full Stall Training Tasks
- Section II—Additional Qualification Requirements for Upset Prevention and Recovery Training Tasks
- c. Section III—Additional Qualification Requirements for Engine and Airframe Icing
- d. Section IV—Additional Qualification Requirements for Takeoff and Landing in Gusting Crosswinds
- e. Section V—Additional Qualification Requirements for Bounced Landing Recovery Training Tasks
- 4. A copy of this Directive (along with all required Statements of Compliance and objective test results) must be filed in the MQTG in the designated FSTD Directive Section, and its inclusion must be annotated on the Index of Effective FSTD Directives chart. See Attachment 4, Appendix A for a sample MQTG Index of Effective FSTD Directives chart.

SECTION I—EVALUATION REQUIREMENTS FOR FULL STALL TRAINING TASKS

1. This section applies to previously qualified Level C and Level D FSTDs being used to obtain credit for stall training maneuvers beyond the first indication of a stall (such as

stall warning system activation, stick shaker, etc.) in an FAA approved training program.

- 2. The evaluation requirements in this Directive are intended to validate FSTD fidelity at angles of attack sufficient to identify the stall, to demonstrate aircraft performance degradation in the stall, and to demonstrate recovery techniques from a fully stalled flight condition.
- 3. After March 12, 2019, any FSTD being used to obtain credit for full stall training maneuvers in an FAA approved training program must be evaluated and issued additional qualification in accordance with this Directive and the following sections of Appendix A of this Part:
- a. Table A1A, General Requirements, Section 2.m. (High Angle of Attack Modeling)
- b. Table A1A, General Requirements, Section
 3.f. (Stick Pusher System) [where applicable]
- c. Table A2A, Objective Testing Requirements, Test 2.a.10 (Stick Pusher Force Calibration) [where applicable]
- d. Table A2A, Objective Testing Requirements, Test 2.c.8.a (Stall Characteristics)
- e. Table A2A, Objective Testing Requirements, Test 3.f.5 (Characteristic Motion Vibrations—Stall Buffet) [See paragraph 4 of this section for applicability on previously qualified FSTDs]
- f. Table A3A, Functions and Subjective Testing Requirements, Test 5.b.1.b. (High Angle of Attack Maneuvers)
- g. Attachment 7, Additional Simulator Qualification Requirements for Stall, Upset Prevention and Recovery, and Engine and Airframe Icing Training Tasks (High Angle of Attack Model Evaluation)
- 4. For FSTDs initially qualified before May 31, 2016, including FSTDs that are initially qualified under the grace period conditions as defined in \$60.15(c):
- a. Objective testing for stall characteristics (Table A2A, test 2.c.8.a.) will only be required for the (wings level) second segment climb and approach or landing flight conditions. In lieu of objective testing for the high altitude cruise and turning flight stall conditions, these maneuvers may be subjectively evaluated by a qualified subject matter expert (SME) pilot and addressed in the required statement of compliance.
- b. Where existing flight test validation data in the FSTD's Master Qualification Test Guide (MQTG) is missing required parameters or is otherwise unsuitable to fully meet the objective testing requirements of this Directive, the FAA may accept alternate sources of validation, including subjective validation by an SME pilot with direct experience in the stall characteristics of the aircraft.

- c. Objective testing for characteristic motion vibrations (Stall buffet—Table A2A, test 3.f.5) is not required where the FSTD's stall buffets have been subjectively evaluated by an SME pilot. For previously qualified Level D FSTDs that currently have objective stall buffet tests in their approved MQTG, the results of these existing tests must be provided to the FAA with the updated stall and stall buffet models in place.
- d. As described in Attachment 7 of this Appendix, the FAA may accept a statement of compliance from the data provider which confirms the stall characteristics have been subjectively evaluated by an SME pilot on an engineering simulator or development simulator that is acceptable to the FAA. Where this evaluation takes place on an engineering or development simulator, additional objective "proof-of-match" testing for all flight conditions as described in tests 2.c.8.a. and 3.f.5.will be required to verify the implementation of the stall model and stall buffets on the training FSTD.
- 5. Where qualification is being sought to conduct full stall training tasks in accordance with this Directive, the FSTD Sponsor must conduct the required evaluations and modifications as prescribed in this Directive and report compliance to the responsible Flight Standards office in accordance with §60.23 using the standardized FSTD Sponsor Notification Form. At a minimum, this form must be accompanied with the following information:
- a. A description of any modifications to the FSTD (in accordance with §60.23) necessary to meet the requirements of this Directive.
- b. Statements of Compliance (High Angle of Attack Modeling/Stick Pusher System)—See Table A1A, Section 2.m., 3.f., and Attachment 7
- c. Statement of Compliance (SME Pilot Evaluation)—See Table A1A, Section 2.m. and Attachment 7
- d. Copies of the required objective test results as described above in sections 3.c., 3.d., and 3.e.
- 6. The responsible Flight Standards office will review each submission to determine if the requirements of this Directive have been met and respond to the FSTD Sponsor as described in §60.23(c). Additional responsible Flight Standards office conducted FSTD evaluations may be required before the modified FSTD is placed into service. This response, along with any noted restrictions, will serve as interim qualification for full stall training tasks until such time that a permanent change is made to the Statement of Qualification (SOQ) at the FSTD's next scheduled evaluation.

SECTION II—EVALUATION REQUIREMENTS FOR UPSET PREVENTION AND RECOVERY TRAINING TASKS

- 1. This section applies to previously qualified FSTDs being used to obtain training, testing, or checking credits for upset prevention and recovery training tasks (UPRT) as defined in Appendix A, Table A1A, Section 2.n. of this part. Additionally, FSTDs being used for unusual attitude training maneuvers that are intended to exceed the parameters of an aircraft upset must also be evaluated and qualified for UPRT under this section. These parameters include pitch attitudes greater than 25 degrees nose up; pitch attitudes greater than 10 degrees nose down, and bank angles greater than 45 degrees.
- 2. The requirements contained in this section are intended to define minimum standards for evaluating an FSTD for use in upset prevention and recovery training maneuvers that may exceed an aircraft's normal flight envelope. These standards include the evaluation of qualified training maneuvers against the FSTD's validation envelope and providing the instructor with minimum feedback tools for the purpose of determining if a training maneuver is conducted within FSTD validation limits and the aircraft's operating limits.
- 3. This Directive contains additional subjective testing that exceeds the evaluation requirements of previously qualified FSTDs. Where aerodynamic modeling data or validation data is not available or insufficient to meet the requirements of this Directive, the responsible Flight Standards office may limit additional qualification to certain upset prevention and recovery maneuvers where adequate data exists.
- 4. After March 12, 2019, any FSTD being used to obtain training, testing, or checking credit for upset prevention and recovery training tasks in an FAA approved flight training program must be evaluated and issued additional qualification in accordance with this Directive and the following sections of Appendix A of this part:
- a. Table A1A, General Requirements, Section 2.n. (Upset Prevention and Recovery)
- b. Table A3A, Functions and Subjective Testing, Test 5.b.3. (Upset Prevention and Recovery Maneuvers)
- c. Attachment 7, Additional Simulator Qualification Requirements for Stall, Upset Prevention and Recovery, and Engine and Airframe Icing Training Tasks (Upset Prevention and Recovery Training Maneuver Evaluation)
- 5. Where qualification is being sought to conduct upset prevention and recovery training tasks in accordance with this Directive, the FSTD Sponsor must conduct the required evaluations and modifications as prescribed in this Directive and report compliance to the responsible Flight Standards of-

fice in accordance with \$60.23 using the standardized FSTD Sponsor Notification Form. At a minimum, this form must be accompanied with the following information:

- a. A description of any modifications to the FSTD (in accordance with §60.23) necessary to meet the requirements of this Directive.
- b. Statement of Compliance (FSTD Validation Envelope)—See Table A1A, Section 2.n. and Attachment 7
- c. A confirmation statement that the modified FSTD has been subjectively evaluated by a qualified pilot as described in 60.16(a)(1)(iii).
- 6. The responsible Flight Standards office will review each submission to determine if the requirements of this Directive have been met and respond to the FSTD Sponsor as described in §60.23(c). Additional responsible Flight Standards office conducted FSTD evaluations may be required before the modified FSTD is placed into service. This response, along with any noted restrictions, will serve as an interim qualification for upset prevention and recovery training tasks until such time that a permanent change is made to the Statement of Qualification (SOQ) at the FSTD's next scheduled evaluation

SECTION III—EVALUATION REQUIREMENTS FOR ENGINE AND AIRFRAME ICING TRAINING TASKS

- 1. This section applies to previously qualified Level C and Level D FSTDs being used to obtain training, testing, or checking credits in maneuvers that demonstrate the effects of engine and airframe ice accretion.
- 2. The requirements in this section are intended to supersede and improve upon existing Level C and Level D FSTD evaluation requirements on the effects of engine and airframe icing. The requirements define a minimum level of fidelity required to adequately simulate the aircraft specific aerodynamic characteristics of an in-flight encounter with engine and airframe ice accretion as necessary to accomplish training objectives.
- 3. This Directive contains additional subjective testing that exceeds the evaluation requirements of previously qualified FSTDs. Where aerodynamic modeling data is not available or insufficient to meet the requirements of this Directive, the responsible Flight Standards office may limit qualified engine and airframe icing maneuvers where sufficient aerodynamic modeling data exists.
- 4. After March 12, 2019, any FSTD being used to conduct training tasks that demonstrate the effects of engine and airframe icing must be evaluated and issued additional qualification in accordance with this Directive and the following sections of Appendix A of this part:
- a. Table A1A, General Requirements, Section 2.j. (Engine and Airframe Icing)

- b. Attachment 7, Additional Simulator Qualification Requirements for Stall, Upset Prevention and Recovery, and Engine and Airframe Icing Training Tasks (Engine and Airframe Icing Evaluation; Paragraphs 1, 2, and 3). Objective demonstration tests of engine and airframe icing effects (Attachment 2, Table A2A, test 2.i. of this Appendix) are not required for previously qualified FSTDs.
- 5. Where continued qualification is being sought to conduct engine and airframe icing training tasks in accordance with this Directive, the FSTD Sponsor must conduct the required evaluations and modifications as prescribed in this Directive and report compliance to the responsible Flight Standards office in accordance with \$60.23 using the standardized FSTD Sponsor Notification Form. At a minimum, this form must be accompanied with the following information:
- a. A description of any modifications to the FSTD (in accordance with §60.23) necessary to meet the requirements of this Directive;
- b. Statement of Compliance (Ice Accretion Model)—See Table A1A, Section 2.j., and Attachment 7; and
- c. A confirmation statement that the modified FSTD has been subjectively evaluated by a qualified pilot as described in \$60.16(a)(1)(iii).
- 6. The responsible Flight Standards office will review each submission to determine if the requirements of this Directive have been met and respond to the FSTD Sponsor as described in §60.23(c). Additional responsible Flight Standards office conducted FSTD evaluations may be required before the modified FSTD is placed into service. This response, along with any noted restrictions, will serve as an interim update to the FSTD's Statement of Qualification (SOQ) until such time that a permanent change is made to the SOQ at the FSTD's next scheduled evaluation.

SECTION IV—EVALUATION REQUIREMENTS FOR TAKEOFF AND LANDING IN GUSTING CROSSWIND

- 1. This section applies to previously qualified FSTDs that will be used to obtain training, testing, or checking credits in takeoff and landing tasks in gusting crosswinds as part of an FAA approved training program. The requirements of this Directive are applicable only to those Level B and higher FSTDs that are qualified to conduct takeoff and landing training tasks.
- 2. The requirements in this section introduce new minimum simulator requirements for gusting crosswinds during takeoff and landing training tasks as well as additional subjective testing that exceeds the evaluation requirements of previously qualified FSTDs.
- 3. After March 12, 2019, any FSTD that is used to conduct gusting crosswind takeoff

and landing training tasks must be evaluated and issued additional qualification in accordance with this Directive and the following sections of Appendix A of this part:

- a. Table A1A, General Requirements, Section 2.d.3. (Ground Handling Characteristics);
- b. Table A3A, Functions and Subjective Testing Requirements, test 3.a.3 (Takeoff, Crosswind—Maximum Demonstrated and Gusting Crosswind); and
- c. Table A3A, Functions and Subjective Testing Requirements, test 8.d. (Approach and landing with crosswind—Maximum Demonstrated and Gusting Crosswind).
- 4. Where qualification is being sought to conduct gusting crosswind training tasks in accordance with this Directive, the FSTD Sponsor must conduct the required evaluations and modifications as prescribed in this Directive and report compliance to the responsible Flight Standards office in accordance with §60.23 using the standardized FSTD Sponsor Notification Form. At a minimum, this form must be accompanied with the following information:
- a. A description of any modifications to the FSTD (in accordance with §60.23) necessary to meet the requirements of this Directive.
- b. Statement of Compliance (Gusting Crosswind Profiles)—See Table A1A, Section 2.d.3.
- c. A confirmation statement that the modified FSTD has been subjectively evaluated by a qualified pilot as described in §60.16(a)(1)(iii).
- 5. The responsible Flight Standards office will review each submission to determine if the requirements of this Directive have been met and respond to the FSTD Sponsor as described in §60.23(c). Additional responsible Flight Standards office conducted FSTD evaluations may be required before the modified FSTD is placed into service. This response, along with any noted restrictions, will serve as an interim qualification for gusting crosswind training tasks until such time that a permanent change is made to the Statement of Qualification (SOQ) at the FSTD's next scheduled evaluation.

SECTION V—EVALUATION REQUIREMENTS FOR BOUNCED LANDING RECOVERY TRAINING TASKS

- 1. This section applies to previously qualified FSTDs that will be used to obtain training, testing, or checking credits in bounced landing recovery as part of an FAA approved training program. The requirements of this Directive are applicable only to those Level B and higher FSTDs that are qualified to conduct takeoff and landing training tasks.
- 2. The evaluation requirements in this section are intended to introduce new evaluation requirements for bounced landing recovery training tasks and contains additional

- 3. After March 12, 2019, any FSTD that is used to conduct bounced landing training tasks must be evaluated and issued additional qualification in accordance with this Directive and the following sections of Appendix A of this Part:
- a. Table A1A, General Requirements, Section 2.d.2. (Ground Reaction Characteristics)
- b. Table A3A, Functions and Subjective Testing Requirements, test 9.e. (Missed Approach—Bounced Landing)
- 4. Where qualification is being sought to conduct bounced landing training tasks in accordance with this Directive, the FSTD Sponsor must conduct the required evaluations and modifications as prescribed in this Directive and report compliance to the responsible Flight Standards office in accordance with §60.23 using the standardized FSTD Sponsor Notification Form. At a minimum, this form must be accompanied with the following information:
- A description of any modifications to the FSTD (in accordance with §60.23) necessary to meet the requirements of this Directive;
 and
- b. A confirmation statement that the modified FSTD has been subjectively evaluated by a qualified pilot as described in \$60.16(a)(1)(iii).
- 5. The responsible Flight Standards office will review each submission to determine if the requirements of this Directive have been met and respond to the FSTD Sponsor as described in §60.23(c). Additional responsible Flight Standards office conducted FSTD evaluations may be required before the modified FSTD is placed into service. This response, along with any noted restrictions, will serve as an interim qualification for bounced landing recovery training tasks until such time that a permanent change is made to the Statement of Qualification (SOQ) at the FSTD's next scheduled evaluation

ATTACHMENT 7 TO APPENDIX A TO PART 60— ADDITIONAL SIMULATOR QUALIFICATION RE-QUIREMENTS FOR STALL, UPSET PREVENTION AND RECOVERY, AND ENGINE AND AIRFRAME ICING TRAINING TASKS

BEGIN QPS REQUIREMENTS

A. High Angle of Attack Model Evaluation (Table A1A, Section 2.m.)

1. Applicability: This attachment applies to all simulators that are used to satisfy training requirements for stall maneuvers that are conducted at angles of attack beyond the activation of the stall warning system. This attachment is not applicable for those FSTDs that are only qualified for ap-

proach to stall maneuvers where recovery is initiated at the first indication of the stall. The material in this section is intended to supplement the general requirements, objective testing requirements, and subjective testing requirements contained within Tables A1A, A2A, and A3A, respectively.

- 2. General Requirements: The requirements for high angle of attack modeling are intended to evaluate the recognition cues and performance and handling qualities of a developing stall through the stall identification angle-of-attack and recovery. Strict time-history-based evaluations against flight test data may not adequately validate the aerodynamic model in an unsteady and potentially unstable flight regime, such as stalled flight. As a result, the objective testing requirements defined in Table A2A do not prescribe strict tolerances on any parameter at angles of attack beyond the stall identification angle of attack. In lieu of mandating such objective tolerances, a Statement of Compliance (SOC) will be required to define the source data and methods used to develop the stall aerodynamic model.
- 3. Fidelity Requirements: The requirements defined for the evaluation of full stall training maneuvers are intended to provide the following levels of fidelity:
- a. Airplane type specific recognition cues of the first indication of the stall (such as the stall warning system or aerodynamic stall buffet):
- b. Airplane type specific recognition cues of an impending aerodynamic stall; and
- c. Recognition cues and handling qualities from the stall break through recovery that are sufficiently exemplar of the airplane being simulated to allow successful completion of the stall recovery training tasks.

For the purposes of stall maneuver evaluation, the term "exemplar" is defined as a level of fidelity that is type specific of the simulated airplane to the extent that the training objectives can be satisfactorily accomplished.

- 4. Statement of Compliance (Aerodynamic Model): At a minimum, the following must be addressed in the SOC:
- a. Source Data and Modeling Methods: The SOC must identify the sources of data used to develop the aerodynamic model. These data sources may be from the airplane original equipment manufacturer (OEM), the original FSTD manufacturer/data provider, or other data provider acceptable to the FAA. Of particular interest is a mapping of test points in the form of alpha/ beta envelope plot for a minimum of flaps up and flaps down aircraft configurations. For the flight test data, a list of the types of maneuvers used to define the aerodynamic model for angle of attack ranges greater than the first indication of stall must be provided per flap setting. In cases

where it is impractical to develop and validate a stall model with flight-test data (e.g.), due to safety concerns involving the collection of flight test data past a certain angle of attack), the data provider is expected to make a reasonable attempt to develop a stall model through the required angle of attack range using analytical methods and empirical data (e.g.), wind-tunnel data);

- b. Validity Range: The FSTD sponsor must declare the range of angle of attack and sideslip where the aerodynamic model remains valid for training. For stall recovery training tasks, satisfactory aerodynamic model fidelity must be shown through at least 10 degrees beyond the stall identification angle of attack. For the purposes of determining this validity range, the stall identification angle of attack is defined as the angle of attack where the pilot is given a clear and distinctive indication to cease any further increase in angle of attack where one or more of the following characteristics occur:
- No further increase in pitch occurs when the pitch control is held at the full aft stop for 2 seconds, leading to an inability to arrest descent rate;
- ii. An uncommanded nose down pitch that cannot be readily arrested, which may be accompanied by an uncommanded rolling motion:
- iii. Buffeting of a magnitude and severity that is a strong and effective deterrent to further increase in angle of attack; and

iv. Activation of a stick pusher.

- The model validity range must also be capable of simulating the airplane dynamics as a result of a pilot initially resisting the stick pusher in training. For aircraft equipped with a stall envelope protection system, the model validity range must extend to 10 degrees of angle of attack beyond the stall identification angle of attack with the protection systems disabled or otherwise degraded (such as a degraded flight control mode as a result of a pitot/static system failure).
- c. Model Characteristics: Within the declared range of model validity, the SOC must address, and the aerodynamic model must incorporate, the following stall characteristics where applicable by aircraft type:
- Degradation in static/dynamic lateral-directional stability;
- ii. Degradation in control response (pitch, roll, yaw);
- iii. Uncommanded roll acceleration or rolloff requiring significant control deflection to counter:
- iv. Apparent randomness or non-repeatability;
- v. Changes in pitch stability;
- vi. Stall hysteresis;

vii. Mach effects;

viii. Stall buffet; and

ix. Angle of attack rate effects.

- An overview of the methodology used to address these features must be provided.
- 5. Statement of Compliance (Subject Matter Expert Pilot Evaluation): The sponsor must provide an SOC that confirms the FSTD has been subjectively evaluated by a subject matter expert (SME) pilot who is knowledgeable of the aircraft's stall characteristics. In order to qualify as an acceptable SME to evaluate the FSTD's stall characteristics, the SME must meet the following requirements:
- a. Has held a type rating/qualification in the aircraft being simulated;
- b. Has direct experience in conducting stall maneuvers in an aircraft that shares the same type rating as the make, model, and series of the simulated aircraft. This stall experience must include hands on manipulation of the controls at angles of attack sufficient to identify the stall (e.g., deterrent buffet, stick pusher activation, etc.) through recovery to stable flight:
- c. Where the SME's stall experience is on an airplane of a different make, model, and series within the same type rating, differences in aircraft specific stall recognition cues and handling characteristics must be addressed using available documentation. This documentation may include aircraft operating manuals, aircraft manufacturer flight test reports, or other documentation that describes the stall characteristics of the aircraft; and
- d. Must be familiar with the intended stall training maneuvers to be conducted in the FSTD (e.g., general aircraft configurations, stall entry methods, etc.) and the cues necessary to accomplish the required training objectives. The purpose of this requirement is to ensure that the stall model has been sufficiently evaluated in those general aircraft configurations and stall entry methods that will likely be conducted in training.

This SOC will only be required once at the time the FSTD is initially qualified for stall training tasks as long as the FSTD's stall model remains unmodified from what was originally evaluated and qualified. Where an FSTD shares common aerodynamic and flight control models with that of an engineering simulator or development simulator that is acceptable to the FAA, the FAA will accept an SOC from the data provider that confirms the stall characteristics have been subjectively assessed by an SME pilot on the engineering or development simulator.

An FSTD sponsor may submit a request to the Administrator for approval of a deviation from the SME pilot experience requirements in this paragraph. This request for deviation must include the following information:

- a. An assessment of pilot availability that demonstrates that a suitably qualified pilot meeting the experience requirements of this section cannot be practically located; and
- b. Alternative methods to subjectively evaluate the FSTD's capability to provide the stall recognition cues and handling characteristics needed to accomplish the training objectives.
- B. Upset Prevention and Recovery Training (UPRT) Maneuver Evaluation (Table A1A, Section 2.n.)
- 1. Applicability: This attachment applies to all simulators that are used to satisfy training requirements for upset prevention and recovery training (UPRT) maneuvers. For the purposes of this attachment (as defined in the Airplane Upset Recovery Training Aid), an aircraft upset is generally defined as an airplane unintentionally exceeding the following parameters normally experienced in line operations or training:
- a. Pitch attitude greater than 25 degrees nose up;
- b. Pitch attitude greater than 10 degrees nose down:
- c. Bank angles greater than 45 degrees; and
- d. Within the above parameters, but flying at airspeeds inappropriate for the conditions. FSTDs that will be used to conduct training maneuvers where the FSTD is either repositioned into an aircraft upset condition or an artificial stimulus (such as weather phenomena or system failures) is applied that is intended to result in a flightcrew entering an aircraft upset condition must be evaluated and qualified in accordance with this section.
- 2. General Requirements: The general requirement for UPRT qualification in Table AlA defines three basic elements required for qualifying an FSTD for UPRT maneuvers:
- a. FSTD Training Envelope: Valid UPRT should be conducted within the high and moderate confidence regions of the FSTD validation envelope as defined in paragraph 3 below.
- b. Instructor Feedback: Provides the instructor/evaluator with a minimum set of feedback tools to properly evaluate the trainee's performance in accomplishing an upset recovery training task.
- c. Upset Scenarios: Where dynamic upset scenarios or aircraft system malfunctions are used to stimulate the FSTD into an aircraft upset condition, specific guidance must be available to the instructor on the IOS that describes how the upset scenario is driven along with any malfunction or degradation in FSTD functionality that is required to stimulate the upset.
- 3. FSTD Validation Envelope: For the purposes of this attachment, the term "flight

- envelope" refers to the entire domain in which the FSTD is capable of being flown with a degree of confidence that the FSTD responds similarly to the airplane. This envelope can be further divided into three subdivisions (see Appendix 3-D of the Airplane Upset Recovery Training Aid):
- a. Flight test validated region: This is the region of the flight envelope which has been validated with flight test data, typically by comparing the performance of the FSTD against the flight test data through tests incorporated in the QTG and other flight test data utilized to further extend the model beyond the minimum requirements. Within this region, there is high confidence that the simulator responds similarly to the aircraft. Note that this region is not strictly limited to what has been tested in the QTG; as long as the aerodynamics mathematical model has been conformed to the flight test results, that portion of the mathematical model can be considered to be within the flight test validated region.
- b. Wind tunnel and/or analytical region: This is the region of the flight envelope for which the FSTD has not been compared to flight test data, but for which there has been wind tunnel testing or the use of other reliable predictive methods (typically by the aircraft manufacturer) to define the aerodynamic model. Any extensions to the aerodynamic model that have been evaluated in accordance with the definition of an exemplar stall model (as described in the stall maneuver evaluation section) must be clearly indicated. Within this region, there is moderate confidence that the simulator will respond similarly to the aircraft.
- c. Extrapolated: This is the region extrapolated beyond the flight test validated and wind tunnel/analytical regions. The extrapolation may be a linear extrapolation, a holding of the last value before the extrapolation began, or some other set of values. Whether this extrapolated data is provided by the aircraft or simulator manufacturer, it is a "best guess" only. Within this region, there is low confidence that the simulator will respond similarly to the aircraft. Brief excursions into this region may still retain a moderate confidence level in FSTD fidelity; however, the instructor should be aware that the FSTD's response may deviate from the actual air-
- 4. Instructor Feedback Mechanism: For the instructor/evaluator to provide feedback to the student during UPRT maneuver training, additional information must be accessible that indicates the fidelity of the simulation, the magnitude of trainee's flight control inputs, and aircraft operational limits that could potentially affect the successful completion of the maneuver(s). At a minimum,

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. A

the following must be available to the instructor/evaluator:

- a. FSTD Validation Envelope: The FSTD must employ a method to display the FSTD's expected fidelity with respect to the FSTD validation envelope. This may be displayed as an angle of attack vs sideslip (alpha/beta) envelope cross-plot on the Instructor Operating System (IOS) or other alternate method to clearly convey the FSTD's fidelity level during the maneuver. The cross-plot or other alternative method must display the relevant validity regions for flaps up and flaps down at a minimum. This validation envelope must be derived by the aerodynamic data provider or derived using information and data sources provided by the original aerodynamic data provider.
- b. Flight Control Inputs: The FSTD must employ a method for the instructor/evaluator to assess the trainee's flight control inputs during the upset recovery maneuver. Additional parameters, such as cockpit control forces (forces applied by the pilot to the controls) and the flight control law mode for fly-by-wire aircraft, must be portrayed in this feedback mechanism as well. For passive sidesticks, whose displacement is the flight control input, the force applied by the pilot to the controls does not need to be displayed. This tool must include a time history or other equivalent method of recording flight control positions
- c. Aircraft Operational Limits: The FSTD must employ a method to provide the in-

structor/evaluator with real-time information concerning the aircraft operating limits. The simulated aircraft's parameters must be displayed dynamically in real-time and also provided in a time history or equivalent format. At a minimum, the following parameters must be available to the instructor:

- i. Airspeed and airspeed limits, including the stall speed and maximum operating limit airspeed (Vmo/Mmo);
- ii. Load factor and operational load factor limits; and
- iii. Angle of attack and the stall identification angle of attack. See section A, paragraph 4.b. of this attachment for additional information concerning the definition of the stall identification angle of attack. This parameter may be displayed in conjunction with the FSTD validation envelope.

END QPS REQUIREMENTS

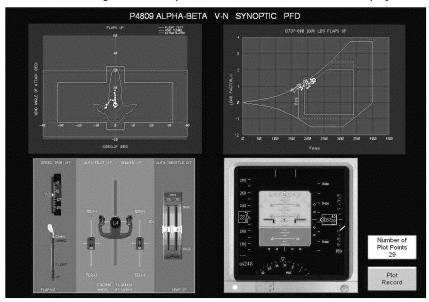
BEGIN INFORMATION

An example FSTD "alpha/beta" envelope display and IOS feedback mechanism are shown below in Figure 1 and Figure 2. The following examples are provided as guidance material on one possible method to display the required UPRT feedback parameters on an IOS display. FSTD sponsors may develop other methods and feedback mechanisms that provide the required parameters and support the training program objectives.

P4801 ALPHA-BETA PLOT

Figure 1 – Example FSTD Alpha/Beta Envelope Plot

Figure 2 – Example IOS Instructor UPRT Feedback Display



END INFORMATION

BEGIN QPS REQUIREMENTS

- C. Engine and Airframe Icing Evaluation (Table AIA. Section 2.j.)
- 1. Applicability: This section applies to all FSTDs that are used to satisfy training requirements for engine and airframe icing. New general requirements and objective requirements for simulator qualification have been developed to define aircraft specific icing models that support training objectives for the recognition and recovery from an inflight ice accretion event.
- 2. General Requirements: The qualification of engine and airframe icing consists of the following elements that must be considered when developing ice accretion models for use in training:
- a. Ice accretion models must be developed to account for training the specific skills required for recognition of ice accumulation and execution of the required response.
- b. Ice accretion models must be developed in a manner to contain aircraft specific recognition cues as determined with aircraft OEM supplied data or other suitable analytical methods.
- c. At least one qualified ice accretion model must be objectively tested to demonstrate that the model has been implemented correctly and generates the correct cues as necessary for training.
- 3. Statement of Compliance: The SOC as described in Table A1A, Section 2.j. must contain the following information to support FSTD qualification of aircraft specific ice accretion models:
- a. A description of expected aircraft specific recognition cues and degradation effects due to a typical in-flight icing encounter. Typical cues may include loss of lift, decrease in stall angle of attack, changes in pitching moment, decrease in control effectiveness, and changes in control forces in addition to any overall increase in drag. This description must be based upon relevant source data, such as aircraft OEM supplied data, accident/incident data, or other acceptable data sources. Where a particular airframe has demonstrated vulnerabilities to a specific type of ice accretion (due to accident/incident history) which requires specific training (such as supercooled large-droplet icing or tailplane icing), ice accretion models must be developed that address the training requirements.
- b. A description of the data sources utilized to develop the qualified ice accretion models. Acceptable data sources may be, but are not limited to, flight test data, aircraft certification data, aircraft OEM engineering simulation data, or other analytical methods based upon established engineering principles.

- 4. Objective Demonstration Testing: The purpose of the objective demonstration test is to demonstrate that the ice accretion models as described in the Statement of Compliance have been implemented correctly and demonstrate the proper cues and effects as defined in the approved data sources. At least one ice accretion model must be selected for testing and included in the Master Qualification Test Guide (MQTG). Two tests are required to demonstrate engine and airframe icing effects. One test will demonstrate the FSTDs baseline performance without icing, and the second test will demonstrate the aerodynamic effects of ice accretion relative to the baseline test.
- a. Recorded Parameters: In each of the two required MQTG cases, a time history recording must be made of the following parameters:
- i. Altitude;
- ii. Airspeed:
- iii. Normal Acceleration;
- iv. Engine Power/settings;
- v. Angle of Attack/Pitch attitude;
- vi. Bank Angle;
- vii. Flight control inputs;
- viii. Stall warning and stall buffet onset; and ix. Other parameters as necessary to demonstrate the effects of ice accretions.
- b. Demonstration maneuver: The FSTD sponsor must select an ice accretion model as identified in the SOC for testing. The selected maneuver must demonstrate the effects of ice accretion at high angles of attack from a trimmed condition through approach to stall and "full" stall as compared to a baseline (no ice buildup) test. The ice accretion models must demonstrate the cues necessary to recognize the onset of ice accretion on the airframe, lifting surfaces, and engines and provide representative degradation in performance and handling qualities to the extent that a recovery can be executed. Typical recognition cues that may be present depending upon the simulated aircraft include:
- i. Decrease in stall angle of attack;
- ii. Increase in stall speed;
- iii. Increase in stall buffet threshold of perception speed;
- iv. Changes in pitching moment;
- v. Changes in stall buffet characteristics:
- vi. Changes in control effectiveness or control forces; and
- vii. Engine effects (power variation, vibration, etc.);

The demonstration test may be conducted by initializing and maintaining a fixed amount of ice accretion throughout the maneuver in order to consistently evaluate the aero-dynamic effects.

END OPS REQUIREMENTS

[Doc. No. FAA-2002-12461, 73 FR 26490, May 9, 2008, as amended by Docket FAA-2014-0391, Amdt. 60-4, 81 FR 18218, 18219, 18240, 18283, 18300, and 18303, Mar. 30, 2016; 81 FR 32016 and 32066, May 20, 2016; Docket FAA-2018-0119, Amdt. 60-5, 83 FR 9170, Mar. 5, 2018; Amdt. 60-6, 83 FR 30275, June 27, 2018; Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75711, Dec. 9, 20221

APPENDIX B TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR AIR-PLANE FLIGHT TRAINING DEVICES

BEGIN INFORMATION

This appendix establishes the standards for Airplane FTD evaluation and qualification at Level 4, Level 5, Level 6, or Level 7. The Flight Standards Service, is responsible for the development, application, and implementation of the standards contained within this appendix. The procedures and criteria specified in this appendix will be used by the responsible Flight Standards office when conducting airplane FTD evaluations.

Table of Contents

- 1. Introduction
- 2. Applicability (§§ 60.1 and 60.2).
- 3. Definitions ($\S 60.3$).
- $\begin{array}{lll} \text{4.} & \text{Qualification} & \text{Performance} & \text{Standards} \\ & (\S 60.4). \end{array}$
- 5. Quality Management System (§60.5).
- 6. Sponsor Qualification Requirements $(\S 60.7)$.
- 7. Additional Responsibilities of the Sponsor (§60.9).
- 8. FTD Use (§60.11).
- 9. FTD Objective Data Requirements (§60.13).
- Special Equipment and Personnel Requirements for Qualification of the FTD (§60.14).
- Initial (and Upgrade) Qualification Requirements (§ 60.15).
- Additional Qualifications for Currently Qualified FTDs (§60.16).
- 13. Previously Qualified FTDs (§60.17).
- 14. Inspection, Continuing Qualification Evaluation, and Maintenance Requirements (§ 60.19).
- 15. Logging FTD Discrepancies (§60.20).
- 16. Interim Qualification of FTDs for New Airplane Types or Models (§60.21).
- 17. Modifications to FTDs (§60.23).
- 18. Operations with Missing, Malfunctioning, or Inoperative Components (§ 60.25).
- Automatic Loss of Qualification and Procedures for Restoration of Qualification (§ 60.27).

- 20. Other Losses of Qualification and Procedures for Restoration of Qualification (\$60.29).
- 21. Record Keeping and Reporting (§60.31).
- Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements (§60.33).
- 23. [Reserved]
- 24. Levels of FTD.
- 25. FTD Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA) (§ 60.37).
- Attachment 1 to Appendix B to Part 60—General FTD Requirements.
- Attachment 2 to Appendix B to Part 60—Flight Training Device (FTD) Objective Tests.
- Attachment 3 to Appendix B to Part 60— Flight Training Device (FTD) Subjective Evaluation.
- Attachment 4 to Appendix B to Part 60— Sample Documents.

END INFORMATION

1. Introduction

BEGIN INFORMATION

- a. This appendix contains background information as well as regulatory and informative material as described later in this section. To assist the reader in determining what areas are required and what areas are permissive, the text in this appendix is divided into two sections: "QPS Requirements" and "Information." The QPS Requirements sections contain details regarding compliance with the part 60 rule language. These details are regulatory, but are found only in this appendix. The Information sections contain material that is advisory in nature, and designed to give the user general information about the regulation.
- b. [Reserved]
- c. The responsible Flight Standards office encourages the use of electronic media for all communication, including any record, report, request, test, or statement required by this appendix. The electronic media used must have adequate security provisions and be acceptable to the responsible Flight Standards office.
 - d. Related Reading References.
 - (1) 14 CFR part 60.
 - (2) 14 CFR part 61.
 - (3) 14 CFR part 63.
 - (4) 14 CFR part 119.
 - (5) 14 CFR part 121.
 - (6) 14 CFR part 125.
 - (7) 14 CFR part 135.(8) 14 CFR part 141.
- (9) 14 CFR part 142.

on I APBH6H6I 3 with DISTILLE

- (10) AC 120-28, as amended, Criteria for Approval of Category III Landing Weather Minima.
- (11) AC 120-29, as amended, Criteria for Approving Category I and Category II Landing Minima for part 121 operators.
- (12) AC 120-35, as amended, Flightcrew Member Line Operational Simulations: Line-Oriented Flight Training, Special Purpose Operational Training, Line Operational Evaluation.
- (13) AC 120-41, as amended, Criteria for Operational Approval of Airborne Wind Shear Alerting and Flight Guidance Systems
- (14) AC 120-45, as amended, Airplane Flight Training Device Qualification.
- (14) AC 120-57, as amended, Surface Movement Guidance and Control System (SMGCS).
- (15) AC 150/5300–13, as amended, Airport Design.
- (16) AC 150/5340-1, as amended, Standards for Airport Markings.
- (17) AC 150/5340-4, as amended, Installation Details for Runway Centerline Touchdown Zone Lighting Systems.
- (18) AC 150/5340-19, as amended, Taxiway Centerline Lighting System.
- (19) AC 150/5340-24, as amended, Runway and Taxiway Edge Lighting System.
- (20) AC 150/5345–28, as amended, Precision Approach Path Indicator (PAPI) Systems.
- (21) International Air Transport Association document, "Flight Simulation Training Device Design and Performance Data Requirements," as amended.
 (22) AC 25-7, as amended, Flight Test Guide
- (22) AC 25–7, as amended, Flight Test Guide for Certification of Transport Category Airplanes.
- (23) AC 23-8A, as amended, Flight Test Guide for Certification of Part 23 Airplanes.
- (24) International Civil Aviation Organization (ICAO) Manual of Criteria for the Qualification of Flight Simulation Training Devices, as amended.
- (25) Aeroplane Flight Simulation Training Device Evaluation Handbook, Volume I, as amended and Volume II, as amended, The Royal Aeronautical Society, London, UK.
- (26) FAA Airman Certification Standards and Practical Test Standards for Airline Transport Pilot, Type Ratings, Commercial Pilot, and Instrument Ratings.
- (27) The FAA Aeronautical Information Manual (AIM). An electronic version of the AIM is on the Internet at http://www.faa.gov/atpubs.
- (28) Aeronautical Radio, Inc. (ARINC) document number 436, titled *Guidelines For Electronic Qualification Test Guide* (as amended).
- (29) Aeronautical Radio, Inc. (ARINC) document 610, Guidance for Design and Integration of Aircraft Avionics Equipment in Simulators (as amended).

14 CFR Ch. I (1-1-24 Edition)

END INFORMATION

2. Applicability (§§ 60.1 and 60.2)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.1, Applicability, or to §60.2, Applicability of sponsor rules to person who are not sponsors and who are engaged in certain unauthorized activities.

3. Definitions (§60.3)

See appendix F of this part for a list of definitions and abbreviations from part 1, part 60, and the QPS appendices of part 60.

4. QUALIFICATION PERFORMANCE STANDARDS (§ 60.4)

No additional regulatory or informational material applies to §60.4, Qualification Performance Standards.

5. QUALITY MANAGEMENT SYSTEM (§60.5)

Additional regulatory material and informational material regarding Quality Management Systems for FTDs may be found in appendix E of this part.

END INFORMATION

6. Sponsor Qualification Requirements. (§ 60.7).

BEGIN INFORMATION

- a. The intent of the language in §60.7(b) is to have a specific FTD, identified by the sponsor, used at least once in an FAA-approved flight training program for the airplane simulated during the 12-month period described. The identification of the specific FTD may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FTD at least once during the prescribed period. There is no minimum number of hours or minimum FTD periods required.
- b. The following examples describe acceptable operational practices:
- (1) Example One.
- (a) A sponsor is sponsoring a single, specific FTD for its own use, in its own facility or elsewhere— this single FTD forms the basis for the sponsorship. The sponsor uses that FTD at least once in each 12-month period in that sponsor's FAA-approved flight training program for the airplane simulated. This 12-month period is established according to the following schedule:
- (i) If the FTD was qualified prior to May 30, 2008, the 12-month period begins on the date of the first continuing qualification evaluation conducted in accordance with

- (ii) A device qualified on or after May 30, 2008, will be required to undergo an initial or upgrade evaluation in accordance with §60.15. Once the initial or upgrade evaluation is complete, the first continuing qualification evaluation will be conducted within 6 months. The 12 month continuing qualification evaluation cycle begins on that date and continues for each subsequent 12-month period.
- (b) There is no minimum number of hours of FTD use required.
- (c) The identification of the specific FTD may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FTD at least once during the prescribed period.
 - (2) Example Two.
- (a) A sponsor sponsors an additional number of FTDs, in its facility or elsewhere. Each additionally sponsored FTD must be—
- (i) Used by the sponsor in the sponsor's FAA-approved flight training program for the airplane simulated (as described in $\S60.7(\mathrm{d})(1)$); or
- (ii) Used by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the airplane simulated (as described in \$60.7(d)(1)). This 12-month period is established in the same manner as in example one; or
- (iii) Provided a statement each year from a qualified pilot, (after having flown the airplane, not the subject FTD or another FTD, during the preceding 12-month period) stating that the subject FTD's performance and handling qualities represent the airplane (as described in $\S60.7(d)(2)$). This statement is provided at least once in each 12-month period established in the same manner as in example one.
- (b) There is no minimum number of hours of FTD use required.
 - (3) Example Three.
- (a) A sponsor in New York (in this example, a Part 142 certificate holder) establishes "satellite" training centers in Chicago and Moscow.
- (b) The satellite function means that the Chicago and Moscow centers must operate under the New York center's certificate (in accordance with all of the New York center's practices, procedures, and policies; e.g., instructor and/or technician training/checking requirements, record keeping, QMS program).
- (c) All of the FTDs in the Chicago and Moscow centers could be dry-leased (i.e., the certificate holder does not have and use FAA-approved flight training programs for the FTDs in the Chicago and Moscow centers) because—
- (i) Each FTD in the Chicago center and each FTD in the Moscow center is used at least once each 12-month period by another

FAA certificate holder in that other certificate holder's FAA-approved flight training program for the airplane (as described in §60.7(d)(1)); or

(ii) A statement is obtained from a qualified pilot (having flown the airplane, not the subject FTD or another FTD during the preceding 12-month period) stating that the performance and handling qualities of each FTD in the Chicago and Moscow centers represents the airplane (as described in §60.7(d)(2)).

END INFORMATION

7. Additional Responsibilities of the Sponsor (§60.9)

BEGIN INFORMATION

The phrase "as soon as practicable" in §60.9(a) means without unnecessarily disrupting or delaying beyond a reasonable time the training, evaluation, or experience being conducted in the FTD.

8. FTD USE (§ 60.11)

No additional regulatory or informational material applies to §60.11, FTD use.

END INFORMATION

9. FTD Objective Data Requirements (§60.13)

BEGIN QPS REQUIREMENTS

- a. Flight test data used to validate FTD performance and handling qualities must have been gathered in accordance with a flight test program containing the following:
 - (1) A flight test plan consisting of:
- (a) The maneuvers and procedures required for aircraft certification and simulation programming and validation.
 - (b) For each maneuver or procedure—
- (i) The procedures and control input the flight test pilot and/or engineer used.
- (ii) The atmospheric and environmental conditions.
 - (iii) The initial flight conditions.
- (iv) The airplane configuration, including weight and center of gravity.
- (v) The data to be gathered.
- (vi) All other information necessary to recreate the flight test conditions in the FTD.
- (2) Appropriately qualified flight test personnel.
- (3) An understanding of the accuracy of the data to be gathered using appropriate alternative data sources, procedures, and instrumentation that is traceable to a recognized

standard as described in Attachment 2, Table B2F of this appendix.

- (4) Appropriate and sufficient data acquisition equipment or system(s), including appropriate data reduction and analysis methods and techniques, acceptable to the FAA's Aircraft Certification Service.
- b. The data, regardless of source, must be presented:
- (1) In a format that supports the FTD validation process;
- (2) In a manner that is clearly readable and annotated correctly and completely;
- (3) With resolution sufficient to determine compliance with the tolerances set forth in Attachment 2, Table B2A, Appendix B;
- (4) With any necessary guidance information provided; and
- (5) Without alteration, adjustments, or bias. Data may be corrected to address known data calibration errors provided that an explanation of the methods used to correct the errors appears in the QTG. The corrected data may be re-scaled, digitized, or otherwise manipulated to fit the desired presentation.
- c. After completion of any additional flight test, a flight test report must be submitted in support of the validation data. The report must contain sufficient data and rationale to support qualification of the FTD at the level requested.
- d. As required by §60.13(f), the sponsor must notify the responsible Flight Standards office when it becomes aware that an addition to or a revision of the flight related data or airplane systems related data is available if this data is used to program and operate a qualified FTD. The data referred to in this sub-section are those data that are used to validate the performance, handling qualities, or other characteristics of the aircraft, including data related to any relevant changes occurring after the type certification is issued. The sponsor must—
- (1) Within 10 calendar days, notify the responsible Flight Standards office of the existence of this data; and
- (2) Within 45 calendar days, notify the responsible Flight Standards office of—
- (i) The schedule to incorporate this data into the FTD; or
- (ii) The reason for not incorporating this data into the FTD.
- e. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot test results" in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.

END QPS REQUIREMENTS

REGIN INFORMATION

- f. The FTD sponsor is encouraged to maintain a liaison with the manufacturer of the aircraft being simulated (or with the holder of the aircraft type certificate for the aircraft being simulated if the manufacturer is no longer in business), and if appropriate, with the person having supplied the aircraft data package for the FTD in order to facilitate the notification described in this paragraph.
- g. It is the intent of the responsible Flight Standards office that for new aircraft entering service, at a point well in advance of preparation of the QTG, the sponsor should submit to the responsible Flight Standards office for approval, a descriptive document (see Appendix A, Table A2C, Sample Validation Data Roadmap for Airplanes) containing the plan for acquiring the validation data, including data sources. This document should clearly identify sources of data for all required tests, a description of the validity of these data for a specific engine type and thrust rating configuration, and the revision levels of all avionics affecting the performance or flying qualities of the aircraft. Additionally, this document should provide other information such as the rationale or explanation for cases where data or data parameters are missing, instances where engineering simulation data are used, or where flight test methods require further explanations. It should also provide a brief narrative describing the cause and effect of any deviation from data requirements. The aircraft manufacturer may provide this document.
- h. There is no requirement for any flight test data supplier to submit a flight test plan or program prior to gathering flight test data. However, the responsible Flight Standards office notes that inexperienced data gatherers often provide data that is irrelevant, improperly marked, or lacking adequate justification for selection. Other problems include inadequate information regarding initial conditions or test maneuvers. The responsible Flight Standards office has been forced to refuse these data submissions as validation data for an FTD evaluation. It is for this reason that the responsible Flight Standards office recommends that any data supplier not previously experienced in this area review the data necessary for programming and for validating the performance of the FTD and discuss the flight test plan anticipated for acquiring such data with the responsible Flight Standards office well in advance of commencing the flight tests.
- i. The responsible Flight Standards office will consider, on a case-by-case basis, whether to approve supplemental validation data derived from flight data recording systems such as a Quick Access Recorder or Flight Data Recorder.

END INFORMATION

10. SPECIAL EQUIPMENT AND PERSONNEL RE-QUIREMENTS FOR QUALIFICATION OF THE FTD (§60.14).

BEGIN INFORMATION

- a. In the event that the responsible Flight Standards office determines that special equipment or specifically qualified persons will be required to conduct an evaluation. the responsible Flight Standards office will make every attempt to notify the sponsor at least one (1) week, but in no case less than 72 hours, in advance of the evaluation. Examples of special equipment include flight control measurement devices, accelerometers, or oscilloscopes. Examples of specially qualified personnel include individuals specifically qualified to install or use any special equipment when its use is required.
- b. Examples of a special evaluation include an evaluation conducted after: An FTD is moved; at the request of the TPAA; or as a result of comments received from users of the FTD that raise questions about the continued qualification or use of the FTD.

END INFORMATION

11. Initial (and Upgrade) Qualification REQUIREMENTS (§ 60.15).

BEGIN QPS REQUIREMENT

- a. In order to be qualified at a particular qualification level, the FTD must:
- (1) Meet the general requirements listed in Attachment 1 of this appendix;
- (2) Meet the objective testing requirements listed in Attachment 2 of this appendix (Level 4 FTDs do not require objective tests);
- (3) Satisfactorily accomplish the subjective tests listed in Attachment 3 of this ap-
- b. The request described in §60.15(a) must include all of the following:
- (1) A statement that the FTD meets all of the applicable provisions of this part and all applicable provisions of the QPS.
- (2) Unless otherwise authorized through prior coordination with the responsible Flight Standards office, a confirmation that the sponsor will forward to the responsible Flight Standards office the statement described in §60.15(b) in such time as to be received no later than 5 business days prior to the scheduled evaluation and may be forwarded to the responsible Flight Standards office via traditional or electronic means.

- (3) Except for a Level 4 FTD, a QTG, acceptable to the responsible Flight Standards office, that includes all of the following:
- (a) Objective data obtained from aircraft testing or another approved source.
- (b) Correlating objective test results obtained from the performance of the FTD as prescribed in the appropriate QPS.
- (c) The result of FTD subjective tests prescribed in the appropriate QPS.
- (d) A description of the equipment necessary to perform the evaluation for initial qualification and the continuing qualification evaluations.
- c. The QTG described in paragraph a(3) of this section, must provide the documented proof of compliance with the FTD objective tests in Attachment 2, Table B2A of this appendix.
- d. The QTG is prepared and submitted by the sponsor, or the sponsor?s agent on behalf of the sponsor, to the responsible Flight Standards office for review and approval, and must include, for each objective test:
- (1) Parameters, tolerances, and flight conditions:
- (2) Pertinent and complete instructions for conducting automatic and manual tests;
- (3) A means of comparing the FTD test results to the objective data;
- (4) Any other information as necessary to assist in the evaluation of the test results:
- (5) Other information appropriate to the qualification level of the FTD.
- e. The QTG described in paragraphs (a)(3) and (b) of this section, must include the following:
- (1) A QTG cover page with sponsor and FAA approval signature blocks (see Attachment 4, Figure B4C, of this appendix, for a sample QTG cover page).
 - (2) [Reserved]
- (3) An FTD information page that provides the information listed in this paragraph, if applicable (see Attachment 4, Figure B4B, of this appendix, for a sample FTD information page). For convertible FTDs, the sponsor must submit a separate page for each configuration of the FTD.
- (a) The sponsor's FTD identification number or code.
- (b) The airplane model and series being simulated.
- (c) The aerodynamic data revision number or reference.
- (d) The source of the basic aerodynamic model and the aerodynamic coefficient data used to modify the basic model.
- (e) The engine model(s) and its data revision number or reference.
- (f) The flight control data revision number or reference
- (g) The flight management system identification and revision level.
 - (h) The FTD model and manufacturer.
 - (i) The date of FTD manufacture.

173

(j) The FTD computer identification.

- (k) The visual system model and manufacturer, including display type.
- (1) The motion system type and manufacturer, including degrees of freedom.
 - (4) A Table of Contents.
- (5) A log of revisions and a list of effective pages.
- (6) List of all relevant data references.
- (7) A glossary of terms and symbols used (including sign conventions and units).
- (8) Statements of compliance and capability (SOCs) with certain requirements.
- (9) Recording procedures or equipment required to accomplish the objective tests.
- (10) The following information for each objective test designated in Attachment 2 of this appendix, as applicable to the qualification level sought:
 - (a) Name of the test.
 - (b) Objective of the test.
 - (c) Initial conditions.
 - (d) Manual test procedures.
- (e) Automatic test procedures (if applicable).
- (f) Method for evaluating FTD objective test results.
- (g) List of all relevant parameters driven or constrained during the automatic test(s).
- (h) List of all relevant parameters driven or constrained during the manual test(s).
 - (i) Tolerances for relevant parameters.
- (j) Source of Validation Data (document and page number).
- (k) Copy of the Validation Data (if located in a separate binder, a cross reference for the identification and page number for pertinent data location must be provided).
- (1) FTD Objective Test Results as obtained by the sponsor. Each test result must reflect the date completed and must be clearly labeled as a product of the device being tested.
- f. A convertible FTD is addressed as a separate FTD for each model and series airplane to which it will be converted and for the FAA qualification level sought. The responsible Flight Standards office will conduct an evaluation for each configuration. If a sponsor seeks qualification for two or more models of an airplane type using a convertible FTD, the sponsor must provide a QTG for each airplane model, or a QTG for the first airplane model and a supplement to that QTG for each additional airplane model. The responsible Flight Standards office will conduct evaluations for each airplane model.
- g. The form and manner of presentation of objective test results in the QTG must include the following:
- (1) The sponsor's FTD test results must be recorded in a manner acceptable to the responsible Flight Standards office, that allows easy comparison of the FTD test results to the validation data (e.g., use of a multichannel recorder, line printer, cross plotting, overlays, transparencies).
- (2) FTD results must be labeled using terminology common to airplane parameters as

- opposed to computer software identifications.
- (3) Validation data documents included in a QTG may be photographically reduced only if such reduction will not alter the graphic scaling or cause difficulties in scale interpretation or resolution.
- (4) Scaling on graphical presentations must provide the resolution necessary to evaluate the parameters shown in Attachment 2, Table B2A of this appendix.
- (5) Tests involving time histories, data sheets (or transparencies thereof) and FTD test results must be clearly marked with appropriate reference points to ensure an accurate comparison between FTD and airplane with respect to time. Time histories recorded via a line printer are to be clearly identified for cross-plotting on the airplane data. Overplots may not obscure the reference data.
- h. The sponsor may elect to complete the QTG objective and subjective tests at the manufacturer's facility or at the sponsor's training facility (or other sponsor designated location where training will take place). If the tests are conducted at the manufacturer's facility, the sponsor must repeat at least one-third of the tests at the sponsor's training facility in order to substantiate FTD performance. The QTG must be clearly annotated to indicate when and where each test was accomplished. Tests conducted at the manufacturer's facility and at the sponsor's designated training facility must be conducted after the FTD is assembled with systems and sub-systems functional and operating in an interactive manner. The test results must be submitted to the responsible Flight Standards office.
- i. The sponsor must maintain a copy of the MQTG at the FTD location. $\,$
- j. All FTDs for which the initial qualification is conducted after May 30, 2014, must have an electronic MQTG (Emqtg) including all objective data obtained from airplane testing, or another approved source (reformatted or digitized), together with correlating objective test results obtained from the performance of the FTD (reformatted or digitized) as prescribed in this appendix. The Emqtg must also contain the general FTD performance or demonstration results (reformatted or digitized) prescribed in this appendix, and a description of the equipment necessary to perform the initial qualification evaluation and the continuing qualification evaluations. The Emqtg must include the original validation data used to validate FTD performance and handling qualities in either the original digitized format from the data supplier or an electronic scan of the original time-history plots that were provided by the data supplier. A copy of the Emgtg must be provided to the responsible Flight Standards office.
- k. All other FTDs (not covered in subparagraph "j") must have an electronic copy of

the MQTG by and after May 30, 2014. An electronic copy of the copy of the MQTG must be provided to the responsible Flight Standards office. This may be provided by an electronic scan presented in a Portable Document File (PDF), or similar format acceptable to the responsible Flight Standards office.

1. During the initial (or upgrade) qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FTD.

END QPS REQUIREMENTS

BEGIN INFORMATION

m. Only those FTDs that are sponsored by a certificate holder as defined in Appendix F will be evaluated by the responsible Flight Standards office. However, other FTD evaluations may be conducted on a case-by-case basis as the Administrator deems appropriate, but only in accordance with applicable agreements.

- n. The responsible Flight Standards office will conduct an evaluation for each configuration, and each FTD must be evaluated as completely as possible. To ensure a thorough and uniform evaluation, each FTD is subjected to the general FTD requirements in Attachment 1 of this appendix, the objective tests listed in Attachment 2 of this appendix, and the subjective tests listed in Attachment 3 of this appendix. The evaluations described herein will include, but not necessarily be limited to the following:
- (1) Airplane responses, including longitudinal and lateral-directional control responses (see Attachment 2 of this appendix);
- (2) Performance in authorized portions of the simulated airplane's operating envelope, to include tasks evaluated by the responsible Flight Standards office in the areas of surface operations, takeoff, climb, cruise, descent, approach and landing, as well as abnormal and emergency operations (see Attachment 2 of this appendix);
- (3) Control checks (see Attachment 1 and Attachment 2 of this appendix);
- (4) Flight deck configuration (see Attachment 1 of this appendix);
- (5) Pilot, flight engineer, and instructor station functions checks (see Attachment 1 and Attachment 3 of this appendix);
- (6) Airplane systems and sub-systems (as appropriate) as compared to the airplane simulated (see Attachment 1 and Attachment 3 of this appendix):
- (7) FTD systems and sub-systems, including force cueing (motion), visual, and aural (sound) systems, as appropriate (see Attachment 1 and Attachment 2 of this appendix); and

- (8) Certain additional requirements, depending upon the qualification level sought, including equipment or circumstances that may become hazardous to the occupants. The sponsor may be subject to Occupational Safety and Health Administration requirements.
- o. The responsible Flight Standards office administers the objective and subjective tests, which includes an examination of functions. The tests include a qualitative assessment of the FTD by a pilot from the responsible Flight Standards office. The evaluation team leader may assign other qualified personnel to assist in accomplishing the functions examination and/or the objective and subjective tests performed during an evaluation when required.
- (1) Objective tests provide a basis for measuring and evaluating FTD performance and determining compliance with the requirements of this part.
- (2) Subjective tests provide a basis for:
- (a) Evaluating the capability of the FTD to perform over a typical utilization period;
- (b) Determining that the FTD satisfactorily simulates each required task;
- (c) Verifying correct operation of the FTD controls, instruments, and systems; and
- (d) Demonstrating compliance with the requirements of this part.
- p. The tolerances for the test parameters listed in Attachment 2 of this appendix reflect the range of tolerances acceptable to the responsible Flight Standards office for FTD validation and are not to be confused with design tolerances specified for FTD manufacture. In making decisions regarding tests and test results, the responsible Flight Standards office relies on the use of operational and engineering judgment in the application of data (including consideration of the way in which the flight test was flown and way the data was gathered and applied), data presentations, and the applicable tolerances for each test.
- q. In addition to the scheduled continuing qualification evaluation, each FTD is subject to evaluations conducted by the responsible Flight Standards office at any time without prior notification to the sponsor. Such evaluations would be accomplished in a normal manner (i.e., requiring exclusive use of the FTD for the conduct of objective and subjective tests and an examination of functions) if the FTD is not being used for flight crewmember training, testing, or checking. However, if the FTD were being used, the evaluation would be conducted in a non-exclusive manner. This non-exclusive evaluation will be conducted by the FTD evaluator accompanying the check airman, instructor, Aircrew Program Designee (APD), or FAA inspector aboard the FTD along with the student(s) and observing the operation of the FTD during the training, testing, or checking activities.

- r. Problems with objective test results are handled as follows:
- (1) If a problem with an objective test result is detected by the evaluation team during an evaluation, the test may be repeated or the QTG may be amended.
- (2) If it is determined that the results of an objective test do not support the qualification level requested but do support a lower level, the responsible Flight Standards office may qualify the FTD at a lower level. For example, if a Level 6 evaluation is requested, but the FTD fails to meet the spiral stability test tolerances, it could be qualified at Level 5.
- s. After an FTD is successfully evaluated, the responsible Flight Standards office issues an SOQ to the sponsor, the responsible Flight Standards office recommends the FTD to the TPAA, who will approve the FTD for use in a flight training program. The SOQ will be issued at the satisfactory conclusion of the initial or continuing qualification evaluation and will list the tasks for which the FTD is qualified, referencing the tasks described in Table B1B in Attachment 1 of this appendix. However, it is the sponsor's responsibility to obtain TPAA approval prior to using the FTD in an FAA-approved flight training program.
- t. Under normal circumstances, the responsible Flight Standards office establishes a date for the initial or upgrade evaluation within ten (10) working days after determining that a complete QTG is acceptable. Unusual circumstances may warrant establishing an evaluation date before this determination is made. A sponsor may schedule an evaluation date as early as 6 months in advance. However, there may be a delay of 45 days or more in rescheduling and completing the evaluation if the sponsor is unable to meet the scheduled date. See Attachment 4, Figure B4A, Sample Request for Initial, Upgrade, or Reinstatement Evaluation, of this appendix.
- u. The numbering system used for objective test results in the QTG should closely follow the numbering system set out in Attachment 2, FTD Objective Tests, Table B2A, of this appendix.
- v. Contact the responsible Flight Standards office for additional information regarding the preferred qualifications of pilots used to meet the requirements of §60.15(d).
- w. Examples of the exclusions for which the FTD might not have been subjectively tested by the sponsor or the responsible Flight Standards office and for which qualification might not be sought or granted, as described in §60.15(g)(6), include engine out maneuvers or circling approaches.

12. Additional Qualifications for Currently Qualified FTDs (§60.16).

No additional regulatory or informational material applies to §60.16, Additional Qualifications for a Currently Qualified FTD.

END INFORMATION

13. Previously Qualified FTDs (§60.17).

BEGIN QPS REQUIREMENTS

- a. In instances where a sponsor plans to remove an FTD from active status for a period of less than two years, the following procedures apply:
- (1) The responsible Flight Standards office must be notified in writing and the notification must include an estimate of the period that the FTD will be inactive;
- (2) Continuing Qualification evaluations will not be scheduled during the inactive period:
- (3) The responsible Flight Standards office will remove the FTD from the list of qualified FTDs on a mutually established date not later than the date on which the first missed continuing qualification evaluation would have been scheduled;
- (4) Before the FTD is restored to qualified status, it must be evaluated by the responsible Flight Standards office. The evaluation content and the time required to accomplish the evaluation is based on the number of continuing qualification evaluations and sponsor-conducted quarterly inspections missed during the period of inactivity.
- (5) The sponsor must notify the responsible Flight Standards office of any changes to the original scheduled time out of service;
- b. FTDs qualified prior to May 31, 2016, and replacement FTD systems, are not required to meet the general FTD requirements, the objective test requirements, and the subjective test requirements of Attachments 1, 2, and 3 of this appendix as long as the FTD continues to meet the test requirements contained in the MQTG developed under the original qualification basis.
- c. [Reserved]
- d. FTDs qualified prior to May 31, 2016, may be updated. If an evaluation is deemed appropriate or necessary by the responsible Flight Standards office after such an update, the evaluation will not require an evaluation to standards beyond those against which the FTD was originally qualified.
- e. Other certificate holders or persons desiring to use an FTD may contract with FTD sponsors to use FTDs previously qualified at a particular level for an airplane type and approved for use within an FAA-approved flight training program. Such FTDs are not required to undergo an additional qualification process, except as described in §60.16.

- f. Each FTD user must obtain approval from the appropriate TPAA to use any FTD in an FAA-approved flight training program.
- g. The intent of the requirement listed in §60.17(b), for each FTD to have an SOQ within 6 years, is to have the availability of that statement (including the configuration list and the limitations to authorizations) to provide a complete picture of the FTD inventory regulated by the FAA. The issuance of the statement will not require any additional evaluation or require any adjustment to the evaluation basis for the FTD.
- h. Downgrading of an FTD is a permanent change in qualification level and will necessitate the issuance of a revised SOQ to reflect the revised qualification level, as appropriate. If a temporary restriction is placed on an FTD because of a missing, malfunctioning, or inoperative component or ongoing repairs, the restriction is not a permanent change in qualification level. Instead, the restriction is temporary and is removed when the reason for the restriction has been resolved.
- i. The responsible Flight Standards office will determine the evaluation criteria for an FTD that has been removed from active status for a prolonged period. The criteria will be based on the number of continuing qualification evaluations and quarterly inspections missed during the period of inactivity. For example, if the FTD were out of service for a 1 year period, it would be necessary to complete the entire QTG, since all of the quarterly evaluations would have been missed. The responsible Flight Standards office will also consider how the FTD was stored, whether parts were removed from the FTD and whether the FTD was disassembled.
- j. The FTD will normally be requalified using the FAA-approved MQTG and the criteria that was in effect prior to its removal from qualification. However, inactive periods of 2 years or more will require re-qualification under the standards in effect and current at the time of requalification.

END INFORMATION

14. INSPECTION, CONTINUING QUALIFICATION, EVALUATION, AND MAINTENANCE REQUIREMENTS (§ 60.19).

BEGIN QPS REQUIREMENT

a. The sponsor must conduct a minimum of four evenly spaced inspections throughout the year. The objective test sequence and content of each inspection in this sequence must be developed by the sponsor and must be acceptable to the responsible Flight Standards office.

- b. The description of the functional preflight check must be contained in the sponsor's QMS.
- c. Record "functional preflight" in the FTD discrepancy log book or other acceptable location, including any item found to be missing, malfunctioning, or inoperative.
- d. During the continuing qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FTD.

END QPS REQUIREMENTS

BEGIN INFORMATION

- e. The sponsor's test sequence and the content of each quarterly inspection required in §60.19(a)(1) should include a balance and a mix from the objective test requirement areas listed as follows:
 - (1) Performance.
 - (2) Handling qualities.
 - (3) Motion system (where appropriate).
- (4) Visual system (where appropriate).
- (5) Sound system (where appropriate).
- (6) Other FTD systems.
- f. If the evaluator plans to accomplish specific tests during a normal continuing qualification evaluation that requires the use of special equipment or technicians, the sponsor will be notified as far in advance of the evaluation as practical; but not less than 72 hours. Examples of such tests include latencies, control sweeps, or motion or visual system tests.
- g. The continuing qualification evaluations described in §60.19(b) will normally require 4 hours of FTD time. However, flexibility is necessary to address abnormal situations or situations involving aircraft with additional levels of complexity (e.g., computer controlled aircraft). The sponsor should anticipate that some tests may require additional time. The continuing qualification evaluations will consist of the following:
- (1) Review of the results of the quarterly inspections conducted by the sponsor since the last scheduled continuing qualification evaluation.
- (2) A selection of approximately 8 to 15 objective tests from the MQTG that provide an adequate opportunity to evaluate the performance of the FTD. The tests chosen will be performed either automatically or manually and should be able to be conducted within approximately one-third (1/3) of the allotted FTD time.
- (3) A subjective evaluation of the FTD to perform a representative sampling of the tasks set out in attachment 3 of this appendix. This portion of the evaluation should

take approximately two-thirds (2/3) of the allotted FTD time.

(4) An examination of the functions of the FTD may include the motion system, visual system, sound system as applicable, instructor operating station, and the normal functions and simulated malfunctions of the airplane systems. This examination is normally accomplished simultaneously with the subjective evaluation requirements.

h. The requirement established in §60.19(b)(4) regarding the frequency of responsible Flight Standards office-conducted continuing qualification evaluations for each FTD is typically 12 months. However, the establishment and satisfactory implementation of an approved QMS for a sponsor will provide a basis for adjusting the frequency of evaluations to exceed 12-month intervals.

15. Logging FTD Discrepancies (§60.20)

No additional regulatory or informational material applies to §60.20. Logging FTD Discrepancies.

16. INTERIM QUALIFICATION OF FTDs FOR NEW AIRPLANE TYPES OR MODELS (§ 60.21)

No additional regulatory or informational material applies to §60.21, Interim Qualification of FTDs for New Airplane Types or Models.

END INFORMATION

17. Modifications to FTDs ($\S60.23$)

BEGIN QPS REQUIREMENTS

a. The notification described in $\S60.23(c)(2)$ must include a complete description of the planned modification, with a description of the operational and engineering effect the proposed modification will have on the operation of the FTD and the results that are expected with the modification incorporated.

b. Prior to using the modified FTD:

(1) All the applicable objective tests completed with the modification incorporated, including any necessary updates to the MQTG (e.g., accomplishment of FSTD Directives) must be acceptable to the responsible Flight Standards office; and

(2) The sponsor must provide the responsible Flight Standards office with a statement signed by the MR that the factors listed in §60.15(b) are addressed by the appropriate personnel as described in that section.

END QPS REQUIREMENTS

BEGIN INFORMATION

c. FSTD Directives are considered modification of an FTD. See Attachment 4 of this

14 CFR Ch. I (1-1-24 Edition)

appendix for a sample index of effective FSTD Directives.

END INFORMATION

18. OPERATION WITH MISSING, MALFUNC-TIONING, OR INOPERATIVE COMPONENTS (§60.25)

BEGIN INFORMATION

a. The sponsor's responsibility with respect to §60.25(a) is satisfied when the sponsor fairly and accurately advises the user of the current status of an FTD, including any missing, malfunctioning, or inoperative (MMI) component(s).

b. It is the responsibility of the instructor, check airman, or representative of the administrator conducting training, testing, or checking to exercise reasonable and prudent judgment to determine if any MMI component is necessary for the satisfactory completion of a specific maneuver, procedure, or task.

c. If the 29th or 30th day of the 30-day period described in 60.25(b) is on a Saturday, a Sunday, or a holiday, the FAA will extend the deadline until the next business day.

d. In accordance with the authorization described in §60.25(b), the sponsor may develop a discrepancy prioritizing system to accomplish repairs based on the level of impact on the capability of the FTD. Repairs having a larger impact on the FTD's ability to provide the required training, evaluation, or flight experience will have a higher priority for repair or replacement.

END INFORMATION

19. Automatic Loss of Qualification and Procedures for Restoration of Qualification ($\S 60.27$)

BEGIN INFORMATION

If the sponsor provides a plan for how the FTD will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FTD is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing that required for requalification.

END INFORMATION

20. Other Losses of Qualification and Procedures for Restoration of Qualification (§ 60.29)

BEGIN INFORMATION

If the sponsor provides a plan for how the FTD will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FTD is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing that required for requalification.

END INFORMATION

21. RECORDKEEPING AND REPORTING (§60.31)

BEGIN QPS REQUIREMENTS

a. FTD modifications can include hardware or software changes. For FTD modifications involving software programming changes, the record required by \$60.31(a)(2) must consist of the name of the aircraft system software, aerodynamic model, or engine model change, the date of the change, a summary of the change, and the reason for the change.

b. If a coded form for record keeping is used, it must provide for the preservation and retrieval of information with appropriate security or controls to prevent the inappropriate alteration of such records after the fact.

END QPS REQUIREMENTS

 APPLICATIONS, LOGBOOKS, REPORTS, AND RECORDS: FRAUD, FALSIFICATION, OR INCOR-RECT STATEMENTS (§60.33)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.33, Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements.

END INFORMATION

23. [Reserved]

24. Levels of FTD.

BEGIN INFORMATION

a. The following is a general description of each level of FTD. Detailed standards and tests for the various levels of FTDs are fully defined in Attachments 1 through 3 of this appendix.

(1) Level 4. A device that may have an open airplane-specific flight deck area, or an enclosed airplane-specific flight deck and at least one operating system. Air/ground logic is required (no aerodynamic programming required). All displays may be flat/LCD panel representations or actual representations of displays in the aircraft. All controls, switches, and knobs may be touch sensitive activation (not capable of manual manipulation of the flight controls) or may physically replicate the aircraft in control operation.

(2) Level 5. A device that may have an open airplane-specific flight deck area, or an enclosed airplane-specific flight deck; generic aerodynamic programming; at least one operating system; and control loading that is representative of the simulated airplane only at an approach speed and configuration. All displays may be flat/LCD panel representations or actual representations of displays in the aircraft. Primary and secondary flight controls (e.g., rudder, aileron, elevator, flaps, spoilers/speed brakes, engine controls, landing gear, nosewheel steering, trim, brakes) must be physical controls. All other controls, switches, and knobs may be touch sensitive activation.

(3) Level 6. A device that has an enclosed airplane-specific flight deck; airplane-specific aerodynamic programming; all applicable airplane systems operating; control loading that is representative of the simulated airplane throughout its ground and flight envelope; and significant sound representation. All displays may be flat/LCD panel representations or actual representations of displays in the aircraft, but all controls, switches, and knobs must physically replicate the aircraft in control operation.

END INFORMATION

(4) Level 7. A Level 7 device is one that has an enclosed airplane-specific flight deck and aerodynamic program with all applicable airplane systems operating and control loading that is representative of the simulated airplane throughout its ground and flight envelope and significant sound representation. All displays may be flat/LCD panel representations or actual representations of displays in the aircraft, but all controls, switches, and knobs must physically replicate the aircraft in control operation. It also has a visual system that provides an out-of-the-flight deck view, providing cross-flight deck viewing (for both pilots simultaneously) of a

field-of-view of at least 180° horizontally and 40° vertically.

25. FTD QUALIFICATION ON THE BASIS OF A BI-LATERAL AVIATION SAFETY AGREEMENT (BASA) (§ 60.37)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.37, FTD Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA).

END INFORMATION

ATTACHMENT 1 TO APPENDIX B TO PART 60—GENERAL FTD REQUIREMENTS

BEGIN QPS REQUIREMENTS

1. Requirements

- a. Certain requirements included in this appendix must be supported with an SOC as defined in Appendix F, which may include objective and subjective tests. The requirements for SOCs are indicated in the "General FTD Requirements" column in Table B1A of this appendix.
- b. Table B1A describes the requirements for the indicated level of FTD. Many devices include operational systems or functions that exceed the requirements outlined in this section. In any event, all systems will be tested and evaluated in accordance with this appendix to ensure proper operation.

END QPS REQUIREMENTS

14 CFR Ch. I (1-1-24 Edition)

BEGIN INFORMATION

2. Discussion

- a. This attachment describes the general requirements for qualifying Level 4 through Level 6 FTDs. The sponsor should also consult the objectives tests in Attachment 2 of this appendix and the examination of functions and subjective tests listed in Attachment 3 of this appendix to determine the complete requirements for a specific level FTD.
- b. The material contained in this attachment is divided into the following categories:
 - (1) General Flight deck Configuration.
 - (2) Programming.
 - (3) Equipment Operation.
- (4) Equipment and facilities for instructor/evaluator functions.
- (5) Motion System.
- (6) Visual System.
- (7) Sound System.
- c. Table B1A provides the standards for the General FTD Requirements.
- d. Table B1B provides the tasks that the sponsor will examine to determine whether the FTD satisfactorily meets the requirements for flight crew training, testing, and experience, and provides the tasks for which the simulator may be qualified.
- e. Table B1C provides the functions that an instructor/check airman must be able to control in the simulator.
- f. It is not required that all of the tasks that appear on the List of Qualified Tasks (part of the SOQ) be accomplished during the initial or continuing qualification evaluation.

END INFORMATION

	INFORMATION		Notes	
			-	7
		FTD	Level	5 (
				4
Table B1A – Minimum FTD Requirement	QPS REQUIREMENTS		General FTD Requirements	•
		T. T. T.	FILLY	Number

1. Genera	1. General Flight deck Configuration.				
1.a.	The FTD must have a flight deck that is a replica of the airplane simulated	X	X	X X For FTD purposes, the flight	
	with controls, equipment, observable flight deck indicators, circuit breakers,			deck consists of all that space	
	and bulkheads properly located, functionally accurate and replicating the			forward of a cross section of	
	airplane. The direction of movement of controls and switches must be			the fuselage at the most	
	identical to that in the airplane. Pilot seat(s) must afford the capability for the			extreme aft setting of the	
	occupant to be able to achieve the design "eye position." Equipment for the			pilots' seats including	
	operation of the flight deck windows must be included, but the actual			additional, required flight	
	windows need not be operable. Fire axes, extinguishers, and spare light bulbs			crewmember duty stations and	
	must be available in the flight FTD, but may be relocated to a suitable			those required bulkheads aft of	
	location as near as practical to the original position. Fire axes, landing gear			the pilot seats. For	
	pins, and any similar purpose instruments need only be represented in			clarification, bulkheads	
	silhouette.			containing only items such as	
				landing gear pin storage	
				compartments, fire axes and	

Instruments replicate those of the airplane including full instrument

correct with differences, if any, being imperceptible to the pilot;

(1) All instruments and instrument panel layouts are dimensionally for FTD instruments and/or instrument panels is acceptable provided:

(4) Instrument display characteristics replicate those of the airplane

Instruments displayed are free of quantization (stepping);

(3)

functionality and embedded logic;

including: resolution, colors, luminance, brightness, fonts, fill Overlay or masking, including bezels and bugs, as applicable,

patterns, line styles and symbology;

replicates the airplane panel(s);

. ම

window panes may be omitted For Level 6 FTDs, flight deck subjectively acceptable to conduct qualified training where non-distracting and

×

×

training/checking events to be accomplished. The installed equipment must be instrument, when viewed from the principle operator's angle, should replicate that of the actual airplane instrument. Any instrument reading inaccuracy due flight deck area. Additional equipment required for the authorized training/checking events must be available in the FTD, but may be located in to viewing angle and parallax present in the actual airplane instrument should be duplicated in the simulated instrument display image. Viewing angle error located in a spatially correct location and may be in a flight deck or an open The FTD must have equipment (e.g., instruments, panels, systems, circuit mechanical instrument, should appear to have the same three dimensional and parallax must be minimized on shared instruments such and engine a suitable location as near as practical to the spatially correct position depth as the replicated instrument. The appearance of the simulated breakers, and controls) simulated sufficiently for the authorized displays and standby indicators

ER09DE22.058<//MATH>

As applicable, instruments must have faceplates that replicate those in

the airplane; and

8

Level 7 FTD only;

The display image of any three dimensional instrument, such as an electro-

commensurate with other lighting operated by that same control; and

the FSTD control for that lighting and, if applicable, is at a level

Instrument lighting replicates that of the airplane and is operated from

6

Instrument controls and switches replicate and operate with the same

technique, effort, travel and in the same direction as those in the

Actuation of equipment must replicate the appropriate function in the airplane. Fire axes, landing gear pins, and any similar purpose instruments need only be represented in silhouette.					
Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate.			X		_
2. Programming.					_
The FTD must provide the proper effect of aerodynamic changes for the combinations of drag and thrust normally encountered in flight. This must include the effect of change in airplane attitude, thrust, drag, altitude, temperature, and configuration. Level 6 additionally requires the effects of changes in gross weight and center of gravity. Level 5 requires only generic aerodynamic programming. An SOC is required.	×	X			
A flight dynamics model that accounts for various combinations of drag and thrust normally encountered in flight must correspond to actual flight conditions, including the effect of change in airplane attitude, thrust, drag, altitude, temperature, gross weight, moments of inertia, center of gravity location, and configuration. The effects of pitch attitude and of fuel slosh on the aircraft center of gravity must be simulated. An SOC is required.			X		
The FTD must have the computer capacity, accuracy, resolution, and dynamic response needed to meet the qualification level sought. An SOC is required.	X	×	×		
Relative responses of the flight deck instruments must be measured by latency tests, or transport delay tests, and may not exceed 300 milliseconds. The instruments must respond to abrupt input at the pilot's position within the allotted time, but not before the time when the airplane responds under the same conditions. (1) Latency: The FTD instrument and, if applicable, the motion system and the visual system response must not be prior to that time when the	×	×		The intent is to verify that the FTD provides instrument cues that are, within the stated time delays, like the airplane responses. For airplane response, acceleration in the appropriate, corresponding rotational axis is preferred.	

	airplane responds and may respond up to 300 milliseconds after that time under the same conditions.		Additional information regarding Latency and
	(2) Transport Delay: As an alternative to the Latency requirement, a		Transport Delay testing may
	transport delay objective test may be used to demonstrate that the FTD		be found in Appendix A,
	system does not exceed the specified limit. The sponsor must measure all the delay encountered by a step signal migrating from the pilot's		Attachment 2, paragraph 15.
	control through all the simulation software modules in the correct		
	order, using a handshaking protocol, finally through the normal output		
	interfaces to the instrument display and, if applicable, the motion system, and the visual system.		
2.c.2.	Relative responses of the motion system, visual system, and flight deck	×	The intent is to verify that the
	instruments, measured by latency tests or transport delay tests. Motion onset		FTD provides instrument,
	should occur before the start of the visual scene change (the start of the scan		motion, and visual cues that
	of the first video field containing different information) but must occur before		are, within the stated time
	the end of the scan of that video field. Instrument response may not occur		delays, like the airplane
	prior to motion onset. Test results must be within the following limits:		responses. For airplane
			response, acceleration in the
	100 ms for the motion (if installed) and instrument systems; and		appropriate, corresponding
	120 ms for the visual system.		rotational axis is preferred.
2.d.	Ground handling and aerodynamic programming must include the following:		
2.d.1.	Ground effect.	X	l
			modeling that accounts for
			roundout, flare, touchdown,
			lift, drag, pitching moment,
			trim, and power while in
			ground effect.
2.d.2.	Ground reaction.	×	Ground reaction includes
			modeling that accounts for
			strut deflections, tire friction,
			and side forces. This is the
			reaction of the airplane upon
			contact with the runway during
			landing, and may differ with
			changes in factors such as
			gross weight, airspeed, or rate
		_ _	of descent on touchdown.

2.d.3.	Ground handling characteristics, including aerodynamic and ground reaction modeling including steering inputs, operations with crosswind, gusting crosswind, braking, thrust reversing, deceleration, and turning radius.	×	
.e.	If the aircraft being simulated is one of the aircraft listed in § 121.358, Lowaltitude windshear system equipment requirements, the FTD must employ windshear models that provide training for recognition of windshear phenomena and the execution of recovery procedures. Models must be available to the instructor/evaluator for the following critical phases of flight: (1) Prior to takeoff rotation; (2) At liftoff; (3) During initial climb; and (4) On final approach, below 500 ft AGL. The QTG must reference the FAA Windshear Training Aid or present alternate airplane related data, including the implementation method(s) used. If the alternate method is selected, wind models from the Royal Aerospace Establishment (RAE), the Joint Airport Weather Studies (JAWS) Project and other recognized sources may be implemented, but must be supported and properly referenced in the QTG. The addition of realistic levels of turbulence associated with each required windshear profile must be available and selectable to the instructor. In addition to the four basic windshear models required for qualification, at least two additional "complex" windshear models must be available in the takeoff and landing configurations and must consist of independent variable winds in multiple simultaneous components. The Windshear Training Aid provides two such example "complex" windshear models that may be used to satisfy this requirement.		Windshear models may consist of independent variable winds in multiple simultaneous components. The FAA Windshear Training Aid presents one acceptable means of compliance with FTD wind model requirements. The FTD should employ a method to ensure the required survivable and non-survivable windshear scenarios are repeatable in the training environment. For Level 7 FTDs, windshear training tasks may only be qualified for aircraft equipped with a synthetic stall warning system. The qualified windshear profile(s) are evaluated to ensure the synthetic stall warning (and not the stall buffet) is first indication of the stall.
2.f.	The FTD must provide for manual and automatic testing of FTD hardware and software programming to determine compliance with FTD objective tests as prescribed in Attachment 2 of this appendix. An SOC is required.	×	Automatic "flagging" of out- of-tolerance situations is encouraged.
2.g.	The FTD must accurately reproduce the following runway conditions: (1) Dry; (2) Wet;	×	

	(3) Icy; (4) Patchy Wet; (5) Patchy Icy; and (6) Wet on Rubber Residue in Touchdown Zone. An SOC is required.		
2.h.	The FTD must simulate: (1) brake and tire failure dynamics, including antiskid failure; and (2) decreased brake efficiency due to high brake temperatures, if applicable. An SOC is required	X	FTD pitch, side loading, and directional control characteristics should be representative of the airplane.
2.i.	Engine and Airframe Icing Modeling that includes the effects of icing, where appropriate, on the airframe, aerodynamics, and the engine(s). Icing models must simulate the aerodynamic degradation effects of ice aecretion on the airplane lifting surfaces including loss of lift, decrease in stall angle of attack, change in pitching moment, decrease in control effectiveness, and changes in control forces in addition to any overall increase in drag. Aircraft systems (such as the stall protection system and autoflight system) must respond properly to ice accretion consistent with the simulated aircraft. Aircraft OEM data or other acceptable analytical methods must be utilized to develop ice accretion models that are representative of the simulated aircraft's performance degradation in a typical in-flight icing encounter. Acceptable analytical methods may include wind tunnel analysis and/or engineering analysis of the aerodynamic effects of icing on the lifting surfaces coupled with tuning and supplemental subjective assessment by a subject matter expert pilot. SOC required.	×	SOC should be provided describing the effects which provide training in the specific skills required for recognition of icing phenomena and execution of recovery. The SOC should describe the source data and any analytical methods used to develop ice accretion models including verification that these effects have been tested. Icing effects simulation models are only required for those airplanes authorized for operations in icing conditions. Icing simulation models should be developed to provide training in the specific skills required for recognition of ice accumulation and execution of the required response. See Attachment 7 of this Appendix for further guidance material

2.j.	The aerodynamic modeling in the FTD must include: (1) Low-altitude level-flight ground effect.			×	See Attachment 2 of this appendix, paragraph 5, for
	(2) Mach effect at high altitude;				further information on ground
	(3) Normal and reverse dynamic thrust effect on control surfaces;				effect.
	(4) Aeroelastic representations; and				
	(5) Nonlinearities due to sideslip.				
	An SOC is required and must include references to computations of				
	aeroelastic representations and of nonlinearities due to sideslip.				
2.k.	The FTD must have aerodynamic and ground reaction modeling for the effects of reverse thrust on directional control if amplicable			×	
	An COC is resourced				
2 Fourinm	2 Paninmant Onometion	-			
J. Eduipiii	All adjacent inchanged indications investigated in the cianaletics of the ciantons		>	>	
3.a.	All relevant instrument indications involved in the simulation of the alliplane must automatically respond to control movement or external disturbances to	<	<	<	
	the simulated airplane: e o turbulence or windshear Numerical values must				
	be presented in the appropriate units.				
	For Level 7 FTDs, instrument indications must also respond to effects				
	resulting from Icing.	4			
3.b.1.	Navigation equipment must be installed and operate within the tolerances	×	×		
	applicable for the airplane.				
	Levels 6 must also include communication equipment (inter-phone and				
	air/ground) like that in the airplane and, if appropriate to the operation being				
	conducted, an oxygen mask microphone system.				
	Level 5 need have only that navigation equipment necessary to fly an				
	instrument approach.				
3.b.2.	Communications, navigation, caution, and warning equipment must be			X	See Attachment 3 of this
	installed and operate within the tolerances applicable for the airplane.				appendix for further
					information regarding long-
	Instructor control of internal and external navigational aids. Navigation aids				range navigation equipment.
	must be usable within range or line-ot-sight without restriction, as applicable				
	to the geographic area.				
3.b.3.	Complete navigation database for at least 3 airports with corresponding			×	
	precision and non-precision approach procedures, including navigational database inclasses.				
	damouse aparties.			1	

3.c.1.	Installed systems must simulate the applicable airplane system operation, both on the ground and in flight. Installed systems must be operative to the extent that applicable normal, abnormal, and emergency operating procedures included in the sponsor's training programs can be accomplished. Level 6 must simulate all applicable airplane flight, navigation, and systems operation. Level 5 must have at least functional flight and navigational controls, displays, and instrumentation. Level 4 must have at least one airplane system installed and functional.	X	X			
3.c.2.	Simulated airplane systems must operate as the airplane systems operate under normal, abnormal, and emergency operating conditions on the ground and in flight. Once activated, proper systems operation must result from system management by the crew member and not require any further input from the instructor's controls.			×	Airplane system operation should be predicated on, and traceable to, the system data supplied by the airplane manufacturer, original equipment manufacturer or alternative approved data for the airplane system or component.	T .
					At a minimum, alternate approved data should validate the operation of all normal, abnormal, and emergency operating procedures and training tasks the FSTD is qualified to conduct.	
3.d.	The lighting environment for panels and instruments must be sufficient for the operation being conducted.	X	X	X	Back-lighted panels and instruments may be installed but are not required.	
3.e.	The FTD must provide control forces and control travel that corresponds to the airplane being simulated. Control forces must react in the same manner as in the airplane under the same flight conditions. For Level 7 FTDs, control systems must replicate airplane operation for the normal and any non-normal modes including back-up systems and should reflect failures of associated systems. Appropriate cockpit indications and messages must be replicated.		×	×		
	messages must be replicated.	-	_			

3.f.	The FTD must provide control forces and control travel of sufficient precision	_	×		
	to manually fly an instrument approach.		\dashv		
3.e.	FTD control feel dynamics must replicate the airplane. This must be			×	
	determined by comparing a recording of the control feel dynamics of the FTD				
	to airplane measurements. For initial and upgrade qualification evaluations,				
	the control dynamic characteristics must be measured and recorded directly				
	from the flight deck controls, and must be accomplished in takeoff, cruise,				
,	and landing flight conditions and configurations.		-	4	
4. Instruct	4. Instructor or Evaluator Facilities.		- 1	ŀ	
4.a.1.	In addition to the flight crewmember stations, suitable seating arrangements	×	$\frac{\times}{\times}$	<u> </u>	These seats need not be a
	for an instructor/check airman and FAA Inspector must be available. These				replica of an aircraft seat and
	seats must provide adequate view of crewmember's panel(s).				may be as simple as an office
					chair placed in an appropriate position.
4.a.2.	In addition to the flight crewmember stations, the FTD must have at least two			×	
	suitable seats for the instructor/check airman and FAA inspector. These seats				Standards office will consider
	must provide adequate vision to the pilot's panel and forward windows. All				alternatives to this standard for
	seats other than flight crew seats need not represent those found in the				additional seats based on
	airplane, but must be adequately secured to the floor and equipped with				unique flight deck
	similar positive restraint devices.				configurations.
4.b.1.	The FTD must have instructor controls that permit activation of normal,	×	X	×	
	abnormal, and emergency conditions as appropriate. Once activated, proper				
	system operation must result from system management by the crew and not				
	require input from the instructor controls.		_	_	
4.b.2.	The FTD must have controls that enable the instructor/evaluator to control all			×	
	required system variables and insert all abnormal or emergency conditions				
	into the simulated airplane systems as described in the sponsor's FAA-				
	approved training program; or as described in the relevant operating manual				
	as appropriate.		-	-	
4.c.	The FTD must have instructor controls for all environmental effects expected			×	
	to be available at the IOS; e.g., clouds, visibility, icing, precipitation,				
	temperature, storm cells and microbursts, turbulence, and intermediate and				
	high altitude wind speed and direction.				
4.d.	The FTD must provide the instructor or evaluator the ability to present ground			×	
	and air hazards.				crossing the active runway or
					converging airborne traffic.
5. Motion System.	System.				

5.a.	The FTD may have a motion system, if desired, although it is not required. If a motion system is installed and additional training, testing, or checking credits are being sought on the basis of having a motion system, the motion system operation may not be distracting and must be coupled closely to provide integrated sensory cues. The motion system must also respond to abrupt input at the pilot's position within the allotted time, but not before the time when the airplane responds under the same conditions.	F1	×	X	The motion system standards set out in part 60, Appendix A for at least Level A simulators is acceptable.
5.b.	If a motion system is installed, it must be measured by latency tests or transport delay tests and may not exceed 300 milliseconds. Instrument response may not occur prior to motion onset.		<u> </u>	×	The motion system standards set out in part 60, Appendix A for at least Level A simulators is acceptable.
6. Visual System.	ystem.				
6.a.	The FTD may have a visual system, if desired, although it is not required. If a visual system is installed, it must meet the following criteria:	×	×	_	
6.a.1.	The visual system must respond to abrupt input at the pilot's position. An SOC is required.	7	X		
6.a.2.	The visual system must be at least a single channel, non-collimated display. An SOC is required.	×	×	J.	
6.a.3.	The visual system must provide at least a field-of-view of 18° vertical / 24° horizontal for the pilot flying. An SOC is required.	×	×	<u> </u>	
6.a.4.	The visual system must provide for a maximum parallax of 10° per pilot. An SOC is required.	×	×	<u> </u>	
6.a.5.	The visual scene content may not be distracting. An SOC is required.	×	×	×	
6.a.6.	The minimum distance from the pilot's eye position to the surface of a direct view display may not be less than the distance to any front panel instrument. An SOC is required.				
6.a.7.	The visual system must provide for a minimum resolution of 5 arc-minutes for both computed and displayed pixel size. An SOC is required.	×	×	w.	
6.b.	If a visual system is installed and additional training, testing, or checking credits are being sought on the basis of having a visual system, a visual system meeting the standards set out for at least a Level A FFS (see Appendix A of this part) will be required. A "direct-view," non-collimated visual system (with the other requirements for a Level A visual system met) may be considered satisfactory for those		7	×	Directly projected, non-collimated visual displays may prove to be unacceptable for dual pilot applications.

	X	×		the field-of-view is technically no less than 176°. Additional	field-of-view capability may be added at the sponsor's	discretion provided the minimum fields of view are	retained.	-	X Non-realistic cues might		and image "roll-off," that may	lead a pilot to make incorrect	assessments of speed,	acceletation, of situational awareness.	X	X			X		A This will show the modeling	localizer for a given weight,	configuration, and speed within
installations where the visual system design "eye point" is appropriately adjusted for each pilot's position such that the parallax error is at or less than 10° simultaneously for each pilot. An SOC is required.	The FTD must have a visual system providing an out-of-the-flight deck view.	The FTD must provide a continuous visual field-of-view of at least 176° horizontally and 36° vertically or the number of degrees necessary to meet the	visual ground segment requirement, whichever is greater. The minimum	horizontal field-of-view coverage must be plus and minus one-half $(/2)$ of the minimum continuous field-of-view requirement, centered on the zero degree	azimuth line relative to the aircraft fuselage.	An SOC is required and must explain the system geometry measurements including system linearity and field-of-view.	Collimation is not required but parallax effects must be minimized (not	greater than 10 for each pilot when aligned for the point midway between the left and right east available.	The visual system must be free from optical discontinuities and artifacts that	create non-realistic cues.					The FTD must have operational landing lights for night scenes. Where used, dusk (or twilight) scenes require operational landing lights.	The FTD must have instructor controls for the following:	(1) Visibility in statute miles (km) and runway visual range (RVR) in ft.(m);	(2) Airport selection; and (3) Airport lighting.	The FTD must provide visual system compatibility with dynamic response	programming.	I he F LD must snow that the segment of the ground visible from the F LD	THERE GEOR IS THE SAILTE AS TROTH THE ALL PRAILE THERE GEOR (WITHIN ESTABLISHED	
	6.c.	6.d.							6.e.						6.f.	6.g.			6.h.		0.1.		

	tolerances) when at the correct airspeed, in the landing configuration, at the appropriate height above the touchdown zone, and with appropriate visibility.		the airplane's operational envelope for a normal approach and landing.
6.j.	The FTD must provide visual cues necessary to assess sink rates (provide depth perception) during takeoffs and landings, to include: (1) Surface on runways, taxiways, and ramps; and (2) Terrain features.	×	
6.k.	The FTD must provide for accurate portrayal of the visual environment relating to the FTD attitude.	×	Visual attitude vs. FTD attitude is a comparison of pitch and roll of the horizon as displayed in the visual scene compared to the display on the attitude indicator.
6.1.	The FTD must provide for quick confirmation of visual system color, RVR, focus, and intensity. An SOC is required.	×	
6.т.	The FTD must be capable of producing at least 10 levels of occulting.	X	
6.n.	Night Visual Scenes. When used in training, testing, or checking activities, the FTD must provide night visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights.	X	
6.0.	Dusk (or Twilight) Visual Scenes. When used in training, testing, or checking activities, the FTD must provide dusk (or twilight) visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Dusk (or twilight) scenes, as a minimum, must provide full color presentations of reduced ambient intensity, sufficient surfaces with appropriate textural cues that include self-illuminated objects such as road networks, ramp lighting and airport signage, to conduct a visual approach, landing and airport movement (taxi). Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by airplane landing lights. If provided, directional horizon lighting must have correct orientation and be consistent with surface shading effects. Total night or dusk (twilight) scene	×	

	×	K For example: short runways, landing approaches over water, uphill or downhill runways, rising terrain on the approach path, unique topographic features.	x	×	X Scud effects are low, detached, and irregular clouds below a defined cloud layer.
content must be comparable in detail to that produced by 10,000 visible textured surfaces and 15,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects. An SOC is required.	Daylight Visual Scenes. The FTD must provide daylight visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Any ambient lighting must not "washout" the displayed visual scene. Total daylight scene content must be comparable in detail to that produced by 10,000 visible textured surfaces and 6,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects. The visual display must be free of apparent and distracting quantization and other distracting visual effects while the FTD is in motion.	The FTD must provide operational visual scenes that portray physical relationships known to cause landing illusions to pilots.	The FTD must provide special weather representations of light, medium, and heavy precipitation near a thunderstorm on takeoff and during approach and landing. Representations need only be presented at and below an altitude of 2,000 ft. (610 m) above the airport surface and within 10 miles (16 km) of the airport.	The FTD must present visual scenes of wet and snow-covered runways, including runway lighting reflections for wet conditions, partially obscured lights for snow conditions, or suitable alternative effects.	The f 1D must present realistic color and directionality of all airport lighting. The following weather effects as observed on the visual system must be simulated and respective instructor controls provided. (1) Multiple cloud layers with adjustable bases, tops, sky coverage and scud effect; (2) Storm cells activation and/or deactivation;
	6.p.	6 -q.	6.r.	6.8.	6.u.

	 (3) Visibility and runway visual range (RVR), including fog and patchy fog effect; (4) Effects on ownship external lighting; (5) Effects on airport lighting (including variable intensity and fog effects); (6) Surface contaminants (including wind blowing effect); (7) Variable precipitation effects (rain, hail, snow); (8) In-cloud airspeed effect; and (9) Gradual visibility changes entering and breaking out of cloud. 			
6.v.	The simulator must provide visual effects for: (1) Light poles; (2) Raised edge lights as appropriate; and (3) Glow associated with approach lights in low visibility before physical lights are seen,		×	Visual effects for light poles and raised edge lights are for the purpose of providing additional depth perception during takeoff, landing, and taxi training tasks. Three dimensional modeling of the actual poles and stanchions is not required.
7. Sound System.	ystem.			•
7.a.	The FTD must provide flight deck sounds that result from pilot actions that correspond to those that occur in the airplane.	×	×	
7.b.	The volume control must have an indication of sound level setting which meets all qualification requirements.		×	This indication is of the sound level setting as evaluated during the FTD's initial evaluation.
7.c.	The FTD must accurately simulate the sound of precipitation, windshield wipers, and other significant airplane noises perceptible to the pilot during normal and abnormal operations, and include the sound of a crash (when the FTD is landed in an unusual attitude or in excess of the structural gear limitations); normal engine and thrust reversal sounds; and the sounds of flap, gear, and spoiler extension and retraction. Sounds must be directionally representative.		×	

The FTD must provide realistic amplitude and frequency of flight deck noises and sounds. FTD performance must be recorded, subjectively assessed for the initial evaluation, and be made a part of the QTG.

X

ER20MY16.091</GPH>

	Table B1B - Table of Tasks vs. FTD Level	evel			ŀ	
	QPS REQUIREMENTS					INFORMATION
	Subjective Requirements		FTD			
Entry	In order to be qualified at the FTD qualification level indicated, the FTD must be able to		Level	ᇹ		Notes
Number	perform at least the tasks associated with that level of qualification. See Notes 1, 2 and 3 at the end of the Table	4	w	9	_	
4.b.	Holding		4	×	×	
4.c.	Precision Instrument					
4.c.1.	All engines operating.		V	×	×	e.g., Autopilot, Manual (Flt. Dir. Assisted), Manual (Raw Data)
4.c.2.	One engine inoperative.				Е	e.g., Manual (Flt. Dir. Assisted), Manual (Raw Data)
4.d.	Non-precision Instrument Approach		< −	×	×	e.g., NDB, VOR, VOR/DME, VOR/TAC, RNAV, LOC, LOC/BC, ADF, and SDF.
4.e.	Circling Approach (requires visual system)			A	×	Specific authorization required.
4.f.	Missed Approach					
4.f.1.	Normal.		Ą	×	×	
4.f.2.	One engine Inoperative.				T	
5. Landings	5. Landings and Approaches to Landings.					
5.a.	Normal and Crosswind Approaches and Landings				T	
5.b.	Landing From a Precision / Non-Precision Approach				L	
5.c.	Approach and Landing with (Simulated) Engine Failure – Multiengine Airplane				T	
5.d.	Landing From Circling Approach				L	
5.e.	Rejected Landing				T	
5.f.	Landing From a No Flap or a Nonstandard Flap Configuration Approach				T	
5. Normal a	i. Normal and Abnormal Procedures.					
6.a.	Engine (including shutdown and restart)	Α	A	X	X	
6.b.	Fuel System	Ą	4	×	×	
6.c.	Electrical System	Ą	¥	×	×	
6.d.	Hydraulic System	Ą	V	×	×	
6.e.	Environmental and Pressurization Systems	Ą	V	×	×	
6.f.	Fire Detection and Extinguisher Systems	¥	V	×	×	
6.g.	Navigation and Avionics Systems	V	V	×	×	
6.h.	Automatic Flight Control System, Electronic Flight Instrument System, and Related Subsystems	A	¥	×	×	

Note 1: An "A" in the table indicates that the system, task, or procedure, although not required to be present, may be examined if the appropriate airplane system is simulated in the FTD and is working properly

Note 2: Items not installed or not functional on the FTD and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

Note 3: A "T" in the table indicates that the task may only be qualified for introductory initial or recurrent qualification training. These tasks may not be qualified for proficiency testing or checking credits in an FAA approved flight training program.</PHOTO>

ER20MY16.093</GPH>

TABLE B1C—TABLE OF FTD SYSTEM TASKS QPS REQUIREMENTS

	QPS Requirements				Information
Entry No.	Subjective Requirements In order to be qualified at the FTD qualification level indicated, the FTD must be able to per- form at least the tasks associated with that level	FT	TD le	vel	Notes
	of qualification.	4	5	6	
1. Instructor	Operating Station (IOS).			•	
1.a	Power switch(es)	х	х	Х	
1.b	Airplane conditions	А	х	Х	e.g., GW, CG, Fuel loading, Systems, Ground Crew.
1.c	Airports/Runways	х	х	Х	e.g., Selection and Presets; Surface and Lighting controls if equipped with a visual system.
1.d	Environmental controls	x	x	х	e.g., Temp, Wind.
1.e	Airplane system malfunctions (Insertion/deletion)	А	х	Х	
1.f	Locks, Freezes, and Repositioning	х	х	Х	
1.g	Sound Controls. (On/off/adjustment)	х	х	Х	
1.h	Motion/Control Loading System, as appropriate. On/off/emergency stop.	А	А	Α	
2. Observer	Seats/Stations.				
2.a	Position/Adjustment/Positive restraint system	х	х	х	

Note 1: An "A" in the table indicates that the system, task, or procedure, although not required to be present, may be examined if the appropriate system is in the FTD and is working properly.

ATTACHMENT 2 TO APPENDIX B TO PART 60-FLIGHT TRAINING DEVICE (FTD) OBJECTIVE Tests

BEGIN INFORMATION

1. Discussion

- a. For the purposes of this attachment, the flight conditions specified in the Flight Conditions Column of Table B2A, are defined as follows:
- (1) Ground—on ground, independent of airplane configuration;
- (2) Take-off-gear down with flaps/slats in any certified takeoff position;
- (3) First segment climb—gear down with flaps/slats in any certified takeoff position (normally not above 50 ft AGL);
- (4) Second segment climb—gear up with flaps/slats in any certified takeoff position (normally between 50 ft and 400 ft AGL);
- (5) Clean—flaps/slats retracted and gear up; (6) Cruise—clean configuration at cruise
- altitude and airspeed: (7) Approach—gear up or down with flaps/
- slats at any normal approach position as recommended by the airplane manufacturer; and
- (8) Landing—gear down with flaps/slats in any certified landing position.
- b. The format for numbering the objective tests in Appendix A, Attachment 2, Table

- A2A, and the objective tests in Appendix B. Attachment 2, Table B2A, is identical. However, each test required for FFSs is not necessarily required for FTDs. Also, each test required for FTDs is not necessarily required for FFSs. Therefore, when a test number (or series of numbers) is not required, the term "Reserved" is used in the table at that location. Following this numbering format provides a degree of commonality between the two tables and substantially reduces the potential for confusion when referring to objective test numbers for either FFSs or FTDs.
- c. The reader is encouraged to review the Airplane Flight Simulator Evaluation Handbook, Volumes I and II, published by the Royal Aeronautical Society, London, UK, and FAA AC 25-7, as amended, Flight Test Guide for Certification of Transport Category Airplanes, and AC 23-8, as amended, Flight Test Guide for Certification of Part 23 Airplanes, for references and examples regarding flight testing requirements and techniques.
- d. If relevant winds are present in the objective data, the wind vector should be clearly noted as part of the data presentation, expressed in conventional terminology, and related to the runway being used for the test.
- e. A Level 4 FTD does not require objective tests and therefore, Level 4 is not addressed in the following table.

END INFORMATION

BEGIN QPS REQUIREMENTS

2. Test Requirements

- a. The ground and flight tests required for qualification are listed in Table B2A Objective Tests. Computer generated FTD test results must be provided for each test except where an alternate test is specifically authorized by the responsible Flight Standards office. If a flight condition or operating condition is required for the test but does not apply to the airplane being simulated or to the qualification level sought, it may be disregarded (e.g., an engine out missed approach for a single-engine airplane; a maneuver using reverse thrust for an airplane without reverse thrust capability). Each test result is compared against the validation data described in §60.13, and in Appendix B. The results must be produced on an appropriate recording device acceptable to the responsible Flight Standards office and must include FTD number, date, time, conditions, tolerances, and appropriate dependent variables portrayed in comparison to the validation data. Time histories are required unless otherwise indicated in Table B2A. All results must be labeled using the tolerances and units given.
- b. Table B2A in this attachment sets out the test results required, including the parameters, tolerances, and flight conditions for FTD validation. Tolerances are provided for the listed tests because mathematical modeling and acquisition and development of reference data are often inexact. All tolerances listed in the following tables are applied to FTD performance. When two tolerance values are given for a parameter, the less restrictive may be used unless otherwise indicated. In those cases where a tolerance is expressed only as a percentage, the tolerance percentage applies to the maximum value of that parameter within its normal operating range as measured from the neutral or zero position unless otherwise indicated.
- c. Certain tests included in this attachment must be supported with a SOC. In Table B2A, requirements for SOCs are indicated in the "Test Details" column.
- d. When operational or engineering judgment is used in making assessments for flight test data applications for FTD validity, such judgment may not be limited to a single parameter. For example, data that exhibit rapid variations of the measured parameters may require interpolations or a "best fit" data section. All relevant parameters related to a given maneuver or flight condition must be provided to allow overall interpretation. When it is difficult or impossible to match FTD to airplane data throughout a time history, differences must

be justified by providing a comparison of other related variables for the condition being assessed.

- e. It is not acceptable to program the FTD so that the mathematical modeling is correct only at the validation test points. Unless otherwise noted, FTD tests must represent airplane performance and handling qualities at operating weights and centers of gravity (CG) typical of normal operation. FTD tests at extreme weight or CG conditions may be acceptable where required for concurrent aircraft certification testing. Tests of handling qualities must include validation of augmentation devices.
- f. When comparing the parameters listed to those of the airplane, sufficient data must also be provided to verify the correct flight condition and airplane configuration changes. For example, to show that control force is within the parameters for a static stability test, data to show the correct airspeed, power, thrust or torque, airplane configuration, altitude, and other appropriate datum identification parameters must also be given. If comparing short period dynamics, normal acceleration may be used to establish a match to the airplane, but airspeed, altitude, control input, airplane configuration, and other appropriate data must also be given. If comparing landing gear change dynamics, pitch, airspeed, and altitude may be used to establish a match to the airplane, but landing gear position must also be provided. All airspeed values must be properly annotated (e.g., indicated versus calibrated). In addition, the same variables must be used for comparison (e.g., compare inches to inches rather than inches to centimeters).
- g. The QTG provided by the sponsor must clearly describe how the FTD will be set up and operated for each test. Each FTD subsystem may be tested independently, but overall integrated testing of the FTD must be accomplished to assure that the total FTD system meets the prescribed standards. A manual test procedure with explicit and detailed steps for completing each test must also be provided.
- h. For previously qualified FTDs, the tests and tolerances of this attachment may be used in subsequent continuing qualification evaluations for any given test if the sponsor has submitted a proposed MQTG revision to the responsible Flight Standards office and has received responsible Flight Standards office approval.
- i. FTDs are evaluated and qualified with an engine model simulating the airplane data supplier's flight test engine. For qualification of alternative engine models (either variations of the flight test engines or other manufacturer's engines) additional tests with the alternative engine models may be required. This attachment contains guidelines for alternative engines.

Federal Aviation Administration, DOT

- j. Testing Computer Controlled Aircraft (CCA) simulators, or other highly augmented airplane simulators, flight test data is required for the Normal (N) and/or Non-normal (NN) control states, as indicated in this attachment. Where test results are independent of control state, Normal or Non-normal control data may be used. All tests in Table B2A require test results in the Normal control state unless specifically noted otherwise in the Test Details section following the CCA designation. The responsible Flight Standards office will determine what tests are appropriate for airplane simulation data. When making this determination, the responsible Flight Standards office may require other levels of control state degradation for specific airplane tests. Where Nonnormal control states are required, test data must be provided for one or more Non-normal control states, and must include the least augmented state. Where applicable, flight test data must record Normal and Non-normal states for:
- (1) Pilot controller deflections or electronically generated inputs, including location of input; and
- (2) Flight control surface positions unless test results are not affected by, or are independent of, surface positions.
- k. Tests of handling qualities must include validation of augmentation devices. FTDs for highly augmented airplanes will be validated both in the unaugmented configuration (or failure state with the maximum permitted degradation in handling qualities) and the augmented configuration. Where various levels of handling qualities result from failure states, validation of the effect of the failure is necessary. Requirements for testing will be mutually agreed to between

the sponsor and the responsible Flight Standards office on a case-by-case basis.

- 1. Some tests will not be required for airplanes using airplane hardware in the FTD flight deck (e.g., "side stick controller"). These exceptions are noted in Section 2 "Handling Qualities" in Table B2A of this attachment. However, in these cases, the sponsor must provide a statement that the airplane hardware meets the appropriate manufacturer's specifications and the sponsor must have supporting information to that fact available for responsible Flight Standards office review.
- m. For objective test purposes, see Appendix F of this part for the definitions of "Near maximum," "Light," and "Medium" gross weight.

END QPS REQUIREMENTS

BEGIN INFORMATION

- n. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot test results" in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.
- o. Refer to AC 120-27, "Aircraft Weight and Balance" and FAA-H-8083-1, "Aircraft Weight and Balance Handbook" for more information.

END INFORMATION

	INFORMATION	Notes	53301	
		FTD	Cevel	6 7
		Ľ	_	2
Table B2A - Flight Training Device (FTD) Objective Tests	QPS REQUIREMENTS			Conditions Details
Table B	40		Tolerance	
		Test		Title
				Entry Number

1. Performance.	nance.					
1.a.	Taxi.					
l.a.1	Minimum radius turn.	±0.9 m (3 ft) or ±20% of airplane turn radius.	Ground.	Plot both main and nose gear loci and key engine parameter(s). Land for no bakes and the minimum thrust required to maintain a steady turn except for airplanes requiring asymmetric turns or braking to achieve the minimum radius turn.	×	
1.a.2	Rate of turn versus nosewheel steering angle (NWA).	±10% or ±2°/s of turn rate.	Ground.	Record for a minimum of two speeds, greater than minimum turning radius speed with one at a typical taxi speed, and with a spread of at least 5	Х	
i.b.	Takeoff.			Note.—For Level 7 FTD, all airplane manufacturer commonly-used certificated lake-off flap settings must be demonstrated at least once either in minimum unstick speed (1, b, 3), mornal take-off (1, b, 4), critical engine faithme on take-off (1, b, 5) or crossward take-off (1, b, 6) or crossward take-off (1, b, 6).		
1.6.1	Ground acceleration time and distance.	#1.5 s or #5.0 of thine; and #6.1 in (200 ft) or #5% of distance. For Level 6 FTD: #1.5 s or #5% of time.	Takcoff.	Acceleration time and distance must be recorded X for a minimum of 80% of the total time from brake release to V., Preliminary aircraft certification data may be used.	X	take be combined with normal takeoff (1.6.4.) or rejected takeoff (1.6.7.). Plotted data should be shown using appropriate scales for each portion of the maneuver. For Level 6 FTD, this test is required only if RTD training credit is sought.
1.b.2	speed, ground (V _{mep}) supply ground (V _{mep}) using aerodynamic controls only per applicable applicable airordrimess requirement or alternative engine inoperative test to demonstrate ground characteristics.	#25% of maximum airphune lateral deviation reached or #1.5 m (5 ft). For airphanes with reversible flight control systems: #10% or #2.2 daN (5 lbf) rudder pedal force.	Takcoff.	Engine failure speed must be within =1 kt of any origine engine failure speed. Engine thrust decay must be that resulting from the mathematical model for the engine applicable to the FTD under ariplane manufacturer's flight test engine, as the ariplane manufacturer's flight test engine, a further test may be run with the same initial conditions using the thrust from the flight test data as the driving parameter.	x	If if a V _{era} lest is not available, an acceptable attentance is a flight test snap organic develeration to its snap organic develeration to all and a speed between V ₁ and V ₁ -10 kt, followed by control of heading using areodynamic control only and recovery should be achieved with the nanin gear on the ground. To resure only aerodynamic control, nosewheel steering must be disabled (i.e. castored) or the ground.

	speed (V _{ma}) or equivalent test to demonstrate early rotation take-off characteristics.	±1.5° pitch angle.		start of rotation until at least 5 seconds after the occurrence of main gear lift-off.	1	speed at which the last main harding geat leaves the ground. Main landing geat struct compression or equivalent compression or equivalent artiforum signals alsould be recorded. If a V _m , test is not available, alternative acceptable light tests are a constant high-attride takeoff run through main geat lith-off or an early rolation takeoff. If either of these alternative contact/tail strike protection functionality, if present on the functionality, if present on the functionality, if present on the
1.b.4	Normal take-off.	#3 kt airspeed. #1.5° pitch angle. #1.5° AOA. #6 m (20 ft) height. For airplanes with reversible flight control systems: #2.2 daN (5 lbf) or. #109. of column force.	Takcoff.	Data required for near maximum certificated takeoff weight at mid center of gravity location and light takeoff weight at an aft center of gravity location. If the airplane has more than one certificated take-off configuration a different configuration must be used for each weight. Record takeoff profile from brake release to at least 61 m (200 ft) AGL.	×	The test may be used for ground acceleration time and distance (1.b.1). The test may be used for ground acceleration time and distance (1.b.1). The test may be used for ground using appropriate scales for each portion of the maneuver.
1.b.5	Critical engine failure on take-off.	±3 kt airspeed. ±1.5° pitch angle. ±1.5° AOA. ±2° on angle. ±2° side-slip angle. ±3° tade-slip angle. For airplanes with reversible light control systems. ±2.2 daN (5 lb) or ±10% of column force; ±1.3 daN (3 lb) or ±10% of wheel force; and	Takeoff.	Record takeoff profile to at least 61 m (200 ft) AGL. Engine failure speed must be within ±3 kt of airplame data. Test at near maximum takeoff weight	×	

													_				
	In those situations where a maximum crosswind or a	maximum demonstrated crosswind is not known, contact	the responsible Flight Standards office.										Autobrakes will be used where	applicable.			For Level 6 FTD, this test is required only if RTO training credit is sought.
	X												×				
																	×
	Record takeoff profile from brake release to at least 61 m (200 ft) AGL.	This test requires test data including wind	profile, for a crosswind component of at least 600% of the girdleng parformance data value	measured at 10 m (33 ft) above the runway.	Wind components must be provided as headwind	and crosswing values with respect to the fullway.							Record at mass near maximum takeoff weight.	Speed for reject must be at least 80% of V ₁ . Maximum braking effort, auto or manual.	Where a maximum braking demonstration is not available, an acceptable alternative is a test using approximately 80% braking and full reverse, if applicable.	Time and distance must be recorded from brake release to a full stop.	Record time for at least 80% of the segment from initiation of the rejected takeoff to full stop.
	Takeoff.												Takeoff.				Takeoff
±2.2 daN (5 lbf) or ±10% of rudder pedal force.	± 3 kt airspeed.	±1.5° pitch angle.	±1.5° AOA.	±6 m (20 ft) height.	±2° roll angle.	±2° side-slip angle.	±3° heading angle.	Correct trends at ground speeds below 40 kt for rudder/pedal and heading angle.	For airplanes with reversible flight control systems:	±2.2 daN (5 lbf) or ±10% of column force;	±1.3 daN (3 lbf) or ±10% of wheel force; and	±2.2 daN (5 lbf) or ±10% of rudder pedal force.	±5% of time or ±1.5 s.	±7.5% of distance or ±76 m (250 ft).	For Level 6 FTD: ±5% of time or ±1.5 s.		±5% of time or ±1.5 s.
	Crosswind take-off.												Rejected Takeoff.				Rejected Takeoff.
	1.b.6												1.b.7.a.				1.b.7.b.

Dynamic Eng Failure After Takeoff.	Dynamic Engine Failure After Takeoff.	±2°/s or ±20% of body angular rates.	Takeoff.	Engine failure speed must be within ±3 kt of airplane data.		×	For safety considerations, airplane flight test may be performed out of ground effect
				Engine failure may be a snap deceleration to idle.		-	at a safe altitude, but with
				Record hands-off from 5 s before engine failure to +5 s or 30° roll angle, whichever occurs first.			and airspeed.
				CCA: Test in Normal and Non-normal control state.			
pe Jii.	Normal Climb, all engines operating.	±3 kt airspeed. ±0.5 m/s (100 ft/ min)	Clean.	Flight test data are preferred; however, airplane performance manual data are an acceptable alternative.	×	×	For Level 5 and Level 6 FTDs, this may be a snapshot test result.
				Record at nominal climb speed and mid initial climb altitude.			
				FTD performance is to be recorded over an interval of at least 300 m (1, 000 ft).			
One-engine- inoperative 2nd segment climb.	2nd nb.	±3 kt airspeed. ±0.5 m/s (100 ft/ min)	2nd segment climb.	Flight test data is preferred; however, airplane performance manual data is an acceptable alternative.		×	
		but not less than		Record at nominal climb speed.			
		data requirements.		FTD performance is to be recorded over an interval of at least 300 m (1,000 ft).			
				Test at WAT (weight, altitude or temperature) limiting condition.			
One Engine Inoperative E Climb.	One Engine Inoperative En route Climb.	±10% time, ±10% distance, ±10% fuel used	Clean	Flight test data or airplane performance manual data may be used. Test for at least a 1.550 m (5.000 ft) seement.		×	
One Engine	One Engine Inoperative Approach	±3 kt airspeed.	Approach	Flight test data or airplane performance manual		×	Airplane should be configured
raii	Climb for airplanes with icing	±0.5 m/s (100 ft/ min) or ±5% rate of climb.		udia may be used. ETD norformance to be recorded over an interval			systems operating normally, gear
accountability if provided in the	y if he	but not less than airplane performance		of at least 300 m (1,000 ft).			ap and go accountability
perf his j	airplane performance data for this phase of flight.	data.		Test near maximum certificated landing weight as may be applicable to an approach in icing conditions			considerations, in accordance with the airplane performance data for an approach in icing
Des	Cruise / Descent.				+	+	conditions, should be applied.
Level flight acceleration		±5% Time	Cruise	Time required to increase airspeed a minimum of 50 kt, using maximum continuous thrust rating or		×	
				equivalent.			

				Stabilized descent to be conducted with speed brakes extended if applicable, at mid altitude and near V _{ms} or according to emergency descent ancounting to emergency descent procedure.					
	×	×	×	×		×		×	×
									<u> </u>
	A .								<u> </u>
For airplanes with a small operating speed range, speed change may be reduced to 80% of operational speed change.	Time required to decrease aispeed a minimum of 50 kt, using idle power. For airplanes with a small operating speed range, speed change, operational speed change.	The test may be a single snapshot showing instantaneous fuel flow, or a minimum of two consecutive snapshots with a spread of at least 3 minutes in seeady flight.	Idle power stabilized descent at normal descent speed at mid altitude. FTD performance to be recorded over an interval of at least 300 m (1,000 ft).	FTD performance to be recorded over an interval of at least 900 m (3,000 ft).		Time and distance must be recorded for at least 80% of the total time from touchdown to a full stop. stop. Position of ground spoilers and brake system pressure must be plotted (if apolicable).	Data required for medium and near maximum certificated landing weight. Engineering data may be used for the medium weight condition.	Time and distance must be recorded for at least 90% of the total time from initiation of reverse thrust to full thrust reverser minimum operating speed. Position of ground spoilers must be plotted (if applicable). Data required for medium and near maximum ecrificated landing weight. Engineering data may be used for the medium experiences.	Either flight test or manufacturer's performance manual data must be used, where available.
	Cruise	Cruise.	Clean.	As per airplane performance data.		Landing.		Landing	Landing.
	±5% Time	±.05 EPR or ±3% N1 or ±5% of torque. ±5% of fuel flow.	±3 kt airspeed. ±1.0 m/s (200 ft/min) or ±5% of rate of descent.	±5 kt airspeed. ±1.5 m/s (300 f/min) or ±5% of rate of descent.		±1.5 s or ±5% of time. For distances up to 1,220 m (4,000 ft), the smaller of ±61 m (200 ft) or ±10% of distance.	For distances greater than 1,220 m (4,000 ft), ±5% of distance.	±1.5 s or ±5% of time; and the smaller of ±61 m (200 ft) or ±10% of distance.	±61 m (200 ft) or ±10% of distance.
	Level flight deceleration.	Cruise performance.	Idle descent.	Emergency descent.	Stopping.	Deceleration time and distance, manual wheel brakes, dry runway, no reverse thrust.		Deceleration time and distance, reverse thrust, no wheel brakes, dry runway.	Stopping distance, wheel brakes, wet runway.
	1.d.2.	1.d.3.	1.d.4.	1.d.5.	1.e.	1.e.1.		1.6.2.	I.e.3.

				Engineering data, based on dry runway flight test stopping distance and the effects of contaminated runway braking coefficients, are an acceptable alternative.		
1.e.4.	Stopping distance, wheel brakes, icy	±61 m (200 ft) or ±10% of distance.	Landing.	Either flight test or manufacturer's performance manual data must be used, where available.	×	
	runway.			Engineering data based on dry minway flight test		
				stopping distance and the effects of contaminated		
				runway oraking coefficients, are an acceptable alternative.		
1.f.	Engines.					
.ig:	Acceleration.	For Level 7 FTD: ±10% Ti or ±0.25 s; and	Approach or landing	Total response is the incremental change in the critical engine parameter from idle power to go-	×	See Appendix F of this part for definitions of T _i and T _i .
		±10% Tt or ±0.25 s.		around power.		
		For Level 6 FTD: $\pm 10\%$ Tt or ± 0.25 s.				
		For Level 5 FTD: ±1 s				
1.f.2.	Deceleration.	For Level 7 FTD:	Ground	Total response is the incremental change in the X	$\mathbf{x} \mid \mathbf{x} \mid$	See Appendix F of this part for definitions of T. and T.
		±10% Tt or ±0.25 s, and ±10% Tt or ±0.25 s.		critical engine parameter from maximum taxe-off power to idle power.		definitions of the
		For Level 6 FTD:				
		±10% Tt or ±0.25 s.				
		For Level 5 FTD: ±1 s				
2. Handlin,	2. Handling Qualities.					
2.a.	Static Control Tests.					
	Note. I — Testing of pos	sition versus force is not app	licable if forces are general	Note. I — Testing of position versus force is not applicable if forces are generated solely by use of airplane hardware in the FTD. Note 2 — Birch roll and wow controlles position versus force or time should be managed at the control as alternative method in lian of external test fortunes.	oxtornal to	of firtunes
	at the flight controls wo	uld be to have recording an	d measuring instrumentation	of the flight controls would be recording in easily or time and are measured at the flight controls would be recording in the angle and measured in the flight controls would be recording in the angle and measured in the flight controls would be recording in the angle and measured in the flight controls would be recording in the statementation of the flight controls would be recording and measured in the flight controls would be recording and measured in the statement of the flight controls would be recording to the flight controls which in the flight controls would be recorded in the flight controls which is the flight control which is the flight controls which is the flight	s instrumen	st features station could
	be airectly recorded am static control checks, or	a maicnea to tne atripiane aa r equivalent means, and that	ra. Frovidea ine instrumente evidence of the satisfactory	oe alvecty vecoraea ana matenea to the atrotaea adut. Frontaea the instrumentation was veripea of using externa static control checks, or equivalent means, and that evidence of the satisfactory comparison is included in the MQTC, the instrumentation could be used for both	r wnne con n could be	aucing ine used for both
	initial and recurrent ever should be repeated if m	aluations for the measureme aior modifications and/or re	nt of all required control che vairs are made to the contro	initial and recurrent evaluations for the measurement of all required control checks. Verification of the instrumentation by using external measuring equipment should be reveated if major modifications and/or repairs are made to the control loading system. Such a permanent installation could be used without any time	l measurin used with	g equipment out anv time
	being lost for the installation of ex validation data where applicable.	lation of external devices. Sti poplicable,	atic and dynamic flight conti	being lost for the installation of external devices. Static and dynamic flight control tests should be accomplished at the same feel or impact pressures as the validation data where applicable.	ct pressure	s as the
	Note 3 — (Level 7 FTD only) FTD. A rationale is required,	only) FTD static control tes uired from the data provider	ting from the second set of p if a single set of data is app	Note 3— (Level 7 FTD only) FTD static control testing from the second set of pilot controls is only required if both sets of controls are not mechanically interconnected on the PTD, and are the required from the data provider if a single set of data is applicable to both sides. If controls are mechanically interconnected in the FTD, a many many and controls are mechanically interconnected in the FTD, a	not mechan onnected in	ically interconnected on the the FTD, a
2.a.1.a.	Pitch controller	±0.9 daN (2 lbf)	Ground.	Record results for an uninterrupted control sweep	X	Test results should be validated
	position versus force and surface position	breakout.		to the stops.		
	calibration.	±2.2 daN (5 lbf) or				stability, stalls, etc.
		±10% of force.				
		±2° elevator angle.				
2.a.1.b.	Pitch controller	±0.9 daN (2 lbf)	As determined by	Record results during initial qualification X		Applicable only on continuing
	position versus torce	breakout.	sponsor	evanianon for all uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing		quantication evaluations. The intent is to design the control feel for Level 5 to be able to
				quantication evaluations.		manually fly an instrument

approach; and not to compare results to flight test or other such data.	Test results should be validated with in-flight data from tests such as engine-out trims, steady state side-slips, etc.		Applicable only on continuing audification ventuations. The intent is to design the control feel for Level 5 to be able to manually fly an instrument approach; and not ocompare assults to flight test or other such data.	Test results should be validated with in-flight data from tests with in-flight data from tests state side-slips, etc.	Applicable only on continuing applicable only on continuing underfraction evaluations. The intent is of design the control feed for Level 5 to be able to manually lty an instrument approach; and not to compare designs to flight test or other such data.				The purpose of the test is to compare FSTD surface position indicator against the FSTD flight controls model computed value.
	×			×		X		×	×
	×			×			×	×	×
			×		×				
	Record results for an uninterrupted control sweep to the stops.		Record results during initial qualification evaluation for a uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing qualification evaluations.	Record results for an uninterrupted control sweep to the stops.	Record results during initial qualification evaluation for an uninterrupted control sweep to the stops. The recorded tolerances apply to subsequent comparisons on continuing qualification evaluations.	Record results of an uninterrupted control sweep to the stops.	Record results of an uninterrupted control sweep to the stops.	Record results of an uninterrupted control sweep to the stops.	
	Ground.		As determined by sponsor	Ground.	As determined by sponsor	Ground.	Ground.	Ground.	Ground.
±2.2 daN (5 lbf) or ±10% of force.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force.	±2° aileron angle. ±3° spoiler angle.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force.	#2.2 daN (5 lbf) breakout. #2.2 daN (5 lbf) or #10% of force. #2° rudder angle.	±2.2 daN (5 lbf) breakout. ±2.2 daN (5 lbf) or ±10% of force.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force. ±2° NWA.	±0.9 daN (2 lbf) breakout. ±1.3 daN (3 lbf) or ±10% of force.	±2° NWA.	±0.5° trim angle.
	Roll controller position versus force and surface position calibration.		Roll controller position versus force	Rudder pedal position versus force and surface position calibration.	Rudder pedal position versus force	Nosewheel Steering Controller Force and Position Calibration.	Nosewheel Steering Controller Force	Rudder Pedal Steering Calibration.	Pitch Trim Indicator vs. Surface Position Calibration.
	2.a.2.a.		2.a.2.b.	2.a.3.a.	2.a.3.b.	2.a.4.a.	2.a.4.b.	2.a.5.	2.a.6.

	Data from a test airplane or engineering test bench are acceptable, provided the correct engine controller (both hardware and software) is used. In the case of propeller-driven airplanes, if an additional lever, usually referred to as the troppeller propeller lever, is present, it should also be checked. This test may be a series of snapshot tests.	FTD computer output results may be used to show compliance.	FTD computer output results may be used to show compliance. Test not required unless RTO credit is sought.			n = the sequential period of a full oscillation. Refer to paragraph 4 of Appendix A, Attachment 2 for additional information	For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.
×	×	×				x	
	×		×				
#							
Trim rate to be checked at pilot primary induced trim rate (ground) and autopilot or pilot primary trim rate in-flight at go-around flight conditions. For CCA, representative flight test conditions must be used.	Simultaneous recording for all engines. The tolerances apply against airplane data. For airplanes with throttle detents, all detents to be presented and a least one position between detents campoints (where practical). For airplanes without detents, end points and at least three other positions are to be presented.	Relate the hydraulic system pressure to pedal position in a ground static test. Both left and right pedals must be checked.	Two data points are required: zero and maximum deflection. Computer output results may be used to show compliance.		Note—Tests, B. I., 2. B. 2 and 2. B. 3 are not applicable for FTDs where the control forces are completely generated within the airplane controller unit installed in the FTD. Power setting may be that required for level flight unless otherwise specified. See paragraph 4 of Appendix 4. Attachment 2.	Data must be for normal control displacements in both directions (epiproximately 22% to 50% of full throw or approximately 23% to 50% of maximum allowable pitch controller deflection for fight conditions limited by the maneuvering load envelope.)	Tolerances apply against the absolute values of each period (considered independently).
Ground and approach.	Ground	Ground.	Ground.		ole for FTDs where the contr setting may be that require	Takeoff, Cruise, and Landing.	
±10% of trim rate (°/s) or ±0.1°/s trim rate.	When matching engine parameters: ±5° of TLA. When matching detents: ±3% N1 or ±03 EPR or ±3% notque, or ±3% notque, or ±3% maximum rated manifold pressure, or equivalent. Where the levers do not have angular travel, a noterance of ±2 cm	#2.2 daN (5 lbf) or #10% of force. #1.0 MPa (150 psi) or #10% of brake system pressure.	±2.2 daN (5 lbf) or ±10% of force.	š	2 and 2.b.3 are not applicate installed in the FTD. Power ix A, Attachment 2.	For underdamped systems: T(P ₀) ±10% of P ₀ or ±0.05 s.	T(P ₁) ±20% of P ₁ or ±0.05 s. T(P ₂) ±30% of P ₂ or ±0.05 s. T(P ₂) ±10*(n+1)% of P _n
Pitch Trim Rate.	Alignment of cockpit throttle lover versus selected engine parameter.	Brake pedal position versus force and brake system pressure calibration.	Brake pedal position versus force	Dynamic Control Tests.	Note.— Tests 2.b.1, 2.b.2 and 2.b.3 are no airplane controller unit installed in the FT paragraph 4 of Appendix A, Attachment 2.	Pitch Control.	
2.a.7.	2.5 %	2.a.9.a.	2.a.9.b.	2.b.		2.b.1.	

								Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.	For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.	Refer to paragraph 4 of Appendix A, Attachment 2 for additional information.
								×		×
								Data must be for normal control displacement (approximately 23% to 50% of full throw or approximately 25% to 50% of maximum allowable roll controller deflection for flight	conditions limited by the maneuvering load envelope).	Data must be for normal control displacement (approximately 25% to 50% of full throw).
								Takeoff, Cruise, and Landing.		Takeoff, Cruise, and Landing.
or ±0.05 s.	$T(A_n) \pm 10\%$ of A_{max} where A_{max} is the largest amplitude or $\pm 0.5\%$ of the total control travel (stop to stop).	$T(A_d) \pm 5\%$ of $A_d =$ residual band or $\pm 0.5\%$ of the maximum control travel = residual band.	±1 significant overshoots (minimum of 1 significant overshoot).	Steady state position within residual band.	Note 1.— Tolerances should not be applied on period or amplitude after the last significant overshoot.	Note 2.— Oscillations within the residual band are not considered significant and are not subject to tolerances.	For overdamped and critically damped systems only, the following tolerance applies: T(P_0)=10% of P_0 or +0.05 s.	Same as 2.b.1.		Same as 2.b.1.
								Roll Control.		Yaw Control.
								2.b.2.		2.b.3.

itically igure r an													
For overdamped and critically damped systems, see Figure A2B of Appendix A for an illustration of the reference measurement.													
For dan A21 illu mes				\									
	×			×					×				
	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2% pitch rate). Test in both directions.	Show time history data from 5 s before until at least 5 s after initiation of control input.	If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s roll rate).	Test in one direction. For airplanes that exhibit non-symmetrical behavior, test in both directions.	Show time history data from 5 s before until at least 5 s after initiation of control input.	If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.	CCA: Test in normal and non-normal control state.	Control inputs must be typical of minor corrections made while established on an ILS approach (approximately 0.5 to 2°/s yaw rate).	Test in both directions.	Show time history data from 5 s before until at least 5 s after initiation of control input.	If a single test is used to demonstrate both directions, there must be a minimum of 5 s before control reversal to the opposite direction.	CCA: Test in normal and non-normal control state.
	Approach or Landing.			Approach or landing.					Approach or landing.				
	±0.15% body pitch rate or ±20% of peak body pitch rate applied throughout the time history.			±0.15°/s body roll rate or ±20% of peak body roll rate applied throughout the time history.	•				±0.15°/s body yaw rate or ±20% of peak body yaw rate applied throughout the time	history.			
	Small Control Inputs – Pitch.			Small Control Inputs - Roll.					Small Control Inputs - Yaw.				
	2.b.4.			2.b.5.					2.b.6.				

2.c.	Longitudinal Control Tests.	Tests.					
	Power setting is that rec	Power setting is that required for level flight unless otherwise specified.	otherwise specified.				
2.c.1.a.	Power Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.3° or ±20% of pitch angle.	Approach.	Power change from thrust for approach or level flight to maximum continuous or go-around power. Time history of uncontrolled free response for a time instory of uncontrolled free response for a initiation of the power change to the completion of the power change to the completion of the power change. CCAS, Test in normal and non-normal control		×	
2.c.1.b.	Power Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Approach.	May be a series of snapshot test results. Power Change dynamics test as described in test 2.c.1.a. will be accepted. CCA: Test in Normal and Non-normal control mode.	×		
2.c.2.a.	Flap/Slat Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Takeoff through initial flap retraction, and approach to landing.	Time history of uncontrolled free response for a time interent equal to at least 5 selection initiation of the reconfiguration change to the completion of the reconfiguration change + 15 s. CCA: Test in normal and non-normal control mode		×	
2.c.2.b.	Flap/Slat Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Takeoff through initial flap retraction, and approach to landing.	May be a series of snapshot test results. Flap/Slat X change dynamics test as described in test 2.c.2.a. will be accepted. CA: Test in Normal and Non-normal control mode.	x		
2.c.3.	Spoiler/Speedbrake Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Cruise.	Time history of uncontrolled free response for a time insternent equal or at least 5 selection intrinsion of the configuration change to the completion of the configuration change +15 s. Results required for both extension and retraction. CCA: Test in normal and non-normal control		x	
2.c.4.a.	Gear Change Dynamics.	±3 kt airspeed. ±30 m (100 ft) altitude. ±1.5° or ±20% of pitch angle.	Takeoff (retraction), and Approach (extension).	Time history of uncontrolled free response for a time bristory of uncontrolled rese before time invertenent equal to at least 5 s before initiation of the configuration change to the completion of the configuration change + 15 s. CCAs. Test in normal and non-normal control mode		×	
2.c.4.b.	Gear Change Force.	±5 lb (2.2 daN) or, ±20% pitch control force.	Takeoff (retraction) and Approach (extension).	May be a series of snapshot test results. Gear change dynamics test as described in test 2.c.4.a. will be accepted.	×		

				CCA: Test in Normal and Non-normal control	
2.c.5.	Longitudinal Trim.	±1° elevator angle.	Cruise, Approach, and	Steady-state wings level trim with thrust for level X X X	λ
		±0.5° stabilizer or trim	Landing.	flight. This test may be a series of snapshot tests.	
		surface angle.		Level 5 FTD may use equivalent stick and trim controllers in lieu of elevator and trim surface.	
		±1 puen angle.		CCA: Test in normal or non-normal control	
		±5% of net thrust or equivalent.		mode, as applicable.	
2.c.6.	Longitudinal Maneuvering Stability (Stick	±2.2 daN (5 lbf) or ±10% of pitch controller	Cruise, Approach, and Landing.	Continuous time history data or a series of X X snapshot tests may be used.	
	Force/g).	Torce. Alternative method:		Test up to approximately 30° of roll angle for	
		±1° or ±10% of the		approximately 45° of roll angle for the cruise configuration.	
		change of elevator angle.		Force tolerance not applicable if forces are	
				generated solely by the use of airplane hardware in the FTD.	
				Alternative method applies to airplanes which do not exhibit stick-force-per-g characteristics.	
				CCA: Test in normal or non-normal control mode	
2.c.7.	Longitudinal Static Stability.	±2.2 daN (5 lbf) or ±10% of pitch controller	Approach.	Data for at least two speeds above and two speeds X X X below trim speed. The speed range must be	~
		force.		sufficient to demonstrate stick force versus speed characteristics.	
		Alternative method:			
		±1° or ±10% of the		This test may be a series of snapshot tests.	
		change of elevator angle.		Force tolerance is not applicable if forces are generated solely by the use of airplane hardware in the FTD.	
				Alternative method applies to airplanes which do not exhibit speed stability characteristics.	
				Level 5 must exhibit positive static stability, but need not comply with the numerical tolerance.	
				CCA: Test in normal or non-normal control mode, as applicable.	
2.c.8.a.	Approach to Stall Characteristics	±3 kt airspeed for initial buffet, stall warning, and stall speeds.	Second Segment Climb, High Altitude Cruise (Near Performance	nethods must be three required	X Tests may be conducted at centers of gravity typically required for airplane
		Control inputs must be plotted and demonstrate	Limited Condition), and Approach or Landing	Stall entry at wings level (1g) Stall entry in turning flight of at least 25° bank angle (accelerated stall)	certification stall testing.

		correct trend and magnitude.		 Stall entry in a power-on condition (required only for turboprop aircraft) 			
		±2.0° pitch angle ±2.0° angle of attack ±2.0° bank angle ±2.0° sideslip angle		The required cruise condition must be conducted in a flaps-up (clean) configuration. The second segment climb and approach/landing conditions must be conducted at different flap settings.			
		Additionally, for those simulators with reversible flight control systems:		For airplanes that exhibit stall buffer as the first indication of a stall, for qualification of this task, the FTD must be equipped with a voltration system that meets the applicable subjective and objective requirements in Appendix A of this Part.			
		daln)) strek/Column force (prior to "g break" only).					
2.c.8.b.	Stall Warning (actuation of stall warning device.)	±3 kts. airspeed, ±2° bank for speeds greater than actuation of stall warning device or initial buffer	Second Segment Climb, and Approach or Landing.	The stall maneuver must be entered with thrust at or near idle power and wings level (1g). Record the stall warning signal and initial buffer if applicable.	×		
				CCA: Test in Normal and Non-normal control states.			
2.c.9.a.	Phugoid Dynamics.	±10% of period.	Cruise.	Test must include three full cycles or that	×	×	
		±10% of time to one half or double amplitude or ±0.02 of damping ratio.		necessary to determine time to one han or double amplitude, whichever is less. CCA: Test in non-normal control mode.			
2.c.9.b.	Phugoid Dynamics.	±10% period, Representative damping.	Cruise.	The test must include whichever is less of the following: Three full cycles (six overshoots after the input is completed), or the number of cycles sufficient to determine representative damping.	×		
2.c.10	Short Period Dynamics.	$\pm 1.5^{\circ}$ pitch angle or $\pm 2^{\circ}$ /s pitch rate.	Cruise.	CCA: (Level 7 FTD) Test in normal and non- normal control mode.	×	×	
		±0.1 g normal acceleration		(Level 6 FTD) Test in non-normal control mode.			
.c.11.	(Reserved)						
2.d.	Lateral Directional Tests.	sts.					
	Power setting is that req	Power setting is that required for level flight unless otherwise specified.	otherwise specified.				
2.d.1.	Minimum control speed, air (V _{mea}) or landing (V _{mel}), per	±3 kt airspeed.	Takeoff or Landing (whichever is most critical in the airplane).	Takeoff thrust must be set on the operating engine(s).		Х	Minimum speed may be defined by a performance or control limit which prevents
	airworthiness			Time history or snapshot data may be used.			demonstration of V _{mcs} or V _{mcl} in the conventional manner.
	speed engine- inoperative handling characteristics in the			CCA: Test in normal or non-normal control state, as applicable.			
	an.				-		

								_			_		_					-
			With wings level, apply a step roll control input using annoximately one-third of the	approximately one units of the reaching approximately 20° to 30° of bank, abstractly return the	roll controller to neutral and allow approximately 10 seconds of airplane free response.								Test should be performed in a	manner similar to that for which a pilot is trained to trim an	engine failure condition.	2nd segment climb test should be at takeoff thrust. Approach or landing test should be at thrust	for level flight.	
×			×			×							×					X
×			×						X									×
×												×						
Test with normal roll control displacement (approximately one-third of maximum roll controller travel).	This test may be combined with step input of flight deck roll controller test 2.d.3.		This test may be combined with roll response (rate) test 2.d.2.	CCA: (Level 7 FTD) Test in normal and non- normal control mode.	(Level 6 FTD) Test in non-normal control mode.	Airplane data averaged from multiple tests may be used.	Test for both directions. As an alternative test, show lateral control required to maintain a steady turn with a roll angle of approximately 30°.	CCA: Test in non-normal control mode.	Airplane data averaged from multiple tests may be used.	Test for both directions. As an alternative test, show lateral control required to maintain a steady turn with a roll angle of approximately 30°.	CCA: Test in non-normal control mode.	Airplane data averaged from multiple tests may be used. CA. Test in non-normal control mode	This test may consist of snapshot tests.					For Level 7 FTD: Test with stability augmentation on and off.
Cruise, and Approach or Landing.			Approach or Landing.			Cruise, and Approach or Landing.			Cruise			Cruise	Second Segment Climb,	and Approach or Landing.				Approach or Landing.
±2°/s or ±10% of roll rate.	For airplanes with reversible flight control systems (Level 7 FTD only):	±1.3 daN (3 lbf) or ±10% of wheel force.	±2° or ±10% of roll angle.			Correct trend and $\pm 2^{\circ}$ or $\pm 10\%$ of roll angle in 20 s.	If alternate test is used: correct frend and ±2° aileron angle.		Correct trend and $\pm 3^{\circ}$ or $\pm 10\%$ of roll angle in 20 s.			Correct frend	±1° rudder angle or ±1°	tab angle or equivalent rudder pedal.	±2° side-slip angle.			±2°/s or ±10% of yaw rate.
Roll Response (Rate).			Step input of flight deck roll controller.			Spiral Stability.			Spiral Stability.			Spiral Stability.	Engine Inoperative	Trim.				Rudder Response.
2.d.2.			2.d.3.			2.d.4.a.			2.d.4.b.			2.d.4.c.	2.d.5.					2.d.6.a.

Pt. 60, App. B

May be accomplished as a yaw response test, in which case the procedures and requirements of test 2.d.6.a. will apply.							
	×		×				
×	×		×				
May be roll response to a given rudder deflection. Y CCA: Test in Normal and Non-normal control states.	Test for at least six cycles with stability augmentation off. CCA: Test in non-normal control mode.		This test may be a series of snapshot tests using at least two rudder positions (in each direction for propeller-driven airplanes), one of which must be near maximum allowable rudder.	(Level 5 and Level 6 FTD only); Sideslip angle is matched only for repeatability and only on continuing qualification evaluations.			
Approach or Landing.	Cruise, and Approach or Landing.		Approach or Landing.				
Roll rate ±2°/sec, bank angle ±3°.	±0.5 s or ±10% of period. ±10% of time to one half or double amplitude or ±.02 of damping ratio.	(Level 7 FTD only): ±1 s or ±20% of time difference between peaks of roll angle and side-slip angle.	For a given rudder position: ±2° roll angle;	±1° side-slip angle; ±2° or ±10% of aileron angle; and	±5° or ±10% of spoiler or equivalent roll controller position or force.	For airplanes with reversible flight control systems (Level 7 FTD only):	±1.3 daN (3 lbf) or ±10% of wheel force.
Rudder Response.	Dutch Roll		Steady State Sideslip.				
2.d.6.b.	2.d.7.		2.d.8.				

		±2.2 daN (5 lbf) or ±10% of rudder pedal				
		force.				
2.e.	Landings.					
2.e.1.	Normal Landing.	±3 kt airspeed.	Landing.	Test from a minimum of 61 m (200 ft) AGL to nosewheel touchdown.	×	Two tests should be shown, including two normal landing
		±1.5° pitch angle.				flaps (if applicable) one of
		±1.5° AOA.		CCA: I est in normal and non-normal control mode, if applicable.		which should be near maximum certificated landing mass, the
		±3 m (10 ft) or ±10% of height.				oner at right of medium mass.
		For airplanes with reversible flight control systems:				
		±2.2 daN (5 lbf) or ±10% of column force.				
2.e.2.	Minimum Flap Landing.		Minimum Certified Landing Flap	Test from a minimum of 61 m (200 ft) AGL to nosewheel fouchdown	×	
	,	±1.5° pitch angle.	Configuration.			
		±1.5° AOA.		Test at near maximum certificated landing weight.		
		±3 m (10 ft) or ±10% of height.				
		For airplanes with reversible flight control systems:				
		±2.2 daN (5 lbf) or ±10% of column force.				
2.e.3.	Crosswind Landing.	±3 kt airspeed.	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown	×	In those situations where a maximum crosswind or a
		±1.5° pitch angle.		paads.		maximum demonstrated crosswind is not known, contact
		±1.5° AOA.		It requires test data, including wind profile, for a		the responsible Flight Standards office.
		±3 m (10 ft) or ±10% of height.		crosswind component of at least 04% of airplane performance data value measured at 10 m (33 ft) above the runway.		
		±2° roll angle.		Wind components must be provided as headwind and crosswind values with respect to the runway		
		±2° side-slip angle.				
		±3° heading angle.				
					-	

Pt. 60, App. B

One Engine Inoperative Landing. Autopilot landing (if applicable). All-engine autopilot go-around. One engine inoperative go around.			For airplanes with reversible flight control systems:				
#1.3 daN (3 lbf) or #1.9% of wheel force. #2.2 daN (5 lbf) or force. #1.5° pich angle. #1.5° AOA. #3 m airspeed. #1.5° pich angle. #2° side-slip angle. #3.8 m (10 ft) lare Landing. #40.7 m/s (140 fb/min) #40.7 m/s (140 fb/min) #40.7 m/s (140 fb/min) #40.8 m airspeed. #41.5° pich angle. #41.5° pich angle. #41.5° pich angle. #42° AOA. #42° AOA. #42° AOA. #42° AOA. #42° Fold angle. #42° Fold angle.			±2.2 daN (5 lbf) or ±10% of column force.				
#2.2 daN (5 lbf) or hoperative Landing. 10			± 1.3 daN (3 lbf) or $\pm 10\%$ of wheel force.				
One Engine ±3 kt airspeed. Landing.			±2.2 daN (5 lbf) or ±10% of rudder pedal force.				
#1.5° AOA. #2 m (10 ft) or ±10% of height. #2° roll angle. #2° side-slip angle. #2° roll angle. #2° roll angle. #2° roll angle. #3° height angle. #40.7 m/s (140 ft/min) rate of descent at round-down from or deviation during roll. #41.5° pitch angle. #41.5° AOA. #42° roll angle. #43° Ra tisspeed. #41.5° AOA. #42° roll angle. #43° Ra tisspeed. #44° spitch angle. #45° pitch angle. #45° pitch angle. #45° pitch angle. #45° roll angle. #45° roll angle. #45° roll angle.	2.e.4.	One Engine Inoperative Landing.	±3 kt airspeed.	Landing.	Test from a minimum of 61 m (200 ft) AGL to a 50% decrease in main landing gear touchdown	×	
#1.5° AOA. #3 m (10 ft) or ±10% of height. #2° roll angle. #2° side-slip angle. #3° heading angle. #3° heading angle. #3° height. #0.5 or ± 10% of Tf. #0.5 or ± 10% of Tf. #0.7 m/s (140 fr/min) rate of descent at rouchdown. #3 m (10 ft) lateral deviation during roll- out. #3 m (10 ft) lateral deviation during roll- out. #3 k a sirspeed. #1.5° pitch angle. #1.5° AOA. #1.5° pitch angle. #1.5° AOA. #2° roll angle. #1.5° AOA. #2° roll angle. #2° roll angle.		0	±1.5° pitch angle.		speed.		
#3 m (10 ft) or ±10% of height. #2° roll angle. #2° side-slip angle. #2° side-slip angle. #1.5 m (5 ft) flare #0.5 s or ± 10% of Tf. #0.5 s or ± 10% of Tf. #0.7 m/s (140 ft/min) rate of descent at touchdown. #3 m (10 ft) lateral deviation during roll- All-engine autopilot #3 kt airspeed. #1.5° AOA. #2° roll angle. #1.5° AOA. #2° roll angle. #1.5° AOA. #2° roll angle.			±1.5° AOA.				
#2° roll angle. #2° side-slip angle. #1° beading angle. #1° beading angle. #0.5 sor ± 10% of Tf. #0.5 sor ± 10% of Tf. #0.7 m/s (140 f/min) rate of descent at touchdown. #3 m (10 ft) lateral deviation during roll- All-engine autopilot #3 kt airspeed. #1.5° pich angle. #1.5° AOA. #2° roll angle. #1.5° AOA. #2° roll angle. #1.5° roll angle.			±3 m (10 ft) or ±10% of height.				
#2° side-slip angle. Autopilot landing (if #1.5 m (5 ft) flare applicable). #0.5 s or ± 10% of TT. #0.7 m/s (140 f/min) rate of descent at touchdown. #3 m (10 ft) lateral deviation during roll-out. All-engine autopilot #3 kt airspeed. So-around. #1.5° pitch angle. #1.5° AOA. #2° roll angle. #1.5° pote angle.			±2° roll angle.				
Autopilot landing (if 11.5 m (5 ft) flare applicable) 40.5 s or ± 10% of TT. 40.5 s or ± 10% of TT. 40.7 m/s (140 ft/min) rate of descent at round/or mine autopilot 43 kt airspeed. All-engine autopilot 43 kt airspeed. All-so pitch angle. 41.5° pitch angle.			±2° side-slip angle.				
Autopilot landing (if ±1.5 m (5 ft) flare applicable). ±0.5 s or ± 10% of Tf. ±0.7 m/s (140 ft/min) rate of descent at touchdown. ±3. m (10 ft) lateral deviation during roll-dout. All-engine autopilot ±3 kt airspeed. All-engine autopilot ±1.5° pitch angle. ±1.5° AOA. ±1.5° pitch angle.			±3° heading angle.				
#0.5 s or ± 10% of Tf. #0.7 m/s (140 ft/min) rate of descent at touchdown. #3 m (10 ft) lateral deviation during roll- out. All-engine autopilot #3 kt airspeed. performance data. #1.5° pitch angle. #1.5° pitch angle. One engine #3 kt airspeed. As per airplane	2.e.5.	Autopilot landing (if applicable).	±1.5 m (5 ft) flare height.	Landing.	If autopilot provides roll-out guidance, record lateral deviation from touchdown to a 50% decrease in main landing oper touchdown stoned	X See	See Appendix F of this part for definition of T _r
### 1.5° pitch angle. All-engine autopilot ### 1.5° pitch angle. All-engine autopilot ### 1.5° pitch angle. All-engine autopilot ### 1.5° pitch angle. All-engine autopilot ### 1.5° pitch angle. All-engine ### 1.5° pitch angle. All-so per airplane performance data. #### 1.5° pitch angle. All-so pot airplane #### 1.5° pitch angle. All-so pitch angle. ##### 1.5° pitch angle. All-so pitch angle. ###################################			± 0.5 s or \pm 10% of Tf.		decrease in minimum minimum green construction above.		
#3 m (10 ft) lateral deviation during roll- All-engine autopilot #3 kt airspeed. As per airplane go-around. #1.5° pitch angle. #1.5° pitch angle. One engine #3 kt airspeed. As per airplane inoperative go #1.5° pitch angle. #1.5° AOA. #1.5° pitch angle. #1.5° AOA. #1.5° pold angle.			±0.7 m/s (140 ft/min) rate of descent at touchdown.		I me of autophiot fare mode engage and main gear touchdown must be noted.		
All-engine autopilot #3 kt airspeed. As per airplane go-around. #1.5° pitch angle. #1.5° potch angle. #1.5° potch angle. #1.5° pitch angle. Performance data. around. #1.5° pitch angle. #1.5° AOA. #1.5° AOA. #1.5° AOA. #1.5° AOA.			±3 m (10 ft) lateral deviation during roll-out.				
#1.5° pitch angle. #1.5° AOA. One engine #3 kt airspeed. As per airplane inoperative go #1.5° pitch angle. #1.5° AOA. #2. roll angle.	2.e.6.	All-engine autopilot go-around.	±3 kt airspeed.	As per airplane performance data.	Normal all-engine autopilot go-around must be demonstrated (if applicable) at medium weight.	×	
±1.5° AOA. As per airplane inoperative go		,	±1.5° pitch angle.				
One engine #3 kt airspeed. As per airplane inoperative go #1.5° pitch angle. #1.5° AOA. #25° roll angle.			±1.5° AOA.				
±1.5° pitch angle. ±1.5° AOA. ±2° roll angle.	2.e.7.	One engine	±3 kt airspeed.	As per airplane nerformance data	Engine inoperative go-around required near	Х	
		around.	±1.5° pitch angle.		critical engine inoperative.		
			±1.5° AOA.		Provide one test with autopilot (if applicable) and		
			±2° roll angle.		one without autophot.		

		±2° side-slip angle.		CCA: Non-autopilot test to be conducted in non-normal mode.		
2.e.8.	Directional control (rudder effectiveness) with symmetric reverse thrust	±5 kt airspeed. ±2°/s yaw rate.	Landing.	Apply rudder pedal input in both directions using full reverse thrust until reaching full thrust reverser minimum operating speed.	×	
2.e.9.	Directional control (rudder effectiveness) with asymmetric reverse thrust.	±5 kt airspeed. ±3° heading angle.	Landing.	With full reverse thrust on the operating engines, maintain heading with rudder pedal input until maximum rudder pedal input until maximum rudder pedal input or thrust reverser minimum operation speed is reached.	×	
2.f.	Ground Effect.					
	Test to demonstrate Ground Effect.	±1° elevator angle.	Landing.	A rationale must be provided with justification of results.	×	See paragraph on Ground Effect in this attachment for additional
		±0.5° stabilizer angle.		CCA. Test in normal or non-normal control		information.
		±5% of net thrust or equivalent.		CCA: 1 est in notifial of non-notifial control mode, as applicable.		
		±1° AOA.				
		±1.5 m (5 ft) or ±10% of height.				
		±3 kt airspeed.				
		±1° pitch angle.				
2.g.	Reserved					
2.h.	Flight Maneuver and	Flight Maneuver and Envelope Protection Functions.	ions.			
	Note. — The to control inputs during is different) are require	requirements of 2.h are onl entry into each envelope pr d. Set thrust as required to r	Note — The requirements of 2.h are only applicable to computer-controlled as to control inpute it is with normal and to control inputs during entry into each entrope protection function function is different are required. Set thinst as required to reach the emelope protection function is different.	Note. — The requirements of 2 h are only applicable to computer-controlled airplanes. Time history results of response to control inpus during early nine edit oweelpge protections function is differently are equired. Set thirst as required. Set thirst as required. Set thirst as required. Set thirst as required.		
2.h.1.	Overspeed.	±5 kt airspeed.	Cruise.		×	
2.h.2.	Minimum Speed.	±3 kt airspeed.	Takeoff, Cruise, and Approach or Landing.		×	
2.h.3.	Load Factor.	±0.1g normal load factor	Takeoff, Cruise.		×	
2.h.4.	Pitch Angle.	±1.5° pitch angle	Cruise, Approach.		X	
2.h.5.	Bank Angle.	±2° or ±10% bank angle	Approach.		X	
2.h.6.	Angle of Attack.	±1.5° angle of attack	Second Segment Climb, and Approach or Landing.		×	
3. Reserved	P					
4. Visual System.	System.					
4.a.	Visual scene quality					
4.a.1.	Continuous cross- cockpit visual field of view.	Visual display providing each pilot with a minimum of 176° horizontal and 36° vertical continuous field of view.	Not applicable.	Required as part of MQTG but not required as part of continuing evaluations.	×	Field of view should be measured using a visual test pattern filling the entire visual scene (all channels) consisting of a matrix of black and white 5° squares.

					Installed alignment should be confirmed in an SOC (this would generally consist of results from acceptance testing).
4.a.2.	System Geometry	Geometry of image should have no distracting discontinuities.		(X
4.a.3	Surface resolution (object detection).	Not greater than 4 are minutes.	Not applicable.		A Resolution will be demonstrated by a test of objects shown to occupy the required visual angle in each visual display used on a sene from the pilot's eyepoint. The object will subtend 4 arc minutes to the eye. This may be demonstrated using threshold bars for a horizontal test. A vertical test should also be demonstrated. The subtended angles should be confirmed by calculations in an SOC.
4.a.4	Light point size.	Not greater than 8 arc minutes.	Not applicable.		Light point size should be measured using a test pattern consisting of a centrally located single row of white light points and splayed as both a horizontal and splayed as both a horizontal and vertical row of the light points relative to the light points relative to the light points relative to the eyepoint in all axes. At a point where modulation is just discernible in each visual channel, a calculation should be made to determine the light spacing. An SOC is required to state test method and calculation.
4.a.5	Raster surface contrast ratio.	Not less than 5:1.	Not applicable.		X Surface contrast ratio should be measured using a raster drawn test pattern filling the entire visual scene (all channels). The test pattern should consist of black and white sequence, 5° per square, with a white square in the center of each channel.

Measurement should be made on the center bright square for each channel using a 1° spot photometer. This value should have a minimum brightness of 7 ed/m² (2 th-lamberts). Measure any adjacent dark squares. The contrast ratio is the bright square value, fivided by the dark square value. Note 1. — During contrast ratio testing, FTD ajf-each and fight deck ambient light levels should be as low as possible. Note 2. — Measurements should be taken at the center of squares to avoid light spill into the measurements should be taken at the center of squares to avoid light spill into the measurement device.	Light point contrast ratio should be measured sings at sets pattern demonstrating an area of greater than 1° area filled with white light points and should be compared to the adjacent background. Note. — Light point modulity paint and adjacent modulation should be just descentible on callidgraphic systems but will not be discernable on raster systems. Measurements of the discound should be taken such that the bright square is just out of the light meter FOV. Note. — During contrast ratio esting, FTD aff-cab and fight deck ambient light leaves should be us to out of the light meter FOV.	Light points should be displayed as a matrix creating a square. On calligraphic systems the light points should just merge.
	×	×
	Not applicable.	Not applicable.
	Not less than 10.1.	Not less than 20 cd/m² (5.8 ft-lamberts).
	Light point contrast ratio.	Light point brightness.
	4.a.6	4.a.7

On raster systems the light points should overlap such that the square is continuous (individual light points will not be visible).	Surface brightness should be measured on a white raster, measuring the brightness using the 1' spot photometer. Light points are not acceptable. Use of calligraphic capabilities a certained acceptable acceptable and a specific acceptable.		Alignment requirement only applies to the pilot flying.	A statement of the system capabilities should be provided and the capabilities demonstrated	Alignment requirement only applies to the pilot flying.		Alignment requirement only applies to the pilot flying. Note.— The effects of the alignment tolerance in 4,b,1 should be taken nno account.	Infra-red scene representative of both 350 m (1,200 ft), and 1,609 m (1 sm) RVR. Visual scene may be removed.	The scene will correctly represent the thermal
	×		×	×	×		×	×	×
	Not applicable.				Flight		Takeoff point and on approach at 200 ft.	Flight	Day and night
	Not less than 14 ed/m² (4.1 ft-lamberts) on the display.		Static alignment with displayed image. HUD bore sight must align with the center of the displayed image spherical pattern. Tolerance +-/- 6 are min.	All functionality in all flight modes must be demonstrated.	Pitch and roll align with aircraft instruments.		Alignment between EFVS display and out of the window image must represent the alignment typical of the aircraft and system type.	The scene represents the EFVS view at 350 m (1,200 ft) and 1,609 m (1 sm) RVR including correct light intensity.	Demonstrate thermal crossover effects during day to night transition.
	Surface brightness.	Head-Up Display (HUD)	Static Alignment.	System display.	HUD attitude versus FTD attitude indicator (pitch and roll of horizon).	Enhanced Flight Vision System (EFVS)	Registration test.	EFVS RVR and visibility calibration.	Thermal crossover.
	4.a.8	4.b	4.b.1	4.b.2	4.b.3	4.c	4.c.1	4.c.2	4.c.3

						characteristics of the scene during a day to night transition.
4.d	Visual ground segment					
4411	Visual ground segment (VGS).	Near end: the correct number of approach ingins within the computed VGS must be visible. Far end: ±20% of the computed VGS. The threshold lights computed to be visible must be visible in the FTD.	Trimmed in the landing configuration at 30 m (onfiguration at 30 m (100 ft) wheel height above touchdown zone on gilde slope at an RVR setting of 300 m (1,000 ft) or 350 m (1,200 ft).	This test is designed to assess items impacting the accuracy of the visual scene presented to a pilot an ecuation of the visual scene presented to a pilot. These items include: 1) RVR/Visibility; 2) gide slope (G/S) and localizer modeling accuracy (location and slope) for an ILS; 3) for a given weight, configuration and speed representative of a point within the airplane's operational envelope for a normal approach and landing; and 4) Radio altimeter. 4) Radio altimeter. 4) Radio altimeter is a normal approach and should be described and included in the sloud should be described and included in the sloud should be described and included in the sloud ronge visibility calculation is seed in the VCS computation.	×	Pre-position for this test is eventuaged but may be achieved via manual or autoplist control to the desired position.
4.e	Visual System Capacity					
4.e.1	System capacity – Day mode.	Not less than: 10,000 visible textured surfaces, 6,000 light points, 16 moving models.	Not applicable		×	Demonstrated through use of a visual scene randered with the same image generator modes used to produce scenes for training. The required surfaces, light points, and moving models simultaneously.
4.e.2	System capacity – Twilight/night mode.	Not less than: 10,000 visible textured visible textured and affaces, 15,000 light points, 15 moving models.	Not applicable		×	Demonstrated through use of a visual scene rendered with the same image generator modes used to produce scenes for training. The required surfaces, light points, and moving models should be displayed simultaneously.
5. Sound System. The sponsor will rappropriate) durin compared to the ir sound system. If the test or the spon	ystem. or will not be required to r c) during continuing quali or the initial qualification rm. If the frequency respo	epeat the operational sound to fication evaluations if freque evaluation results, and the sp mse test method is chosen an expeat the operational sound to	tests (i.e., tests 5.a.l. through necessions and backgroun sonsor shows that no softwarn drails, the sponsor may electests. If the operational sound	5. Sound System. The sponsor will not be required to repeat the operational sound tests (i.e., tests 5.a.l. through 5.a.8. (or 5.b.l. through 5.b.9.) and 5.c., as proportion of unitarity confined to the state of the state of the state of admittance or evaluation restraints and the sponsor and background noise test results are within otherance when compared to the initial qualification evaluation restraints, and the sponsor shows that no software changes have occurred that will affect the FTD's sound system. If the frequency response test method is chosen and fails, the sponsor may elect to fix the frequency response problem and repeat the test or the sponsor may elect to repeat the operational sound tests. If the operational sound tests are repeated during continuing qualification		

evaluations unweighted from where	evaluations, the results may be compared against initial qualify unweighted 1/3-octave band format from band 17 to 42 (50 H. from where the initial evaluation sound results were gathered.	vared against initial qualification band 17 to 42 (50 Hz to m results were gathered.	tion evaluation results. All to 16 kHz). A minimum 20 se	evaluations, the results may be compared against initial qualification evaluation results. All tests in this section must be presented using an unweighed 113-cave behad format from band 17 to 42 (50 Hz to 16 kHz). A minimum 20 second average must be taken at a common location from where the mittal evaluation sound results were gathered.		
5.a.	Turbo-jet airplanes.					All tests in this section should be presented using an unweighted 1/3-octave band format from at least band 17 to 42 (50 Hz to 16 kHz).
						A measurement of minimum 20 should be taken at the location corresponding to the approved data set.
						Refer to paragraph 7 of Appendix A, Attachment 2.
5.a.1.	Ready for engine start.	Initial evaluation: Subjective assessment of 1/3 octave bands.	Ground.	Normal condition prior to engine start. The APU must be on if appropriate.	X	
		Recurrent evaluation: cannot evecede ± dB difference on three consecutive bands when compared to initial compared to initial avarage of the absolute differences between initial and recurrent evaluation results evaluation results				
5.a.2.	All engines at idle.	Initial evaluation: Subjective assessment of 1/3 octave bands.	Ground.	Normal condition prior to takeoff.	×	
		evenion yearangement of another personal difference on three consecutive bands when consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results				
5.a.3.	All engines at maximum allowable thrust with brakes set.	Initial evaluation: Subjective assessment of 1/3 octave bands.	Ground.	Normal condition prior to takeoff.	×	
		Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when				

	x	×	x	x
		8		
	Medium altitude.	Normal cruise configuration.	Normal and constant speed brake deflection for descent at a constant airspeed and power setting.	Constant airspeed, gear up, flaps/slats as appropriate.
	En-route climb.	Cruise.	Cruise.	Approach.
compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: Subjective assessment of 1/3 octave bands. Recurrent evaluation: cannot exceed ±5 dB difference on three compact to initial and evaluation and the average of the absolute differences between initial and recurrent evaluation results evaluation results	Initial evaluation. Subjective assessment of 1/3 octave bands. Recurrent evaluation: cannot exceed ±5 dB difference on three compared to initial and evaluation and the average of the absolute differences between initial and recurrent evaluation results evaluation results	Initial evaluation. Subjective assessment of 1/3 octave bands. Recurrent evaluation: cannot exceed ±5 dB difference on three compared to initial and compared to initial and evaluation and the average of the absolute differences between initial and recurrent evaluation results evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands.
	Climb	Critise	Spreed brake/spoilers extended (as appropriate).	Initial approach.
	5.a.4.	5.a.5.	5.a.6.	5.a.7

		All tests in this section should be presented sing an unweighted 1/3-octave band format from at least band 17 to 42 (50 Hz to 16 kHz). A measurement of minimum 20 s should be taken at the location corresponding to the approved data set. Refer to paragraph 7 of Appendix A, Attachment 2.	
	×		×
	Constant airspeed, gear down, landing configuration flaps.		Normal condition prior to engine start. The APU must be on if appropriate.
	Landing.		Ground.
Recurrent evaluation: cannot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results	Initial evaluation: Subjective assessment of 1/3 cotave bands. Recurrent evaluation: amnot exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between mittal and recurrent evaluation results evaluation results	lance	Initial evaluation: Subjective assessment of 1/3 cetave bands. Recurrent evaluation: Recurrent evaluation: Compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation essults cannot essueed 2 dB.
	Final approach.	Propeller-driven airplanes	Ready for engine start.
	જ. લ.	5.b	5.b.l.

×	×	×	×
off.	J.L.	Ħ	JH.
to take-	to take	to take	to take
n prior	n prior	n prior	n prior
onditio	onditio	onditio	onditio
Normal condition prior to take-off.	Normal condition prior to takeoff.	Normal condition prior to takeoff.	Normal condition prior to takeoff.
2	2	2	2
ri	Ti.	ri	-
Ground.	Ground	Ground	Ground
ent	ent	ent B B when	ent B when
Intrial evaluation: Subjective assessment Subjective assessment Subjective bands. Recurrent evaluation: cannot exceed ±5 dB Gifference on three bands when consecutive bands when consecutive bands when differences between intial and recurrent initial and recurrent initial and recurrent evaluation results evaluation results evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands. Recurrent evaluation: Recurrent evaluation: eamon exceed ±5 dB difference on three consecutive bands when compared to initial evaluation and the average of the absolute differences between initial and recurrent evaluation results	Initial evaluation: Subjective assessment of 1/3 octiave bands. Recurrent evaluation: cannot exceed ±5 dB difference on the pant's when consecutive bands when consecutive bands when consecutive bands when differences between differences between initial and recurrent initial and recurrent initial and recurrent evaluation results evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands. Georrent evaluation: amont exceed ±5 dB difference on three consecutive bands when ocmpared to initial evaluation and the
Initial evaluation: Subjective assessand of IJ3 courve bands of IJ3 courve bands Recurrent evaluatic earnot eveced ±3 difference on three consecutive bands, average of the abso- differences between the contraction and the availation and the average of the abso- initial and recurrent evaluation results.	Initial evaluation: Subjective assessm of 1/3 coave bands of 1/3 coave bands Recurrent evaluatic cannot evected ±3 difference on three consecutive bands or onescentive bands are areage of the abso- differences between the	Initial evaluation: Subjective assessment of 1/3 corave bande Recurrent evaluatic earnot eveced ±3 difference on three consecutive bands consecutive bands evaluation and the average of the abso- differences betwee initial and recurren evaluation results	Initial evaluation: Subjective assessm of 1/3 octave band Recurrent evaluatic eannot exceed ±5 ed difference on three consecutive bands compared to initial
Subjort Subjor	Initia Subj of 1/ Recu cann diffe const comp evalt aver diffe initia evalt	Initite Subjoof 1/1/10 of	Inititie Subjort 1/10 of 1/1 o
			wable ikes
pellers 3d, if ble.	ent.	ent.	ines at allo and allo with bra
All propellers feathered, if applicable.	Ground idle or equivalent.	Flight idle or equivalent.	All engines at maximum allowable power with brakes set.
5.b.2	5.b.3.	5.b.4	5.b.5

Pt. 60, App. B

	×	×	×	×
	Medium altitude.	Normal cruise configuration.	Constant airspeed, gear up, gar up, faps extended as appropriate, RPM as per operating manual.	Constant airspeed, gear down, landing configuration flaps, RPM as per operating manual.
	En-route climb.	Cruise.	Approach.	Landing.
average of the absolute differences between initial and recurrent evaluation results cannot exceed 2 dB.	Initial evaluation: Subjective assessment of 13 octave bands. Information: Consecutive bands and the consecutive bands when mintial and recurrent evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands. Recurrent evaluation: Recurrent evaluation: Conspective bands when conspective bands when compared to initial average of the absolute differences between initial and recurrent evaluation results evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands. Recurrent evaluation: Recurrent evaluation: Compared on initial average of the absolute average of the absolute differences between initial and recurrent evaluation results evaluation results	Initial evaluation: Subjective assessment of 1/3 octave bands.
	Climb,	Cruise	Initial approach.	Final approach.
	5.b.6	S.b.7	S.b.8	5.b.9

Recurrent evaluation: compared to mine and advanced and difference on three compared to mine and advanced actual difference between initial and accurrent compared to mine average of the absolute compared to mine average of the absolute initial and accurrent compared to mine average of the absolute compared to mine average of the absolute compared to mine average of the absolute and fifteence assessment of 13 octave bands. Subjective assessment of 13 octave bands and consecutive bands when compared to mine and approved by the responsible Fight average of the absolute initial and certain and approved by the responsible Fight average of the absolute band compared to initial evaluation: ### Frequency response Initial evaluation: ### Recurrent evaluation: ### Additionate on three consecutive bands when consecutive bands when evaluation and the average of the absolute band severage of the absolute band severage of the absolute consecutive bands when evaluation and the average of the absolute band severage of the absolute band severage of the absolute average of the absolute band severage of the absolute average of the
difference on three consecutive bands when consecutive bands when consecutive bands when consecutive bands and recurrent witigal and recurrent evaluation results cannot exceed 2 dB. Initial evaluation: Subjective assessment of 1/3 octave bands. Recurrent evaluation: Subjective bands when compared to initial and recurrent evaluation: amont exceed ±5 dB difference of the absolute difference of the absolute difference of the absolute differences between initial and recurrent evaluation and the avaluation background noise levels must fall below the sound levels described in Appendix A. Attachment 2. Paragraph 7.c.(5). Recurrent evaluation: Attachment 2. Paragraph 7.c.(5). Recurrent evaluation: and difference on three consecutive bands when compared to initial evaluation. Attachment 2. Recurrent evaluation: and difference of the absolute difference of the average of the absolute difference between the average of the absolute that a surge of the average
Special cases. FTD background noise Frequency response

_			
			cech axis. Where EFVS systems are installed, the EFVS response should be within + or - 30 ms from visual system response, and not before motion system response. Note.—The delay from the airplane EFTS electronic elements should be added to the 30 ms tolerance before elements should be added to the 30 ms tolerance before elements should be added to the 30 ms tolerance before in the system reglerence. If transport delay is the chosen method to demonstrate relative responses, the sponsor and the responsible Flight Standards office will use the latency values to ensure proper FTD response when reviewing those existing tests where latency can be identified (e.g., short period, roll response, rudder response).
			×
			×
			×
			Pitch, roll and yaw.
			Instrument response: 100 ms (or less) after airplane response. Visual system response. 120 ms (or less) after airplane response. 300 milliseconds or less after controller movement.
	SYSTEMS INTEGRATION	System response time	Iransport delay.
	9	6.а.	6.a.1 6.a.2

BEGIN INFORMATION

- 3. FOR ADDITIONAL INFORMATION ON THE FOL-LOWING TOPICS, PLEASE REFER TO APPENDIX A, ATTACHMENT 2, AND THE INDICATED PARA-GRAPH WITHIN THAT ATTACHMENT
 - · Control Dynamics, paragraph 4.
 - Motion System, paragraph 6.
 - Sound System, paragraph 7.
- Engineering Simulator Validation Data, paragraph 9.
- Validation Test Tolerances, paragraph 11.
 - Validation Data Road Map, paragraph 12.
- Acceptance Guidelines for Alternative Engines Data, paragraph 13.
- Acceptance Guidelines for Alternative Avionics, paragraph 14.
- Transport Delay Testing, paragraph 15.
- Continuing Qualification Evaluation Validation Data Presentation, paragraph 16.

END INFORMATION

4. ALTERNATIVE OBJECTIVE DATA FOR FTD LEVEL 5

BEGIN QPS REQUIREMENTS

- a. This paragraph (including the following tables) is relevant only to FTD Level 5. It is provided because this level is required to simulate the performance and handling characteristics of a set of airplanes with similar characteristics, such as normal airspeed/altitude operating envelope and the same number and type of propulsion systems (engines).
- b. Tables B2B through B2E reflect FTD performance standards that are acceptable to the FAA. A sponsor must demonstrate that a device performs within these parameters, as applicable. If a device does not meet the established performance parameters for some or for all of the applicable tests listed in Tables B2B through B2E, the sponsor may

use FAA accepted flight test data for comparison purposes for those tests.

- c. Sponsors using the data from Tables B2B through B2E must comply with the following:
- (1) Submit a complete QTG, including results from all of the objective tests appropriate for the level of qualification sought as set out in Table B2A. The QTG must highlight those results that demonstrate the performance of the FTD is within the allowable performance ranges indicated in Tables B2B through B2E, as appropriate.
- (2) The QTG test results must include all relevant information concerning the conditions under which the test was conducted; e.g., gross weight, center of gravity, airspeed, power setting, altitude (climbing, descending, or level), temperature, configuration, and any other parameter that impacts the conduct of the test.
- (3) The test results become the validation data against which the initial and all subsequent continuing qualification evaluations are compared. These subsequent evaluations will use the tolerances listed in Table B2A.
- (4) Subjective testing of the device must be performed to determine that the device performs and handles like an airplane within the appropriate set of airplanes.

END QPS REQUIREMENTS

BEGIN INFORMATION

d. The reader is encouraged to consult the Airplane Flight Simulator Evaluation Handbook, Volumes I and II, published by the Royal Aeronautical Society, London, UK, and AC 25–7, Flight Test Guide for Certification of Transport Category Airplanes, and AC 23–8A, Flight Test Guide for Certification of Part 23 Airplanes, as amended, for references and examples regarding flight testing requirements and techniques.

END INFORMATION

	Table B2B - Alternative Data Source for FTD Level 5	ce for FTD Level 5
	Small, Single Engine (Reciprocating) Airplane	ating) Airplane
	QPS REQUIREMENT	INT
	The performance parameters in this table must be used to program the FTD	t be used to program the FTD
	if flight test data is not used to program the FTD.	ogram the FTD.
	Applicable Test	A set to mirror
Entry Number	Title and Procedure	Aunotized Performance Range
1.	Performance.	
1.c	Climb.	
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb airsneed	Climb rate = $500 - 1200$ fpm (2.5 - 6 m/sec).
1.f.	Engines.	
1.f.1.	Acceleration; idle to takeoff power.	2 - 4 Seconds.
1.f.2.	Deceleration; takeoff power to idle.	2 - 4 Seconds.
2.	Handling Qualities.	
2.c.	Longitudinal Tests.	
2.c.1.	Power change force.	
	(a) Trim for straight and level flight at 80% of normal cruise airspeed	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	with necessary power. Reduce power to flight idle. Do not change	
	trim or configuration. After stabilized, record column force necessary	
	to maintain original airspeed.	
	OR	

	Table BZB - Alternative Data Source for FTD Level 5	ree for FTD Level 5
	Small, Single Engine (Reciprocating) Airplane	ating) Airplane
	QPS REQUIREMENT	INE
	The performance parameters in this table must be used to program the FTD	t be used to program the FTD
	if flight test data is not used to program the FTD.	rogram the FTD.
	Applicable Test	Authorizad
Entry Number	Title and Procedure	Performance Range
	(b) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Add power to maximum setting. Do	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
	not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	
2.c.2.	Flap/slat change force.	
	(a) Trim for straight and level flight with flaps fully retracted at a	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	constant an speed within the haps-extended an speed range. Do not adjust trim or power. Extend the flaps to 50 percent of full flap travel.	
	After stabilized, record stick force necessary to maintain original	
	airspeed.	
	OR	
	b) Trim for straight and level flight with flaps extended to 50% of full	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
	flap travel, at a constant airspeed within the flaps-extended airspeed	
	range. Do not adjust trim or power. Retract the flaps to zero. After	
	stabilized, record stick force necessary to maintain original airspeed.	
2.c.4.	Gear change force.	
	(a) Trim for straight and level flight with landing gear retracted at a	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).
	constant airspeed within the landing gear-extended airspeed range.	
	Do not adjust trim or power. Extend the landing gear. After	
	stabilized, record stick torce necessary to maintain original airspeed.	
	OR	
	(b) Trim for straight and level flight with landing gear extended, at a	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).
	constant airspeed within the landing gear-extended airspeed range.	
	Do not adjust trim or power. Retract the landing gear. After	
	stabilized, record stick force necessary to maintain original airspeed.	
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the
		following configurations: cruise; approach; and landing.
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.

	Table B2B - Alternative Data Source for FTD Level 5	rce for FTD Level 5
	Small, Single Engine (Reciprocating) Airplane	cating) Airplane
	QPS REQUIREMENT	ENT
	The performance parameters in this table must be used to program the FTD	st be used to program the FTD
	if flight test data is not used to program the FTD.	rogram the FTD.
	Applicable Test	bosino de la
Entry Number	Title and Procedure	Aumorized Performance Range
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross	
	weight; wings level; and a deceleration rate of not more than three (3)	
	knots per second.	
	a) Landing configuration.	$40 - 60 \text{ knots}; \pm 5^{\circ} \text{ of bank}.$
	b) Clean configuration.	Landing configuration speed + 10 - 20%.
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. Mag
		½ or double amplitude in less than 2 cycles.
2.d.	Lateral Directional Tests.	
2.d.2.	Roll response (rate).	Must have a roll rate of 4° - 25°/second.
	Roll rate must be measured through at least 30 degree of roll. Aileron	
	control must be deflected 1/3 (33.3 percent) of maximum travel.	
2.d.4.c.	Spiral stability.	Initial bank angle (\pm 5°) after 20 seconds.
	Cruise configuration and normal cruise airspeed. Establish a 20	
	degree - 30 degree bank. When stabilized, neutralize the aileron	
	control and release. Must be completed in both directions of turn.	
2.d.6.b.	Rudder response.	2° - 6° /second yaw rate.
	Use 25 percent of maximum rudder deflection.	
	(Applicable to approach or landing configuration.)	
2.d.8.	Steady state sideslip.	2 percent – 10 percent of bank; 4 percent - 10 percent of sic
	Use 50 percent rudder deflection.	2 percent -10 percent of aileron.
	(Applicable to approach and landing configurations.)	
6.	FTD System Response Time.	
6.а.	Flight deck instrument systems response to an abrupt pilot controller input. One test is required in each axis (pitch. roll, yaw).	300 milliseconds or less.

	Table B2C - Alternative Data Source for FTD Level 5	Source for FTD Level 5
	Small, Multi-Engine (Reciprocating) Airplane	procating) Airplane
	QPS REQUIREMENT The performance parameters in this table must be used to program the FTD	SMENT must be used to program the FTD
	if Hight test data is not used to program the FTD. Applicable Test	
Entry Number	Title and Procedure	Authorized Performance Range
1.	Performance.	
1.c	Climb.	
1.c.1.	Normal climb with nominal gross weight, at best rate-of-climb	Climb airspeed = $95 - 115$ knots.
1.f.	Engines.	
1.f.1.	Acceleration; idle to takeoff power.	2 - 5 Seconds.
1.f.2.	Deceleration; takeoff power to idle.	2 - 5 Seconds.
2.	Handling Qualities.	
2.c.	Longitudinal Tests.	
2.c.1.	Power change force.	
	(a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	10 - 25 lbs (2.2 - 6.6 daN) of force (Push).
	OR	
	(b) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Add power to maximum serting. Do not change trim or configuration. After stabilized	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
	record column force necessary to maintain original airspeed.	
2.c.2.	Flap/slat change force.	
	(a) Trim for straight and level flight with flaps fully retracted at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or notice. Extend the flaps to 50 percent of full	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	not adjust time of power. External the raps to 50 percent of tun. flap travel. After stabilized, record stick force necessary to maintain original airspeed.	

Œ
ш
⊒
⊢.
<u>s</u>
ō
₹
>
Š.
16L3 v
6H6L3 v
H6H6L3 v
16H6L3 v
APBH6H6L3 v
эвненега и
n LAPBH6H6L3 v

	Table B2C - Alternative Data Source for FTD Level 5	Source for FTD Level 5
	Small, Multi-Engine (Reciprocating) Airplane	procating) Airplane
	QPS REQUIREMENT	EMENT
	The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD.	must be used to program the FTD to program the FTD.
	Applicable Test	Australia
Entry Number	Title and Procedure	Aumorizea Performance Range
	OR	
	(b) Trim for straight and level flight with flaps extended to 50 nercent of full flan travel at a constant aircneed within the flans.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
	extended airspeed range. Do not adjust trim prower. Retract	
	the haps to zero. After stabilized, record stick force necessary to maintain original airspeed.	
2.c.4.	Gear change force.	
	(a) Trim for straight and level flight with landing gear retracted	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).
	at a constant airspeed within the landing gear-extended airspeed	
	range. Do not aujust unit of power. Exterior tile railoring gear. After stabilized, record stick force necessary to maintain original	
	airspeed.	
	OR	
	(b) Trim for straight and level flight with landing gear extended,	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).
	at a constant an speed within the fanding gear-extended an speed range. Do not adjust trim or power. Retract the landing gear.	
	After stabilized, record stick force necessary to maintain original	
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the
		following configurations: cruise; approach; and landing.
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.
2.c.8.	Stall warning (actuation of stall warning device) with nominal	
	gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.	

Table B2D - Alternative Data Source for FTD Level 5 Small, Single Engine (Turbo-Propeller) Airplane	ne am the FTD Authorized Performance Range
Small, Single Engine (Turbo-Properties)	ne am the FTD Authorized Performance Range
The performance parameters in this table mus if flight test data is not used to promance. Intry Performance. Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trint and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	am the FTD Authorized Performance Range
The performance parameters in this table mus if flight test data is not used to proper any and a performance. Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trint and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	am the FTD Authorized Performance Range
ntry mber Performance. Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trint and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	Authorized Performance Range
mber Title and Procedure Performance. Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trint for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	Authorized Performance Range
Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	D
Climb. Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Normal climb with nominal gross weight, at best rate-of-climb airspeed. Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Engines. Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	95 – 115 knots. – 1800 fpm (4 - 9 m/sec)
Acceleration; idle to takeoff power. Deceleration; takeoff power to idle. Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Handling Qualities. Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Longitudinal Tests. Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
Power change force. a) Trim for straight and level flight at 80 percent of normal cruise airspeed with necessary power. Reduce power to flight idle. Do	
not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	8 lbs (3.5 daN) of Push force – 8 lbs (3.5 daN) of Pull force.
OR	
b) Trim for straight and level flight at 80 percent of normal cruise 12 - 22 lbs (5.3 – 9.7 daN) of force (Pull).	9.7 daN) of force (Pull).
airspeed with necessary power. Add power to maximum setting. Do not change trim or configuration. After stabilized, record	
column force necessary to maintain original airspeed.	
2.c.2. Flap/slat change force.	
I	6 daN) of force (Push).
constant airspeed within the flaps-extended airspeed range. Do	
not adjust trim or power. Extend the flaps to 50 percent of full	
tlap travel. After stabilized, record stick force necessary to	
OR OR	

	Table B2D - Alternative Data Source for FTD Level 5	irce for FTD Level 5
	Small, Single Engine (Turbo-Propeller) Airplane	ropeller) Airplane
	QPS REQUIREMENT	ENT
	The performance parameters in this table must be used to program the FTD	st be used to program the FTD
	if flight test data is not used to program the FTD	rogram the FTD.
	Applicable Test	Anthonizoe
Entry Number	Title and Procedure	Performance Range
	b) Trim for straight and level flight with flaps extended to 50 percent of full flap travel, at a constant airspeed within the flapsextended airspeed range. Do not adjust trim or power. Retract the	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
	flaps to zero. After stabilized, record stick force necessary to maintain original airspeed.	
2.c.4.	Gear change force.	
	a) Trim for straight and level flight with landing gear retracted at a constant aircneed within the landing oear-extended aircneed range	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).
	Do not adjust trim or power. Extend the landing gear. After	
	stabilized, record stick force necessary to maintain original	
	airspeed.	
	OR	
	b) Trim for straight and level flight with landing gear extended, at	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).
	a constant airspeed within the landing gear-extended airspeed	
	range. Do not adjust trim or power. Ketract the landing gear. After stabilized, record stick force necessary to maintain original	
	airspeed.	
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the following configurations: cruise: approach; and landing.
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.
2.c.8.	Stall warning (actuation of stall warning device) with nominal	
	gross weight; wings level; and a deceleration rate of not more than three (3) knots ner second	
	a) Landing configuration.	60 - 90 knots: + 5 degree of hank.
	b) Clean configuration.	Landing configuration speed + 10 - 20 percent.
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of $30 - 60$ seconds. May not reach $1/2$ or double amplitude in less than 2 cycles.

	Table B2E - Alternative Data Source for FTD Level 5	urce for FTD Level 5
	Multi-Engine (Turbo-Propeller) Airplane	oeller) Airplane
	QPS REQUIREMENT	AENT
	The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD.	ust be used to program the FTD program the FTD.
	Applicable Test	
Entry Number	Title and Procedure	Authorized Performance Range
	Performance.	
j.	Climb.	
l.c.1.	Normal climb with nominal gross weight, at best rate-of-climb airspeed.	Climb airspeed = 120 – 140 knots. Climb rate = 1000 – 3000 fpm (5 - 15 m/sec)
J.	Engines.	
.f.1.	Acceleration; idle to takeoff power.	2 - 6 Seconds.
l.f.2.	Deceleration; takeoff power to idle.	1 - 5 Seconds.
	Handling Qualities.	
.c.	Longitudinal Tests.	
2.c.1.	Power change force.	
	a) Trim for straight and level flight at 80 percent of normal cruise	8 lbs (3.5 daN) of Push force to 8 lbs (3.5 daN) of Pull force.
	airspeed with necessary power. Reduce power to flight idle. Do	
	not change trim or configuration. After stabilized, record column force necessary to maintain original airspeed.	
	OR	
	b) Trim for straight and level flight at 80 percent of normal cruise	12 - 22 lbs (5.3 – 9.7 daN) of force (Pull).
	airspeed with necessary power. Add power to maximum setting.	
	Do not change trim or configuration. After stabilized, record	
	column force necessary to maintain original airspeed.	
2.c.2.	Flap/slat change force.	
	a) Trim for straight and level flight with flaps fully retracted at a	5 - 15 lbs (2.2 - 6.6 daN) of force (Push).
	constant airspeed within the flaps-extended airspeed range. Do	
	not adjust trim or power. Extend the flaps to 50 percent of full	
	flap travel. After stabilized, record stick force necessary to	
	maintain original airspeed.	
	OR	

	Table B2E - Alternative Data Source for FTD Level 5	urce for FTD Level 5
	Multi-Engine (Turbo-Propeller) Airplane	oeller) Airplane
	QPS REQUIREMENT	AENT
	The performance parameters in this table must be used to program the FTD if flight test data is not used to program the FTD.	ist be used to program the FTD program the FTD.
	Applicable Test	Positivo el tra
Entry Number	Title and Procedure	Aumorizeu Performance Range
	b) Trim for straight and level flight with flaps extended to 50 percent of full flap travel, at a constant airspeed within the flaps-extended airspeed range. Do not adjust trim or power. Retract the flaps to zero. After stabilized, record stick force necessary to maintain original airspeed.	5 - 15 lbs (2.2 - 6.6 daN) of force (Pull).
2.c.4.	Gear change force.	
	a) Trim for straight and level flight with landing gear retracted at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Extend the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Push).
	OR	
	b) Trim for straight and level flight with landing gear extended, at a constant airspeed within the landing gear-extended airspeed range. Do not adjust trim or power. Retract the landing gear. After stabilized, record stick force necessary to maintain original airspeed.	2 - 12 lbs (0.88 - 5.3 daN) of force (Pull).
2.c.5.	Longitudinal trim.	Must be able to trim longitudinal stick force to "zero" in each of the following configurations: cruise; approach; and landing.
2.c.7.	Longitudinal static stability.	Must exhibit positive static stability.
2.c.8.	Stall warning (actuation of stall warning device) with nominal gross weight; wings level; and a deceleration rate of not more than three (3) knots per second.	
	a) Landing configuration.	80 - 100 knots; $\pm 5^{\circ}$ of bank.
	b) Clean configuration.	Landing configuration speed + 10 - 20 percent.
2.c.9.b.	Phugoid dynamics.	Must have a phugoid with a period of 30 - 60 seconds. May not reach $^{1/2}$ or double amplitude in less than 2 cycles.
2.d.	Lateral Directional Tests.	

END QPS REQUIREMENTS

BEGIN OPS REQUIREMENTS

- 5. ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION: LEVEL 6 FTD ONLY
- a. Sponsors are not required to use the alternative data sources, procedures, and instrumentation. However, a sponsor may choose to use one or more of the alternative sources, procedures, and instrumentation described in Table B2F.

END QPS REQUIREMENTS

BEGIN INFORMATION

- b. It has become standard practice for experienced FTD manufacturers to use such techniques as a means of establishing data bases for new FTD configurations while awaiting the availability of actual flight test data; and then comparing this new data with the newly available flight test data. The results of such comparisons have, as reported by some recognized and experienced simulation experts, become increasingly consistent and indicate that these techniques, applied with appropriate experience, are becoming dependably accurate for the development of aerodynamic models for use in Level 6 FTDs.
- c. In reviewing this history, the responsible Flight Standards office has concluded that, with proper care, those who are experienced in the development of aerodynamic models for FTD application can successfully use these modeling techniques to acceptably alter the method by which flight test data may be acquired and, when applied to Level 6 FTDs, does not compromise the quality of that simulation.
- d. The information in the table that follows (Table of Alternative Data Sources, Procedures, and Information: Level 6 FTD Only) is presented to describe an acceptable alternative to data sources for Level 6 FTD modeling and validation, and an acceptable alternative to the procedures and instrumentation found in the flight test methods traditionally accepted for gathering modeling and validation data.
- (1) Alternative data sources that may be used for part or all of a data requirement are

- the Airplane Maintenance Manual, the Airplane Flight Manual (AFM), Airplane Design Data, the Type Inspection Report (TIR), Certification Data or acceptable supplemental flight test data.
- (2) The responsible Flight Standards office recommends that use of the alternative instrumentation noted in Table B2F be coordinated with the responsible Flight Standards office prior to employment in a flight test or data gathering effort.
- e. The responsible Flight Standards office position regarding the use of these alternative data sources, procedures, and instrumentation is based on three primary preconditions and presumptions regarding the objective data and FTD aerodynamic program modeling.
- (1) Data gathered through the alternative means does not require angle of attack (AOA) measurements or control surface position measurements for any flight test. AOA can be sufficiently derived if the flight test program insures the collection of acceptable level, unaccelerated, trimmed flight data. Angle of attack may be validated by conducting the three basic "fly-by" trim tests. The FTD time history tests should begin in level, unaccelerated, and trimmed flight, and the results should be compared with the flight test pitch angle.
- (2) A simulation controls system model should be rigorously defined and fully mature. It should also include accurate gearing and cable stretch characteristics (where applicable) that are determined from actual aircraft measurements. Such a model does not require control surface position measurements in the flight test objective data for Level 6 FTD applications.
- f. Table B2F is not applicable to Computer Controlled Aircraft FTDs.
- g. Utilization of these alternate data sources, procedures, and instrumentation does not relieve the sponsor from compliance with the balance of the information contained in this document relative to Level 6 FTDs.
- h. The term "inertial measurement system" allows the use of a functional global positioning system (GPS).

END INFORMATION

TABLE B2F—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION LEVEL 6 FTD

The standards in this table are requi	QPS Requirements red if the data gathering methods described in paragraph 9 of Appendix B are not used.	Information
Objective test reference number and title	Alternative data sources, procedures, and instrumentation	Notes
1.b.1	Data may be acquired through a synchronized video recording of a stop watch and the calibrated airplane airspeed indicator. Hand-record the flight conditions and airplane configuration.	This test is required only if RTO is sought.
1.b.7. Performance. Takeoff. Rejected takeoff.	Data may be acquired through a synchronized video recording of a stop watch and the calibrated airplane airspeed indicator. Hand-record the flight conditions and airplane configuration.	This test is required only if RTO is sought.
1.c.1	Data may be acquired with a synchronized video of calibrated airplane instruments and engine power throughout the climb range.	
1.f.1. Performance. Engines. Acceleration	Data may be acquired with a synchronized video recording of engine instruments and throttle position.	
1.f.2. Performance. Engines. Deceleration	Data may be acquired with a synchronized video recording of engine instruments and throttle position.	
2.a.1.a. Handling qualities. Static control tests. Pitch controller position vs. force and surface position calibration.	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant column positions (encompassing significant column position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same column position data points	For airplanes with reversible control sys- tems, surface position data acquisition should be ac- complished with winds less than 5 kts.
2.a.2.a. Handling qualities. Static control tests. Wheel position vs. force and surface position calibration	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant wheel positions (encompassing significant wheel position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same wheel position data points	For airplanes with reversible control sys- tems, surface position data acquisition should be ac- complished with winds less than 5 kts.
2.a.3.a. Handling qualities. Static control tests. Rudder pedal position vs. force and surface position calibration	Surface position data may be acquired from flight data recorder (FDR) sensor or, if no FDR sensor, at selected, significant rudder pedal positions (encompassing significant rudder pedal position data points), acceptable to the responsible Flight Standards office, using a control surface protractor on the ground. Force data may be acquired by using a hand held force gauge at the same rudder pedal position data points	For airplanes with reversible control sys- tems, surface position data acquisition should be ac- complished with winds less than 5 kts.
2.a.4	Breakout data may be acquired with a hand held force gauge. The remainder of the force to the stops may be calculated if the force gauge and a protractor are used to measure force after breakout for at least 25% of the total displacement capability.	nto.
2.a.5 Handling qualities. Static control tests. Rudder pedal steering calibration.	Data may be acquired through the use of force pads on the rudder pedals and a pedal position measurement device, together with design data for nosewheel position.	

Table B2F—Alternative Data Sources, Procedures, and Instrumentation Level 6 FTD—Continued

The standards in this table are requi	QPS Requirements ired if the data gathering methods described in paragraph 9 of Appendix B are not used.	Information
Objective test reference number and title	Alternative data sources, procedures, and instrumentation	Notes
2.a.6	Data may be acquired through calculations.	
2.a.8. Handling qualities. Static control tests. Alignment of power lever angle vs. selected engine parameter (e.g., EPR, N ₁ , Torque, Manifold pressure).	Data may be acquired through the use of a temporary throttle quadrant scale to document throttle position. Use a synchronized video to record steady state instrument readings or hand-record steady state engine performance readings.	
2.a.9	Use of design or predicted data is acceptable. Data may be acquired by measuring deflection at "zero" and at "maximum."	
2.c.1. Handling qualities. Longitudinal control tests. Power change force.	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments, throttle position, and the force/position measurements of flight deck controls.	Power change dynamics test is acceptable using the same data ac- quisition methodology.
2.c.2. Handling qualities. Longitudinal control tests. Flap/slat change force.	Data may be acquired by using an inertial measurement system and a synchronized video of calibrated airplane instruments, flap/slat position, and the force/position measurements of flight deck controls.	Flap/slat change dynamics test is acceptable using the same data ac- quisition methodology.
2.c.4	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments, gear position, and the force/position measurements of flight deck controls.	Gear change dy- namics test is acceptable using the same data ac- quisition methodology.
2.c.5. Handling qualities. Longitudinal control tests. Longitudinal trim.	Data may be acquired through use of an inertial measurement system and a synchronized video of flight deck controls position (previously calibrated to show related surface position) and engine instrument readings.	
2.c.6	Data may be acquired through the use of an inertial measurement system and a synchronized video of the calibrated airplane instruments; a temporary, high resolution bank angle scale affixed to the attitude indicator; and a wheel and column force measurement indication.	
2.c.7	Data may be acquired through the use of a synchronized video of the airplane flight instruments and a hand held force gauge.	
2.c.8	Data may be acquired through a synchronized video recording of a stop watch and the calibrated airplane airspeed indicator. Handrecord the flight conditions and airplane configuration.	Airspeeds may be cross checked with those in the TIR and AFM.

TABLE B2F—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION LEVEL 6 FTD—Continued

The standards in this table are requi	QPS Requirements ired if the data gathering methods described in paragraph 9 of Appendix B are not used.	Information
Objective test reference number and title	Alternative data sources, procedures, and instrumentation	Notes
2.c.9.a. Handling qualities. Longitudinal control tests. Phugoid dynamics.	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck controls.	
2.c.10	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck controls.	
2.c.11	May use design data, production flight test schedule, or maintenance specification, together with an SOC.	
2.d.2	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck lateral controls.	
2.d.3	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck lateral controls.	
2.d.4	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments; the force/position measurements of flight deck controls; and a stop watch.	
2.d.6.a. Handling qualities. Lateral directional tests. Rudder response.	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments; the force/position measurements of rudder pedals.	
2.d.7	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck controls.	
2.d.8	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated airplane instruments and the force/position measurements of flight deck controls.	

ATTACHMENT 3 TO APPENDIX B TO PART 60—FLIGHT TRAINING DEVICE (FTD) SUBJECTIVE EVALUATION

BEGIN INFORMATION

1. Discussion

a. The subjective tests provide a basis for evaluating the capability of the FTD to perform over a typical utilization period. The items listed in the Table of Functions and Subjective Tests are used to determine whether the FTD competently simulates

each required maneuver, procedure, or task; and verifying correct operation of the FTD controls, instruments, and systems. The tasks do not limit or exceed the authorizations for use of a given level of FTD as described on the SOQ or as approved by the TPAA. All items in the following paragraphs are subject to examination.

b. All simulated airplane systems functions will be assessed for normal and, where appropriate, alternate operations. Simulated airplane systems are listed separately under "Any Flight Phase" to ensure appropriate attention to systems checks. Operational

navigation systems (including inertial navigation systems, global positioning systems, or other long-range systems) and the associated electronic display systems will be evaluated if installed. The pilot will include in his report to the TPAA, the effect of the system operation and any system limitation.

c. At the request of the TPAA, the Pilot may assess the FTD for a special aspect of a sponsor's training program during the functions and subjective portion of an evaluation. Such an assessment may include a portion of a specific operation (e.g., a Line Oriented Flight Training (LOFT) scenario) or special emphasis items in the sponsor's training program. Unless directly related to a requirement for the qualification level, the results of such an evaluation would not affect the qualification of the FTD.

END INFORMATION

	TABLE B3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 6 FTD
	QPS requirements
Entry No.	Operations tasks
Tasks in this	table are subject to evaluation if appropriate for the airplane system or systems simulated as indicated in the SOQ Configuration List as defined in Appendix B, Attachment 2 of this part.
1. Preflight	
	Accomplish a functions check of all installed switches, indicators, systems, and equipment at all crewmembers' and instructors' stations, and determine that the flight deck (or flight deck area) design and functions replicate the appropriate airplane.
2. Surface O	perations (pre-takeoff)
2.a	Engine start:
2.a.1	Normal start.
2.a.2	Alternative procedures start.
2.a.3	Abnormal procedures start/shut down.
2.b	Pushback/Powerback (powerback requires visual system).
3. Takeoff (re	equires appropriate visual system as set out in Table B1A, item 6; Appendix B, Attachment 1.)
3.a	Instrument takeoff:
3.a.1	Engine checks (e.g., engine parameter relationships, propeller/mixture controls).
3.a.2	Acceleration characteristics.
3.a.3	Nosewheel/rudder steering.
3.a.4	Landing gear, wing flap, leading edge device operation.
3.b	Rejected takeoff:
3.b.1	Deceleration characteristics.
3.b.2	Brakes/engine reverser/ground spoiler operation.
3.b.3	Nosewheel/rudder steering.
4. In-Flight C	perations
4.a	Normal climb.
4.b	Cruise:
4.b.1	Demonstration of performance characteristics (speed vs. power).
4.b.2	Normal turns.
4.b.3	Demonstration of high altitude handling.
4.b.4	Demonstration of high airspeed handling/overspeed warning.
4.b.5	Demonstration of Mach effects on control and trim.

	QPS requirements	
Entry No.	Operations tasks	
4.b.6	Steep turns.	
4.b.7	In-Flight engine shutdown (procedures only).	
4.b.8	In-Flight engine restart (procedures only).	
4.b.9	Specific flight characteristics.	
4.b.10	Response to loss of flight control power.	
4.b.11	Response to other flight control system failure modes.	
4.b.12	Operations during icing conditions.	
4.b.13	Effects of airframe/engine icing.	
4.c	Other flight phase:	
4.c.1	Approach to stalls in the following configurations:	
4.c.1.a	Cruise.	
4.c.1.b	Takeoff or approach.	
4.c.1.c	Landing.	
4.c.2	High angle of attack maneuvers in the following configurations:	
4.c.2.a	Cruise.	
4.c.2.b	Takeoff or approach.	
4.c.2.c	Landing.	
4.c.3	Slow flight.	
4.c.4	Holding.	
5. Approach	es	
5.a.	Non-precision Instrument Approaches:	
5.a.1	With use of autopilot and autothrottle, as applicable.	
5.a.2	Without use of autopilot and autothrottle, as applicable.	
5.a.3	With 10 knot tail wind.	
5.a.4	With 10 knot crosswind.	
5.b	Precision Instrument Approaches:	
5.b.1	With use of autopilot, autothrottle, and autoland, as applicable.	
5.b.2	Without use of autopilot, autothrottle, and autoland, as applicable.	
5.b.3	With 10 knot tail wind.	
5.b.4	With 10 knot crosswind.	
6. Missed Approach		
6.a	Manually controlled.	
6.b	Automatically controlled (if applicable).	
7. Any Flight Phase, as appropriate		
7.a	Normal system operation (installed systems).	
7.b	Abnormal/Emergency system operation (installed systems).	

TABLE B3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 6 FTD—Continued

	QPS requirements	
Entry No.	Operations tasks	
7.c	Flap operation.	
7.d	Landing gear operation.	
7.e	Engine Shutdown and Parking.	
7.e.1	Systems operation.	
7.e.2	Parking brake operation.	
	Operating Station (IOS), as appropriate. Functions in this section are subject to evaluation only if appropriate lane and/or installed on the specific FTD involved	
8.a	Power Switch(es).	
8.b	Airplane conditions.	
8.b.1	Gross weight, center of gravity, and fuel loading and allocation.	
8.b.2	Airplane systems status.	
8.b.3	Ground crew functions (e.g., external power, push back).	
8.c	Airports.	
8.c.1	Selection.	
8.c.2	Runway selection.	
8.c.3	Preset positions (e.g., ramp, over FAF).	
8.d	Environmental controls.	
8.d.1	Temperature.	
8.d.2	Climate conditions (e.g., ice, rain).	
8.d.3	Wind speed and direction.	
8.e	Airplane system malfunctions.	
8.e.1	Insertion/deletion.	
8.e.2	Problem clear.	
8.f	Locks, Freezes, and Repositioning.	
8.f.1	Problem (all) freeze/release.	
8.f.2	Position (geographic) freeze/release.	
8.f.3	Repositioning (locations, freezes, and releases).	
8.f.4	Ground speed control.	
8.f.5	Remote IOS, if installed.	
9. Sound Controls. On/off/adjustment		
10. Control Loading System (as applicable) On/off/emergency stop.		
11. Observer Stations.		
11.a	Position.	
11.b	Adjustments.	
	End QPS Requirements	

TABLE B3B—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 5 FTD

Accomplish a functions check of all installed switches, indicators, systems, and equipment at all crewmember and instructors' stations, and determine that the flight deck (or flight deck area) design and functions replicat the appropriate airplane. 2. Surface Operations (pre-takeoff) 2. a		QPS requirements
Accomplish a functions check of all installed switches, indicators, systems, and equipment at all crewmember and instructors' stations, and determine that the flight deck (or flight deck area) design and functions replicat the appropriate airplane. 2. Surface Operations (pre-takeoff) 2. a	Entry No.	Operations tasks Tasks in this table are subject to evaluation if appropriate for the airplane system or systems simulated as indicated in the SOQ Configuration List as defined in Appendix B, Attachment 2 of this part.
and instructors' stations, and determine that the flight deck (or flight deck area) design and functions replicat the appropriate airplane. 2. Surface Operations (pre-takeoff) 2. a	1. Preflight	
2.a		Accomplish a functions check of all installed switches, indicators, systems, and equipment at all crewmembers' and instructors' stations, and determine that the flight deck (or flight deck area) design and functions replicate the appropriate airplane.
2.a.1. Normal start. 2.a.2. Alternative procedures start. 2.a.3. Abnormal/Emergency procedures start/shut down. 3. In-Flight Operations 3.a. Normal climb. 3.b. Cruise: 3.b.1. Performance characteristics (speed vs. power). 3.b.2. Normal turns. 3.c. Normal descent. 4. Approaches 4.a. Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5.a. Normal system operation (Installed systems). 5.b. Abnormal/Emergency system operation (Installed systems). 5.c. Flap operation. 5.c. Engine Shutdown and Parking (if installed). 5.e. Parking brake operation. 6. Instructor Operating Station (IOS) 6.a. Power Switch(es). 6.b. Preset positions—ground, air. 6.c. Airplane system malfunctions (Installed systems). 6.c. Insertion/deletion.	2. Surface O	perations (pre-takeoff)
Alternative procedures start. 2.a.2	2.a	Engine start (if installed):
2.a.3. Abnormal/Emergency procedures start/shut down. 3. In-Flight Operations 3.a. Normal climb. 3.b. Cruise: 3.b.1. Performance characteristics (speed vs. power). 3.b.2. Normal turns. 3.c. Normal turns. 3.c. Normal descent. 4. Approaches 4.a. Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5.a. Normal system operation (Installed systems). 5.b. Abnormal/Emergency system operation (Installed systems). 5.c. Flap operation. 5.d. Landing gear operation 5.e. Engine Shutdown and Parking (if installed). 5.e.1. Systems operation. 6. Instructor Operating Station (IOS) 6.a. Power Switch(es). 6.b. Preset positions—ground, air. 6.c. Airplane system malfunctions (Installed systems). 6.c.1. Insertion/deletion.	2.a.1	Normal start.
3. In-Flight Operations 3. a	2.a.2	Alternative procedures start.
3.a. Normal climb. 3.b. Cruise: 3.b.1. Performance characteristics (speed vs. power). 3.b.2. Normal turns. 3.c. Normal descent. 4. Approaches 4.a. Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5.a. Normal system operation (Installed systems). 5.b. Abnormal/Emergency system operation (Installed systems). 5.c. Flap operation. 5.d. Landing gear operation 5.e. Engine Shutdown and Parking (if installed). 5.e.1. Systems operation. 6.e.2. Parking brake operation. 6. Instructor Operating Station (IOS) 6.a. Power Switch(es). 6.b. Preset positions—ground, air. 6.c. Airplane system malfunctions (Installed systems). 6.c.1. Insertion/deletion.	2.a.3	Abnormal/Emergency procedures start/shut down.
3.b	3. In-Flight (Operations
3.b.1 Performance characteristics (speed vs. power). 3.b.2 Normal turns. 3.c Normal descent. 4. Approaches 4.a Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5.a Normal system operation (Installed systems). 5.b Abnormal/Emergency system operation (Installed systems). 5.c Flap operation. 5.d Landing gear operation 5.e Engine Shutdown and Parking (if installed). 5.e.1 Systems operation. 5.e.2 Parking brake operation. 6. Instructor Operating Station (IOS) 6.a Power Switch(es). 6.b Preset positions—ground, air. 6.c Airplane system malfunctions (Installed systems). 6.c.1 Insertion/deletion.	3.a	Normal climb.
3.b.2 Normal turns. 3.c Normal descent. 4. Approaches 4.a Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5.a Normal system operation (Installed systems). 5.b Abnormal/Emergency system operation (Installed systems). 6.c Flap operation. 6.d Landing gear operation 6.e Engine Shutdown and Parking (if installed). 6.e Systems operation. 6.e Parking brake operation. 6. Instructor Operating Station (IOS) 6.a Power Switch(es). 6.b Preset positions—ground, air. 6.c Airplane system malfunctions (Installed systems). 6.c Insertion/deletion.	3.b	Cruise:
A. Approaches 4.a	3.b.1	Performance characteristics (speed vs. power).
4. Approaches 4. a	3.b.2	Normal turns.
Coupled instrument approach maneuvers (as applicable for the systems installed). 5. Any Flight Phase 5. a	3.c	Normal descent.
5. Any Flight Phase 5. a	4. Approach	es
Normal system operation (Installed systems). 5.b	4.a	Coupled instrument approach maneuvers (as applicable for the systems installed).
Abnormal/Emergency system operation (Installed systems). 5.c	5. Any Fligh	t Phase
5.c	5.a	Normal system operation (Installed systems).
5.d Landing gear operation 5.e Engine Shutdown and Parking (if installed). 5.e.1 Systems operation. 5.e.2 Parking brake operation. 6. Instructor Operating Station (IOS) 6.a Power Switch(es). 6.b Preset positions—ground, air. 6.c Airplane system malfunctions (Installed systems). 6.c.1 Insertion/deletion.	5.b	Abnormal/Emergency system operation (Installed systems).
5.e	5.c	Flap operation.
5.e.1 Systems operation. 5.e.2 Parking brake operation. 6. Instructor Operating Station (IOS) 6.a Power Switch(es). 6.b Preset positions—ground, air. 6.c Airplane system malfunctions (Installed systems). 6.c.1 Insertion/deletion.	5.d	Landing gear operation
5.e.2 Parking brake operation. 6. Instructor Operating Station (IOS) 6.a Power Switch(es). 6.b Preset positions—ground, air. 6.c Airplane system malfunctions (Installed systems). 6.c.1 Insertion/deletion.	5.e	Engine Shutdown and Parking (if installed).
6. Instructor Operating Station (IOS) 6.a	5.e.1	Systems operation.
6.a	5.e.2	Parking brake operation.
6.b	6. Instructor	Operating Station (IOS)
6.c Airplane system malfunctions (Installed systems). 6.c.1 Insertion/deletion.	6.a	Power Switch(es).
6.c.1 Insertion/deletion.	6.b	Preset positions—ground, air.
	6.c	Airplane system malfunctions (Installed systems).
6.c.2 Problem clear.	6.c.1	Insertion/deletion.
I	6.c.2	Problem clear.

Pt. 60, App. B

Table B3C

	Table Bac		
	Table of Functions and Subjective Tests		
	Level 4 FTD		
	QPS requirements		
	Operations tasks		
Entry	Tasks in this table are subject to evaluation if appropriate for the airplane system or systems		
No.	simulated as indicated in the SOQ Configuration List as defined in Appendix B, Attachment		
	2 of this part.		

1.	Level 4 FTDs are required to have at least one operational system. The responsible Flight
	Standards office will accomplish a functions check of all installed systems, switches,
	indicators, and equipment at all crewmembers' and instructors' stations, and determine that
	the flight deck (or flight deck area) design and functions replicate the appropriate airplane

Table B3D - Table of Functions and Subjective Tests		
	Level 7 FTD OPS REQUIREMENTS	
Entry	CIVEMENTO SELVENTE ID	
Number	Operations Tasks	
	Tasks in this table are subject to evaluation if appropriate for the airplane	
	simulated as indicated in the SOQ Configuration List or the level of FTD	
	qualification involved. Items not installed or not functional on the FTD and,	
	therefore, not appearing on the SOQ Configuration List, are not required to be	
1.	listed as exceptions on the SOQ. Preparation For Flight	
	1	
1.a.	Pre-flight. Accomplish a functions check of all switches, indicators, systems, and equipment at all crew members' and instructors' stations and determine that:	
1.a.1	The flight deck design and functions are identical to that of the airplane simulated.	
2.	Surface Operations (pre-flight).	
2.a.	Engine Start.	
2.a.1.	Normal start.	
2.a.2.	Alternate start procedures.	
2.a.3.	Abnormal starts and shutdowns (e.g., hot/hung start, tail pipe fire).	
2.b.	Taxi.	
2.b.1	Pushback/powerback	
2.b.2.	Thrust response.	
2.b.3.	Power lever friction.	
2.b.4.	Ground handling.	
2.b.5.	Reserved	
2.b.6.	Taxi aids (e.g. taxi camera, moving map)	
2.b.7.	Low visibility (taxi route, signage, lighting, markings, etc.)	
2.c.	Brake Operation Brake operation (normal and alternate/emergency).	
2.c.1. 2.c.2.	Brake fade (if applicable).	
3.	Take-off.	
3.a.	Normal.	
3.a.1.	Airplane/engine parameter relationships, including run-up.	
3.a.2.	Nosewheel and rudder steering.	
3.a.3.	Crosswind (maximum demonstrated and gusting crosswind).	
3.a.4.	Special performance	
3.a.4.a	Reduced V ₁	
3.a.4.b	Maximum engine de-rate.	
3.a.4.c	Soft surface.	
3.a.4.d	Short field/short take-off and landing (STOL) operations.	
3.a.4.e	Obstacle (performance over visual obstacle).	
3.a.5.	Low visibility take-off.	
3.a.6.	Landing gear, wing flap leading edge device operation.	
3.a.7.	Contaminated runway operation.	
3.b.	Abnormal/emergency.	

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD QPS REQUIREMENTS		
Entur	QFS REQUIREMENTS	
Entry Number	Operations Tasks	
3.b.1.	Rejected Take-off.	
3.b.2.	Rejected special performance (e.g., reduced V ₁ , max de-rate, short field	
	operations).	
3.b.3.	Rejected take-off with contaminated runway.	
3.b.4.	Takeoff with a propulsion system malfunction (allowing an analysis of causes,	
	symptoms, recognition, and the effects on aircraft performance and handling) at	
	the following points: .	
	(iii) Prior to V1 decision speed.	
	(iv) Between V1 and Vr (rotation speed).	
21.5	(iii)Between Vr and 500 feet above ground level.	
3.b.5.	Flight control system failures, reconfiguration modes, manual reversion and	
4.	associated handling.	
	Normal.	
4.a. 4.b.	One or more engines inoperative.	
4.c.	Approach climb in icing (for airplanes with icing accountability).	
5.	Cruise.	
5.a.	Performance characteristics (speed vs. power, configuration, and attitude)	
5.a.1.	Straight and level flight.	
5.a.1.	Change of airspeed.	
5.a.3.	High altitude handling.	
5.a.4.	High Mach number handling (Mach tuck, Mach buffet) and recovery (trim	
J	change).	
5.a.5.	Overspeed warning (in excess of V_{mo} or M_{mo}).	
5.a.6.	High IAS handling.	
5.b.	Maneuvers.	
5.b.1.	High Angle of Attack	
5.b.1.a	High angle of attack, approach to stalls, stall warning, and stall buffet (take-off,	
	cruise, approach, and landing configuration) including reaction of the autoflight	
	system and stall protection system.	
5.b.1.b	Reserved	
5.b.2.	Slow flight	
5.b.3.	Reserved	
5.b.4.	Flight envelope protection (high angle of attack, bank limit, overspeed, etc.).	
5.b.5.	Turns with/without speedbrake/spoilers deployed.	
5.b.6.	Normal and standard rate turns.	
5.b.7.	Steep turns	
5.b.8.	Performance turn	
5.b.9.	In flight engine shutdown and restart (assisted and windmill).	
5.b.10.	Maneuvering with one or more engines inoperative, as appropriate.	
5.b.11.	Specific flight characteristics (e.g., direct lift control).	
5.b.12.	Flight control system failures, reconfiguration modes, manual reversion and associated handling.	
5.b.13	Gliding to a forced landing.	
2.0.13	Onemg to a refered fanding.	

Table B3D - Table of Functions and Subjective Tests		
	Level 7 FTD QPS REQUIREMENTS	
Entry	Q15 REQUIREMENTS	
Number	Operations Tasks	
5,b,14	Visual resolution and FSTD handling and performance for the following (where	
	applicable by aircraft type and training program):	
5.b.14.a	Terrain accuracy for forced landing area selection.	
5.b.14.b	Terrain accuracy for VFR Navigation.	
5.b.14.c	Eights on pylons (visual resolution).	
5.b.14.d	Turns about a point.	
5.b.14.e	S-turns about a road or section line.	
6.	Descent.	
6.a.	Normal.	
6.b.	Maximum rate/emergency (clean and with speedbrake, etc.).	
6.c.	With autopilot.	
6.d.	Flight control system failures, reconfiguration modes, manual reversion and	
	associated handling.	
7.	Instrument Approaches And Landing.	
	Those instrument approach and landing tests relevant to the simulated airplane	
	type are selected from the following list. Some tests are made with limiting wind	
	velocities, under windshear conditions, and with relevant system failures,	
	including the failure of the Flight Director. If Standard Operating Procedures	
	allow use autopilot for non-precision approaches, evaluation of the autopilot will	
	be included.	
7.a.	Precision approach	
7.a.1	CAT I published approaches.	
7.a.1.a	Manual approach with/without flight director including landing.	
7.a.1.b	Autopilot/autothrottle coupled approach and manual landing.	
7.a.1.c	Autopilot/autothrottle coupled approach, engine(s) inoperative.	
7.a.1.d	Manual approach, engine(s) inoperative.	
7.a.1.e	HUD/EFVS	
7.a.2	CAT II published approaches.	
7.a.2.a	Autopilot/autothrottle coupled approach to DH and landing (manual and	
	autoland).	
7.a.2.b	Autopilot/autothrottle coupled approach with one-engine-inoperative	
	approach to DH and go-around (manual and autopilot).	
7.a.2.c	HUD/EFVS	
7.a.3	CAT III published approaches.	
7.a.3.a	Autopilot/autothrottle coupled approach to landing and roll-out (if applicable) guidance (manual and autoland).	
7 - 2 h	Autopilot/autothrottle coupled approach to DH and go-around (manual and	
7.a.3.b	autopilot/autothrottle coupled approach to DH and go-around (manual and autopilot).	
7.a.3.c	Autopilot/autothrottle coupled approach to land and roll-out (if applicable)	
/.a.s.c	guidance with one engine inoperative (manual and autoland).	
7.a.3.d	Autopilot/autothrottle coupled approach to DH and go-around with one	
/.a.s.u	engine inoperative (manual and autopilot).	
7.a.3.e	HUD/EFVS	
7.a.3.e 7.a.4	Autopilot/autothrottle coupled approach (to a landing or to a go-around):	
/.a.4	Autophorautounoute coupled approach (to a failuing of to a go-around).	

Table B3D - Table of Functions and Subjective Tests		
Level 7 FTD		
	QPS REQUIREMENTS	
Entry Number	Operations Tasks	
7.a.4.a	With generator failure.	
7.a.4.b.1	With maximum tail wind component certified or authorized.	
7.a.4.b.2	Reserved	
7.a.4.c.1	With maximum crosswind component demonstrated or authorized.	
7.a.4.c.2	Reserved	
7.a.5	PAR approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.a.6	MLS, GBAS, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.	Non-precision approach.	
7.b.1	Surveillance radar approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.2	NDB approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.3	VOR, VOR/DME, TACAN approach, all engines(s) operating and with one or more engine(s) inoperative.	
7.b.4	RNAV / RNP / GNSS (RNP at nominal and minimum authorized temperatures) approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.5	ILS LLZ (LOC), LLZ back course (or LOC-BC) approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.b.6	ILS offset localizer approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.c	Approach procedures with vertical guidance (APV), e.g. SBAS, flight path vector.	
7.c.1	APV/baro-VNAV approach, all engine(s) operating and with one or more engine(s) inoperative.	
7.c.2	Area navigation (RNAV) approach procedures based on SBAS, all engine(s) operating and with one or more engine(s) inoperative.	
8.	Visual Approaches (Visual Segment) And Landings.	
	Flight simulators with visual systems, which permit completing a special approach procedure in accordance with applicable regulations, may be approved for that particular approach procedure.	
8.a.	Maneuvering, normal approach and landing, all engines operating with and without visual approach aid guidance.	
8.b.	Approach and landing with one or more engines inoperative.	
8.c.	Operation of landing gear, flap/slats and speedbrakes (normal and abnormal).	
8.d.	Approach and landing with crosswind (max. demonstrated and gusting crosswind).	
8.e.	Approach and landing with flight control system failures, reconfiguration modes, manual reversion and associated handling (most significant degradation which is probable).	
8.e.1.	Approach and landing with trim malfunctions.	
8.e.1.a	Longitudinal trim malfunction.	
8.e.1.b	Lateral-directional trim malfunction.	

Table B3D - Table of Functions and Subjective Tests							
Level 7 FTD							
QPS REQUIREMENTS							
Entry Number	Operations Tasks						
8.f.	Approach and landing with standby (minimum) electrical/hydraulic power.						
8.g.	Approach and landing from circling conditions (circling approach).						
8.h.	Approach and landing from visual traffic pattern.						
8.i.	Approach and landing from non-precision approach.						
8.j.	Approach and landing from precision approach.						
9.	Missed Approach.						
9.a.	All engines, manual and autopilot.						
9.b.	Engine(s) inoperative, manual and autopilot.						
9.c.	Rejected landing						
9.d.	With flight control system failures, reconfiguration modes, manual reversion and						
	associated handling.						
9.e.	Reserved						
10.	Surface Operations (landing, after-landing and post-flight).						
10.a	Landing roll and taxi.						
10.a.1	HUD/EFVS.						
10.a.2.	Spoiler operation.						
10.a.3.	Reverse thrust operation.						
10.a.4.	Directional control and ground handling, both with and without reverse thrust.						
10.a.5.	Reduction of rudder effectiveness with increased reverse thrust (rear pod-						
	mounted engines).						
10.a.6.	Brake and anti-skid operation						
10.a.6.a	Brake and anti-skid operation with dry, patchy wet, wet on rubber residue, and						
	patchy icy conditions.						
10.a.6.b	Reserved						
10.a.6.c	Reserved						
10.a.6.d	Auto-braking system operation.						
10.b	Engine shutdown and parking.						
10.b.1	Engine and systems operation.						
10.b.2	Parking brake operation.						
11.	Any Flight Phase.						
11.a.	Airplane and engine systems operation (where fitted).						
11.a.1.	Air conditioning and pressurization (ECS).						
11.a.2.	De-icing/anti-icing.						
11.a.3.	Auxiliary power unit (APU).						
11.a.4.	Communications.						
11.a.5.	Electrical.						
11.a.6.	Fire and smoke detection and suppression.						
11.a.7.	Flight controls (primary and secondary).						
11.a.8.	Fuel and oil						
11.a.9.	Hydraulic						
11.a.10.	Pneumatic						
11.a.11.	Landing gear.						
11.a.12.	Oxygen.						
11.a.13.	Engine.						

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. B

Table B3D - Table of Functions and Subjective Tests							
Level 7 FTD							
	QPS REQUIREMENTS						
Entry Number							
11.a.14.	Airborne radar.						
11.a.15.	Autopilot and Flight Director.						
11.a.16.	Terrain awareness warning systems and collision avoidance systems (e.g. EGPWS, GPWS, TCAS).						
11.a.17.	Flight control computers including stability and control augmentation.						
11.a.18.	Flight display systems.						
11.a.19.	Flight management computers.						
11.a.20.	Head-up displays (including EFVS, if appropriate).						
11.a.21.	Navigation systems						
11.a.22.	Stall warning/avoidance						
11.a.23.	Wind shear avoidance/recovery guidance equipment						
11.a.24.	Flight envelope protections						
11.a.25.	Electronic flight bag						
11.a.26.	Automatic checklists (normal, abnormal and emergency procedures).						
11.a.27.	Runway alerting and advisory system.						
11.b.	Airborne procedures.						
11.b.1.	Holding.						
11.b.2.	Air hazard avoidance (traffic, weather, including visual correlation).						
11.b.3.	Windshear.						
11.b.3.a	Prior to take-off rotation.						
11.b.3.b	At lift-off						
11.b.3.c	During initial climb.						
11.b.3.d	On final approach, below 150 m (500 ft) AGL.						
11.b.4.	Reserved						

Table B3E - Functions And Subjective Tests							
Level 7 FTD							
QPS REQUIREMENTS							
Entry Number	Airport Modeling Requirements						
	cifies the minimum airport model content and functionality to qualify a simulator at the l. This table applies only to the airport models required for FTD qualification.						
	Begin QPS Requirements						
1.	Reserved						
2.a.	Functional test content requirements						
2.a.1	Airport scenes						
2.a.1.a	A minimum of three (3) real-world airport models to be consistent with published data used for airplane operations and capable of demonstrating all the visual system features below. Each model should be in a different visual scene to permit assessment of FSTD automatic visual scene changes. The model identifications must be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.						
2.a.1.b	Reserved						
2.a.1.c	Reserved						
2.a.1.d	Airport model content. For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intended landing. If all runways in an airport model used to meet the requirements of this attachment are not designated as "in use," then the "in use" runways must be listed on the SOQ (e.g., KORD, Rwys 9R, 14L, 22R). Models of airports with more than one runway must have all significant runways not "in-use" visually depicted for airport and runway recognition purposes. The use of white or off white light strings that identify the runway threshold, edges, and ends for twilight and night scenes are acceptable for this requirement. Rectangular surface depictions are acceptable for daylight scenes. A visual system's capabilities must be balanced between providing airport models with an accurate representation of the airport and a realistic representation of the surrounding environment. Airport model detail must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that such models contain details that are beyond the design capability of the currently qualified visual system. Only one "primary" taxi route from parking to the runway end will be required for each "in-use" runway.						
2.a.2	Visual scene fidelity.						
2.a.2.a	The visual scene must correctly represent the parts of the airport and its surroundings used						
2.a.2.b	in the training program. Reserved						
2.a.2.b 2.a.2.c	Reserved						
2.a.2.c 2.a.3	Runways and taxiways.						
2.a.3.a	Reserved						
2.a.3.b	Representative runways and taxiways.						
2.a.3.c	Reserved						
2.a.4	Reserved						
2.a.5	Runway threshold elevations and locations must be modeled to provide correlation with airplane systems (e.g. HUD, GPS, compass, altimeter).						

	Table B3E - Functions And Subjective Tests							
	Level 7 FTD							
OPS REQUIREMENTS								
Entry Number	Airport Modeling Requirements							
2.a.12.a.2	Representative airport buildings, structures and lighting.							
2.a.12.a.3	Reserved							
2.a.12.b	Reserved							
2.a.12.c	Representative moving and static airport clutter (e.g. other airplanes, power carts, tugs,							
	fuel trucks, additional gates).							
2.a.12.d	Reserved							
2.a.13	Terrain and obstacles.							
2.a.13.a	Reserved							
2.a.13.b	Representative depiction of terrain and obstacles within 46 km (25 NM) of the reference airport.							
2.a.14	Significant, identifiable natural and cultural features.							
2.a.14.a	Reserved							
2.a.14.b	Representative depiction of significant and identifiable natural and cultural features within 46 km (25 NM) of the reference airport. Note.— This refers to natural and cultural features that are typically used for pilot orientation in flight. Outlying airports not intended for landing need only provide a reasonable facsimile of							
	runway orientation.							
2.a.14.c	Representative moving airborne traffic (including the capability to present air hazards – e.g. airborne traffic on a possible collision course).							
2.b	Visual scene management.							
2.b.1	Reserved							
2.b.2	Airport runway, approach and taxiway lighting and cultural lighting intensity for any approach should be set at an intensity representative of that used in training for the visibility set; all visual scene light points must fade into view appropriately.							
2.b.3	Reserved							
2.c	Visual feature recognition. Note.— The following are the minimum distances at which runway features should be visible. Distances are measured from runway threshold to an airplane aligned with the runway on an extended 3-degree glide slope in suitable simulated meteorological conditions. For circling approaches, all tests below apply both to the runway used for the initial approach and to the runway of intended landing.							
2.c.1	Runway definition, strobe lights, approach lights, and runway edge white lights from 8 km (5 sm) of the runway threshold.							
2.c.2	Visual approach aids lights.							
2.c.2.a	Reserved							
2.c.2.b	Visual approach aids lights from 4.8 km (3 sm) of the runway threshold.							
2.c.3								
2.c.4								
2.c.5	Reserved							
2.c.6	For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-distracting manner.							
2.d	Selectable airport visual scene capability for:							

Table B3E - Functions And Subjective Tests							
Level 7 FTD							
QPS REQUIREMENTS							
Airport Modeling Requirements							
2.d.1	Night.						
2.d.2	Twilight.						
2.d.3	Day.						
2.d.4	Dynamic effects — the capability to present multiple ground and air hazards such as another airplane crossing the active runway or converging airborne traffic; hazards must be selectable via controls at the instructor station.						
2.d.5	Reserved						
2.e	Correlation with airplane and associated equipment.						
2.e.1	Visual cues to relate to actual airplane responses.						
2.e.2	Visual cues during take-off, approach and landing.						
2.e.2.a	Visual cues to assess sink rate and depth perception during landings.						
2.e.2.b	Reserved						
2.e.3	Accurate portrayal of environment relating to airplane attitudes.						
2.e.4	The visual scene must correlate with integrated airplane systems, where fitted (e.g. terrain, traffic and weather avoidance systems and HUD/EFVS).						
2.e.5	Reserved						
2.f	Scene quality.						
2.f.1	Quantization.						
2.f.1.a	Surfaces and textural cues must be free from apparent quantization (aliasing).						
2.f.1.b	Reserved						
2.f.2	System capable of portraying full color realistic textural cues.						
2.f.3	The system light points must be free from distracting jitter, smearing or streaking.						
2.f.4 2.f.5	Reserved System capable of providing light point perspective growth (e.g. relative size of runway and taxiway edge lights increase as the lights are approached).						
2.g	Environmental effects.						
2.g.1	Reserved						
2.g.2	Reserved						
2.g.3	Reserved						
2.g.4	Reserved						
2.g.5	Reserved						
2.g.6	Reserved						
2.g.7	Visibility and RVR measured in terms of distance. Visibility/RVR must be checked at and below a height of 600 m (2 000 ft) above the airport and within a radius of 16 km (10 sm) from the airport.						
2.g.8	Reserved						
2.g.9	Reserved						
2.g.10	Reserved						
2.g.11	Reserved						
	End QPS Requirement						
	Begin Information						
	- B						

	Table B3E - Functions And Subjective Tests						
	Level 7 FTD						
	QPS REQUIREMENTS						
Airport Modeling Requirements							
3.	An example of being able to "combine two airport models to achieve two "in-use" runways:						
	One runway designated as the "in use" runway in the first model of the airport, and the second runway designated as the "in use" runway in the second model of the same airport. For example, the clearance is for the ILS approach to Runway 27, Circle to Land on Runway 18 right. Two airport visual models might be used: the first with Runway 27 designated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right designated as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may change to the second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pilot would make a visual approach and landing. This process is acceptable to the FAA as long as the temporary interruption due to the visual model change is not distracting to the pilot, does not cause changes in navigational radio frequencies, and does not cause undue instructor/evaluator time.						
4.	Sponsors are not required to provide every detail of a runway, but the detail that is provided should be correct within the capabilities of the system.						
	End Information						

ATTACHMENT 4 TO APPENDIX B TO PART 60—SAMPLE DOCUMENTS

BEGIN INFORMATION

TABLE OF CONTENTS

Title of Sample

Figure B4A Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation

Figure B4B Attachment: FTD Information Form

Figure B4C Sample Letter of Compliance Figure B4D Sample Qualification Test Guide Cover Page Figure B4E Sample Statement of Qualification—Certificate

Figure B4F Sample Statement of Qualification—Configuration List

Figure B4G Sample Statement of Qualification—List of Qualified Tasks

Figure B4H [Reserved]

Figure B4I Sample MQTG Index of Effective FTD Directives

ATTACHMENT 4 TO APPENDIX B TO PART 60— FIGURE B4A—SAMPLE LETTER, REQUEST FOR INITIAL, UPGRADE, OR REINSTATEMENT EVALUATION

INFORMATION

Date
RE: Request for Initial/Upgrade Evaluation Date
This is to advise you of our intent to request an (initial or upgrade) evaluation of our (FTD Manufacturer), (Aircraft
Type/Level) Flight Training Device (FTD), (FAA ID Number, if previously qualified), located in (City, State) at
the (Facility) on (Proposed Evaluation Date). (The proposed evaluation date shall not be more than 180 days
following the date of this letter.) The FTD will be sponsored by (Name of Training Center/Air Carrier), FAA
Designator (4 Letter Code). The FTD will be sponsored as follows; (Select One)
☐ The FTD will be used within the sponsor's FAA approved training program and placed on the sponsor's
Training/Operations Specifications.
☐ The FTD will be used for dry lease only.
We agree to provide the formal request for the evaluation to your staff as follows: (check one)
For QTG tests run at the factory, not later, than 45 days prior to the proposed evaluation date with the
additional "I/3 on-site" tests provided not later than 14 days prior to the proposed evaluation date.
For QTG tests run on-site, not later than 30 days prior to the proposed evaluation date.
We understand that the formal request will contain the following documents:
1. Sponsor's Letter of Request (Company Compliance Letter).
2. Principal Operations Inspector (POI) or Training Center Program Manager's (TCPM) endorsement.
3. Complete QTG.
If we are unable to meet the above requirements, we understand this may result in a significant delay, perhaps 45
days or more, in rescheduling and completing the evaluation.
(The sponsor should add additional comments as necessary).
•

Please contact (Name Telephone and Fax Number of Sponsor's Contact) to confirm the date for this initial evaluation. We understand a member of your National Simulator Program staff will respond to this request within

A copy of this letter of intent has been provided to (Name), the Principal Operations Inspector (POI) and/or Training Center Program Manager (TCPM).

Sincerely,
Attachment: FTD Information and Characteristics Form
cc: POI/TCPM

Attachment 4 to Appendix B to Part 60—
Figure B4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation
Attachment: FSTD Information Form INFORMATION

Date:			- 109	to an				
	Section	1. FSTD	Informa	tion and	l Characteri	stics		
Sponsor Name:			FSTD Location:					
Address:	38:			Phys	ical Address:	I	•	
City:			City	City:				
State:				State	:			
Country:				Cour	ıtry:			
ZIP:				ZIP:			•	
Manager								
Sponsor ID No: (Four Letter FAA Designator)					est Airport: ort Designator)			
Type of Evaluation Requested	4.		□ Initi	al 🗆 Lina	rade 🔲 Continu	ina Ou	alification	Canalal Canalal
Type of Evaluation Requester	u:			ai 🗀 Opg istatemeni		ing Qu	аппсацоп	Special
Aircraft Make/model/series:								
Initial Qualification: (If Applicable)	Date: MM/DD/YY	Level		Manufa Identific Number	cation or Serial			-
Upgrade Qualification: (If Applicable)	Date: MM/DD/Y	Level YYY		□ eMQ	TG			
Qualification Basis:		□ A	□В		Interim C		\Box C	□ D
		□ 6			Provisional	Status		
Other Technical Information	:	8						
FAA FSTD ID No: (If Applicable)	I			FSTD Manufacturer:				
Convertible FSTD:	□Yes:			Date of Manufacture: MM/DD/YYYY				
Related FAA ID No. (If Applicable)				Sponsor FSTD ID No:				
Engine model(s) and data rev	ision:			Source of aerodynamic model:				
FMS identification and revisi	on level:			Source of aerodynamic coefficient data:				
Visual system manufacturer/	model:			Aerodynamic data revision number:				
Flight control data revision:				Visual system display:				
Mot ion system manufactures	/type:			FSTD computer(s) identification:				
National Aviation Authority (NAA): (If Applicable)		-						
NAA FSTD ID No:			Last NAA Evaluation Date:					
NAA Qualification Level:								
NAA Qualification Basis:								
Visual System Manufacturer		FS	TD Seats	Met	on System Mani	ıfactur.	ar I	
and Type:			ailable:					*

Attachment 4 to Appendix B to Part 60— Figure B4B – Sample Letter , Request for Initial, Upgrade, or Reinstatement Evaluation Attachment: FSTD Information Form INFORMATION

Aircraft Equipment:	Engine Type(s):	☐ EFIS ☐ TCAS ☐ GPS ☐	umentation: HUD HC GPWS Pla FMS Type: Iar Other:	in View	Engine Instrumentation: EICAS FADEC Other:
Airport Models	3.6.1		3.6.2		3.6.3
Airport Models:	Airport De	signator		Designator	Airport Designator
Circle to Land:	3. 7.1		3. 7.2		3. 7.3
Visual Ground Segment	Airport De 3.8.1	signator	3.8.2	oach	Landing Runway 3. 8.3
	Airport D	esignator	Appro	oach	Landing Runway
	Section 2	2. Supplen	ientary Info	rmation	
FAA Training Program A				TCPM 🔲 Othe	er:
Name:			Office:		_
Tel:			Fax:		And the state of t
Email:					
FSTD Scheduling Person					
Name:					
Address 1:			Address 2		
City:			State:		
ZIP:			Email:		
Tel:			Fax:		
1 61.			Pax.		
FSTD Technical Contact:					
Name:					
Address 1:			Address 2	······································	
City:			State:		
ZIP:			Email:		
Tel:			Fax:		
			1- ""		
	Section 3. Trainin	g, Testing			
Area/Function/Maneuver			Request	ed Remark	S
Private Pilot - Training /					
Commercial Pilot - Training /Checks:(142)					
Multi-Engine Rating - Training / Checks (142)					
Instrument Rating -Training / Checks (142)					
Type Rating - Training / Checks (135/121/142)					
Proficiency Checks (135/121/142)					
CAT I: (RVR 2400/1800	ft. DH200 ft)				

Attachment 4 to Appendix B to Part 60—
Figure B4B – Sample Letter , Request for Initial, Upgrade, or Reinstatement Evaluation
Attachment: FSTD Information Form
INFORMATION

and an analysis of the second
-

ATTACHMENT 4 TO APPENDIX B TO PART 60-FIGURE B4C—SAMPLE LETTER OF COMPLIANCE

Information

(Date)

Mr. (Name of Training Program Approval Authority):

(Name of responsible Flight Standards office)

(Address)

(City/State/Zip)

Dear Mr. (Name of TPAA):

RE: Letter of Compliance

(Operator Sponsor Name) requests evaluation of our (Aircraft Type) FTD for Level (__) qualification. The (FTD Manufacturer Name) FTD with (Visual System Manufacturer Name/Model) system is fully defined on the FTD Information page of the accompanying Qualification Test Guide (QTG). We have completed the tests of the FTD and certify that it meets all applicable requirements of FAR parts 121, 125, or 135), and the guidance of (AC 120-40B or 14 CFR Part 60). Appropriate hardware and software configuration control procedures have been established. Our Pilot(s), (Name(s)), who are qualified on (Aircraft Type) aircraft have assessed the FTD and have found that it conforms to the (Operator/Sponsor) (Aircraft Type) flight deck configuration and that the simulated systems and subsystems function equivalently to those in the aircraft. The above named pilot(s) have also assessed the performance and the flying qualities of the FTD and find that it represents the respective aircraft.

(Added Comments may be placed here)

Sincerely,

(Sponsor Representative)

ATTACHMENT 4 TO APPENDIX B TO PART 60— FIGURE B4D—SAMPLE QUALIFICATION TEST GUIDE COVER PAGE

INFORMATION

SPONSOR NAME SPONSOR ADDRESS FAA QUALIFICATION TEST GUIDE (SPECIFIC AIRPLANE MODEL) for example Stratos BA797-320A (Type of FTD) (FTD Identification Including Manufacturer, Serial Number, Visual System Used) (FTD Level) (Qualification Performance Standard Used) (FTD Location) **FAA Initial Evaluation** Date: ____ Date: _ (Sponsor) ____ Date: ____ FAA

ATTACHMENT 4 TO APPENDIX B TO PART 60—FIGURE B4E—SAMPLE STATEMENT OF QUALIFICATION—CERTIFICATE

Information

Federal Aviation Administration



Certificate of Qualification

This is to certify that representatives of the FAA Completed an evaluation of the

Go-Fast Airlines Farnsworth Z-100 Flight Training Device

FAA Identification Number 998

And pursuant to 14 CFR Part 60 found it to meet its original qualification basis, AC 120-45A (MM/DD/YY)

The Master Qualification Test Guide and the attached Configuration List and Restrictions List Provide the Qualification Basis for this device to operate at

Level 6

Until March 31, 2010

Unless sooner rescinded or extended by the FAA

February 15, 2009	B. Williamson
(date)	(for the FAA)

Attachment 4 to Appendix B to Part 60— Figure B4F – Sample Statement of Qualification; Configuration List INFORMATION

CERTIFICATE OF QUALIFICATION CONFIGURATION LIST

Date:		·					
	Section 1, FSTD	Informat	ion and Characteris	ties			
Sponsor Name:			FSTD Location:				
Address:			Physical Address:				
City:	γ: <u></u>			City:			
State:			State:				
Country:			Country:				
ZIP:			ZIP:	Annual Control of the			
Manager							
Sponsor ID No: (Four Letter FAA Designator)			Nearest Airport: (Airport Designator)				
Type of Evaluation Requested	:		al 🔲 Upgrade 🔲 Continui statement	ng Qualification 🗌 Special			
Aircraft Make/model/series:							
Initial Qualification: (If Applicable)	Date: Level MM/DD/YYYY	Manufacturer's Identification or Serial Number					
Upgrade Qualification: (If Applicable)	Date: Level MM/DD/YYYY		☐ eMQTG				
Qualification Basis:	_A	□В	☐ Interim C	□ C			
	□ 6	□ 7	Provisional S	Status			
Other Technical Information:							
FAA FSTD ID No: (If Applicable)			FSTD Manufacturer:				
Convertible FSTD:	☐Yes:		Date of Manufacture: MM/DD/YYYY				
Related FAA ID No. (If Applicable)			Sponsor FSTD ID No:				
Engine model(s) and data revi	sion:		Source of aerodynamic model:				
FMS identification and revisio	n level:		Source of aerodynamic coefficient data:				
Visual system manufacturer/n	odel:		Aerodynamic data revision number:				
Flight control data revision:			Visual system display:				
Mot ion system manufacturer/	type:		FSTD computer(s) identification:				
National Aviation Authority (NAA): (If Applicable)							
NAA FSTD ID No:			Last NAA Evaluation Date:				
NAA Qualification Level:							
NAA Qualification Basis:							

Attachment 4 to Appendix B to Part 60— Figure B4F – Sample Statement of Qualification; Configuration List INFORMATION

Visual System Manufacturer and Type:			FSTD Seats Available:		Motion System Manufactur and Type:		ırer	:
Aircraft Equipment:	aft Equipment: Engine Type(s): Flight Instrumentation: Engine Type(s): Flight Instrumentation: EFIS			Engine Instrumentation: EICAS FADEC Other:				
		100000000000000000000000000000000000000	Marie III					
Airport Models:		3.6.1 Airport Des	signator	3.6.2 Airport	Desig	nator	3.6.3 _ Air	port Designator
Circle to Land:		3. 7.1		3. 7.2			3.7.3	
Visual Ground Segmen	t	3.8.1 Airport D		3.8.2 Appr			3. 8.3	nding Runway
		7 mport B	coignator	1 11991	ouch		1.70	alding Rullway
		Section 2	. Suppleme	ntary Info	rm	ition		
FAA Training Program	Approval A			POI	TCP	M 🔲 Other:		
Name:		_		Office:				
Tel:				Fax:				
Email:								
								A CALL STORY
FSTD Scheduling Perso	on:							
Name:								
Address 1:				Address 2			-	
City:				State:				
ZIP:				Email:				
Tel:		THE RESERVE OF THE PARTY OF THE		Fax:				
	100							
FSTD Technical Contac	ct:							
Name:	NAME OF THE PARTY							
Address 1:				Address 2				
City:				State:				
ZIP:				Email:				
Tel:				Fax:			******************	
		n 3. Trainin	g, Testing a				tions	
Area/Function/Maneuv	er			Reques	ted	Remarks		
Private Pilot - Training		,						
Commercial Pilot - Tra							-	
Multi-Engine Rating -	Fraining / Cl	hecks (142)					-	
Instrument Rating -Tra	ining / Chec	ks (142)						
Type Rating - Training	g / Checks (1	35/121/142)						
<u> </u>		······································	····			1		

Attachment 4 to Appendix B to Part 60— Figure B4F – Sample Statement of Qualification; Configuration List INFORMATION

INFORMATION		
Proficiency Checks (135/121/142)		
CAT I: (RVR 2400/1800 ft. DH200 ft)		
CAT II: (RVR 1200 ft. DH 100 ft)		
CAT III * (lowest minimum) RVR ft.		
* State CAT III (≤ 700 ft.), CAT IIIb (≤ 150 ft.), or CAT IIIc (0 ft.) Circling Approach	10	
·		
Windshear Training:		West and desirate
Windshear Training IAW 121.409(d) (121 Turbojets Only)		
Generic Unusual Attitudes and Recoveries within the Normal Flight Envelope		AAANGERFAGUUAAGUSTAAAAGUST
Specific Unusual Attitudes Recoveries		
Auto-coupled Approach/Auto Go Around		
Auto-land / Roll Out Guidance		
TCAS/ACAS I / II		
WX-Radar		
HUD		
HGS		
EFVS		
Future Air Navigation Systems		
GPWS / EGPWS		
ETOPS Capability		
GPS		
SMGCS		
Helicopter Slope Landings		
Helicopter External Load Operations		
Helicopter Pinnacle Approach to Landings		
Helicopter Night Vision Maneuvers		
Helicopter Category A Takeoffs	1	

Attachment 4 to Appendix B to Part 60— Figure B4G – Sample Statement of Qualification;– List of Qualified Tasks INFORMATION

CERTIFICATE OF QUALIFICATION List of Qualified Tasks

Go Fast Airline Training -- Farnsworth Z-100 -- Level D -- FAA ID# 999

The FTD is qualified to perform all of the tasks listed in
Appendix 1, Table B1B
for its assigned level of qualification except for the following listed tasks.

Qualified for all tasks in	Table B1B, for v	vhich the sponsor .	has requested (qualification, except
for the following:				

4.e. Circling Approx	ac	proa	Apr	cling	Ci	4.e.
----------------------	----	------	-----	-------	----	------

- 6. (a) Emergency Descent (maximum rate)
- 6. (b) Inflight Fire and Smoke Removal
- 6. (c) Rapid Decompression
- 6. (d) Emergency Evacuation

Additional tasks for which this FTD is qualified (i.e., in addition to the list in Table B1B):

NONE

ATTACHMENT 4 TO APPENDIX B TO PART 60—FIGURE B4H [RESERVED]

Attachment 4 to Appendix B to Part 60— Figure B4I – Sample MQTG Index of Effective FSTD Directives INFORMATION

	Index of Effective FSTD Directives Filed in this Section									
Number	Effective Date	Date of Notification	Details							

Continue as Necessary....

[Doc. No. FAA–2002–12461, 73 FR 26490, May 9, 2008, as amended by Docket FAA–2014–0391, Amdt. 60–4, 81 FR 18306, 18307, 18327, and 18376, Mar. 30, 2016; 81 FR 32087, 32110, 32111, and 32165, May 20, 2016; Amdt. 60–6, 83 FR 30275, June 27, 2018; Docket No. FAA–2022–1355, Amdt. No. 60–7, 87 FR 75771, Dec. 9, 2022]

APPENDIX C TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR HEL-ICOPTER FULL FLIGHT SIMULATORS

BEGIN INFORMATION

This appendix establishes the standards for Helicopter FFS evaluation and qualification. The Flight Standards Service is responsible for the development, application, and implementation of the standards contained within this appendix. The procedures and criteria specified in this appendix will be used by the responsible Flight Standards office when conducting helicopter FFS evaluations.

TABLE OF CONTENTS

- 1. Introduction.
- 2. Applicability (§ 60.1) and (§ 60.2).
- 3. Definitions (§ 60.3).
- $\begin{array}{lll} \text{4.} & \text{Qualification} & \text{Performance} & \text{Standards} \\ & (\S 60.4). \end{array}$
- 5. Quality Management System (§60.5).
- 6. Sponsor Qualification Requirements (§60.7).

- 7. Additional Responsibilities of the Sponsor ($\S 60.9$).
- 8. FFS Use (§60.11).
- 9. FFS Objective Data Requirements (§60.13).
- Special Equipment and Personnel Requirements for Qualification of the FFS (§ 60.14).
- 11. Initial (and Upgrade) Qualification Requirements (§ 60.15).
- 12. Additional Qualifications for a Currently Qualified FFS (§60.16).
- 13. Previously Qualified FFSs (§60.17).
- 14. Inspection, Continuing Qualification Evaluation, and Maintenance Requirements (§ 60.19).
- 15. Logging FFS Discrepancies (§60.20).
- 16. Interim Qualification of FFSs for New Helicopter Types or Models (§ 60.21).
- 17. Modifications to FFSs (§ 60.23).
- 18. Operations with Missing, Malfunctioning, or Inoperative Components (§ 60.25).
- Automatic Loss of Qualification and Procedures for Restoration of Qualification (\$60.27).
- Other Losses of Qualification and Procedures for Restoration of Qualification (§ 60.29).
- 21. Record Keeping and Reporting (§60.31).

y on LAPBH6H6L3 with DISTILL

- Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements (§60.33).
- 23. [Reserved]
- 24. [Reserved]
- FFS Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA) (860.37)
- Attachment 1 to Appendix C to Part 60—General Simulator Requirements.
- Attachment 2 to Appendix C to Part 60—FFS Objective Tests.
- Attachment 3 to Appendix C to Part 60—Simulator Subjective Evaluation.
- Attachment 4 to Appendix C to Part 60—Sample Documents.
- Attachment 5 to Appendix C to Part 60—FSTD Directives Applicable to Helicopter FFSs

END INFORMATION

1. Introduction

BEGIN INFORMATION

- a. This appendix contains background information as well as regulatory and informative material as described later in this section. To assist the reader in determining what areas are required and what areas are permissive, the text in this appendix is divided into two sections: "QPS Requirements" and "Information." The QPS Requirements sections contain details regarding compliance with the part 60 rule language. These details are regulatory, but are found only in this appendix. The Information sections contain material that is advisory in nature, and designed to give the user general information about the regulation.
- b. [Reserved]
- c. The responsible Flight Standards office encourages the use of electronic media for all communication, including any record, report, request, test, or statement required by this appendix. The electronic media used must have adequate security provisions and be acceptable to the responsible Flight Standards office.
- d. Related Reading References.
- (1) 14 CFR part 60.
- (2) 14 CFR part 61.
- (3) 14 CFR part 63.
- (4) 14 CFR part 119.
- (5) 14 CFR part 121.(6) 14 CFR part 125.
- (7) 14 CFR part 125.
- (8) 14 CFR part 141.
- (9) 14 CFR part 142.
- (10) AC 120-35, as amended, Flightcrew Member Line Operational Simulations: Line-Oriented Flight Training, Special Purpose Operational Training, Line Operational Evaluation.

14 CFR Ch. I (1-1-24 Edition)

- (11) AC 120-57, as amended, Surface Movement Guidance and Control System (SMGCS).
- (12) AC 120-63, as amended, Helicopter Simulator Qualification.
- (13) AC 150/5300-13, as amended, Airport Design.
- (14) AC 150/5340-1, as amended, Standards for Airport Markings.
- (15) AC 150/5340-4, as amended, Installation Details for Runway Centerline Touchdown Zone Lighting Systems.
- (16) $\stackrel{.}{AC}$ 150/5340–19, as amended, Taxiway Centerline Lighting System.
- (17) AC 150/5340-24, as amended, Runway and Taxiway Edge Lighting System.
- (18) AC 150/5345–28, as amended, Precision Approach Path Indicator (PAPI) Systems
- (19) AC 150/5390–2, as amended, Heliport Design
- (20) International Air Transport Association document, "Flight Simulator Design and Performance Data Requirements," as amended.
- (21) AC 29-2, as amended, Flight Test Guide for Certification of Transport Category Rotorcraft.
- (22) AC 27–1, as amended, Flight Test Guide for Certification of Normal Category Rotor-craft.
- (23) International Civil Aviation Organization (ICAO) Manual of Criteria for the Qualification of Flight Simulators, as amended.
- (24) Airplane Flight Simulator Evaluation Handbook, Volume I, as amended and Volume II, as amended, The Royal Aeronautical Society, London, UK.
- (25) FAA Airman Certification Standards and Practical Test Standards for Airline Transport Pilot, Type Ratings, Commercial Pilot, and Instrument Ratings.
- (26) The FAA Aeronautical Information Manual (AIM). An electronic version of the AIM is on the Internet at http://www.faa.gov/atnubs.
- (27) Aeronautical Radio, Inc. (ARINC) document number 436, titled Guidelines For Electronic Qualification Test Guide (as amended).
- (28) Aeronautical Radio, Inc. (ARINC) document 610, Guidance for Design and Integration of Aircraft Avionics Equipment in Simulators (as amended).

END INFORMATION

2. Applicability (§§ $60.1~\mathrm{And}~60.2)$

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.1, Applicability, or to §60.2, Applicability of sponsor rules to person who are not sponsors and who are engaged in certain unauthorized activities.

3. Definitions (§60.3)

BEGIN INFORMATION

See Appendix F of this part for a list of definitions and abbreviations from part 1 and part 60, including the appropriate appendices of part 60.

END INFORMATION

4. QUALIFICATION PERFORMANCE STANDARDS (§ 60.4)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.4, Qualification Performance Standards.

END INFORMATION

5. Quality Management System ($\S60.5$)

BEGIN INFORMATION

See Appendix E of this part for additional regulatory and informational material regarding Quality Management Systems.

END INFORMATION

6. Sponsor Qualification Requirements $(\S\,60.7)$

BEGIN INFORMATION

- a. The intent of the language in §60.7(b) is to have a specific FFS, identified by the sponsor, used at least once in an FAA-approved flight training program for the helicopter simulated during the 12-month period described. The identification of the specific FFS may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FFS at least once during the prescribed period. There is no minimum number of hours or minimum FFS periods required.
- b. The following examples describe acceptable operational practices:
- (1) Example One.
- (a) A sponsor is sponsoring a single, specific FFS for its own use, in its own facility or elsewhere—this single FFS forms the basis for the sponsorship. The sponsor uses that FFS at least once in each 12-month period in that sponsor's FAA-approved flight

training program for the helicopter simulated. This 12-month period is established according to the following schedule:

- (i) If the FFS was qualified prior to May 30, 2008, the 12-month period begins on the date of the first continuing qualification evaluation conducted in accordance with \$60.19 after May 30, 2008, and continues for each subsequent 12-month period;
- (ii) A device qualified on or after May 30, 2008, will be required to undergo an initial or upgrade evaluation in accordance with §60.15. Once the initial or upgrade evaluation is complete, the first continuing qualification evaluation will be conducted within 6 months. The 12 month continuing qualification evaluation cycle begins on that date and continues for each subsequent 12-month period
- (b) There is no minimum number of hours of FFS use required.
- (c) The identification of the specific FFS may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FFS at least once during the prescribed period.
- (2) Example Two.
- (a) A sponsor sponsors an additional number of FFSs, in its facility or elsewhere. Each additionally sponsored FFS must be—
- (i) Used by the sponsor in the sponsor's FAA-approved flight training program for the helicopter simulated (as described in $\S60.7(\mathrm{d})(1)$); or
- (ii) Used by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the helicopter simulated (as described in §60.7(d)(1)). This 12-month period is established in the same manner as in example one; or
- (iii) Provided a statement each year from a qualified pilot, (after having flown the helicopter, not the subject FFS or another FFS, during the preceding 12-month period) stating that the subject FFS's performance and handling qualities represent the helicopter (as described in §60.7(d)(2)). This statement is provided at least once in each 12-month period established in the same manner as in example one.
- (b) There is no minimum number of hours of FFS use required.
 - (3) Example Three.
- (a) A sponsor in New York (in this example, a Part 142 certificate holder) establishes "satellite" training centers in Chicago and Moscow
- (b) The satellite function means that the Chicago and Moscow centers must operate under the New York center's certificate (in accordance with all of the New York center's practices, procedures, and policies; e.g., instructor and/or technician training/checking requirements, record keeping, QMS program).

- (c) All of the FFSs in the Chicago and Moscow centers could be dry-leased (i.e., the certificate holder does not have and use FAA-approved flight training programs for the FFSs in the Chicago and Moscow centers) because—
- (i) Each FFS in the Chicago center and each FFS in the Moscow center is used at least once each 12-month period by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the helicopter (as described in §60.7(d)(1)); OR
- (ii) A statement is obtained from a qualified pilot (having flown the helicopter, not the subject FFS or another FFS during the preceding 12-month period) stating that the performance and handling qualities of each FFS in the Chicago and Moscow centers represents the helicopter (as described in §60.7(d)(2)).

END INFORMATION

7. Additional Responsibilities of the Sponsor (§60.9).

BEGIN INFORMATION

The phrase "as soon as practicable" in §60.9(a) means without unnecessarily disrupting or delaying beyond a reasonable time the training, evaluation, or experience being conducted in the FFS.

END INFORMATION

8. FFS USE (§ 60.11)

BEGIN INFORMATION

No additional regulatory or informational material applies to $\S 60.11,\, FFS$ Use.

END INFORMATION

9. FFS Objective Data Requirements $(\S\,60.13)$

BEGIN QPS REQUIREMENTS

- a. Flight test data used to validate FFS performance and handling qualities must have been gathered in accordance with a flight test program containing the following:
 - (1) A flight test plan consisting of:
- (a) The maneuvers and procedures required for aircraft certification and simulation programming and validation
- (b) For each maneuver or procedure-
- (i) The procedures and control input the flight test pilot and/or engineer used.
- (ii) The atmospheric and environmental conditions.

- (iii) The initial flight conditions.
- (iv) The helicopter configuration, including weight and center of gravity.
 - (v) The data to be gathered.
- (vi) All other information necessary to recreate the flight test conditions in the FFS.
- (2) Appropriately qualified flight test personnel.
- (3) An understanding of the accuracy of the data to be gathered using appropriate alternative data sources, procedures, and instrumentation that is traceable to a recognized standard as described in Attachment 2, Table C2D of this appendix.
- (4) Appropriate and sufficient data acquisition equipment or system(s), including appropriate data reduction and analysis methods and techniques, acceptable to the FAA's Aircraft Certification Service.
- b. The data, regardless of source, must be presented:
- (1) In a format that supports the FFS validation process;
- (2) In a manner that is clearly readable and annotated correctly and completely;
- (3) With resolution sufficient to determine compliance with the tolerances set forth in Attachment 2, Table C2A of this appendix.
- (4) With any necessary instructions or other details provided, such as Stability Augmentation System (SAS) or throttle position; and
- (5) Without alteration, adjustments, or bias. Data may be corrected to address known data calibration errors provided that an explanation of the methods used to correct the errors appears in the QTG. The corrected data may be re-scaled, digitized, or otherwise manipulated to fit the desired presentation.
- c. After completion of any additional flight test, a flight test report must be submitted in support of the validation data. The report must contain sufficient data and rationale to support qualification of the FFS at the level requested.
- d. As required by §60.13(f), the sponsor must notify the responsible Flight Standards office when it becomes aware that an addition to, an amendment to, or a revision of data that may relate to FFS performance or handling characteristics is available. The data referred to in this paragraph is data used to validate the performance, handling qualities, or other characteristics of the aircraft, including data related to any relevant changes occurring after the type certificate was issued. The sponsor must—
- (1) Within 10 calendar days, notify the responsible Flight Standards office of the existence of this data; and
- (2) Within 45 calendar days, notify the responsible Flight Standards office of—
- (a) The schedule to incorporate this data into the FFS; or

Federal Aviation Administration, DOT

- (b) The reason for not incorporating this data into the FFS.
- e. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot test results" in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.

END QPS REQUIREMENTS

BEGIN INFORMATION

- f. The FFS sponsor is encouraged to maintain a liaison with the manufacturer of the aircraft being simulated (or with the holder of the aircraft type certificate for the aircraft being simulated if the manufacturer is no longer in business), and, if appropriate, with the person who supplied the aircraft data package for the FFS in order to facilitate the notification required by \$60.13(f).
- g. It is the intent of the responsible Flight Standards office that for new aircraft entering service, at a point well in advance of preparation of the QTG, the sponsor should submit to the responsible Flight Standards office for approval, a descriptive document (see Table C2D, Sample Validation Data Roadmap for Helicopters) containing the plan for acquiring the validation data, including data sources. This document should clearly identify sources of data for all required tests, a description of the validity of these data for a specific engine type and thrust rating configuration, and the revision levels of all avionics affecting the performance or flying qualities of the aircraft. Additionally, this document should provide other information, such as the rationale or explanation for cases where data or data parameters are missing, instances where engineering simulation data are used or where flight test methods require further explanations. It should also provide a brief narrative describing the cause and effect of any deviation from data requirements. The aircraft manufacturer may provide this document.
- h. There is no requirement for any flight test data supplier to submit a flight test plan or program prior to gathering flight test data. However, the responsible Flight Standards office notes that inexperienced data gatherers often provide data that is irrelevant, improperly marked, or lacking adequate justification for selection. Other problems include inadequate information regarding initial conditions or test maneuvers. The responsible Flight Standards office has been forced to refuse these data submissions as validation data for an FFS evaluation. It is for this reason that the responsible Flight

Standards office recommends that any data supplier not previously experienced in this area review the data necessary for programming and for validating the performance of the FFS, and discuss the flight test plan anticipated for acquiring such data with the responsible Flight Standards office well in advance of commencing the flight tests.

i. The responsible Flight Standards office will consider, on a case-by-case basis, whether to approve supplemental validation data derived from flight data recording systems such as a Quick Access Recorder or Flight Data Recorder.

END INFORMATION

 SPECIAL EQUIPMENT AND PERSONNEL RE-QUIREMENTS FOR QUALIFICATION OF THE FFS (§60.14)

BEGIN INFORMATION

- a. In the event that the responsible Flight Standards office determines that special equipment or specifically qualified persons will be required to conduct an evaluation, the responsible Flight Standards office will make every attempt to notify the sponsor at least one (1) week, but in no case less than 72 hours, in advance of the evaluation. Examples of special equipment include spot photometers, flight control measurement devices, and sound analyzers. Examples of specially qualified personnel include individuals specifically qualified to install or use any special equipment when its use is required.
- b. Examples of a special evaluation include an evaluation conducted after an FFS is moved, at the request of the TPAA, or as a result of comments received from users of the FFS that raise questions about the continued qualification or use of the FFS.

END INFORMATION

11. INITIAL (AND UPGRADE) QUALIFICATION REQUIREMENTS ($\S\,60.15$)

BEGIN QPS REQUIREMENTS

- a. In order to be qualified at a particular qualification level, the FFS must:
- (1) Meet the general requirements listed in Attachment 1 of this appendix;
- (2) Meet the objective testing requirements listed in Attachment 2 of this appendix; and
- (3) Satisfactorily accomplish the subjective tests listed in Attachment 3 of this appendix.
- b. The request described in §60.15(a) must include all of the following:
- (1) A statement that the FFS meets all of the applicable provisions of this part and all applicable provisions of the QPS.

- (2) A confirmation that the sponsor will forward to the responsible Flight Standards office the statement described in §60.15(b) in such time as to be received no later than 5 business days prior to the scheduled evaluation and may be forwarded to the responsible Flight Standards office via traditional or electronic means.
- (3) A QTG, acceptable to the responsible Flight Standards office, that includes all of the following:
- (a) Objective data obtained from aircraft testing or another approved source.
- (b) Correlating objective test results obtained from the performance of the FFS as prescribed in the appropriate QPS.
- (c) The result of FFS subjective tests prescribed in the appropriate QPS.
- (d) A description of the equipment necessary to perform the evaluation for initial qualification and the continuing qualification evaluations.
- c. The QTG described in paragraph (a)(3) of this section, must provide the documented proof of compliance with the simulator objective tests in Attachment 2, Table C2A of this appendix.
- d. The QTG is prepared and submitted by the sponsor, or the sponsor's agent on behalf of the sponsor, to the responsible Flight Standards office for review and approval, and must include, for each objective test:
- (1) Parameters, tolerances, and flight conditions.
- (2) Pertinent and complete instructions for the conduct of automatic and manual tests.
- (3) A means of comparing the FFS test results to the objective data.
- (4) Any other information as necessary, to assist in the evaluation of the test results.
- (5) Other information appropriate to the qualification level of the FFS.
- e. The QTG described in paragraphs (a)(3) and (b) of this section, must include the following:
- (1) A QTG cover page with sponsor and FAA approval signature blocks (see Attachment 4, Figure C4C, of this appendix, for a sample QTG cover page).
- (2) A continuing qualification evaluation schedule requirements page. This page will be used by the responsible Flight Standards office to establish and record the frequency with which continuing qualification evaluations must be conducted and any subsequent changes that may be determined by the responsible Flight Standards office in accordance with \$60.19. See Attachment 4 of this appendix, Figure C4G, for a sample Continuing Qualification Evaluation Requirements page.
- (3) An FFS information page that provides the information listed in this paragraph (see Attachment 4, Figure C4B, of this appendix for a sample FFS information page). For convertible FFSs, the sponsor must submit a

separate page for each configuration of the FFS.

- (a) The sponsor's FFS identification number or code.
- (b) The helicopter model and series being simulated.
- (c) The aerodynamic data revision number or reference
- (d) The source of the basic aerodynamic model and the aerodynamic coefficient data used to modify the basic model.
- (e) The engine model(s) and its data revision number or reference.
- (f) The flight control data revision number or reference.
- (g) The flight management system identification and revision level.
 - (h) The FFS model and manufacturer.
 - (i) The date of FFS manufacture.
 - (j) The FFS computer identification.
- (k) The visual system model and manufacturer, including display type.
- (1) The motion system type and manufacturer, including degrees of freedom.
 - (4) A Table of Contents.
- (5) A log of revisions and a list of effective pages.
 - (6) List of all relevant data references.
- (7) A glossary of terms and symbols used (including sign conventions and units).
- (8) Statements of compliance and capability (SOCs) with certain requirements.
- (9) Recording procedures or equipment required to accomplish the objective tests.
- (10) The following information for each objective test designated in Attachment 2 of this appendix, Table C2A, as applicable to the qualification level sought:
 - (a) Name of the test.
 - (b) Objective of the test.
- $\ \, \text{(c) Initial conditions.}$
- (d) Manual test procedures.
- (e) Automatic test procedures (if applicable).
- (f) Method for evaluating FFS objective test results.
- (g) List of all relevant parameters driven or constrained during the automatically conducted test(s).
- (h) List of all relevant parameters driven or constrained during the manually conducted test(s).
- (i) Tolerances for relevant parameters.
- (j) Source of Validation Data (document and page number).
- (k) Copy of the Validation Data (if located in a separate binder, a cross reference for the identification and page number for pertinent data location must be provided).
- (1) Simulator Objective Test Results as obtained by the sponsor. Each test result must reflect the date completed and must be clearly labeled as a product of the device being tested.
- f. A convertible FFS is addressed as a separate FFS for each model and series helicopter to which it will be converted and for

Federal Aviation Administration, DOT

the FAA qualification level sought. If a sponsor seeks qualification for two or more models of a helicopter type using a convertible FFS, the sponsor must submit a QTG for each helicopter model, or a QTG for the first helicopter model and a supplement to that QTG for each additional helicopter model. The responsible Flight Standards office will conduct evaluations for each helicopter model.

- g. Form and manner of presentation of objective test results in the QTG:
- (1) The sponsor's FFS test results must be recorded in a manner acceptable to the responsible Flight Standards office, that allows easy comparison of the FFS test results to the validation data (e.g., use of a multichannel recorder, line printer, cross plotting, overlays, transparencies).
- (2) FFS results must be labeled using terminology common to helicopter parameters as opposed to computer software identifications.
- (3) Validation data documents included in a QTG may be photographically reduced only if such reduction will not alter the graphic scaling or cause difficulties in scale interpretation or resolution.
- (4) Scaling on graphical presentations must provide the resolution necessary to evaluate the parameters shown in Attachment 2, Table C2A of this appendix.
- (5) Tests involving time histories, data sheets (or transparencies thereof) and FFS test results must be clearly marked with appropriate reference points to ensure an accurate comparison between the FFS and the helicopter with respect to time. Time histories recorded via a line printer are to be clearly identified for cross plotting on the helicopter data. Over-plots must not obscure the reference data.
- h. The sponsor may elect to complete the QTG objective and subjective tests at the manufacturer's facility or at the sponsor's training facility. If the tests are conducted at the manufacturer's facility, the sponsor must repeat at least one-third of the tests at the sponsor's training facility in order to substantiate FFS performance. The QTG must be clearly annotated to indicate when and where each test was accomplished. Tests conducted at the manufacturer's facility and at the sponsor's training facility must be conducted after the FFS is assembled with systems and sub-systems functional and operating in an interactive manner. The test results must be submitted to the responsible Flight Standards office.
- i. The sponsor must maintain a copy of the MQTG at the FFS location.
- j. All FFSs for which the initial qualification is conducted after May 30, 2014, must have an electronic MQTG (EmqTG) including all objective data obtained from helicopter testing, or another approved source (reformatted or digitized), together with corre-

lating objective test results obtained from the performance of the FFS (reformatted or digitized) as prescribed in this appendix. ThE EmqTG must also contain the general FFS performance or demonstration results (reformatted or digitized) prescribed in this appendix, and a description of the equipment necessary to perform the initial qualification evaluation and the continuing qualification evaluations. ThE EmqTG must include the original validation data used to validate FFS performance and handling qualities in either the original digitized format from the data supplier or an electronic scan of the original time-history plots that were provided by the data supplier. A copy of thE EmqTG must be provided to the responsible Flight Standards office.

- k. All other FFSs not covered in subparagraph "j" must have an electronic copy of the MQTG by May 30, 2014. An electronic copy of the MQTG must be provided to the responsible Flight Standards office. This may be provided by an electronic scan presented in a Portable Document File (PDF), or similar format acceptable to the responsible Flight Standards office.
- 1. During the initial (or upgrade) qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person who is a user of the device (e.g., a qualified pilot or instructor pilot with flight time experience in that aircraft) and knowledgeable about the operation of the aircraft and the operation of the FFS.

END QPS REQUIREMENTS

BEGIN INFORMATION

- m. Only those FFSs that are sponsored by a certificate holder as defined in Appendix F of this part will be evaluated by the responsible Flight Standards office. However, other FFS evaluations may be conducted on a case-by-case basis as the Administrator deems appropriate, but only in accordance with applicable agreements.
- n. The responsible Flight Standards office will conduct an evaluation for each configuration, and each FFS must be evaluated as completely as possible. To ensure a thorough and uniform evaluation, each FFS is subjected to the general simulator requirements in Attachment 1 of this appendix, the objective tests listed in Attachment 2 of this appendix, and the subjective tests listed in Attachment 3 of this appendix. The evaluations described herein will include, but not necessarily be limited to the following:
- (1) Helicopter responses, including longitudinal and lateral-directional control responses (see Attachment 2 of this appendix).

- (2) Performance in authorized portions of the simulated helicopter's operating envelope, to include tasks evaluated by the responsible Flight Standards office in the areas of surface operations, takeoff, climb, cruise, descent, approach, and landing as well as abnormal and emergency operations (see Attachment 2 of this appendix).
- (3) Control checks (see Attachment 1 and Attachment 2 of this appendix).
- (4) Flight deck configuration (see Attachment 1 of this appendix).
- (5) Pilot, flight engineer, and instructor station functions checks (see Attachment 1 and Attachment 3 of this appendix).
- (6) Helicopter systems and sub-systems (as appropriate) as compared to the helicopter simulated (see Attachment 1 and Attachment 3 of this appendix).
- (7) FFS systems and sub-systems, including force cueing (motion), visual, and aural (sound) systems, as appropriate (see Attachment 1 and Attachment 2 of this appendix).
- (8) Certain additional requirements, depending upon the qualification level sought, including equipment or circumstances that may become hazardous to the occupants. The sponsor may be subject to Occupational Safety and Health Administration requirements.
- o. The responsible Flight Standards office administers the objective and subjective tests, which includes an examination of functions. The tests include a qualitative assessment of the FFS by a pilot from the responsible Flight Standards office. The evaluation team leader may assign other qualified personnel to assist in accomplishing the functions examination and/or the objective and subjective tests performed during an evaluation when required.
- (1) Objective tests provide a basis for measuring and evaluating FFS performance and determining compliance with the requirements of this part.
 - (2) Subjective tests provide a basis for:
- (a) Evaluating the capability of the FFS to perform over a typical utilization period;
- (b) Determining that the FFS satisfactorily simulates each required task;
- (c) Verifying correct operation of the FFS controls, instruments, and systems; and
- (d) Demonstrating compliance with the requirements of this part.
- p. The tolerances for the test parameters listed in Attachment 2 of this appendix reflect the range of tolerances acceptable to the responsible Flight Standards office for FFS validation and are not to be confused with design tolerances specified for FFS manufacture. In making decisions regarding tests and test results, the responsible Flight Standards office relies on the use of operational and engineering judgment in the application of data (including consideration of the way in which the flight test was flown and way the data was gathered and applied),

data presentations, and the applicable tolerances for each test.

- q. In addition to the scheduled continuing qualification evaluation, each FFS is subject to evaluations conducted by the responsible Flight Standards office at any time without prior notification to the sponsor. Such evaluations would be accomplished in a normal manner (i.e., requiring exclusive use of the FFS for the conduct of objective and subjective tests and an examination of functions) if the FFS is not being used for flight crewmember training, testing, or checking. However, if the FFS were being used, the evaluation would be conducted in a non-exclusive manner. This non-exclusive evaluation will be conducted by the FFS evaluator accompanying the check airman, instructor, Aircrew Program Designee (APD), or FAA inspector aboard the FFS along with the student(s) and observing the operation of the FFS during the training, testing, or checking activities.
- r. Problems with objective test results are handled as follows:
- (1) If a problem with an objective test result is detected by the evaluation team during an evaluation, the test may be repeated or the QTG may be amended.
- (2) If it is determined that the results of an objective test do not support the level requested but do support a lower level, the responsible Flight Standards office may qualify the FFS at that lower level. For example, if a Level D evaluation is requested and the FFS fails to meet sound test tolerances, it could be qualified at Level C.
- s. After an FFS is successfully evaluated, the responsible Flight Standards office issues a certificate of qualification (COQ) to the sponsor. The responsible Flight Standards office recommends the FFS to the TPAA, who will approve the FFS for use in a flight training program. The COQ will be issued at the satisfactory conclusion of the initial or continuing qualification evaluation and will list the tasks for which the FFS is qualified, referencing the tasks described in Table C1B in Attachment 1 of this appendix. However, it is the sponsor's responsibility to obtain TPAA approval prior to using the FFS in an FAA-approved flight training program.
- t. Under normal circumstances, the responsible Flight Standards office establishes a date for the initial or upgrade evaluation within ten (10) working days after determining that a complete QTG is acceptable. Unusual circumstances may warrant establishing an evaluation date before this determination is made. A sponsor may schedule an evaluation date as early as 6 months in advance. However, there may be a delay of 45 days or more in rescheduling and completing the evaluation if the sponsor is unable to meet the scheduled date. See Attachment 4,

Federal Aviation Administration, DOT

of this appendix, Figure C4A, Sample Request for Initial, Upgrade, or Reinstatement Evaluation.

- u. The numbering system used for objective test results in the QTG should closely follow the numbering system set out in Attachment 2, FFS Objective Tests, Table C2A of this appendix.
- v. Contact the responsible Flight Standards office for additional information regarding the preferred qualifications of pilots used to meet the requirements of §60.15(d).
- w. Examples of the exclusions for which the FFS might not have been subjectively tested by the sponsor or the responsible Flight Standards office and for which qualification might not be sought or granted, as described in \$60.15(g)(6), include takeoffs and landing from slopes and pinnacles.

END INFORMATION

12. ADDITIONAL QUALIFICATIONS FOR A CURRENTLY QUALIFIED FFS (§60.16)

No additional regulatory or informational material applies to \$60.16, Additional Qualifications for a Currently Qualified FFS.

13. Previously Qualified FFSs (§60.17)

BEGIN QPS REQUIREMENTS

- a. In instances where a sponsor plans to remove an FFS from active status for a period of less than two years, the following procedures apply:
- (1) The responsible Flight Standards office must be notified in writing and the notification must include an estimate of the period that the FFS will be inactive.
- (2) Continuing Qualification evaluations will not be scheduled during the inactive period.
- (3) The responsible Flight Standards office will remove the FFS from the list of qualified FSTDs on a mutually established date not later than the date on which the first missed continuing qualification evaluation would have been scheduled.
- (4) Before the FFS is restored to qualified status, it must be evaluated by the responsible Flight Standards office. The evaluation content and the time required to accomplish the evaluation is based on the number of continuing qualification evaluations and sponsor-conducted quarterly inspections missed during the period of inactivity.
- (5) The sponsor must notify the responsible Flight Standards office of any changes to the original scheduled time out of service.
- b. Simulators qualified prior to May 30, 2008, are not required to meet the general simulation requirements, the objective test requirements, and the subjective test requirements of attachments 1, 2, and 3, of this

appendix as long as the simulator continues to meet the test requirements contained in the MQTG developed under the original qualification basis.

- c. After May 30, 2009, each visual scene or airport model beyond the minimum required for the FFS qualification level that is installed in and available for use in a qualified FFS must meet the requirements described in Attachment 3 of this appendix.
- d. Simulators qualified prior to May 30, 2008, may be updated. If an evaluation is deemed appropriate or necessary by the responsible Flight Standards office after such an update, the evaluation will not require an evaluation to standards beyond those against which the simulator was originally qualified.

END QPS REQUIREMENTS

BEGIN INFORMATION

- e. Other certificate holders or persons desiring to use an FFS may contract with FFS sponsors to use FFSs previously qualified at a particular level for a helicopter type and approved for use within an FAA-approved flight training program. Such FFSs are not required to undergo an additional qualification process, except as described in §60.16.
- f. Each FFS user must obtain approval from the appropriate TPAA to use any FFS in an FAA-approved flight training program.
- g. The intent of the requirement listed in \$60.17(b), for each FFS to have an SOQ within 6 years, is to have the availability of that statement (including the configuration list and the limitations to authorizations) to provide a complete picture of the FFS inventory regulated by the FAA. The issuance of the statement will not require any additional evaluation or require any adjustment to the evaluation basis for the FFS.
- h. Downgrading of an FFS is a permanent change in qualification level and will necessitate the issuance of a revised SOQ to reflect the revised qualification level, as appropriate. If a temporary restriction is placed on an FFS because of a missing, malfunctioning, or inoperative component or ongoing repairs, the restriction is not a permanent change in qualification level. Instead, the restriction is temporary and is removed when the reason for the restriction has been resolved.
- i. The responsible Flight Standards office will determine the evaluation criteria for an FFS that has been removed from active status. The criteria will be based on the number of continuing qualification evaluations and quarterly inspections missed during the period of inactivity. For example, if the FFS were out of service for a 1 year period, it would be necessary to complete the entire QTG, since all of the quarterly evaluations

would have been missed. The responsible Flight Standards office will also consider how the FFS was stored, whether parts were removed from the FFS and whether the FFS was disassembled.

j. The FFS will normally be requalified using the FAA-approved MQTG and the criteria that was in effect prior to its removal from qualification. However, inactive periods of 2 years or more will require requalification under the standards in effect and current at the time of requalification.

END INFORMATION

14. Inspection, Continuing Qualification Evaluation, and Maintenance Requirements (§60.19)

BEGIN QPS REQUIREMENTS

- a. The sponsor must conduct a minimum of four evenly spaced inspections throughout the year. The objective test sequence and content of each inspection must be developed by the sponsor and must be acceptable to the responsible Flight Standards office.
- b. The description of the functional preflight check must be contained in the sponsor's QMS.
- c. Record "functional preflight" in the FFS discrepancy log book or other acceptable location, including any item found to be missing, malfunctioning, or inoperative.
- d. During the continuing qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FFS.
- e. The responsible Flight Standards office will conduct continuing qualification evaluations every 12 months unless:
- (1) The responsible Flight Standards office becomes aware of discrepancies or performance problems with the device that warrants more frequent evaluations; or
- (2) The sponsor implements a QMS that justifies less frequent evaluations. However, in no case shall the frequency of a continuing qualification evaluation exceed 36 months.

END QPS REQUIREMENTS

BEGIN INFORMATION

- f. The sponsor's test sequence and the content of each quarterly inspection required in $\S 60.19(a)(1)$ should include a balance and a mix from the objective test requirement areas listed as follows:
 - (1) Performance
 - (2) Handling qualities.
 - (3) Motion system (where appropriate).

14 CFR Ch. I (1-1-24 Edition)

- (4) Visual system (where appropriate).
- (5) Sound system (where appropriate).
- (6) Other FFS systems.
- g. If the evaluator plans to accomplish specific tests during a normal continuing qualification evaluation that requires the use of special equipment or technicians, the sponsor will be notified as far in advance of the evaluation as practical; but not less than 72 hours. Examples of such tests include latencies, control dynamics, sounds and vibrations, motion, and/or some visual system tests.
- h. The continuing qualification evaluations, described in §60.19(b), will normally require 4 hours of FFS time. However, flexibility is necessary to address abnormal situations or situations involving aircraft with additional levels of complexity (e.g., computer controlled aircraft). The sponsor should anticipate that some tests may require additional time. The continuing qualification evaluations will consist of the following:
- (1) Review of the results of the quarterly inspections conducted by the sponsor since the last scheduled continuing qualification evaluation.
- (2) A selection of approximately 8 to 15 objective tests from the MQTG that provide an adequate opportunity to evaluate the performance of the FFS. The tests chosen will be performed either automatically or manually and should be able to be conducted within approximately one-third (1/3) of the allotted FFS time.
- (3) A subjective evaluation of the FFS to perform a representative sampling of the tasks set out in attachment 3 of this appendix. This portion of the evaluation should take approximately two-thirds (2/3) of the allotted FFS time.
- (4) An examination of the functions of the FFS may include the motion system, visual system, sound system, instructor operating station, and the normal functions and simulated malfunctions of the simulated helicopter systems. This examination is normally accomplished simultaneously with the subjective evaluation requirements.

END INFORMATION

15. Logging FFS Discrepancies (§60.20)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.20. Logging FFS Discrepancies.

END INFORMATION

16. INTERIM QUALIFICATION OF FFSs FOR NEW HELICOPTER TYPES OR MODELS (§ 60.21)

REGIN INFORMATION

No additional regulatory or informational material applies to §60.21, Interim Qualification of FFSs for New Helicopter Types or Models.

END INFORMATION

17. Modifications to FFSs (§60.23)

BEGIN QPS REQUIREMENTS

a. The notification described in $\S 60.23(c)(2)$ must include a complete description of the planned modification, with a description of the operational and engineering effect the proposed modification will have on the operation of the FFS and the results that are expected with the modification incorporated.

b. Prior to using the modified FFS:

- (1) All the applicable objective tests completed with the modification incorporated, including any necessary updates to the MQTG (e.g., accomplishment of FSTD Directives) must be acceptable to the responsible Flight Standards office; and
- (2) The sponsor must provide the responsible Flight Standards office with a statement signed by the MR that the factors listed in §60.15(b) are addressed by the appropriate personnel as described in that section.

END QPS REQUIREMENTS

BEGIN INFORMATION

(3) FSTD Directives are considered modifications of an FFS. See Attachment 4 of this appendix for a sample index of effective FSTD Directives. See Attachment 6 of this appendix for a list of all effective FSTD Directives applicable to Helicopter FFSs.

END INFORMATION

18. OPERATION WITH MISSING, MALFUNCTIONING, OR INOPERATIVE COMPONENTS (§ 60.25)

BEGIN INFORMATION

a. The sponsor's responsibility with respect to $\S60.25(a)$ is satisfied when the sponsor fairly and accurately advises the user of the current status of an FFS, including any missing, malfunctioning, or inoperative (MMI) component(s).

b. It is the responsibility of the instructor, check airman, or representative of the administrator conducting training, testing, or checking to exercise reasonable and prudent judgment to determine if any MMI component is necessary for the satisfactory completion of a specific maneuver, procedure, or task

- c. If the 29th or 30th day of the 30-day period described in §60.25(b) is on a Saturday, a Sunday, or a holiday, the FAA will extend the deadline until the next business day.
- d. In accordance with the authorization described in \$60.25(b), the sponsor may develop a discrepancy prioritizing system to accomplish repairs based on the level of impact on the capability of the FFS. Repairs having a larger impact on FFS capability to provide the required training, evaluation, or flight experience will have a higher priority for repair or replacement.

END INFORMATION

 AUTOMATIC LOSS OF QUALIFICATION AND PROCEDURES FOR RESTORATION OF QUALI-FICATION (§ 60.27)

BEGIN INFORMATION

If the sponsor provides a plan for how the FFS will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FFS is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing required for requalification.

END INFORMATION

 OTHER LOSSES OF QUALIFICATION AND PRO-CEDURES FOR RESTORATION OF QUALIFICA-TION (§ 60.29)

BEGIN INFORMATION

If the sponsor provides a plan for how the FFS will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FFS is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing required for requalification.

BEGIN QPS REQUIREMENTS

a. FFS modifications can include hardware or software changes. For FFS modifications involving software programming changes, the record required by \$60.31(a)(2) must consist of the name of the aircraft system software, aerodynamic model, or engine model change, the date of the change, a summary of the change, and the reason for the change.

b. If a coded form for record keeping is used, it must provide for the preservation and retrieval of information with appropriate security or controls to prevent the inappropriate alteration of such records after the fact.

END QPS REQUIREMENTS

22. APPLICATIONS, LOGBOOKS, REPORTS, AND RECORDS: FRAUD, FALSIFICATION, OR INCORRECT STATEMENTS (§ 60.33)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.33, Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements.

23. [Reserved]

24. [Reserved]

25. FFS QUALIFICATION ON THE BASIS OF A BI-LATERAL AVIATION SAFETY AGREEMENT (BASA) (§ 60.37)

No additional regulatory or informational material applies to §60.37, FFS Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA).

END INFORMATION

ATTACHMENT 1 TO APPENDIX C TO PART 60—GENERAL SIMULATOR REQUIREMENTS

BEGIN QPS REQUIREMENTS

1. Requirements

a. Certain requirements included in this appendix must be supported with an SOC as

14 CFR Ch. I (1-1-24 Edition)

defined in Appendix F of this part, which may include objective and subjective tests. The requirements for SOCs are indicated in the "General Simulator Requirements" column in Table C1A of this appendix.

b. Table C1A describes the requirements for the indicated level of FFS. Many devices include operational systems or functions that exceed the requirements outlined in this section. However, all systems will be tested and evaluated in accordance with this appendix to ensure proper operation.

END QPS REQUIREMENTS

BEGIN INFORMATION

2. Discussion

- a. This attachment describes the general simulator requirements for qualifying a helicopter FFS. The sponsor should also consult the objective tests in Attachment 2 of this appendix and the examination of functions and subjective tests listed in Attachment 3 of this appendix to determine the complete requirements for a specific level simulator.
- b. The material contained in this attachment is divided into the following categories:
- (1) General flight deck configuration.
- ${\rm (2)\ Simulator\ programming.}$
- (3) Equipment operation.
- (4) Equipment and facilities for instructor/evaluator functions.
- (5) Motion system.
- (6) Visual system.
- (7) Sound system.
- c. Table C1A provides the standards for the General Simulator Requirements.
- d. Table C1B provides the tasks that the sponsor will examine to determine whether the FFS satisfactorily meets the requirements for flight crew training, testing, and experience, and provides the tasks for which the simulator may be qualified.
- e. Table C1C provides the functions that an instructor/check airman must be able to control in the simulator.
- f. It is not required that all of the tasks that appear on the List of Qualified Tasks (part of the SOQ) be accomplished during the initial or continuing qualification evalua-
- g. Table C1A addresses only Levels B, C, and D helicopter simulators because there are no Level A Helicopter simulators.

END INFORMATION

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS

Entry No	QPS requirements	Simu	ılator l	evels	Information
Entry No.	General simulator requirements	В	С	D	Notes
1	General Flight Deck Configuration				
1.a	The simulator must have a flight deck that is a replica of the helicopter being simulated. The simulator must have controls, equipment, observable flight deck indicators, circuit breakers, and bulkheads properly located, functionally accurate and replicating the helicopter. The direction of movement of controls and switches must be identical to that in the helicopter. Pilot seats must afford the capability for the occupant to be able to achieve the design "eye position" established for the helicopter being simulated. Equipment for the operation of the flight deck windows must be included, but the actual windows need not be operable. Fire axes, extinguishers, and spare light bulbs must be available in the FFS but may be relocated to a suitable location as near as practical to the original position. Fire axes, landing gear pins, and any similar purpose instruments need only be represented in silhouette.	X	X	X	For simulator purposes, the flight deck consists of all that space forward of a cross section of the fuselage at the most extreme aft setting of the pilots' seats including additional, required flight crewmember duty stations and those required bulkheads aft of the pilot seats. For clarification, bulkheads containing only items such as landing gear pin storage compartments, fire axes and extinguishers, spare light bulbs, and aircraft documents pouches are not considered essential and may be omitted.
1.b	Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate.	х	х	х	
2	Programming				
2.a	A flight dynamics model that accounts for various combinations of air speed and power normally encountered in flight must correspond to actual flight conditions, including the effect of change in helicopter attitude, aerodynamic and propulsive forces and moments, altitude, temperature, mass, center of gravity location, and configuration.	х	х	х	
2.b	The simulator must have the computer capacity, accuracy, resolution, and dynamic response needed to meet the qualification level sought. An SOC is required	х	х	Х	
2.c	Ground handling (where appropriate) and aerodynamic programming must include the following:.				
2.c.1	Ground effect	х	х	х	Applicable areas include flare and touch down from a running landing as well as for inground-effect (IGE) hover. A reasonable simulation of ground effect includes modeling of lift, drag, pitching moment, trim, and power while in ground effect.
2.c.2	Ground reaction	х	х	х	Reaction of the helicopter upon contact with the landing surface during landing (e.g., strut deflection, tire or skid friction, side forces) may differ with changes in gross weight, airspeed, rate of descent on touch- down, and slide slip.

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

Entry No.	QPS requirements	Simu	ılator l	evels	Information
EIIIIY NO.	General simulator requirements	В	С	D	Notes
2.d	The simulator must provide for manual and automatic testing of simulator hardware and software programming to determine compliance with simulator objective tests as prescribed in Attachment 2 of this appendix. An SOC is required		х	Х	This may include an automated system, which could be used for conducting at least a portion of the QTG tests. Automatic "flagging" of out-of-tolerance situations is encouraged.
2.e	The relative responses of the motion system, visual system, and flight deck instruments must be measured by latency tests or transport delay tests. Motion onset must occur before the end of the scan of that video field. Instrument response may not occur prior to motion onset. Test results must be within the following limits:				The intent is to verify that the simulator provides instrument, motion, and visual cues that are like the helicopter responses within the stated time delays. It is preferable motion onset occur before the start of the visual scene change (the start of the scan of the first video field containing different information). For helicopter response, acceleration in the appropriate corresponding rotational axis is preferred.
2.e.1	Response must be within 150 milliseconds of	х			
2.e.2	the helicopter response. Response must be within 100 milliseconds of the helicopter response.		х	x	
2.f	The simulator must simulate brake and tire failure dynamics (including antiskid failure, if appropriate). An SOC is required		x	X	The simulator should represent the motion (in the appropriate axes) and the directional control characteristics of the helicopter when experiencing simulated brake or tire failures.
2.g	The aerodynamic modeling in the simulator must include:. (1) Ground effect, (2) Effects of airframe and rotor icing (if applicable), (3) Aerodynamic interference effects between the rotor wake and fuselage, (4) Influence of the rotor on control and stabilization systems, (5) Representations of settling with power, and (6) Retreating blade stall. An SOC is required.		x	X	See Attachment 2 of this appendix for further information on ground effect.
2.h	The simulator must provide for realistic mass properties, including gross weight, center of gravity, and moments of inertia as a function of payload and fuel loading. An SOC is required.	x	х	Х	
3	Equipment Operation				
3.a	All relevant instrument indications involved in the simulation of the helicopter must automatically respond to control movement or external disturbances to the simulated helicopter; e.g., turbulence or windshear. Numerical values must be presented in the appropriate units.	x	x	Х	
3.b	Communications, navigation, caution, and warning equipment must be installed and operate within the tolerances applicable for the helicopter being simulated.	х	х	X	See Attachment 3 of this appendix for further information regarding long-range navigation equipment.
3.c	Simulated helicopter systems must operate as the helicopter systems operate under normal, abnormal, and emergency operating conditions on the ground and in flight.	х	х	Х	

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

	QPS requirements Simulator levels		ovole	Information		
Entry No.	General simulator requirements	В	C	D	Notes	
3.d	The simulator must provide pilot controls with control forces and control travel that correspond to the simulated helicopter. The simulator must also react in the same manner as the helicopter under the same flight conditions.	х	х	х		
3.e	Simulator control feel dynamics must replicate the helicopter simulated. This must be determined by comparing a recording of the control feel dynamics of the simulator to helicopter measurements. For initial and upgrade evaluations, the control dynamic characteristics must be measured and recorded directly from the flight deck controls, and must be accomplished in takeoff, cruise, and landing conditions and configurations.		х	х		
4	Instructor/Evaluator Facilities					
4.a	In addition to the flight crewmember stations, the simulator must have at least two suitable seats for the instructor/check airman and FAA inspector. These seats must provide adequate vision to the pilot's panel and forward windows. All seats other than flight crew seats need not represent those found in the helicopter but must be adequately secured to the floor and equipped with similar positive restraint devices.	X	X	X	The responsible Flight Standards office will consider alternatives to this standard for additional seats based on unique flight deck configurations.	
4.b	The simulator must have controls that enable the instructor/evaluator to control all required system variables and insert all abnormal or emergency conditions into the simulated helicopter systems as described in the sponsor's FAA-approved training program, or as described in the relevant operating manual as appropriate.	X	X	X		
4.c	The simulator must have instructor controls for all environmental effects expected to be available at the IOS; e.g., clouds, visibility, icing, precipitation, temperature, storm cells, and wind speed and direction.	х	х	х		
4.d	The simulator must provide the instructor or evaluator the ability to present ground and air hazards.		х	х	For example, another aircraft crossing the active runway and converging airborne traffic.	
4.e	The simulator must provide the instructor or evaluator the ability to present the effect of re-circulating dust, water vapor, or snow conditions that develop as a result of rotor downwash.		х	х	This is a selectable condition that is not required for all operations on or near the surface.	
5	Motion System					
5.a	The simulator must have motion (force) cues perceptible to the pilot that are representative of the motion in a helicopter.	х	х	х	For example, touchdown cues should be a function of the rate of descent (RoD) of the simulated helicopter.	
5.b	The simulator must have a motion (force cueing) system with a minimum of three degrees of freedom (at least pitch, roll, and heave). An SOC is required.	х				

14 CFR Ch. I (1-1-24 Edition)

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

Entry No.	QPS requirements	Simu	ılator l	evels	Information
	General simulator requirements	В	С	D	Notes
5.c	The simulator must have a motion (force cueing) system that produces cues at least equivalent to those of a six-degrees-of-freedom, synergistic platform motion system (i.e., pitch, roll, yaw, heave, sway, and surge). An SOC is required.		X	X	
5.d	The simulator must provide for the recording of the motion system response time. An SOC is required.	x	х	Х	
5.e	The simulator must provide motion effects programming to include the following:. (1) Runway rumble, oleo deflections, effects of ground speed, uneven runway, characteristics. (2) Buffets due to transverse flow effects. (3) Buffet during extension and retraction of landing gear. (4) Buffet due to vortex ring (settling with power). (6) Representative cues resulting from touchdown. (7) High speed rotor vibrations. (8) Tire failure dynamics	X	×	× × ×	For air turbulence, general purpose disturbance models are acceptable if, when used, they produce test results that approximate demonstrable flight test data.
5.f	The simulator must provide characteristic mo- tion vibrations that result from operation of the helicopter (for example, retreating blade stall, extended landing gear, settling with power) in so far as vibration marks an event or helicopter state, which can be sensed in the flight deck.			X	The simulator should be programmed and in- strumented in such a manner that the char- acteristic buffet modes can be measured and compared to helicopter data.
6	Visual System				Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained.
6.a	The simulator must have a visual system providing an out-of-the-flight deck view.	х	х	Х	
6.b	The simulator must provide a continuous field-of-view of at least 75° horizontally and 30° vertically per pilot seat. Both pilot seat visual systems must be operable simultaneously. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. An SOC must explain the geometry of the installation.	x			

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

Entry No.	QPS requirements	Simu	ılator l	evels	Information
EIIIIY NO.	General simulator requirements	В	С	D	Notes
6.c	The simulator must provide a continuous visual field-of-view of at least 146° horizontally and 36° vertically per pilot seat. Both pilot seat visual systems must be operable simultaneously. Horizontal field-of-view is centered on the zero degree azimuth line relative to the aircraft fuselage. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. An SOC must explain the geometry of the installation. Capability for a field-of-view in excess of the minimum is not required for qualification at Level C. However, where specific tasks require extended fields of view beyond the 146° by 36° (e.g., to accommodate the use of "chin windows" where the accommodation is either integral with or separate from the primary visual system display), then the extended fields of view must be provided. When considering the installation and use of augmented fields of view, the sponsor must meet with the NSPM to determine the training, testing, checking, and experience tasks for which the augmented field-of-view capability may be required.		x		Optimization of the vertical field-of-view may be considered with respect to the specific helicopter flight deck cut-off angle. The sponsor may request the responsible Flight Standards office to evaluate the FFS for specific authorization(s) for the following: (1) Specific areas within the database needing higher resolution to support landings, take-offs and ground cushion exercises and training away from a heliport, including elevated heliport, helidecks and confined areas. (2) For cross-country flights, sufficient scene details to allow for ground to map navigation over a sector length equal to 30 minutes at an average cruise speed. (3) For offshore airborne radar approaches (ARA), harmonized visual/radar representations of installations.
6.d	The simulator must provide a continuous visual field-of-view of at least 176° horizontally per 50° vertically per pilot seat. Both pilot seat visual systems must be operable simultaneously. Horizontal field-of-view is centered on the zero degree azimuth line relative to the aircraft fuselage. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. An SOC must explain the geometry of the installation. Capability for a field-of-view in excess of the minimum is not required for qualification at Level D. However, where specific tasks require extended fields of view beyond the 176° by 56° (e.g., to accommodate the use of "chin windows" where the accommodation is either integral with or separate from the primary visual system display), then the extended fields of view must be provided. When considering the installation and use of augmented fields of view, the sponsor must meet with the responsible Flight Standards office to determine the training, testing, checking, and experience tasks for which the augmented field-of-view capability may be required.			X	Optimization of the vertical field-of-view may be considered with respect to the specific helicopter flight deck cut-off angle. The sponsor may request the responsible Flight Standards office to evaluate the FFS for specific authorization(s) for the following: (1) Specific areas within the database needing higher resolution to support landings, take-offs and ground cushion exercises and training away from a heliport, including elevated heliport, helidecks and confined areas. (2) For cross-country flights, sufficient scene details to allow for ground to map navigation over a sector length equal to 30 minutes at an average cruise speed. (3) For offshore airborne radar approaches (ARA), harmonized visual/radar representations of installations.
6.e	The visual system must be free from optical discontinuities and artifacts that create non-realistic cues.	x	х	Х	Nonrealistic cues might include image "swim- ming" and image "roll-off," that may lead a pilot to make incorrect assessments of speed, acceleration and/or situational awareness.

Pt. 60, App. C

14 CFR Ch. I (1-1-24 Edition)

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

Entry No.	QPS requirements	Simu	ılator l	evels	Information
Littly NO.	General simulator requirements	В	С	D	Notes
6.f	The simulator must have operational landing lights for night scenes.Where used, dusk (or twilight) scenes require operational landing lights	х	х	X	
6.g	The simulator must have instructor controls for the following: (1) Visibility in statute miles (kilometers) and runway visual range (RVR) in ft. (meters). (2) Airport or landing area selection (3) Airport or landing area lighting	x	x	X	
6.h	Each airport scene displayed must include the following: (1) Airport runways and taxiways (2) Runway definition (a) Runway surface and markings (b) Lighting for the runway in use, including runway threshold, edge, centerline, touchdown zone, VASI (or PAPI), and approach lighting of appropriate colors, as appropriate (c) Taxiway lights	x	x	X	
6.i	The simulator must provide visual system compatibility with dynamic response programming.	Х	Х	X	
6.j	The simulator must show that the segment of the ground visible from the simulator flight deck is the same as from the helicopter flight deck (within established tolerances) when at the correct airspeed and altitude above the touchdown zone.	x	x	X	This will show the modeling accuracy of the scene with respect to a predetermined position from the end of the runway "in use."
6.k	The simulator must provide visual cues nec- essary to assess rate of change of height, height AGL, and translational displacement and rates during takeoffs and landings.	х			
6.l	The simulator must provide visual cues necessary to assess rate of change of height, height AGL, as well as translational displacement and rates during takeoff, low altitude/low airspeed maneuvering, hover, and landing.		х	Х	
6.m	The simulator must provide for accurate portrayal of the visual environment relating to the simulator attitude.	х	x	X	Visual attitude vs. simulator attitude is a comparison of pitch and roll of the horizon as displayed in the visual scene compared to the display on the attitude indicator.
6.n	The simulator must provide for quick confirmation of visual system color, RVR, focus, and intensity. An SOC is required.		х	Х	
6.0	The simulator must be capable of producing at least 10 levels of occulting.		х	Х	

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

Entry No.	QPS requirements	Simu	ılator le	evels	Information
Entry No.	General simulator requirements	В	С	D	Notes
6.р	Night Visual Scenes. The simulator must provide night visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Night scenes, as a minimum, must provide presentations of sufficient surfaces with appropriate textural cues that include self-illuminated objects such as road networks, ramp lighting, and airport signage, to conduct a visual approach, a landing, and airport movement (taxi). Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by helicopter landing lights.	X	X	X	
6.q	Dusk (Twilight) Visual Scenes. The simulator must provide dusk (or twilight) visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. Dusk (or twilight) scenes, as a minimum, must provide full color presentations of reduced ambient intensity, sufficient surfaces with appropriate textural cues that include self-illuminated objects such as road networks, ramp lighting and airport signage, to conduct a visual approach, landing and airport movement (taxi). Scenes must include a definable horizon and typical terrain characteristics such as fields, roads and bodies of water and surfaces illuminated by representative aircraft lighting (e.g., landing lights). If provided, directional horizon lighting must have correct orientation and be consistent with surface shading effects. Total scene content must be comparable in detail to that produced by 10,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects.		x	x	
6.r	Daylight Visual Scenes. The simulator must have daylight visual scenes with sufficient scene content to recognize the airport, the terrain, and major landmarks around the airport. The scene content must allow a pilot to successfully accomplish a visual landing. No ambient lighting may "washout" the displayed visual scene. Total scene content must be comparable in detail to that produced by 10,000 visible textured surfaces and 6,000 visible lights with sufficient system capacity to display 16 simultaneously moving objects. The visual display must be free of apparent and distracting quantization and other distracting visual effects while the simulator is in motion.		x	x	
6.s	The simulator must provide operational visual scenes that portray physical relationships known to cause landing illusions to pilots.		x	Х	For example: short runways, landing approaches over water, uphill or downhill runways, rising terrain on the approach path, unique topographic features.

TABLE C1A—MINIMUM SIMULATOR REQUIREMENTS—Continued

	QPS requirements	Simu	ılator l	evels	Information
Entry No.	General simulator requirements	В	С	D	Notes
6.t	The simulator must provide special weather representations of light, medium, and heavy precipitation near a thunderstorm on takeoff and during approach and landing. Representations need only be presented at and below an altitude of 2,000 ft. (610 m) above the airport surface and within 10 miles (16 km) of the airport.		x	x	
6.v	The simulator must present visual scenes of wet and snow-covered runways, including runway lighting reflections for wet conditions, and partially obscured lights for snow conditions. The simulator must present realistic color and		X	X	The responsible Flight Standards office will consider suitable alternative effects.
0.v	directionality of all airport lighting.			^	
7	Sound System				
7.a	The simulator must provide flight deck sounds that result from pilot actions that correspond to those that occur in the helicopter.	Х	Х	Х	
7.b	Volume control, if installed, must have an indication of the sound level setting.	х	х	Х	
7.c	The simulator must accurately simulate the sound of precipitation, windshield wipers, and other significant helicopter noises perceptible to the pilot during normal and abnormal operations, and include the sound of a crash (when the simulator is landed in an unusual attitude or in excess of the structural gear limitations); normal engine sounds; and the sounds of gear extension and retraction. An SOC is required.		x	x	
7.d	The simulator must provide realistic amplitude and frequency of flight deck noises and sounds. Simulator performance must be recorded, compared to amplitude and frequency of the same sounds recorded in the helicopter, and made a part of the QTG.			x	

TABLE C1B—TABLE OF TASKS VS. SIMULATOR LEVEL

	QPS requirements	Information			
Entry No.	Subjective requirements The simulator must be able to perform the tasks associated with		mula levels		Notes
•	that level of qualification.		С	D	
1. Preflight F	Procedures				
1.a	Preflight Inspection (Flight deck Only) switches, indicators, systems, and equipment.	Х	Х	Х	
1.b	APU/Engine start and run-up.				
1.b.1	Normal start procedures		х	х	
1.b.2	Alternate start procedures		х	х	
1.b.3	Abnormal starts and shutdowns (hot start, hung start)		Х	х	
1.c	Taxiing—Ground		х	х	
1.d	Taxiing—Hover		х	х	

	QPS requirements				Information
Entry No.	Subjective requirements The simulator must be able to perform the tasks associated with		mula levels		Notes
	that level of qualification.		С	D	
1.e	Pre-takeoff Checks	Х	Х	Х	
2. Takeoff ar	nd Departure Phase				
2.a	Normal takeoff.				
2.a.1	From ground	Х	Х	х	
2.a.2	From hover		Х	х	
2.a.3	Running	Х	Х	х	
2.b	Instrument	Х	х	х	
2.c	Powerplant Failure During Takeoff	х	х	х	
2.d	Rejected Takeoff	х	х	х	
2.e	Instrument Departure	Х	х	х	
3. Climb					1
3.a	Normal	Х	х	х	
3.b	Obstacle clearance	Х	х	х	
3.c	Vertical	Х	х	х	
3.d	One engine inoperative	Х	х	х	
4. In-flight M	aneuvers				
4.a	Turns (timed, normal, steep)	Х	х	х	
4.b	Powerplant Failure—Multiengine Helicopters	Х	х	х	
4.c	Powerplant Failure—Single-Engine Helicopters	Х	х	х	
4.d	Recovery From Unusual Attitudes	Х	х	х	
4.e	Settling with Power	Х	х	х	
4.f	Specific Flight Characteristics incorporated into the user's FAA approved flight training program.	Α	Α	Α	
5. Instrumen	t Procedures				
5.a	Instrument Arrival	Х	х	х	
5.b	Holding	Х	х	х	
5.c	Precision Instrument Approach.				
5.c.1	Normal—All engines operating	Х	х	х	
5.c.2	Manually controlled—One or more engines inoperative	х	Х	х	
5.d	Non-precision Instrument Approach	х	Х	Х	
5.e	Missed Approach.				
5.e.1	All engines operating	Х	Х	х	
5.e.2	One or more engines inoperative	Х	Х	х	
5.e.3	Stability augmentation system failure	х	Х	Х	
6. Landings	and Approaches to Landings				1

TABLE C1B—TABLE OF TASKS VS. SIMULATOR LEVEL—Continued

-	QPS requirements		Information		
Entry No.	Subjective requirements The simulator must be able to perform the tasks associated with that level of qualification. Simulatives		3	Notes	
6.a	·		х	D X	
6.b	Landings.	Х			
6.b.1	Normal/crosswind.				
6.b.1.a	Running	Х	Х	Х	
6.b.1.b	From Hover	^	X	X	
6.b.2	One or more engines inoperative	Х	X	X	
6.b.3	Rejected Landing	X	X	X	
		^	^	^	
	d Abnormal Procedures	· ·	· ·	х	
7.a	Powerplant	X	X		
7.b	Fuel System	X	X	X	
7.c	Electrical System	Х	X	Х	
7.d	Hydraulic System	Х	Х	Х	
7.e	Environmental System(s)	Х	Х	Х	
7.f	Fire Detection and Extinguisher Systems	Х	Х	Х	
7.g	Navigation and Aviation Systems	Х	Х	Х	
7.h	Automatic Flight Control System, Electronic Flight Instrument System, and Related Subsystems.	Х	Х	Х	
7.i	Flight Control Systems	Х	х	Х	
7.j	Anti-ice and Deice Systems	Х	х	Х	
7.k	Aircraft and Personal Emergency Equipment	х	х	х	
7.I	Special Missions tasks (e.g., Night Vision goggles, Forward Looking Infrared System, External Loads and as listed on the SOQ).	Α	Α	х	
8. Emergend	y procedures (as applicable)				
8.a	Emergency Descent	Х	х	Х	
8.b	Inflight Fire and Smoke Removal	х	х	х	
8.c	Emergency Evacuation	Х	х	х	
8.d	Ditching	х	х	х	
8.e	Autorotative Landing	Х	х	х	
8.f	Retreating blade stall recovery	х	х	х	
8.g	Mast bumping		Х	Х	
8.h	Loss of tail rotor effectiveness		Х	Х	
8.i	Vortex recovery	х	Х	Х	
9. Postflight	Procedures				
9.a	After-Landing Procedures	Х	Х	Х	
9.b	Parking and Securing.				
	I .				

Federal Aviation Administration, DOT

Pt. 60, App. C

TABLE C1B—TABLE OF TASKS VS. SIMULATOR LEVEL—Continued

	QPS requirements	Information			
Entry No.	Subjective requirements The simulator must be able to perform the tasks associated with that level of qualification.		mulat evels		Notes
			С	D	
9.b.1	Rotor brake operation	Х	Х	Х	
9.b.2	Abnormal/emergency procedures	Х	Х	Х	

Note: An "A" in the table indicates that the system, task, or procedure may be examined if the appropriate aircraft system or control is simulated in the FFS and is working properly

TABLE C1C—TABLE OF TASKS VS. SIMULATOR LEVEL

	QPS requirements				Information
Entry No.	Subjective requirements		mula:		Notes
•	that level of qualification.	В	С	D	
1	Instructor Operating Station (IOS), as appropriate				
1.a	Power switch(es)	х	х	х	
1.b	Helicopter conditions	Х	Х	Х	e.g., GW, CG, Fuel loading, Systems, Ground Crew.
1.c	Airports/Heliports/Helicopter Landing Areas	х	х	х	e.g., Selection, Surface, Presets, Lighting controls
1.d	Environmental controls.	х	х	х	e.g., Clouds, Visibility, RVR Temp, Wind, Ice, Snow, Rain, and Windshear.
1.e	Helicopter system malfunctions (Insertion/deletion)	х	х	Х	
1.f	Locks, Freezes, and Repositioning	х	х	Х	
2	Sound Controls.	•	•		
2.a	On/off/adjustment	х	х	Х	
3	Motion/Control Loading System	•	•		
3.a	On/off/emergency stop	х	х	х	
4	Observer Seats/Stations				1
4.a	Position/Adjustment/Positive restraint system	х	х	х	
			1		

ATTACHMENT 2 TO APPENDIX C TO PART 60— FFS OBJECTIVE TESTS

TABLE OF CONTENTS—Continued

BEGIN INFORMATION

TABLE OF CONTENTS

Paragraph No.	Title
1	Introduction.
2	Test Requirements.
	Table C2A, Objective Tests.
3	General.

Paragraph No.	Title
4	Control Dynamics.
5	[Reserved]
6	Motion System.
7	Sound System.
8	Additional Information About Flight Simulator Qualification for New or Derivative Helicopters.
9	Engineering Simulator—Validation Data.
10	[Reserved]

299

Pt. 60, App. C

TABLE OF CONTENTS—Continued

Paragraph No.	Title
11	Validation Test Tolerances.
12	Validation Data Roadmap.
13	Acceptance Guidelines for Alternative Engines Data.
14	Acceptance Guidelines for Alternative Avionics (Flight-Related Computers and Controllers).
15	Transport Delay Testing.
16	Continuing Qualification Evaluations—Validation Test Data Presentation.
17	Alternative Data Sources, Procedures, and Instrumentation: Level A and Level B Simulators Only.

1. Introduction

a. If relevant winds are present in the objective data, the wind vector (magnitude and direction) should be clearly noted as part of the data presentation, expressed in conventional terminology, and related to the runway being used for the test.

b. The responsible Flight Standards office will not evaluate any simulator unless the required SOC indicates that the motion system is designed and manufactured to safely operate within the simulator's maximum excursion, acceleration, and velocity capabilities (see Motion System in the following table)

c. Table C2A addresses helicopter simulators at Levels B, C, and D because there are no Level A Helicopter simulators.

END INFORMATION

BEGIN QPS REQUIREMENTS

2. Test Requirements

a. The ground and flight tests required for qualification are listed in Table of C2A, FFS Objective Tests. Computer-generated simulator test results must be provided for each test except where an alternative test is specifically authorized by the responsible Flight Standards office. If a flight condition or operating condition is required for the test but does not apply to the helicopter being simulated or to the qualification level sought, it may be disregarded (e.g., an engine out missed approach for a single-engine helicopter, or a hover test for a Level B simulator). Each test result is compared against the validation data described in §60.13 and in this appendix. Although use of a driver program designed to automatically accomplish the tests is encouraged for all simulators and required for Level C and Level D simulators, each test must be able to be accomplished

manually while recording all appropriate parameters. The results must be produced on an appropriate recording device acceptable to the responsible Flight Standards office and must include simulator number, date, time, conditions, tolerances, and appropriate dependent variables portrayed in comparison to the validation data. Time histories are required unless otherwise indicated in Table C2A. All results must be labeled using the tolerances and units given.

b. Table C2A sets out the test results required, including the parameters, tolerances, and flight conditions for simulator validation. Tolerances are provided for the listed tests because mathematical modeling and acquisition/development of reference data are often inexact. All tolerances listed in the following tables are applied to simulator performance. When two tolerance values are given for a parameter, the less restrictive value may be used unless otherwise indicated. In those cases where a tolerance is expressed only as a percentage, the tolerance percentage applies to the maximum value of that parameter within its normal operating range as measured from the neutral or zero position unless otherwise indicated.

c. Certain tests included in this attachment must be supported with an SOC. In Table C2A, requirements for SOCs are indicated in the "Test Details" column.

d. When operational or engineering judgment is used in making assessments for flight test data applications for simulator validity, such judgment may not be limited to a single parameter. For example, data that exhibit rapid variations of the measured parameters may require interpolations or a "best fit" data selection. All relevant parameters related to a given maneuver or flight condition must be provided to allow overall interpretation. When it is difficult or impossible to match simulator to helicopter data throughout a time history, differences must be justified by providing a comparison of other related variables for the condition being assessed.

e. The FFS may not be programmed so that the mathematical modeling is correct only at the validation test points. Unless noted otherwise, simulator tests must represent helicopter performance and handling qualities at operating weights and centers of gravity (CG) typical of normal operation. If a test is supported by helicopter data at one extreme weight or CG, another test supported by helicopter data at mid-conditions or as close as possible to the other extreme must be included. Certain tests that are relevant only at one extreme CG or weight condition need not be repeated at the other extreme. Tests of handling qualities must include validation of augmentation devices.

f. When comparing the parameters listed to those of the helicopter, sufficient data must also be provided to verify the correct flight

Federal Aviation Administration, DOT

and helicopter configuration condition changes. For example, to show that control force is within ±0.5 pound (0.22 daN) in a static stability test, data to show the correct airspeed, power, thrust or torque, helicopter configuration, altitude, and other appropriate datum identification parameters must also be given. If comparing short period dynamics, normal acceleration may be used to establish a match to the helicopter, but airspeed, altitude, control input, helicopter configuration, and other appropriate data must also be given. All airspeed values must be properly annotated (e.g., indicated versus calibrated). In addition, the same variables must be used for comparison (e.g., compare inches to inches rather than inches to centimeters).

- g. The QTG provided by the sponsor must clearly describe how the simulator will be set up and operated for each test. Each simulator subsystem may be tested independently, but overall integrated testing of the simulator must be accomplished to assure that the total simulator system meets the prescribed standards. A manual test procedure with explicit and detailed steps for completing each test must also be provided.
- h. For previously qualified simulators, the tests and tolerances of this attachment may be used in subsequent continuing qualification evaluations for any given test if the sponsor has submitted a proposed MQTG revision to the responsible Flight Standards office and has received responsible Flight Standards office approval.
 - i. Motion System Tests:
- (a) The minimum excursions, accelerations, and velocities for pitch, roll, and yaw must be measurable about a single, common reference point and must be achieved by driving one degree of freedom at a time.
- (b) The minimum excursions, accelerations, and velocities for heave, sway, and surge may be measured about different, identifiable reference points and must be achieved by driving one degree of freedom at a time
- j. Tests of handling qualities must include validation of augmentation devices. FFSs for highly augmented helicopters will be validated both in the unaugmented configuration (or failure state with the maximum permitted degradation in handling qualities) and the augmented configuration. Where various levels of handling qualities result from failure states, validation of the effect

of the failure is necessary. For those performance and static handling qualities tests where the primary concern is control position in the unaugmented configuration, unaugmented data are not required if the design of the system precludes any affect on control position. In those instances where the unaugmented helicopter response is divergent and non-repeatable, it may not be feasible to meet the specified tolerances. Alternative requirements for testing will be mutually agreed upon by the sponsor and the responsible Flight Standards office on a case-by-case basis.

- k. Some tests will not be required for helicopters using helicopter hardware in the simulator flight deck (e.g., "helicopter modular controller"). These exceptions are noted in Table C2A of this attachment. However, in these cases, the sponsor must provide a statement that the helicopter hardware meets the appropriate manufacturer's specifications and the sponsor must have supporting information to that fact available for responsible Flight Standards office review.
- l. In cases where light-class helicopters are being simulated, prior coordination with the responsible Flight Standards office on acceptable weight ranges is required. The terms "light", "medium", and "near maximum", as defined in Appendix F of this part, may not be appropriate for the simulation of light-class helicopters.

END QPS REQUIREMENTS

BEGIN INFORMATION

- m. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot test results" in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot". The steady state condition must exist from 4 seconds sprior to, through 1 second following, the instant of time captured by the snap shot.
- n. For references on basic operating weight, see AC 120-27, Aircraft Weight and Balance; and FAA-H-8083-1, Aircraft Weight and Balance Handbook.

END INFORMATION

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS

Information	Notes										
	rtor_	٥				×	×	×	×		×
	Simulator level	O				×	×	×	×		×
	0)	В				×	×	×	×		×
OBJECTIVE TESTS	Test details					Record each engine start from the initiation of the start sequence to steady state idle and from steady state idle to operating RPM.	Record both steady state idle and operating RPM conditions. May be a series of snapshot tests.	Record engine response to trim system actuation in both directions.	Record results using a step input to the collective. May be conducted concurrently with climb and descent performance tests.		If brakes are used, brake pedal position and brake system pressure must be matched to the helicopter flight test value.
TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS QPS requirements	Flight condition					Ground with the Rotor Brake Used and Not Used, if ap- plicable.	Ground	Ground	Climb and descent		Ground
TABLE C2A—FULL FLIGHT QPS requirements	Tolerance(s)					Light Off Time—±10% or ±1 sec., Torque—±5%, Rotor Speed—±3%, Fuel Flow—±10%, Gas denerator Speed—±5%, Power Turbine Speed—±5%, Gas Turbine Temp.—±30 °C.	Torque—±3%, Rotor Speed—±1.5%, Fuel Flow—±5%, Gas Generator Speed—±2*, Power Tur- bine Speed—±2%, Turbine Gas Temp.—±20°, Turbine	±10% of total change of power turbine speed, or ±0.5% change of rotor speed.	Torque—±5%, Rator Speed—1,5%.		±3 ft. (0.9m) or 20% of heli- copter turn radius.
	Test	Title	9,	Engine Assessment	Start Operations	Engine start and acceleration (transient).	Steady State Idle and Operating RPM conditions.	Power Turbine Speed Trim	Engine and Rotor Speed Governing.	Surface Operations	Minimum Radius Turn
		Entry No.	1. Performance	1.a	1.a.1	1.a.1.a	1.a.1.b	1.a.2.	1.a.3	1.b	1.b.1
							302				

				nd speed, as appropriate.		Because several kinds of takeoff procedures can be performed, the specific type of takeoff profile should be recorded to ensure the proper takeoff profile comparison test is used.
	×	×	×	grou	×	×
	×	×	×	ed or	×	×
	×	×	×	iirspe	×	×
	If brakes are used, brake pedal position and brake system pressure must be matched to the helicopter flight test value.	Record results for control position and pitch attitude during ground taxi for a specific ground speed, wind speed and direction, and density attitude.		ance may be applied to either a	flight path as appropriate to helicopter model simulated (running takeoff fror Level B, takeoff from a hover for Level C and D). For Level B, the criteria apply only to those segments at airspeeds above effective franslational lift. Results must be recorded from the initiation of the takeoff to at least 200 ft (61m) AGL.	Record takeoff flight path as appropriate to helicopter model simulated. Results must be recorded from the initiation of the takeoff to at least 200 ft (61m) AGL.
	Ground Takeoff	Ground	Ground	speed range for the following tests is less than 40 knots, the applicable airspeed tolerance may be applied to either airspeed or ground speed, as appropriate.	Ground/Takeoff and Initial Segment of Climb.	Ground/Takeoff; and Initial Segment of Climb.
	±10% or ±2%sec. Turn Rate.	Pitch Angle—±1.5°, Torque— ±3%, Longitudinal Control Position—±5%, Lateral Control Position—±5%, Di- rectional Control Position— ±5%, Collective Control Po- sition—±5%.	±10% of time and distance.	ollowing tests is less than 40 km	Airspeed—±3 kt, Altitude— ±20 ft (6.1m), Torque— ±3%, Rotor Speed—±1.5%, Vertical Velocity—±1.00 fpm (0.50m/sec) or 10%, Pitch Attitude—±1.5°, Bank Atti- tude—±2°, Heading—±2°, Longitudinal Control Posi- tion—±1.0%, Lateral Control Position—±1.0%, Direc- itonal Control Position— ±1.0%, Collective Control Position—±1.0%, Collective Control Position—±1.0%, Collective Control	Airspeed—±3 kt, Altitude— ±20 ft (6.1m), Torque— ±3%, Rotor Speed—±1.5%, Vertical Velocity—±1.00 fpm (0.50m/seo) or 10%, Pitch Attitude—±1.5°, Bank Atti- tude—±2°, Heading—±2°, Longitudinal Control Posi- tion—±10%, Lateral Control Position—±10%, Direc- floral Control Position— ±10%, Collective Control Position—±10%, Direc-
	Rate of Turn vs. Pedal Deflection, Brake Application, or Nosewheel Angle, as applicable.	Тахі	Brake Effectiveness	Takeoff When the speed range for the fi	All Engines	One Engine Inoperative continued takeoff.
n DISTILLER	1.b.2	1.b.3	1.b.4	1.c.	1.6.1	1.6.2
REPLANTING ON LAPBH6H6L3 with DISTILLER on LAPBH6H6L3 with DISTILLER of No. 14:00 Ma					303	
के हे WerDate Sep<11>2014 14:00 Ma	r 14, 2024 Jk	t 262047 PO 0000	00 F	Frm 003	:13 Fmt 8010 Sfmt 8002 Q:\1	4\14V2.TXT PC31

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

	Information	Notes							
		tor	۵	×		×		×	
		Simulator level	O	×		×		×	
TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued		Test details	m .	Time history from the take off point to touch down. Test conditions near limiting performance.		Record results for light and heavy gross weights. May be a series of snapshot tests.		Record results for light and heavy gross weights. May be a series of snapshot tests.	
SIMULATOR (FFS) OBJEC	irements	Flight condition)	Ground, Takeoff		In Ground Effect (IGE); and Out of Ground Effect (OGE).		From OGE Hover	
ABLE C2A—FULL FLIGHT	QPS requirements	Tolerance(s)		Airspeed—±3 kt, Altitude— ±20 ft (6.1m), Torque— ±3%, Rotor Speed—±1.5%, Roll angle—±1.5°, Heading— ±2°, Longitudinal Control Position—±10%, Lateral Control Position—±10%, Directional Control Posi- tion—±10%, Collective Control Position—±10%, Distance—±10%, Distance—±75%, or ±30m (100ft).		Torque—±3%, Pitch Atti- tude—±1.5°, Bank Atti- tude—±1.5°, Longitudinal Control Position—±5%, Lateral Corntol Position— ±5%, Directional Control Position—±5%, Collective Control Position—±5%.		Vertical Velocity—±100 fpm (0.50 m/sec) or ±10%. Directional Control Position—±5%, Collective Control Position—±15%.	
F		Test	Title	One Engine inoperative, rejected take off.	Hover	Performance	Vertical Climb	Performance	Level Flight
о різтіцев			Entry No.	1.6.3	1.d		1.e		1.f
O I CAPBH 6H61:3 with DISTILLER OF CAPBH6H61:3 with DISTILLER					ę	304			

		Performance and Trimmed Flight Control Positions.	Torque—±3%, Pitch Atti- tude—±1.5°, Sidesip Angle—±2°, Longitudinal Control Position—±5%, Directoral Control Position—±5%, Collective Control Position—±5%, Collective	Cruise (Augmentation On and Off).	Record results for two gross weight and CG combinations with varying trim speeds throughout the air speed envelope. May be a series of snapshot tests.	×	× ×	This test validates performance at speeds above maximum endurance atrapped.
1.g.f	g	Climb					1	
I		Performance and Trimmed Flight Control Positions.	Vertical Velocity—±100 fpm (6.1m/sec) or ±10%. Pitch Artitude—±1.5°. Sideslip Angle—±2°. Longitudinal Control Position—±5%. Lateral Control Position— ±5%. Directional Control Position—±5%. Collective Control Position—±5%.	All engines operating; One engine inoperative; Augmentation System(s) On and Off.	Record results for two gross weight and CG combinations. The data presented must be for normal climb power conditions. May be a series of snapshot tests.	×	×	
₹	1.h	Descent						-
305	1.h.1.	Descent Performance and Trimmed Flight Control Positions.	Torque—±3%, Pitch Atti- tude—±1.5°, Sideslip Angle—±2°, Longitudinal Control Position—±5%, Lateral Control Position— ±5%, Directional Control Position—±5%, Collective Control Position—±5%.	At or near 1,000 fpm (5 m/ sec) rate of descent (RoD) at normal approach speed. Augmentation System(s) On and Off.	Results must be recorded for two gross weight and CG combinations. May be a series of snapshot tests.	×	×	
l -:	1h.2	Autorotation Performance and Trimmed Flight Control Positions.	Pirch Attitude—±1.5°, Sideslip Angle—±2°, Longitudinal Control Position—±5%, Lateral Control Position—55%, Diectloral Control Position—±5%, Collective Control Position—±5%, Vertical Velocity—±100 fpm or 10%, Rotor Speed—±1.5%.	Sleady descents. Augmentation System(s) On and Off.	Record results for two gross weight conditions. Data must be recorded for normal operating PRM. (Potor speed tolerance applies only if collective control position is full down.) Data must be recorded for speeds from 50 kts, ±5 kts, through at least maximum glide distance airspeed, or maximum allowable autorotation airspeed, whichever is slower. May be a series of snapshot tests.	×	× ×	
;=		Autorotica				1	-	

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

nents Information	Simulator Simulator Flight condition Test details level Notes	О О В	uise or Climb	speed range for tests 1.j.1., 1.j.2., or 1.j.3. is less than 40 knots, the applicable airspeed tolerance may be applied to either airspeed or ground speed, as appro-	proach	Pecord results for both Cat- egory A and Category B egory A and Category B approaches and landing as approaches and landing as approaches not level model simulated. For Level B, the criteria apply only to those segments at air- speeds above effective translational lift.
QPS requirements	Tolerance(s) Flight condition		Rotor Speed—±3%, Pitch Attude— ±2°, Roll Attitude— ±3°, Vaw Attitude—±5°, Italy and Attitude— ±4°, Yaw Attitude—±5°, Italy and Attitude— ### Attispeed—±5 kts. Vertical Velocity—±200 fpm (1.00 m/s white and the property of 10%.	1.1., 1.j.2., or 1.j.3. is less than 40 knots, the applicable airspeed tol	Approach	Approach
	Test	Title	Entry	Landing When the speed range for tests 1 priate.	All Engines	One Engine Inoperative.
		Entry No.		÷;	14,1	1,12

		Alternative approaches for acquiring this data may be acceptable, depending on the aircraft as well as the personnel and the data recording, reduction, and interpretation facilities to be used, are: (1) a simulated autorotational flare and reduction of rate of descent (ROD) at attitude: or (2) a power-on termination following an autorotational approach and flare.			Contact the responsible Flight Standards office for clari- fication of any issue re- garding helicopters with re- versible controls or where the required validation data is not attainable.
	×	×			
	× ×	×		•	
	Record the results for the maneuver initiated from a stabilized approach at the landing decision point (LDP).	Record the results of an autorotational deceleration and landing from a stanilized autorotational descent, to touch down If flight test data containing all required parameters for a complete power-off landing is not available from the aircraft manufacturer for this test and other qualified flight test personnel are not available to acquire this data, the sponsor may coordinate with the responsor may coordinate with the responsible Flight Standards of fice to determine if it is appropriate to accept afternative testing means.			, special test fixtures will not ture results and the results of eement. Repeat of the afterdupgrade evaluations, the ontrols, and must be accom-
	Approach	Landing			For simulators requiring Static or Dynamic tests at the controls (i.e., cyclic, collective, and pedal), special test fixtures will not be required during initial or upgrade evaluations if the sponsor's QTG/MQTG shows both test fixture results and the results of an alternative approach, such as computer plots produced concurrently showing satisfactory agreement. Repeat of the afternative method during the initial or upgrade evaluation satisfies this test requirement. For initial and upgrade evaluations, the control dynamic characteristics must be measured at and recorded directly from the flight deck controls, and must be accomplished in hover, climb, cruise, and autorotation
	Airspeed—±3 kts, Altitude— ±20 ft. (6.1m), Torque— ±3%, Rotor Speed—±1.5%, Pirch Attitude—±1.5°, Bank Attitude—±1.5°, Heading— ±2°, Longitudinal Control Position—±10%, Lateral Control Position—±10%, Directional Control Posi- tion—±10%, Collective Control Position—±10%.	Torque—±3%, Rotor Speed—±3%, Vertical Velocity—±100 fpm (0.50m/vec) or 10%, Pitch Attitude—±2°, Bank Attitude—±2°, Heading—±5°, Longitudinal Comton Position—±10%, Lateral Control Position—±10%, Lateral Control Position—±10%, Collective Control Position—±10%, Lateral Control Position—±10%, Collective Control Position—±10%, Collective Control Position—±10%,		aracteristics	r Dynamic tests at the controls rade evaluations if the sponsor's s computer plots produced cont or upgrade evaluation satisfies I must be measured at and recortand autorotation
	Balked Landing	Autorotational Landing	ualities	Control System Mechanical Characteristics	For simulators requiring Static o be required during initial or upgran an alternative approach, such a native method during the initial control dynamic characteristics replished in hover, climb, cruise, a
th DISTILLER	1.j.3	1.j.4,	2. Handling Qualities	2.a	
woonley on LAPBH6H6L3 with DISTILLER Amondey on LAPBH6H6L3 with DISTILLER		307			
ସ ଟ ଜୁନ୍ତି ଭୁଷ୍ଟ VerDate Sep<11>2014 14:00 Mar	14, 2024 Jkt 262047 PO	00000 Frm 00317 Fmt 8010 Sfmt 8002 C):\14\1	14V2.	.TXT PC31

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

							r	
		QPS requirements	irements					Information
	Test	Tolerance(s)	Flight condition	Test details	Sir	Simulator level	_	Notes
Entry No.	Title				В	O	۵	
2.a.1	Oyelic	Breakout—±0.25 lbs. (0.112 daN) or 25%; Force—±1.0 lb. (0.224 daN) or 10%.	Ground; Static conditions with the hydraulic system (if ap- plicable) pressurized; sup- plemental hydraulic pres- surization system may be used. Tim On and Off. Friction Off Augmentation (if applicable) On and Off.	Record results for an uninter- rupted control sweep to the stops. (This test does not apply if aircraft hardware modular controllers are used.)	×	×	×	Flight Test Data for this test does not require the rotor to be engaged/turning. The phrase "if applicable" regarding stability augmentation systems means if an augmentation system is available and if this system may be operational on the ground under static conditions as described here.
2.a.2	Collective/Pedals	Breakout—10.5 lb, (0.224 daN) or 25%; Force—±1.0 lb. (0.224 daN) or 10%.	Ground; Static conditions with the hydraulic system (if ap- plicable) pressurized; sup- plemental hydraulic pres- surization system may be used. Trim On and Off. Friction Off. Augmentation (if applicable) On and Off.	Record results for an uninterrupted control sweep to the stops.	×	×	×	Flight Test Data for this test does not require the rotor to be engaged/urning. The phrase "if applicable" regarding stability augmentation system means if a station system man is available and if this system is available and if this system may be operational on the ground under static conditions as described here.
2.a.3	Brake Pedal Force vs. Position.	±5 lbs. (2.224 daN) or 10%.	Ground; Static conditions.		×	×	×	
2.a.4	2.a.4 Trim System Rate (all applicable systems).	Rate—±10%.	Ground; Static conditions. Trim On, Friction Off.	The tolerance applies to the recorded value of the trim rate.	×	×	×	

	Typically, control displacement of 25% to 50% is necessary for proper excitation. Control Dynamics for irreversible control systems may be evaluated in a ground/static condition. Additional information on control dynamics is found latter in this attachment. "\text{"\text{is the sequential period of a full cycle of oscillation.}	Flight Test Data for this test does not require the rotor to be engaged/turning.					This is a "short time" test conducted in a hover, in ground effect, without entering translational flight, to provide better visual reference.
	×	×		×	×		×
	×	×		×	×		×
		×					
	Results must be recorded for a normal control displacement in both directions in each axis.	Record and compare results for all controls.		Record results for several airspeed increments to the translational airspeed limits and for 45 kts. forward airspeed. May be a series of snapshot tests.	Record results for three relative wind directions (including the most critical case) in the critical quadrant. May be a series of snapshot tests.		Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.
	Hover/Cruise, Trim On, Friction Off.	Ground; Static conditions; with the hydraulic system (if applicable) pressurized; supplemental hydraulic pressurization system may be used.		Translational Flight IGE— Sideward, rearward, and forward flight. Augmenta- tion On and Off.	Stationary Hover. Augmentation On and Off.		Hover Augmentation On and Off.
	±10% of time for first zero crossing and ±10 (N + 1)% of period thereafter, ±10% of amplitude of first overshoot, 20% of amplitude of 2nd and subsequent overshoots greater than 5% of initial displacement, ±1 overshoot.	±0.10 inches (±2.5 mm).	S	Torque—±3%, Pitch Atti- tude—±1.5°, Bank Atti- tude—±2°, Longitudinal Control Position—±5%. Lateral Control Position— ±5%, Directional Control Position—±5%, Collective Control Position—±5%.	Torque—±3%, Pitch Atti- tude—±1.5°, Bank Atti- tude—±2°, Longfludinal Control Position—±5%, Lateral Control Position— ±5%, Directional Control Position—±5%, Collective Control Position—±5%.		Pitch Rate—±10% or ±2°/ sec., Pitch Attitude Change—±10% or 1.5°.
	Control Dynamics (all axes)	Control System Freeplay	Low Airspeed Handling Qualities	Trimmed Flight Control Positions.	Critical Azimuth	Control Response	Longitudinal
th DISTILLER	2.a.5	2.a.6	2.b	2.b.1	2.b.2	2.b.3	2.b.3.a
REPLICED ON THE PRINCIPLE OF THE PRINCIP	14, 2024 Jkt 262047 PO 00	0000 Frm 0031\$) Fr	309 mt 8010 Sfmt 8002	Q:\14\14V2.TXT PC	231	

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

Information	Simulator Simulator I Test details I level Notes	О В	Product results for a step control input. The Off-axis response must show correct trend for unaugmented cases. This is a "short time" test conducted in a hover, in ground effect, without entering translational flight, the provide better visual refresses.	Pon and Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.	and Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.		An and Results must be recorded for X X X X X X X X X X X X X X X X X X X	odation. Record results for a minimum X X X X and Off. of two speeds on each side of the trim speed. May be a series of snapshot tests.	
			Ę	₽ ····					
	ator	<u> </u>							
	Simul	_	×	×	×				
			ecord results for a step con- trol input. The Off-axis re- sponse must show correct trend for unaugmented cases.	ecord results for a step control input. The Off-axis response must show correct trend for unaugmented cases.	ecord results for a step control input. The Off-axis response must show correct trend for unaugmented cases.		_		
QPS requirements	Flight condition)	Hover Augmentation On and Off.	Hover Augmentation On and Off.	Hover Augmentation On and Off.		Cruise Augmentation On and Off.	Cruise or Climb. Autorotation. Augmentation On and Off.	
QPS requ	Tolerance(s)		Roll Rate—±10% or ±3'/sec., Roll Attitude Change— ±10% or ±3°.	Yaw Rate—±10% or ±2°/sec., Heading Change—±10% or ±2°.	Normal Acceleration—±0.1 g.		Pitch Rate—±10% or ±2°/ sec., Pitch Attitude Change—±10% or ±1.5°.	Longitudinal Control Position: ±10% of change from trim or ±0.25 in. (6.3 mm) or Longitudinal Control Force :±0.5 ib. (0.223 daN) or ±10%.	
	Test	Title	Lateral	Directional	2.b.3.d Vertical	2.c Longitudinal Handling Qualities	Control Response	2.c.2 Static Stability	
		Entry No.	2.b.3.b	2.b.3.c	2.b.3.d	2.c	2.c.1	2.6.2	

	The response may be unrepeatable throughout the stated time for certain helicopters. In these cases, the test should show at the test should show at least that a divergence is identifiable. For example: Displacing the cyclic for a given time normally excites this test or until a given pitch attitude is achieved and then return the cyclic to the original position. For non-periodic responses, results should show the same convergent or direct gent character as the flight test data.	A control doublet inserted at the natural frequency of the aircraft normally excites this test. However, while input doublets are preferred over pulse inputs for Augmentation-Off tests, for Augmentation-Off tests, when the short-term response exhibits 1st-order or deadbeat characterisics, longitudinal pulse inputs may produce a more coherent response.			
	×	×	×		
	×	×	×		
	×	×	×		
	For periodic responses, record results for three full cycles (6 overshoots after input completed) or that sufficient to determine time to ½ or double amplitude, whichever is leave terminated prior to 20 sec. if the test plot determines that the rest plot determines the rest p	Record results for at least two airspeeds.	Record results for at least two airspeeds at 30°-45° roll angle. The force may be shown as a cross plot for irreversible systems. May be a series of snapshot tests.		
	Cruise Augmentation On and Off.	Cruise or Climb. Augmentation On and Off.	Cruise or Climb. Augmentation On and Off.		
	±10% of calculated period, ±10% of time to ½ or dou- ble amplitude or ±0.02 of damping ratio For non-peri- odic responses, the time history must be matched within ±3° pitch; and ±5 kts airspeed over a 20 sec pe- riod following release of the controls.	±1.5° Pitch or ±2°/sec. Pitch Rate. ±0.1 g Normal Acceleration.	Longitudinal Control Position—±10% of change from trim or ±0.25 in. (6.3 mm) or Longitudinal Control Forces—±0.5 lb. (0.223 daN) or ±10%.	g Qualities	
	Long-Term Response.	Short-Term Response.	Maneuvering Stability.	Lateral and Directional Handling Qualities	Control Response
h DISTILLER	2 c. 3 a	2.c.3.b	2.c.4	2.d	2.d.1
REPLICE OF LAPBH6H6L3 with DISTILLER of Amondey on LAPBH6H6L3 with DISTILLER of Amondey		311			

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

Information	Notes				This is a steady heading sideslip test at a fixed collective position.
	tor	D	×	×	×
	Simulator level	ပ	×	×	×
	Ω	В	×	×	×
	Test details		Record results for at least two airspeeds, including the speed at or near the minimum power required airspeed. Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.	Record data for at least two airspeeds, including the speed at or near the minimum power required airspeed. Record results for a step control input. The Off-axis response must show correct frend for unaugmented cases.	Record results for at least wo sideslip angles on either side of the trim point. The force may be shown as a cross plot for irreversible systems. May be a series of snapshot tests.
rements	Flight condition		Cruise Augmentation On and Off.	Cruise Augmentation On and Off.	Cruise; or Climb (may use Descent instead of Climb if desired), Augmentation On and Off.
QPS requirements	Tolerance(s)		Roll Rate—±10% or ±3*/sec., Roll Attitude Change— ±10% or ±3°.	Yaw Rate—±10% or ±2″sec., Yaw Attitude Change— ±10% or ±2°.	Lateral Control Position— ±10% of change from tim or ±0.25 in. (6.3 mm) or Lateral Control Porce— ±0.5 lb. (0.223 daN) or 10%. Roll Attitude—±1.5, Directional Control Posi- tion—±10% of change from tim or ±0.25 in. (6.3 mm) or Directional Control Porce—±1 lb. (0.448 daN) or 10%. Longitudinal Con- trol Position—±10% of change from tim or ±0.25 in. (6.3 mm). Vertical Ve- locity—±100 fpm (0.50m/ sec) or 10%.
	Test	Title	Lateral	Directional	Directional Static Stability.
		Entry No.	2d1a	2.d.1.b	2.4.2.

	×	×	×			×
	×	×	×			×
	×	×	×			×
	Record results for at least wo airspeeds. The test must be initiated with a cylor or a pedad doubler input. Record results for six full cycles (12 overshoots after input completed) or that sufficient to determine time to ½ or double amplitude, whichever is less. The test may be terminated prior to 20 sec if the test pilot determines that the results are becoming uncontrollably divergent.	Record the results of a release from pedal only or cyclic only turns for 20 sec. Results must be recorded from turns in both directions. Terminate check at zero roll angle or when the test pliot determines that the attitude is becoming uncontrollably divergent.	Record the time history of initial entry into cyclic only turns, using only a moderate rate for cyclic input. Results must be recorded for turns in both directions.			Required as part of the MQTG. The test must demonstrate frequency response of the motion system as specified by the applicant for flight simulator qualification.
	Cruise or Climb. Augmentation On and Off.	Cruise or Climb. Augmentation On and Off.	Cruise or Climb. Augmentation On and Off.			N/A
ol Stability	±0.5 sec. or±10% of period, ±10% of time to 1½ or dou- ble amplitude or ±0.02 of damping ratio, ±20% or ±1 sec of time difference be- tween peaks of bank and sidestip. For non-periodic responses, the time history must be matched within ±10 knots Airspeed; ±5% Roll Rate or ±5° Roll Atti- tude, ±4° s Yaw Rate or ±4° Yaw Angle over a 20 sec period roll angle fol- lowing release of the con- trols.	±2° or ±10% roll angle.	Correct Trend, ±2º transient sideslip angle.			Based on Simulator Capability.
Dynamic Lateral and Directional Stability	Lateral-Directional Oscilla- tions.	Spiral Stability.	Adverse/Proverse Yaw.	tem	Frequency response	
h DISTILLER	2.d.3.a	2.d.3.b	2.d.3.c	3. Motion System	3.a	
we vor leave the september of the septem	2024 Jkt 262047 PO 00000 Frm 003	313 323 Fmt 8010 Sfmt 8002	2 Q:\14\14V2.T)	(T P	C31	

TESTS—Continued
FS) OBJECTIVE
SIMULATOR (FI
2A—FULL FLIGHT
TABLE C2/

			Information	Notes							See Paragraph 6.c. in this attachment for additional information. Note: if there is no difference in the model for 'ground" and "tilght" operation of the motion system, this should be described in an SOC and will not require tests in both modes.	
				rto_	٥		×		×		×	
				Simulator level	O		×		×		×	
		7		0)	В		×		×		×	-
		CTIVE TESTS—Continue		Test details			Required as part of the MOTG. The test must demonstrate motion system leg balance as specified by the applicant for flight simulator qualification.		Required as part of the MQTG. The test must demonstrate a smooth turnaround (shift to opposite direction of movement) of the motion system as specified by the applicant for flight simulator qualification.		Required as part of the MOTG. The test is accomplished by injecting a motion signal to generate movement of the platform. The input must be such that the rotational accelerations, rotational rates, and linear accelerations are inserted before the transfer from helicopter center of gravity to the pilot reference point with a minimum amplitude of 5°/sec/sec, 10°/sec and 0.3g, respectively.	
		- Simulator (FFS) Obje	irements	Flight condition			N/A		N/A		Accomplished in both the "ground" mode and in the "flight" mode of the motion system operation.	
		TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued	QPS requirements	Tolerance(s)			Based on Simulator Capa- bility.		Based on Simulator Capa- bility.		With the same input signal, the test results must be repeatable to within ±0.05g actual platform linear acceleration in each axis.	hature
		F		Test	Title	Leg Balance	Leg Balance	Turn Around	Tum Around	Motion system repeatability		Motion cueing performance signature
h DISTILLER					Entry No.	3.b		З.с.		3.d		3.e.
aworley on LAPBH6H6L3 with DISTILLER 6									314			
aworle)	rDate Sep<11>2014	14:00 Mar 14,	2024	Jkt 2	26204	47	PO 00000 Frm	0032	.4 Fmt 8010 Sfmt 8	8002	Q:\14\14V2.TXT PC31	

	See paragraph 6.d., of this attachment, Motion cueing performance signature.	Associated to test number 1.c.1.	Associated to test number 1.d.	Associated to test number 1.i.	Associated to test number 1.j.1.	Associated to test number 1.j.4.		Associated to test number 2.c.1.	Associated to test number 2.d.1.a.	Associated to test number 2.d.1.c.	Characteristic motion cues may be separate from the "main" motion system.
		×	×	×	×	×		×	×	×	i.
		×	×	×	×	×		×	×	×	i
		×			×			×	×	×	i
	Required as part of MOTG. These tests must be run with the motion buffet mode disabled.	Pitch attitude due to initial climb must dominate over cab tilt due to longitudinal acceleration.									nust exhibit the overall appear- kes" being present within ±2
		Ground	Ground	Flight	Flight	Flight		Flight	Ground		tests, the simulator test results in the predominant frequency "spi
		As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.		As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.	As specified by the sponsor for flight simulator qualification.	Characteristic Motion (Vibration) Cues—For all of the following tests, the simulator test results must exhibit the overall appearance and trends of the helicopter data, with at least three (3) of the predominant frequency "spikes" being present within ±2 Hz.
		Takeoff (all engines).	Hover performance (IGE and OGE).	Autorotation (entry).	Landing (all engines).	Autorotation (landing).	Control Response	Longitudinal	Lateral.	Directional	Characteristic Motion (Vibration ance and trends of the helicopt Hz.
h DISTILLER		3.e.1.	3.e.2.	3.e.3.	3.e.4	3.e.5	3.e.6	3.e.6.a	3.e.6.b	3.e.6.c	3.f
RETURNOVIEW ON LAPBH6H6L9.3 with DISTILLER of Amountain on LAPBH6H6L9.3 with DISTILLER of Amountain on LAPBH6H6L9.3 with DISTILLER of Amountain of A	00 May 14 COO4	II+ 0000 1=	DO 2222	00 F*** 0	10225 F	315		2002)	TVT - 2.2	21
§ VerDate Sep<11>2014 14:0	00 Mar 14, 2024	Jkt 262047	PO 0000	υ Frm 0	10325 Fr	nt 8010	Stmt	8002 Q	:\14\14V2.	IXI PC	31

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

		Information	Notes		Correct trend refers to a comparison of vibration amplitudes between different maneuvers, e.g., if the 1/1 rev vibration amplitude in the helicopter is higher during steady state turns than in level light this increasing trend should be demonstrated in the simulator. Additional examples of vibrations may include: (a) Low & High speed transition to and from hover; (b) Level flight; (c) Climb and descent (included service of the conditional service of the condition service of the condition service of the condition service of the conditional service of the condition service of the condition service of the conditional service of the conditional service of the condition service of the	The recorded test results for characteristic buffets should allow the checking of relative amplitude for different frequencies. For atmospheric disturbance, general purpose models are acceptable which approximate demonstrable flight test data.
			Simulator level	С	×	×
			Simu	В		
	TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued		Test details		Characteristic vibrations in- clude those that result from operation of the helicopter (for example, high air- speed, retreating blade stall, extended landing gear, vortex ring or settling with power) in so far as vi- bration marks an event or helicopter state, which can be sensed in the flight deck. [See Table C1A, table entries 5.e. and 5.f.]	Characteristic buffets include those that result from operation of the helicopter (for example, high airspeed, retreating blade stall, extended landing gear, vortex ring or settling with power) in so far as a buffet marks an event or helicopter state, which can be sensed in the flight deck. [See Table C1A, table entries 5.e. and 5.f.]
	SIMULATOR (FFS) OBJE	irements	Flight condition		(a) On ground (idle); (b) In flight	On ground and in flight.
	ABLE C2A—FULL FLIGHT	QPS requirements	Tolerance(s)		+ 3db to - 6db or ±10% of nominal vibration level in flight cruise and correct trend (see comment).	+ 3db to - 6db or ±10% of nominal vibration level in flight cruise and correct trend (see comment).
	F		Test	Title	Vibrations—to include 1/Rev and n/Rev vibrations (where 'h" is the number of main rotor blades).	Buffer—Test against recorded results for characteristic buffet motion that can be sensed in the flight deck.
h DISTILLER				Entry No.	3.f.1.	3.12
H6L3 wit					316	
aworley on LAPBH6H6L3 with DISTILLER According to the Seb < 11 > 2014	14:00 Mar 14, 2	024	Jkt 2	26204	47 PO 00000 Frm 00326 Fmt 8010 Sfmt 8	3002 Q:\14\14V2.TXT PC31

4. Visual System

Visual System Response Time: (Choose either test 4.a.1. or 4.a.2. to satisfy test 4.a., Visual System Response Time Test. This test is also sufficient for motion system response timing and flight deck instrument response timing.) Latency 4.a.1. 4.a.

					If Transport Delay is the chosen method to demonstrate relative responses, the sponsor and the responsible Flight Standards office will use the latency val-	ues to ensure proper simu- lator response when re- viewing those existing tests where latency can be iden- tified (e.g., short period, roll	response, rudder response).			
			×							
			×	-						
		One test is required in each axis (pitch, roll and yaw) for each of the three conditions (take-off, cruise, and approach or landing).	One test is required in each axis (pitch, roll and yaw) for each of the three conditions (take-off, cruise, and approach or landing).	6						
		Takeoff, climb, and descent.	Climb, cruise, descent, and hover.							
		150 ms (or less) after helicopter response.	100 ms (or less) after heli- copter response.							
				. Transport Delay			Field-of-view	_		
ILLER				2.			4 0			
Moorley on LAPBH6H6L3 with DISTILLER Aworley on LAPBH6H6L3 with DISTILLER Aworley on LAPBH6H6L3 with DISTILLER				4.a.2.		31				
VerDate Sep<11>2014	14:00 Mar	14, 2024 Jk	t 262047 P0	000 C	00 Frm 00327	Fmt 8010	Sfmt 8	002	Q:\14\14V2.TXT PC3	31

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

		Information		Notes	Horizontal field-of-view is centered on the zero degree azimuth line relative to the aircraft fuselage. Field-of-view may be measured using a visual test pattern filling the entire visual scene (all channels) with a matrix of black and white 5° squares.
			Simulator	0	
	7		sin	ш	×
	Table C2A—Full Flight Simulator (FFS) Objective Tests—Continued			Test details	An SOC is required and must explain the geometry of the installation. Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained.
	SIMULATOR (FFS) OBJE	irements		Flight condition	N/A
	ABLE C2A—FULL FLIGHT	QPS requirements		Tolerance(s)	The simulator must provide a continuous field-of-view of at least 75° horizontally and 30° vertically per pilot seat or the number of degrees necessary to meet the visual ground segment requirement, whichever is greater. Both pilot seat visual systems must be operable simultaneously. Wide-sangle systems providing (cross-flight deck viewing viewing bed viewent the Image Generator eye point must be 8° or less.
	F		Test	Title	Continuous field-of-view.
DISTILLER				Entry No.	4.b.1.
Manonley on LAPBH6H6L3 with DISTILLER Amondey on LAPBH6H6L3 with DISTILLER Amondey on LAPBH6H6L3 with DISTILLER					318
5 20 20 WerDate Sep<11>2014	14:00 Mar 14,	2024	Jk	t 2620	047 PO 00000 Frm 00328 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT F

	Horizontal field-of-view is centered on the zero degree azmuln line relative to the aircraft fuselage. Field-of-view may be measured using a visual est pattern filling the entire visual scene (all channels) with a matrix of black and white 5° squares.	The horizontal field-of-view is traditionally described as a 180° field-of-view. However, the field-of-view is technically no less than 176°. Field-of-view may be measured using a visual test pattern filling the entire visual scene (all channels) with a matrix of black and white 5° squares.
		×
	×	
	An SOC is required and must explain the geometry of the installation. Horizontal field-of-view of at least 146° (including not less than 73° measured either side of the center of the design eye point). Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained. Verifical field-of-view is retained. Verifical field-of-view of at least 36° measured from the pilot's and co-pilot's eye point.	An SOC is required and must explain the geometry of the installation. Horizontal field-of-view is centered on the zero degree azimuth line relative to the aircraft fuselage. Horizontal field-of-view must be at least 176° (including not less than 88° either side of the center of the design eye point). Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained. Vertical field-of-view is retained.
	N/A	N/A
	The simulator must provide a continuous field-of-view of at least 146' horizontally and 36' vertically or the number of degrees necessary to meet the visual ground segment requirement, whichever is greater. The minimum horizontal field-of-view coverage must be plus and minus one-half (%) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. Any geometric error between the Image Generator eye point and the pilot eye less.	Continuous field-of-view of at least 176° horizontal and 56° vertical field-of-view for each pilot simultaneously. Any geometric error between the Image Generator eye point and the pilot eye point must be 8° or less.
	Continuous field-of-view.	Continuous field-of-view.
h DISTILLER	462	4b3
REJUZION NO LAPBH6H6L3 with DISTILLER on LAPBH6H6H6L3 with DISTILLER on LA		319
verDate Sep<11>2014 14:00 Ma	r 14, 2024 Jkt 262047 PO 00000 Frm 00329	Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

Information	Notes		Measurements may be made using a 1° spot photomete and a raster drawn test pattern filling the entire visual scene (all channels) with a test pattern of black and white squares, 5 per square, with a white square in the center of each channel. During contrast ratio testing, simulator aft-cab and flight deck ambient light levels should be zero.	Measurements may be made using a 1° spot photomete and a raster drawn test pattern filling the entire visual scene (all channels) with a test pattern of black and white squares, 5 per square, with a white square in the center of each channel.
	tor	۵	×	×
	Simulator level	ပ		
	Ø	ш		
	Test details		The ratio is calculated by dividing the brightness level of the center, bright square (providing at 12 footlamberts or 7 cd/m²) by the brightness level of any adjacent dark square.	Measure the brightness of the center, white square while superimposing a highlight on that white square. The use of calligablic capabilities to enhance the raster brightness is acceptable, however, measuring light points is not acceptable.
iirements	Flight condition	•	N/A	N/A
QPS requirements	Tolerance(s)		Not less than 5:1.	Not less than six (6) foot-lamberts (20 cd/m²).
	Test	Title	Surface contrast ratio.	4.d Highlight brightness.
		Entry No.	4.6.	4.0.

	When the eye is positioned on a 3° glide slope at the slant range distances indicated with white runway markings on a black runway surface, the eye will subbend two (2) arc minutes: (1) A slant range of 6,876 ft with stripes 160 ft long and 16 ft wide, spaced 4 ft apart. (2) For Configuration A, a slant range of 5,157 feet with stripes 150 ft long and 12 ft wide, spaced 3 ft apart. (3) For Configuration B, a slant range of 5,157 feet with stripes 150 ft long and 12 ft wide, spaced 3 ft apart. (3) For Configuration B, a slant range of 9,884 feet, with stripes 150 ft long and 5,75 ft apart.	Light point size may be measured using a test pattern consisting of a centrally located single row of light points reduced in length until modulation is just discernible in each wisual channel. A row of 48 lights will form a 4° angle or less.	A 1° spot photometer may be used to measure a square of at least 1° filled with light points (where light point modulation is just dissemible) and compare the results to the measured adjacent background. During contrast ratio testing, simulation att-cab and flight deck annihent light levels should be zero.	
	×	×		
	×	×		
				×
	An SOC is required and must include the appropriate calculations and an explationation of these calculations. Level B requires surface resolution not greater than three (3) arc minutes.	An SOC is required and must include the relevant cal-culations and an explanation of those calculations.		An SOC is required and must include the relevant calculations.
	NA	N/A		N/A
	Not greater than two (2) arc minutes.	Not greater than five (5) arc minutes.		Not less than 10:1
	Surface resolution.	Light point size	Light point contrast ratio.	
nh DISTILLER	6.	4.f.	4.9	4.g.1.
REPLANTILLER OF LAPBH9H9H9H9H9H9H9H9H9H9H9H9H9H9H9H9H9H9H9	r 14, 2024 Jkt 262047 PO 00000 Frm 00331	321 Fmt 8010 Sfmt 8002 C):\14\14V2.TXT PC31	

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

		Information	Notes				Pre-positioning for this test is encouraged, and may be achieved via manual or autopilot control to the desired position.
			ator	٥	×		×
			Simulator level	O	×		×
	p		-	В	-		×
	CTIVE TESTS—Continue		Test details		An SOC is required and must include the relevant calculations.		The QTG must contain appropriate calculations and a drawing showing the data used to establish the helicopter location and the segment of the ground that is visible considering design eye point, the helicopter attitude, flight deck cut-off angle, and a visiblity of 1200 ft (350 m) RVR. Simulator performance must be measured against the QTG calculations. The data submitted must include at least the following:
	SIMULATOR (FFS) OBJE	irements	Flight condition		N/A		Landing configuration, with the aircraft trimmed for the appropriate airspeed, where the MLG are at 100 ft (30 m) above the plane of the touchdown zone, on the electronic glide slope with an RVR value set at 1,200 ft (350 m).
	TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued	QPS requirements	Tolerance(s)		Not less than 25:1		The visible segment in the simulator must be ±20% of the segment computed to be visible from the helicopter flight deck. This tolerance may be applied at the far end of the displayed segment. However, lights and ground objects computed to be visible from the helicopter flight deck at the near end of the visible segment must be visible in the simulator.
	,		Test	Title		Visual ground segment	
th DISTILLER				Entry No.	4.g.2.	4.h	
Navorley on LAPBH6H6L3 with DISTILLER Amondey on LAPBH6H6L3 with DISTILLER Amondey on LAPBH6H6L3 with DISTILLER	14:00 Mar 14, 2	2024	Jkt 2	2620	47 PO 0	0000	322 D. Frm 00332 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31
8 VEIDALE SEPS 1122014	14.00 IVIAI 14, 2	.024	JNI 2	-020	+, FU	JUUL	7 1 1111 00002 1 1111 0010 31111 0002 Q.\14\14\2.1\1 F031

	sons as follows: sons as follows: (i) Horizontal and vertical distance from main landing gear (MLO) to glideslope reception antenna (ii) Horizontal and vertical distance from MLG to pilot's expeption. (iii) Static flight deck cutoff angle. (iii) Static flight deck cutoff angle. (iv) Approach data as follows: (iv) Identification of runway. (ii) Glideslope intercept with runway. (iii) Glideslope intercept with runway. (iv) Glideslope intercept with angle on approach. (iv) Helicopter configuration. (iv) Approach atta for manual testing: (iv) Helicopter configuration. (iv) Approach attraped. (iv) Helicopter configuration. (iv) Approach attraped. (iv) Helicopter configuration. (iv) Approach attraped in horizontal visibility must be described and be included in the start range visibility calculation used in the	compagatoris	The sponsor will not be required to repeat the helicopter tests (i.e., tests 5.a.1. through 5.a.8. (or 5.b.1. through 5.b.9.) and 5.c., as appropriate) during continuing qualification evaluations if frequency response and background noise test results are within tolerance when compared to the initial qualification evaluation results, and the sponsor shows that no software changes have occurred that will affect the helicopter test results. If the frequency response test method is chosen and falls, the sponsor may elect to repeat the helicopter tests are repeated during continuing qualification evaluations, the results may be compared against initial qualification evaluation results or helicopter master data. All tests in this section must be presented using an unweighted 3-cate band format from band 17 to 42 (50 Hz to 16 kHz). A minimum 20 second average must be taken at the location corresponding to the helicopter data set. The helicopter and flight simulator results must be produced using comparable data analysis techniques.	
STILER		Sound system	È	.a Basic requirements
HEHERTS WITH DISTILLERS ON LAPBH6H6L3 with DISTILLERS on LAPBH6H6H6L3 with DISTILLERS on LAPBH6H6H6H6H6L3 with DISTILLERS on LAPBH6H6H6H6H6H6H6H6H6H6H6H6H6H6H6H6H6H6H6	323 4:00 Mar 14, 2024 Jkt 262047 PO 00000 Frm 00333 Fmt 8010 Sfmt 8002 Q:\1	ம்	2.TXT PC31	, 55. E

TABLE C2A—FULL FLIGHT SIMULATOR (FFS) OBJECTIVE TESTS—Continued

		QPS requirements	irements			Information
	Test	Tolerance(s)	Flight condition	Test details	Simulator level	Notes
Entry No.	Title				O	Ω
5.a.1	5.a.1 Ready for engine start.	±5 dB per 1/3 octave band.	Ground	Normal condition prior to engine start. The APU must be on if appropriate.		×
5.a.2	All engines at idle; rotor not turning (if applicable) and rotor turning.	±5 dB per 1/3 octave band.	Ground	Normal condition prior to lift- off.		×
5.a.3	Hover	±5 dB per 1/3 octave band.	Hover			×
5.a.4	Climb	±5 dB per 1/3 octave band.	En-route climb	Medium altitude		×
5.a.5	Cruise	±5 dB per 1/3 octave band.	Cruise	Normal cruise configuration.		×
5.a.6	Final approach	±5 dB per 1/3 octave band.	Landing	Constant airspeed, gear down.		×
5.b	Special cases					
		±5 dB per ⅓ octave band.	As appropriate			X These special cases are identified as particularly significant during critical phases of fight and ground operations for a specific helicopter type or model.
5.c.	Background noise					
		±3 dB per ⅓ octave band.	As appropriate	Results of the background noise at initial qualification must be included in the MGTG. Measurements must be made with the simulation running, the sound muted, and a "dead" flight deck.		X The simulated sound will be evaluated to ensure that the background noise does not interfere with training, testing, or checking.
5.d	5.d Frequency response					

X Measurements are compared to those taken during initial	qualification evaluation.																			
×																				
Applicable only to Continuing Qualification Evaluations. If	frequency response plots are provided for each	channel at the initial eval-	uation, these plots may be	repeated at the continuing	qualification evaluation with	the following tolerances ap-	plied:	(a) The continuing qualifica-	tion 1/3 octave band ampli-	tudes must not exceed ±5	dB for three consecutive	bands when compared to	initial results.	(b) The average of the sum	of the absolute differences	between initial and con-	tinuing qualification results	must not exceed 2 dB	(refer to table C2C in Ap-	pendix C).
±5 dB on three (3) consecutive bands when compared	to initial evaluation; and ±2	erage of the absolute dif-	ferences between initial	and continuing qualification	evaluation.															

BEGIN INFORMATION

3. General

a. If relevant winds are present in the objective data, the wind vector should be clearly noted as part of the data presentation, expressed in conventional terminology, and related to the runway being used for test near the ground.

b. The reader is encouraged to review the Airplane Flight Simulator Evaluation Handbook, Volumes I and II, published by the Royal Aeronautical Society, London, UK, and FAA AC 25-7, as amended, Flight Test Guide for Certification of Transport Category Airplanes, and AC 23-8, as amended, Flight Test Guide for Certification of Part 23 Airplanes, for references and examples regarding flight testing requirements and techniques.

4. Control Dynamics

a. General. The characteristics of a helicopter flight control system have a major effect on the handling qualities. A significant consideration in pilot acceptability of a helicopter is the "feel" provided through the flight controls. Considerable effort is expended on helicopter feel system design so that pilots will be comfortable and will consider the helicopter desirable to fly. In order for an FFS to be representative, it should "feel" like the helicopter being simulated. Compliance with this requirement is determined by comparing a recording of the control feel dynamics of the FFS to actual helicopter measurements in the hover and cruise configurations.

(1) Recordings such as free response to an impulse or step function are classically used to estimate the dynamic properties of electromechanical systems. In any case, it is only possible to estimate the dynamic properties as a result of only being able to estimate true inputs and responses. Therefore, it is imperative that the best possible data be collected since close matching of the FFS control loading system to the helicopter system is essential. The required dynamic control tests are described in Table C2A of this attachment.

(2) For initial and upgrade evaluations, the QPS requires that control dynamics characteristics be measured and recorded directly from the flight controls (Handling Qualities—Table C2A). This procedure is usually accomplished by measuring the free response of the controls using a step or impulse input to excite the system. The procedure should be accomplished in the hover and cruise flight conditions and configurations.

(3) For helicopters with irreversible control systems, measurements may be obtained on the ground if proper pitot-static inputs are provided to represent airspeeds typical of

those encountered in flight. Likewise, it may be shown that for some helicopters, hover, climb, cruise, and autorotation have like effects. Thus, one may suffice for another. If either or both considerations apply, engineering validation or helicopter manufacturer rationale should be submitted as justification for ground tests or for eliminating a configuration. For FFSs requiring static and dynamic tests at the controls, special test fixtures will not be required during initial and upgrade evaluations if the QTG shows both test fixture results and the results of an alternate approach (e.g., computer plots that were produced concurrently and show satisfactory agreement). Repeat of the alternate method during the initial evaluation satisfies this test requirement.

b. Control Dynamics Evaluations. The dynamic properties of control systems are often stated in terms of frequency, damping, and a number of other classical measurements. In order to establish a consistent means of validating test results for FFS control loading, criteria are needed that will clearly define the measurement interpretation and the applied tolerances. Criteria are needed for underdamped, critically damped and overdamped systems. In the case of an underdamped system with very light damping, the system may be quantified in terms of frequency and damping. In critically damped or overdamped systems, the frequency and damping are not readily measured from a response time history. Therefore, the following suggested measurements may be used:

(1) For Levels C and D simulators. Tests to verify that control feel dynamics represent the helicopter should show that the dynamic damping cycles (free response of the controls) match those of the helicopter within specified tolerances. The responsible Flight Standards office recognizes that several different testing methods may be used to verify the control feel dynamic response. The responsible Flight Standards office will consider the merits of testing methods based on reliability and consistency. One acceptable method of evaluating the response and the tolerance to be applied is described below for the underdamped and critically damped cases. A sponsor using this method to comply with the QPS requirements should perform the tests as follows:

(a) Underdamped Response. Two measurements are required for the period, the time to first zero crossing (in case a rate limit is present) and the subsequent frequency of oscillation. It is necessary to measure cycles on an individual basis in case there are non-uniform periods in the response. Each period will be independently compared to the respective period of the helicopter control system and, consequently, will enjoy the full tolerance specified for that period. The

damping tolerance will be applied to overshoots on an individual basis. Care should be taken when applying the tolerance to small overshoots since the significance of such overshoots becomes questionable. Only those overshoots larger than 5 percent of the total initial displacement should be considered significant. The residual band, labeled $T(A_{\text{d}})$ on Figure C2A is ±5 percent of the initial displacement amplitude A_d from the steady state value of the oscillation. Only oscillations outside the residual band are considered significant. When comparing FFS data to helicopter data, the process should begin by overlaying or aligning the FFS and helicopter steady state values and then comparing amplitudes of oscillation peaks, the time of the first zero crossing, and individual periods of oscillation. The FFS should show the same number of significant overshoots to within one when compared against the helicopter data. The procedure for evaluating the response is illustrated in Figure C2A.

- (b) Critically damped and Overdamped Response. Due to the nature of critically damped and overdamped responses (no overshoots), the time to reach 90 percent of the steady state (neutral point) value should be the same as the helicopter within ±10 percent. The simulator response must be critically damped also. Figure C2B illustrates the procedure.
- (c) Special considerations. Control systems that exhibit characteristics other than classical overdamped or underdamped responses should meet specified tolerances. In addition, special consideration should be given to ensure that significant trends are maintained.
 - (2) Tolerances.
- (a) The following summarizes the tolerances, "T" for underdamped systems, and "n" is the sequential period of a full cycle of oscillation. See Figure C2A of this attachment for an illustration of the referenced measurements.

$T(P_0)$	 $\pm 10\%$ of P_0
$T(P_1)$	 ±20% of P ₁
	 ±30% of P ₂
$T(P_n)$	 $\pm 10(n + 1)\%$ of P_n
	 $\pm 10\%$ of A ₁ , $\pm 20\%$
	of Subsequent
	Peaks
$T(A_d)$	 $\pm 5\%$ of $A_d = resid$
	ual band

Significant overshoots. First overshoot and ± 1 subsequent overshoots

(b) The following tolerance applies to critically damped and overdamped systems only. See Figure C2B for an illustration of the reference measurements:

 $T(P_0)$ $\pm 10\%$ of P_0

END INFORMATION

BEGIN QPS REQUIREMENT

- c. Alternative method for control dynamics evaluation.
- (1) An alternative means for validating control dynamics for aircraft with hydraulically powered flight controls and artificial feel systems is by the measurement of control force and rate of movement. For each axis of pitch, roll, and yaw, the control must be forced to its maximum extreme position for the following distinct rates. These tests are conducted under normal flight and ground conditions.
- (a) Static test—Slowly move the control so that a full sweep is achieved within 95–105 seconds. A full sweep is defined as movement of the controller from neutral to the stop, usually aft or right stop, then to the opposite stop, then to the neutral position.
- (b) Slow dynamic test—Achieve a full sweep within 8–12 seconds.
- (c) Fast dynamic test—Achieve a full sweep in within 3-5 seconds.

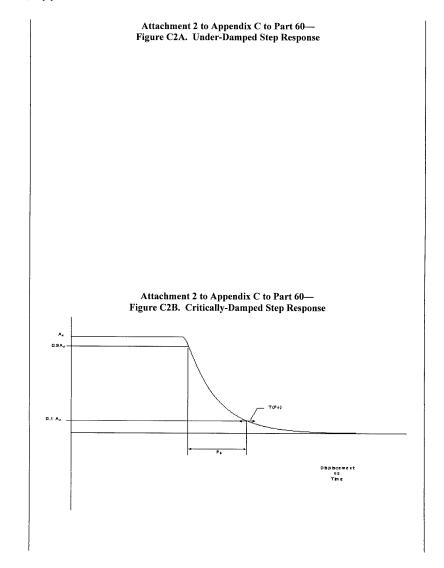
Note: Dynamic sweeps may be limited to forces not exceeding 100 lbs. (44.5 daN).

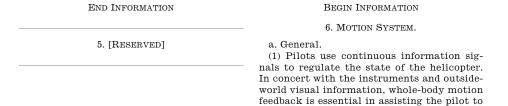
- (d) Tolerances
- (i) Static test—see Table C2A, FFS Objective Tests, Entries 2.a.1., 2.a.2., and 2.a.3.
- (ii) Dynamic test— ± 2 lbs (0.9 daN) or $\pm 10\%$ on dynamic increment above static test.

END QPS REQUIREMENT

BEGIN INFORMATION

d. The FAA is open to alternative means that are justified and appropriate to the application. For example, the method described here may not apply to all manufacturers systems and certainly not to aircraft with reversible control systems. Each case is considered on its own merit on an ad hoc basis. If the FAA finds that alternative methods do not result in satisfactory performance, more conventionally accepted methods will have to be used.





control the helicopter dynamics, particularly in the presence of external disturbances. The motion system should meet basic objective performance criteria, and be subjectively tuned at the pilot's seat position to represent the linear and angular accelerations of the helicopter during a prescribed minimum set of maneuvers and conditions. The response of the motion cueing system should be repeatable.

- (2) The Motion System tests in Section 3 of Table C2A are intended to qualify the FFS motion cueing system from a mechanical performance standpoint. Additionally, the list of motion effects provides a representative sample of dynamic conditions that should be present in the flight simulator. An additional list of representative, trainingcritical maneuvers, selected from Section 1. (Performance tests) and Section 2. (Handling Qualities tests) in Table C2A, that should be recorded during initial qualification (but without tolerance) to indicate the flight simulator motion cueing performance signature have been identified (reference Section 3.e). These tests are intended to help improve the overall standard of FFS motion cueing.
- b. Motion System Checks. The intent of test 3a, Frequency Response, test 3b, Leg Balance, and test 3c, Turn-Around Check, as described in the Table of Objective Tests, is to demonstrate the performance of the motion system hardware, and to check the integrity of the motion set-up with regard to calibration and wear. These tests are independent of the motion cueing software and should be considered robotic tests.
- c. Motion System Repeatability. The intent of this test is to ensure that the motion system software and motion system hardware have not degraded or changed over time. This diagnostic test should be completed during continuing qualification checks in lieu of the robotic tests. This will allow an improved ability to determine changes in the software or determine degradation in the hardware. The following information delineates the methodology that should be used for this test.
- (1) Input: The inputs should be such that rotational accelerations, rotational rates, and linear accelerations are inserted before the transfer from helicopter center of gravity to pilot reference point with a minimum amplitude of 5 deg/sec/sec, 10 deg/sec and 0.3 g, respectively, to provide adequate analysis of the output.
 - (2) Recommended output:
- (a) Actual platform linear accelerations;
 the output will comprise accelerations due
 to both the linear and rotational motion acceleration;
 - (b) Motion actuators position.
 - d. Motion Cueing Performance Signature.
- (1) Background. The intent of this test is to provide quantitative time history records of motion system response to a selected set

of automated QTG maneuvers during initial qualification. It is not intended to be a comparison of the motion platform accelerations against the flight test recorded accelerations (i.e., not to be compared against helicopter cueing). If there is a modification to the initially qualified motion software or motion hardware (e.g., motion washout filter, simulator payload change greater than 10%) then a new baseline may need to be established.

- (2) Test Selection. The conditions identified in Section 3.e. in Table C2A are those maneuvers where motion cueing is the most discernible. They are general tests applicable to all types of helicopters and should be completed for motion cueing performance signature at any time acceptable to the responsible Flight Standards office prior to or during the initial qualification evaluation, and the results included in the MQTG.
- (3) Priority. Motion system should be designed with the intent of placing greater importance on those maneuvers that directly influence pilot perception and control of the helicopter motions. For the maneuvers identified in section 3.e. in Table C2A, the flight simulator motion cueing system should have a high tilt co-ordination gain, high rotational gain, and high correlation with respect to the helicopter simulation model.
- (4) Data Recording. The minimum list of parameters provided should allow for the determination of the flight simulator's motion cueing performance signature for the initial qualification evaluation. The following parameters are recommended as being acceptable to perform such a function:
- (a) Flight model acceleration and rotational rate commands at the pilot reference point:
 - (b) Motion actuators position;
 - (c) Actual platform position;
- (d) Actual platform acceleration at pilot reference point.
- e. Motion Vibrations.
- (1) Presentation of results. The characteristic motion vibrations may be used to verify that the flight simulator can reproduce the frequency content of the helicopter when flown in specific conditions. The test results should be presented as a Power Spectral Density (PSD) plot with frequencies on the horizontal axis and amplitude on the vertical axis. The helicopter data and flight simulator data should be presented in the same format with the same scaling. The algorithms used for generating the flight simulator data should be the same as those used for the helicopter data. If they are not the same then the algorithms used for the flight simulator data should be proven to be sufficiently comparable. As a minimum the results along the dominant axes should be presented and a rationale for not presenting the other axes should be provided.
- (2) Interpretation of results. The overall trend of the PSD plot should be considered

while focusing on the dominant frequencies. Less emphasis should be placed on the differences at the high frequency and low amplitude portions of the PSD plot. During the analysis, certain structural components of the flight simulator have resonant frequencies that are filtered and may not appear in the PSD plot. If filtering is required, the notch filter bandwidth should be limited to 1 Hz to ensure that the buffet feel is not adversely affected. In addition, a rationale should be provided to explain that the characteristic motion vibration is not being adversely affected by the filtering. The amplitude should match helicopter data as described below. However, if the PSD plot was altered for subjective reasons, a rationale should be provided to justify the change. If the plot is on a logarithmic scale it may be difficult to interpret the amplitude of the buffet in terms of acceleration. For example, a 1×10^{-3} g-rms²/Hz would describe a heavy buffet and may be seen in the deep stall regime. Alternatively, a 1×10^{-6} g-rms $^2/\mathrm{Hz}$ buffet is almost imperceptable, but may represent a flap buffet at low speed. The previous two examples differ in magnitude by 1000. On a PSD plot this represents three decades (one decade is a change in order of magnitude of 10, and two decades is a change in order of magnitude of 100).

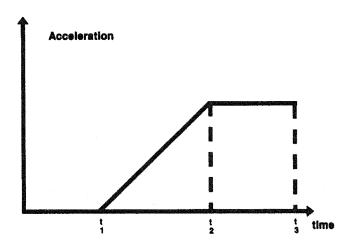
NOTE: In the example, "g-rms2" is the mathematical expression for "g's root mean squared."

f. Table C2B, Motion System Recommendations for Level C and Level D Helicopter Simulators, contains a description of the parameters that should be present in simulator motion systems to provide adequate onset motion cues to helicopter pilots. The information provided covers the six axes of motion (pitch, roll, yaw, vertical, lateral, and longitudinal) and addresses displacement, velocity, and acceleration. Also included is information about the parameters for initial rotational and linear acceleration. The parameters listed in this table apply only to Level C and Level D simulators, and are presented here as recommended targets for motion system capability. They are not require-

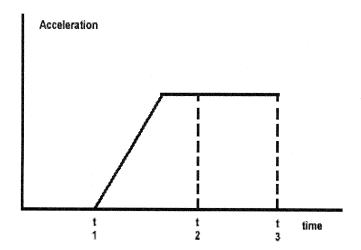
TABLE C2B—MOTION SYSTEM RECOMMENDATIONS FOR LEVEL C AND LEVEL D HELICOPTER SIMULATORS

a	Motion System Envelo	ре
a.1	Pitch	
a.1.a	Displacement	±25°
a.1.b	Velocity	±20°/sec
a.1.c	Acceleration	±100°/sec ²
a.2	Roll	
a.2.a	Displacement	±25°
a.2.b	Velocity	±20°/sec
a.2.c	Acceleration	±100°/sec ²
a.3	Yaw	
a.3.a	Displacement	±25°
a.3.b	Velocity—	±20°/sec
a.3.c	Acceleration	±100°/sec ²
a.4	Vertical	
a.4.a	Displacement	±34 in.
a.4.b	Velocity	±24 in.
a.4.c	Acceleration	±0.8 g.
a.5	Lateral	
a.5.a	Displacement	±45 in.
a.5.b	Velocity	±28 in/sec.
a.5.c	Acceleration	±0.6 g.
a.6	Longitudinal	
a.6.a	Displacement	±34 in.
a.6.b	Velocity	±28 in/sec.
a.6.c	Acceleration	±0.6 g.
a.7	Initial Rotational Acceleration Ratio.	-
		All axes 300°/ sec ² /sec
a.8	Initial Linear Acceleration Ratio.	
a.8.a	Vertical	±6g/sec
a.8.b	Lateral	±3g/sec
a.8.c	Longitudinal	±3g/sec

Attachment 2 to Appendix C to Part 60-Figure C2C. Acceleration Test Signals



Attachment 2 to Appendix C to Part 60-Figure C2D. Test Signal Characteristics



NOTE: Motion system baseline performance repeatability tests should be repeated if the simulator weight changes for any reason (i.e., visual change or structural change). The new results should be used for future comparison.

7. SOUND SYSTEM

a. General. The total sound environment in the helicopter is very complex, and changes with atmospheric conditions, helicopter configuration, airspeed, altitude, and power settings. Flight deck sounds are an important component of the flight deck operational environment and provide valuable information

to the flight crew. These aural cues can either assist the crew (as an indication of an abnormal situation), or hinder the crew (as a distraction or nuisance). For effective training, the flight simulator should provide flight deck sounds that are perceptible to the pilot during normal and abnormal operations, and that are comparable to those of the helicopter. The flight simulator operator should carefully evaluate background noises in the location where the device will be installed. To demonstrate compliance with the sound requirements, the objective or validation tests in this attachment were selected to provide a representative sample of normal static conditions typically experienced by a pilot.

- b. Alternate propulsion. For FFS with multiple propulsion configurations, any condition listed in Table C2A in this attachment should be presented for evaluation as part of the QTG if identified by the helicopter manufacturer or other data supplier as significantly different due to a change in propulsion system (engine or propeller).
 - c. Data and Data Collection System.
- (1) Information provided to the flight simulator manufacturer should comply be presented in the format suggested by "International Air Transport Association (IATA) Flight Simulator Design and Performance Data Requirements," as amended. This information should contain calibration and frequency response data.
- (2) The system used to perform the tests listed in Table C2A should comply with the following standards:
- (a) The specifications for octave, half octave, and third octave band filter sets may be found in American National Standards Institute (ANSI) S1.11-1986.
- (b) Measurement microphones should be type WS2 or better, as described in International Electrotechnical Commission (IEC) 1094-4-1995.
- (3) Headsets. If headsets are used during normal operation of the helicopter they should also be used during the flight simulator evaluation.
- (4) Playback equipment. Playback equipment and recordings of the QTG conditions should be provided during initial evaluations.
 - (5) Background noise.
- (a) Background noise is the noise in the flight simulator that is not associated with the helicopter, but is caused by the flight simulator's cooling and hydraulic systems and extraneous noise from other locations in the building. Background noise can seriously impact the correct simulation of helicopter sounds, and should be kept below the helicopter sounds. In some cases, the sound level of the simulation can be increased to compensate for the background noise. However, this approach is limited by the specified tolerances and by the subjective acceptability

of the sound environment to the evaluation pilot.

- (b) The acceptability of the background noise levels is dependent upon the normal sound levels in the helicopter being represented. Background noise levels that fall below the lines defined by the following points, may be acceptable:
- (i) 70 dB @ 50 Hz;
- (ii) 55 dB @ 1000 Hz:
- (iii) 30 dB @ 16 kHz.

(Note: These limits are for unweighted 1/3 octave band sound levels. Meeting these limits for background noise does not ensure an acceptable flight simulator. Helicopter sounds that fall below this limit require careful review and may require lower limits on background noise.)

- (6) Validation testing. Deficiencies in helicopter recordings should be considered when applying the specified tolerances to ensure that the simulation is representative of the helicopter. Examples of typical deficiencies
 - (a) Variation of data between tail numbers. (b) Frequency response of microphones.

 - (c) Repeatability of the measurements.

TABLE C2C—EXAMPLE OF CONTINUING QUALI-FICATION FREQUENCY RESPONSE TEST TOL-**ERANCE**

Band center frequency	Initial results (DbsPL)	Continuing qualification results (DbsPL)	Absolute difference
50	75.0	73.8	1.2
63	75.9	75.6	0.3
80	77.1	76.5	0.6
100	78.0	78.3	0.3
125	81.9	81.3	0.6
160	79.8	80.1	0.3
200	83.1	84.9	1.8
250	78.6	78.9	0.3
315	79.5	78.3	1.2
400	80.1	79.5	0.9
500	80.7	79.8	0.9
630	81.9	80.4	1.5
800 008	73.2	74.1	0.9
1000	79.2	80.1	0.9
1250	80.7	82.8	2.1
1600	81.6	78.6	3.0
2000	76.2	74.4	1.8
2500	79.5	80.7	1.2
3150	80.1	77.1	3.0
4000	78.9	78.6	0.3
5000	80.1	77.1	3.0
6300	80.7	80.4	0.3
8000	84.3	85.5	1.2
10000	81.3	79.8	1.5
12500	80.7	80.1	0.6
16000	71.1	71.1	0.0
	Ave	erage	1.1

- 8. Additional Information About Flight Simulator Qualification for New or De-RIVATIVE HELICOPTERS
- a. Typically, a helicopter manufacturer's approved final data for performance, handling qualities, systems or avionics is not available until well after a new or derivative helicopter has entered service. However, flight crew training and certification often begins several months prior to the entry of the first helicopter into service. Consequently, it may be necessary to use preliminary data provided by the helicopter manufacturer for interim qualification of flight simulators.
- b. In these cases, the responsible Flight Standards office may accept certain partially validated preliminary helicopter and systems data, and early release ("red label") avionics data in order to permit the necessary program schedule for training, certification, and service introduction.
- c. Simulator sponsors seeking qualification based on preliminary data should consult the responsible Flight Standards office to make special arrangements for using preliminary data for flight simulator qualification. The sponsor should also consult the helicopter and flight simulator manufacturers to develop a data plan and flight simulator qualification plan.
- d. The procedure to be followed to gain the responsible Flight Standards office acceptance of preliminary data will vary from case to case and between helicopter manufacturers. Each helicopter manufacturer's new helicopter development and test program is designed to suit the needs of the particular project and may not contain the same events or sequence of events as another manufacturer's program or even the same manufacturer's program for a different helicopter. Therefore, there cannot be a prescribed invariable procedure for acceptance of preliminary data; instead there should be a statement describing the final sequence of events, data sources, and validation procedures agreed by the simulator sponsor, the helicopter manufacturer, the flight simulator manufacturer, and the responsible Flight Standards office.

Note: A description of helicopter manufacturer-provided data needed for flight simulator modeling and validation is to be found in the "Royal Aeronautical Society Data Package Requirements for Design and Performance Evaluation of Rotary Wing Synthetic Training Devices."

e. The preliminary data should be the manufacturer's best representation of the helicopter, with assurance that the final data will not deviate significantly from the preliminary estimates. Data derived from these predictive or preliminary techniques should be validated by available sources including, at least, the following:

- (1) Manufacturer's engineering report. The report should explain the predictive method used and illustrate past success of the method on similar projects. For example, the manufacturer could show the application of the method to an earlier helicopter model or predict the characteristics of an earlier model and compare the results to final data for that model.
- (2) Early flight test results. This data is often derived from helicopter certification tests and should be used to maximum advantage for early flight simulator validation. Certain critical tests that would normally be done early in the helicopter certification program should be included to validate essential pilot training and certification maneuvers. These tests include cases where a pilot is expected to cope with a helicopter failure mode or an engine failure. The early data available will depend on the helicopter manufacturer's flight test program design and may not be the same in each case. The flight test program of the helicopter manufacturer should include provisions for generation of very early flight tests results for flight simulator validation.
- f. The use of preliminary data is not indefinite. The helicopter manufacturer's final data should be available within 12 months after the helicopter first entry into service or as agreed by the responsible Flight Standards office, the simulator sponsor, and the helicopter manufacturer. When applying for interim qualification using preliminary data, the simulator sponsor and the responsible Flight Standards office should agree on the update program. This includes specifying that the final data update will be installed in the flight simulator within a period of 12 months following the final data release, unless special conditions exist and a different schedule is acceptable. The flight simulator performance and handling validation would then be based on data derived from flight tests. Initial helicopter systems data should be updated after engineering tests. Final helicopter systems data should also be used for flight simulator programming and validation.
- g. Flight simulator avionics should stay essentially in step with helicopter avionics (hardware and software) updates. The permitted time lapse between helicopter and flight simulator updates should be minimal. It may depend on the magnitude of the update and whether the QTG and pilot training and certification are affected. Differences in helicopter and flight simulator avionics versions and the resulting effects on flight simulator qualification should be agreed between the simulator sponsor and the responsible Flight Standards office. Consultation with the flight simulator manufacturer is desirable throughout the qualification process.
- h. The following describes an example of the design data and sources that might be

used in the development of an interim qualification plan.

- (1) The plan should consist of the development of a QTG based upon a mix of flight test and engineering simulation data. For data collected from specific helicopter flight tests or other flights the required design model or data changes necessary to support an acceptable Proof of Match (POM) should be generated by the helicopter manufacturer.
- (2) For proper validation of the two sets of data, the helicopter manufacturer should compare their simulation model responses against the flight test data, when driven by the same control inputs and subjected to the same atmospheric conditions as recorded in the flight test. The model responses should result from a simulation where the following systems are run in an integrated fashion and are consistent with the design data released to the flight simulator manufacturer:
 - (a) Propulsion.
 - (b) Aerodynamics.
 - (c) Mass properties.
 - (d) Flight controls.
 - (e) Stability augmentation.
 - (f) Brakes/landing gear.
- i. A qualified test pilot should be used to assess handling qualities and performance evaluations for the qualification of flight simulators of new helicopter types.

END INFORMATION

BEGIN QPS REQUIREMENT

9. ENGINEERING SIMULATOR—VALIDATION DATA

- a. When a fully validated simulation (i.e., validated with flight test results) is modified due to changes to the simulated helicopter configuration, the helicopter manufacturer or other acceptable data supplier must coordinate with the responsible Flight Standards office to supply validation data from an "audited" engineering simulator/simulation to selectively supplement flight test data. The responsible Flight Standards office must be provided an opportunity to audit the use of the engineering simulation or the engineering simulator during the acquisition of the data that will be used as validation data. Audited data may be used for changes that are incremental in nature. Manufacturers or other data suppliers must be able to demonstrate that the predicted changes in helicopter performance are based on acceptable aeronautical principles with proven success history and valid outcomes. This must include comparisons of predicted and flight test validated data.
- b. Helicopter manufacturers or other acceptable data suppliers seeking to use an engineering simulator for simulation validation data as an alternative to flight-test derived validation data, must contact the re-

sponsible Flight Standards office and provide the following:

- (1) A description of the proposed aircraft changes, a description of the proposed simulation model changes, and the use of an integral configuration management process, including an audit of the actual simulation model modifications that includes a step-by-step description leading from the original model(s) to the current model(s).
- (2) A schedule for review by the responsible Flight Standards office of the proposed plan and the subsequent validation data to establish acceptability of the proposal.
- (3) Validation data from an audited engineering simulator/simulation to supplement specific segments of the flight test data.
- c. To be qualified to supply engineering simulator validation data, for aerodynamic, engine, flight control, or ground handling models, a helicopter manufacturer or other acceptable data supplier must:
 - (1) Be able to verify their ability to:
- (a) Develop and implement high fidelity simulation models; and
- (b) Predict the handling and performance characteristics of a helicopter with sufficient accuracy to avoid additional flight test activities for those handling and performance characteristics.
 - (2) Have an engineering simulator that:
- (a) Is a physical entity, complete with a flight deck representative of the simulated class of helicopter;
- (b) Has controls sufficient for manual flight;
- (c) Has models that run in an integrated manner;
- (d) Had fully flight-test validated simulation models as the original or baseline simulation models;
- (e) Has an out-of-the-flight deck visual system:
- (f) Has actual avionics boxes interchangeable with the equivalent software simulations to support validation of released software:
- (g) Uses the same models as released to the training community (which are also used to produce stand-alone proof-of-match and checkout documents);
- (h) Is used to support helicopter development and certification; and
- (i) Has been found to be a high fidelity representation of the helicopter by the manufacturer's pilots (or other acceptable data supplier), certificate holders, and the responsible Flight Standards office.
- (3) Use the engineering simulator to produce a representative set of integrated proof-of-match cases.
- (4) Use a configuration control system covering hardware and software for the operating components of the engineering simulator
- (5) Demonstrate that the predicted effects of the change(s) are within the provisions of

sub-paragraph "a" of this section, and confirm that additional flight test data are not required.

- d. Additional Requirements for Validation Data
- (1) When used to provide validation data, an engineering simulator must meet the simulator standards currently applicable to training simulators except for the data package
 - (2) The data package used must be:
- (a) Comprised of the engineering predictions derived from the helicopter design, development, or certification process;
- (b) Based on acceptable aeronautical principles with proven success history and valid outcomes for aerodynamics, engine operations, avionics operations, flight control applications, or ground handling;
- (c) Verified with existing flight-test data; and
- (d) Applicable to the configuration of a production helicopter, as opposed to a flight-test helicopter.
- (3) Where engineering simulator data are used as part of a QTG, an essential match must exist between the training simulator and the validation data.
- (4) Training flight simulator(s) using these baseline and modified simulation models must be qualified to at least internationally recognized standards, such as contained in the ICAO Document 9625, the "Manual of Criteria for the Qualification of Flight Simulators."

END QPS REQUIREMENT

10. [RESERVED]

11. VALIDATION TEST TOLERANCES

BEGIN INFORMATION

- a. Non-Flight-Test Tolerances. If engineering simulator data or other non-flight-test data are used as an allowable form of reference validation data for the objective tests listed in Table C2A of this attachment, the data provider must supply a well-documented mathematical model and testing procedure that enables a replication of the engineering simulation results within 20% of the corresponding flight test tolerances.
 - b. Background
- (1) The tolerances listed in Table C2A of this attachment are designed to measure the quality of the match using flight-test data as a reference.
- (2) Good engineering judgment should be applied to all tolerances in any test. A test is failed when the results fall outside of the prescribed tolerance(s).
- (3) Engineering simulator data are acceptable because the same simulation models

used to produce the reference data are also used to test the flight training simulator (i.e., the two sets of results should be "essentially" similar).

- (4) The results from the two sources may differ for the following reasons:
- (a) Hardware (avionics units and flight controls):
 - (b) Iteration rates:
 - (c) Execution order;
 - (d) Integration methods;
 - (e) Processor architecture;
 - (f) Digital drift, including:
 - (i) Interpolation methods;(ii) Data handling differences;
 - (iii) Auto-test trim tolerances.
- (5) The tolerance limit between the reference data and the flight simulator results is generally 20% of the corresponding ifflight-test" tolerances. However, there may be cases where the simulator models used are of higher fidelity, or the manner in which they are cascaded in the integrated testing loop have the effect of a higher fidelity, than those supplied by the data provider. Under these circumstances, it is possible that an error greater than 20% may be generated. An error greater than 20% may be acceptable if
- (6) Guidelines are needed for the application of tolerances to engineering-simulator-generated validation data because:

the simulator sponsor can provide an ade-

- (a) Flight-test data are often not available due to sound technical reasons;
- (b) Alternative technical solutions are being advanced; and
 - (c) The costs are high.

quate explanation.

12. VALIDATION DATA ROADMAP

- a. Helicopter manufacturers or other data suppliers should supply a validation data roadmap (VDR) document as part of the data package. A VDR document contains guidance material from the helicopter validation data supplier recommending the best possible sources of data to be used as validation data in the QTG. A VDR is of special value when requesting interim qualification, qualification of simulators for helicopters certificated prior to 1992, and qualification of alternate engine or avionics fits. A sponsor seeking to have a device qualified in accordance with the standards contained in this QPS appendix should submit a VDR to the responsible Flight Standards office as early as possible in the planning stages. The NSPM is the final authority to approve the data to be used as validation material for the QTG. The responsible Flight Standards office and the Joint Aviation Authorities' Synthetic Training Devices Advisory Board have committed to maintain a list of agreed VDRs.
- b. The VDR should identify (in matrix format) sources of data for all required tests. It should also provide guidance regarding the validity of these data for a specific engine

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. C

type, thrust rating configuration, and the revision levels of all avionics affecting helicopter handling qualities and performance. The VDR should include rationale or explanation in cases where data or parameters are missing, engineering simulation data are to be used, flight test methods require explanation, or where there is any deviation from data requirements. Additionally, the document should refer to other appropriate sources of validation data (e.g., sound and vibration data documents).

c. The Sample Validation Data Roadmap (VDR) for helicopters, shown in Table C2D, depicts a generic roadmap matrix identifying sources of validation data for an abbreviated list of tests. This sample document uses fixed wing parameters instead of helicopter

values. It is merely a sample and does not provide actual data. A complete matrix should address all test conditions for helicopter application and provide actual data and data sources.

d. Two examples of rationale pages are presented in Appendix F of IATA Flight Simulator Design and Performance Data Requirements document. These illustrate the type of helicopter and avionics configuration information and descriptive engineering rationale used to describe data anomalies or provide an acceptable basis for using alternative data for QTG validation requirements.

END INFORMATION

ICA0		F	Validation	100						
or IATA#	Test Description		Source	e e		Validatic	Validation Document	nent		Comments
Notes: 1. Only o	Notes: 1. Only one page is shown; and some test conditions were		1.0	-42		-:				Legend: D71 = Engine Type (Thrust Rating of 71.5K)
deleted fc 2. Releva	deleted for brevity. 2. Relevant regulatory material should be consulted and			(D)	¥	I Doc		V '		D73 = Engine Type (Thrust Rating of 73K)
all applica 3. Valida	all applicable tests addressed. 3. Validation source, document and comments provided	әро	Test I	tor Da	cs POI , Rev.	g bon 2 bon 9 NE	POM Rev. (POM	1' NE. Pis AI	Bold upper case = primary validation source.
herein are	herein are for reference only and do not constitute	W.		einn iign		St-X Suilt	uois			
approval for use. 4. CCA mode n	approval for use. 4. CCA mode must be described for each test	/33		13 E	xxx#.	xx#.c	Indo			Lower case, within parentheses = alternative validation source.
condition.). 			niiə	Doc	Dod	d			D - Dottonals included in the data medianes
5. II moi baseline)	5. If more than one aircraft type (e.g., derivative and baseline) are used as validation data more columns			ußu		OTO		[R - Rationale included in the data package Appendix.
may be n	may be necessary.			ıa						-
1.a.1.	Minimum Radius Turn.		×			D71				
1.a.2.	Rate of Turn vs. Nosewheel Angle (2 speeds).		×			D71				
1.b.1.	Ground Acceleration Time and Distance.		×	Г		(d73)		D73		Primary data contained in IPOM.
1.b.2.	Minimum Control Speed, Ground (Vmcg).		(x)	×	(d71)				D73	See engineering rationale for test data in VDR.
1.b.3.	Minimum Unstick Speed (Vmu).		X		D71					
1.b.4.	Normal Takeoff.		X		(d73)			D73		Primary data contained in IPOM.
1.b.5.	Critical Engine Failure on Takeoff.		×		(1/p)			_	D73	Alternative engine thrust rating flight test data in VDR.
1.b.6.	Crosswind Takeoff.		×		(d71)				D73	Alternative engine thrust rating flight test data in VDR.
1.b.7.	Rejected Takeoff.		×		D71				×	Test procedure anomaly; see rationale.
1.b.8.	Dynamic Engine Failure After Takeoff.			×					D73	No flight test data available; see rationale.
1.c.1.	Normal Climb - All Engines.	1	×		(d71)			D71		Primary data contained in IPOM.
1.c.2.	Climb – Engine-out, Second Segment.		X		(d71)				D73	Alternative engine thrust rating flight test data in VDR.
1.c.3.	Climb - Engine-out, Enroute.		×		(d71)				D73	AFM data available (73K).
1.c.4.	Engine-out, Approach Climb.	-	×		D71					AND THE RESERVE OF THE PROPERTY OF THE PROPERT
1.c.5.a.	Level Flight Acceleration.	1	(X)	×	(d73)				D73	Eng sim data w/ modified EEC accel rate in VDR.
1.c.5.b.	Level Flight Deceleration.	7	×	×	(d73)	1			D73	Eng sim data w/ modified EEC accel rate in VDR.
1.d.1.	Cruise Performance.	1	×	1	170					
1.e.1.a.	Stopping Time & Distance (Wheel brakes / Light weight).			×	D71				(d73)	No flight test data available; see rationale.
1.e.1.b.	Stopping Time & Distance (Wheel brakes/ Med. weight).		×	(x)	D71				(q23)	
1.e.1.c.	Stopping Time & Distance (Wheel brakes / Heavy weight).		×	×	D7.1				(d73)	
1.e.2.a.	Stopping Time & Distance (Reverse thrust / Light weight).		×	×	D7.1				(d73)	
1.e.2.b.	Stopping Time & Distance (Reverse thrust / Med. Weight).			×	(d71)				D73	No flight test data available; see rationale.

13. [Reserved]

14. ACCEPTANCE GUIDELINES FOR ALTERNATIVE AVIONICS (FLIGHT-RELATED COMPUTERS AND CONTROLLERS)

a. Background

- (1) For a new helicopter type, the majority of flight validation data are collected on the first helicopter configuration with a "baseline" flight-related avionics ship-set; (see subparagraph b.(2) of this section). These data are then used to validate all flight simulators representing that helicopter type.
- (2) Additional validation data may be needed for flight simulators representing a helicopter with avionics of a different hardware design than the baseline, or a different software revision than that of previously validated configurations.
- (3) When a flight simulator with additional or alternate avionics configurations is to be qualified, the QTG should contain tests against validation data for selected cases where avionics differences are expected to be significant.

b. Approval Guidelines For Validating Alternate Avionics

- (1) The following guidelines apply to flight simulators representing helicopters with a revised avionics configuration, or more than one avionics configuration.
- (2) The baseline validation data should be based on flight test data, except where other data are specifically allowed (e.g., engineering flight simulator data).
- (3) The helicopter avionics can be segmented into two groups, systems or components whose functional behavior contributes to the aircraft response presented in the QTG results, and systems that do not. The following avionics are examples of contributory systems for which hardware design changes or software revisions may lead to significant differences in the aircraft response relative to the baseline avionics configuration: Flight control computers and controllers for engines, autopilot, braking system, and nosewheel steering system, if applicable. Related avionics such as augmentation systems should also be considered.
- (4) The acceptability of validation data used in the QTG for an alternative avionics fit should be determined as follows:
- (a) For changes to an avionics system or component that do not affect QTG validation test response, the QTG test can be based on validation data from the previously validated avionics configuration.
- (b) For an avionics change to a contributory system, where a specific test is not af-

fected by the change (e.g., the avionics change is a Built In Test Equipment (BITE) update or a modification in a different flight phase), the QTG test can be based on validation data from the previously-validated avionics configuration. The QTG should include authoritative justification (e.g., from the helicopter manufacturer or system supplier) that this avionics change does not affect the test.

- (c) For an avionics change to a contributory system, the QTG may be based on validation data from the previously-validated avionics configuration if no functionality is added and the impact of the avionics change on the helicopter response is based on acceptable aeronautical principles with proven success history and valid outcomes. This should be supplemented with avionics-specific validation data from the helicopter manufacturer's engineering simulation, generated with the revised avionics configuration. The QTG should include an explanation of the nature of the change and its effect on the helicopter response.
- (d) For an avionics change to a contributory system that significantly affects some tests in the QTG, or where new functionality is added, the QTG should be based on validation data from the previously validated avionics configuration and supplemental avionics-specific flight test data sufficient to validate the alternate avionics revision. Additional flight test validation data may not be needed if the avionics changes were certified without the need for testing with a comprehensive flight instrumentation package. The helicopter manufacturer should coordinate flight simulator data requirements in advance with the responsible Flight Standards office.
- (5) A matrix or "roadmap" should be provided with the QTG indicating the appropriate validation data source for each test. The roadmap should include identification of the revision state of those contributory avionics systems that could affect specific test responses.

15. Transport Delay Testing

- a. This paragraph describes how to determine the introduced transport delay through the flight simulator system so that it does not exceed a specific time delay. The transport delay should be measured from control inputs through the interface, through each of the host computer modules and back through the interface to motion, flight instrument, and visual systems. The transport delay should not exceed the maximum allowable interval.
- b. Four specific examples of transport delay are:
- (1) Simulation of classic non-computer controlled aircraft;
- (2) Simulation of Computer Controlled Aircraft using real helicopter black boxes;

- (3) Simulation of Computer Controlled Aircraft using software emulation of helicopter boxes;
- (4) Simulation using software avionics or rehosted instruments.
- c. Figure C2C illustrates the total transport delay for a non-computer-controlled helicopter or the classic transport delay test. Since there are no helicopter-induced delays for this case, the total transport delay is equivalent to the introduced delay.
- d. Figure C2D illustrates the transport delay testing method using the real helicopter controller system.
- e. To obtain the induced transport delay for the motion, instrument and visual signal, the delay induced by the helicopter controller should be subtracted from the total transport delay. This difference represents the introduced delay and should not exceed the standards prescribed in Table C1A.
- f. Introduced transport delay is measured from the flight deck control input to the reaction of the instruments and motion and visual systems (See Figure C2C).
- g. The control input may also be introduced after the helicopter controller system input and the introduced transport delay may be measured directly from the control input to the reaction of the instruments, and simulator motion and visual systems (See Figure C2D).
- h. Figure C2E illustrates the transport delay testing method used on a flight simulator that uses a software emulated helicopter controller system.
- i. It is not possible to measure the introduced transport delay using the simulated helicopter controller system architecture for the pitch, roll and yaw axes. Therefore, the signal should be measured directly from the pilot controller. The flight simulator manufacturer should measure the total transport delay and subtract the inherent delay of the actual helicopter components because the real helicopter controller system has an inherent delay provided by the helicopter manufacturer. The flight simulator manufacturer should ensure that the introduced delay does not exceed the standards prescribed in Table C1A.
- j. Special measurements for instrument signals for flight simulators using a real helicopter instrument display system instead of a simulated or re-hosted display. For flight instrument systems, the total transport

- delay should be measured and the inherent delay of the actual helicopter components subtracted to ensure that the introduced delay does not exceed the standards prescribed in Table C1A.
- (1) Figure C2FA illustrates the transport delay procedure without helicopter display simulation. The introduced delay consists of the delay between the control movement and the instrument change on the data bus.
- (2) Figure C2FB illustrates the modified testing method required to measure introduced delay due to software avionics or rehosted instruments. The total simulated instrument transport delay is measured and the helicopter delay should be subtracted from this total. This difference represents the introduced delay and should not exceed the standards prescribed in Table C1A. The inherent delay of the helicopter between the data bus and the displays is indicated in figure C2FA. The display manufacturer should provide this delay time.
- k. Recorded signals. The signals recorded to conduct the transport delay calculations should be explained on a schematic block diagram. The flight simulator manufacturer should also provide an explanation of why each signal was selected and how they relate to the above descriptions.
- 1. Interpretation of results. Flight simulator results vary over time from test to test due to "sampling uncertainty." All flight simulators run at a specific rate where all modules are executed sequentially in the host computer. The flight controls input can occur at any time in the iteration, but these data will not be processed before the start of the new iteration. For example, a flight simulator running at 60 Hz may have a difference of as much as 16.67 msec between results. This does not mean that the test has failed. Instead, the difference is attributed to variation in input processing. In some conditions, the host simulator and the visual system do not run at the same iteration rate, so the output of the host computer to the visual system will not always be synchronized.
- m. The transport delay test should account for both daylight and night modes of operation of the visual system. In both cases, the tolerances prescribed in Table C1A should be met and the motion response should occur before the end of the first video scan containing new information.

14 CFR Ch. I (1-1-24 Edition)

Figure C2E Transport Delay for simulation of classic non-Computer Controlled Aircraft.

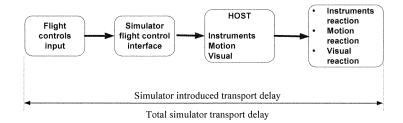


Figure C2F Transport Delay for simulation of Computer Controlled Aircraft using real helicopter black boxes

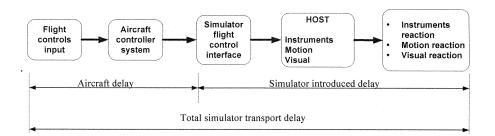


Figure C2G

Transport Delay for simulation of Computer Controlled Aircraft using software emulation of helicopter boxes

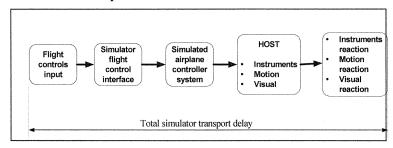
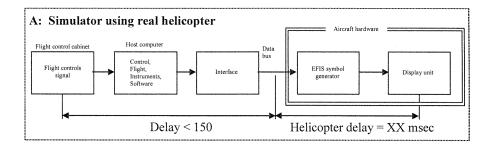
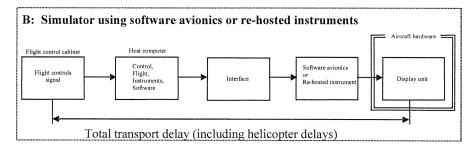


Figure C2HA and C2HB

Transport delay for simulation of helicopters using real or re-hosted instrument drivers





16. CONTINUING QUALIFICATION EVALUATIONS— VALIDATION TEST DATA PRESENTATION

a. Background

- (1) The MQTG is created during the initial evaluation of a flight simulator. This is the master document, as amended, to which flight simulator continuing qualification evaluation test results are compared.
- (2) The currently accepted method of presenting continuing qualification evaluation test results is to provide flight simulator results over-plotted with reference data. Test results are carefully reviewed to determine if the test is within the specified tolerances. This can be a time consuming process, particularly when reference data exhibits rapid variations or an apparent anomaly requiring engineering judgment in the application of

the tolerances. In these cases, the solution is to compare the results to the MQTG. The continuing qualification results are compared to the results in the MQTG for acceptance. The flight simulator operator and the responsible Flight Standards office should look for any change in the flight simulator performance since initial qualification.

b. Continuing Qualification Evaluation Test Results Presentation

- (1) Flight simulator operators are encouraged to over-plot continuing qualification validation test results with MQTG flight simulator results recorded during the initial evaluation and as amended. Any change in a validation test will be readily apparent. In addition to plotting continuing qualification validation test and MQTG results, operators may elect to plot reference data.
- (2) There are no suggested tolerances between flight simulator continuing qualification and MQTG validation test results. Investigation of any discrepancy between the MQTG and continuing qualification flight simulator performance is left to the discretion of the flight simulator operator and the responsible Flight Standards office.
- (3) Differences between the two sets of results, other than variations attributable to repeatability issues that cannot be explained should be investigated.
- (4) The flight simulator should retain the ability to over-plot both automatic and manual validation test results with reference data.

END INFORMATION

BEGIN QPS REQUIREMENTS

- 17. ALTERNATIVE DATA SOURCES, PROCE-DURES, AND INSTRUMENTATION: LEVEL B SIMULATORS ONLY
- a. Sponsors are not required to use the alternative data sources, procedures, and instrumentation. However, any sponsor choosing to use alternative sources must comply with the requirements in Table C2E.

END QPS REQUIREMENTS

BEGIN INFORMATION

b. It has become standard practice for experienced simulator manufacturers to use such techniques as a means of establishing data bases for new simulator configurations while awaiting the availability of actual flight test data. The data generated from the aerodynamic modeling techniques is then compared to the flight test data when it becomes available. The results of such comparisons have become increasingly consistent, indicating that these techniques, ap-

plied with appropriate experience, are dependable and accurate for the development of aerodynamic models for use in Level B simulators.

- c. Based on this history of successful comparisons, the responsible Flight Standards office has concluded that those who are experienced in the development of aerodynamic models for simulator application can successfully use these modeling techniques to alter the method for acquiring flight test data for Level B simulators.
- d. The information in Table C2E (Alternative Data Sources, Procedures, and Information) is presented to describe an acceptable alternative to data sources for simulator modeling and validation and an acceptable alternative to the procedures and instrumentation traditionally used to gather such modeling and validation data.
- (1) Alternative data sources that may be used for part or all of a data requirement are the Helicopter Maintenance Manual, the Rotorcraft Flight Manual (RFM), Helicopter Design Data, the Type Inspection Report (TIR), Certification Data or acceptable supplemental flight test data.
- (2) The sponsor should coordinate with the responsible Flight Standards office prior to using alternative data sources in a flight test or data gathering effort.
- e. The responsible Flight Standards office position on the use of these alternative data sources, procedures, and instrumentation is based on the use of a rigorously defined and fully mature simulation controls system model that includes accurate gearing and cable stretch characteristics (where applicable), determined from actual aircraft measurements. The model does not require control surface position measurements in the flight test objective data in these limited applications.
- f. Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated helicopter instruments, including the inclinometer; the force/position measurements of flight deck controls; and a clear visual directional reference for a known magnetic bearing (e.g., a runway centerline). Ground track and wind corrected heading may be used for sideslip angle.
- g. The sponsor is urged to contact the responsible Flight Standards office for clarification of any issue regarding helicopters with reversible control systems. This table is not applicable to Computer Controlled Aircraft flight simulators.
- h. Use of these alternate data sources, procedures, and instrumentation does not relieve the sponsor from compliance with the balance of the information contained in this document relative to Level B FFSs.
- i. The term "inertial measurement system" is used in table C2E includes the use of a functional global positioning system (GPS).

- j. Synchronized video for the use of alternative data sources, procedures, and instrumentation should have:
- (1) sufficient resolution to allow magnification of the display to make appropriate measurement and comparisons; and
- (2) sufficient size and incremental marking to allow similar measurement and comparison. The detail provided by the video should

provide sufficient clarity and accuracy to measure the necessary parameter(s) to at least ½ of the tolerance authorized for the specific test being conducted and allow an integration of the parameter(s) in question to obtain a rate of change.

END INFORMATION

TABLE C2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION

[The standards in this table are required if the data gathering methods described in paragraph 9 of Appendix C are not used]

		QPS requirements	Information
Table of objective tests	Level By	Alternative data sources, procedures, and instrumentation	Notes
Test entry number and title	only	, , , , , , , , , , , , , , , , , , , ,	
1.a.1.a. Performance. Engine Start and Accelerations.	x	Data may be acquired using a synchronized video recording of all engine instruments, start buttons, means for fuel introduction and means for moving from "idle" to "flight." A stopwatch is necessary.	
1.a.1.b. Performance. Steady State Idle and Operating RPM Condi- tions.	×	Data may be acquired using a synchronized video recording of all engine instruments, and include the status of the means for moving from "idle" to "flight.".	
1.a.2. Performance. Power Turbine Speed Trim.	×	Data may be acquired using a synchronized video recording of all engine instruments. Speed trim actuator position may be hand recorded.	
I.a.3. Performance. Engine and Rotor Speed Governing.	X	Data may be acquired by using a synchronized video of the cali- brated helicopter instruments and the force/position measure- ments of flight deck controls.	
1.b.1. Performance. On Surface Taxi. Minimum Radius Turn.	X	TIR, AFM, or Design data may be used.	
1.b.2. Performance. On Surface Taxi Rate of Turn vs. Nosewheel Steering Angle.	×	Data may be acquired by using a constant tiller position (measured with a protractor), or full pedal application for steady state turn, and synchronized video of heading indicator. If less than full pedal is used, pedal position must be recorded	A single procedure may not be adequate for all rotor-craft steering systems. Appropriate measurement procedures must be devised and proposed for responsible Flight Standards office concurrence.
1.b.3. Performance. Taxi	X	Data may be acquired by using a synchronized video of the cali- brated helicopter instruments and the force/position measure- ments of flight deck controls.	
1.b.4. Performance. Brake	X	Data may be acquired using a stopwatch and a means for meas- uring distance such as runway distance markers conforming with runway distance marker standards.	
1.c.1. Performance. Run- ning Takeoff.	×	Preliminary certification data may be used. Data may be acquired by using a synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls. Collective, cyclic, and pedal position time history must be recorded from the start of collective movement through to normal climb. Indicated torque settings may be hand recorded at the moment of lift-off and in a steady normal climb.	
1.c.2. Performance. One Engine Inoperative (OEI), continued takeoff.	X	Data may be acquired by using a synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls. Collective, cyclic, and pedal position time history must be recorded from the start of collective movement through to normal OEI climb. Indicated torque settings may be hand recorded at the moment of lift-off and in a steady normal OEI climb.	
1.f. Performance. Level Flight. Trimmed Flight Control Positions.	Х	Data may be acquired by using a synchronized video of the cali- brated helicopter instruments and the force/position measure- ments of flight deck controls.	
 1.g. Performance. Normal Climb. Trimmed Flight Control Positions. 	X	Data may be acquired by using a synchronized video of the cali- brated helicopter instruments and the force/position measure- ments of flight deck controls.	

TABLE C2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued [The standards in this table are required if the data gathering methods described in paragraph 9 of Appendix C are not used]

			QPS requirements	Informa
	Table of objective tests Test entry number and title	Level By only	Alternative data sources, procedures, and instrumentation	Notes
	1.h.1. Descent Perform-	X	Data may be acquired by using a synchronized video of the cali-	
	ance and Trimmed Flight Control Positions. 1.h.2. Autorotation Perform-	×	brated helicopter instruments and the force/position measure- ments of flight deck controls. Data may be acquired by using a synchronized video of the cali-	
	ance and Trimmed Flight Control Positions. 1.j.1. Performance. Run-	x	brated helicopter instruments and the force/position measure- ments of flight deck controls. Data may be acquired by using a synchronized video of the cali-	
	ning Landing All Engines. 1.j.2. Performance. Run-	x	brated helicopter instruments and the force/position measurements of flight deck controls. Data may be acquired by using a synchronized video of the cali-	
	ning Landing One Engine Inoperative.		brated helicopter instruments and the force/position measure- ments of flight deck controls.	
	1.j.3. Performance. Balked Landing.	X	Data may be acquired by using a synchronized video of the cali- brated helicopter instruments and the force/position measure- ments of flight deck controls. The synchronized video must record the time of the "balk landing" decision.	
	 2.a.1. Handling Qualities. Static Control Checks. Cyclic Controller Position vs. Force. 	X	Control positions can be obtained using continuous control position recordings. Force data may be acquired by using a hand held force gauge so that the forces can be cross-plotted against control position in each of the control axes.	
	 2.a.2. Handling Qualities. Static Control Checks. Collective/Pedals vs. 	×	Control positions can be obtained using continuous control position recordings. Force data may be acquired by using a hand held force gauge so that the forces can be cross-plotted against con-	
	Force. 2.a.3. Handling Qualities. Brake Pedal Force vs. Position.	x	trol position in each of the control axes. Brake pedal positions can be obtained using continuous position re- cordings. Force data may be acquired by using a hand held force gauge so that the forces can be cross-plotted against brake pedal position.	
	 2.a.4. Handling Qualities. Trim System Rate (all applicable systems). 	×	Control positions can be obtained using continuous control position recordings plotted against time to provide rate in each applicable system.	
	 2.a.6. Handling Qualities. Control System Freeplay. 2.c.1. Longitudinal Handling 	X X	Data may be acquired by direct measurement. Data may be acquired by using an inertial measurement system, a	
	Qualities. Control Response. 2.c.2. Longitudinal Handling	x	synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls. Data may be acquired by using an inertial measurement system, a	
	Qualities. Static Stability.		synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls.	
	 2.c.3.a. Longitudinal Han- dling Qualities. Dynamic Stability, Long Term Re- sponse. 	X	Data may be acquired by using an inertial measurement system, a synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls.	
	 2.c.3.b. Longitudinal Han- dling Qualities. Dynamic Stability, Short Term Re- sponse. 	X	Data may be acquired by using an inertial measurement system, a synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls.	
	 2.c.4. Longitudinal Handling Qualities. Maneuvering stability. 	×	Data may be acquired by using an inertial measurement system, a synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls. Data may be acquired by using an inertial measurement system, a	
	2.d.1.a. Lateral Handling Qualities. Control Re- sponse.2.d.1.b Directional Handling	x	synchronized video of the calibrated helicopter instruments and the force/position measurements of flight deck controls. Data may be acquired by using an inertial measurement system	
	Qualities. Control Response 2.d.2. Handling Qualities. Directional Static Stability.	×	and a synchronized video of calibrated helicopter instruments and force/position measurements of flight deck directional controls. Data may be acquired by using an inertial measurement system and a synchronized video of calibrated helicopter instruments and	
	2.d.3.a. Handling Qualities. Dynamic Lateral and Di- rectional Stability Lateral-	×	force/position measurements of flight deck directional controls. Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated helicopter instruments, the force/position measurements of flight deck controls, and a	
	Directional Oscillations. 2.d.3.b. Handling Qualities. Dynamic Lateral and Di- rectional Stability Spiral Stability.	x	stop watch. Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated helicopter instruments, the force/position measurements of flight deck controls, and a stop watch.	
	Glability.	'	344	
Date Sep<11>2014 14:00	Mar 14. 2024 Jkt 262047 PC	00000	Frm 00354 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31	

TABLE C2E—ALTERNATIVE DATA SOURCES, PROCEDURES, AND INSTRUMENTATION—Continued [The standards in this table are required if the data gathering methods described in paragraph 9 of Appendix C are not used]

		QPS requirements	Information
Table of objective tests	Level By	Alternative data sources, procedures, and instrumentation	Notes
Test entry number and title	only	Alternative data sources, procedures, and institution	Notes
2.d.3.c. Handling Qualities. Dynamic Lateral and Di- rectional Stability. Ad- verse/Proverse Yaw.	х	Data may be acquired by using an inertial measurement system and a synchronized video of the calibrated helicopter instruments, the force/position measurements of flight deck controls.	

BEGIN INFORMATION

18. VISUAL DISPLAY SYSTEMS.

- a. Basic principles of a FFS collimated display:
- (1) The essential feature of a collimated display is that light rays coming from a given point in a picture are parallel. There are two main implications of the parallel rays:
- (a) The viewer's eyes focus at infinity and have zero convergence, providing a cue that the object is distant; and
- (b) The angle to any given point in the picture does not change when viewed from a different position so the object behaves geometrically as though it were located at a significant distance from the viewer. These cues are self-consistent, and are appropriate for any object that has been modeled as being at a significant distance from the viewer.
- (2) In an ideal situation the rays are perfectly parallel, but most implementations provide only an approximation to the ideal. Typically, an FFS display provides an image located not closer than about 20–33 ft (6–10 m) from the viewer, with the distance varying over the field-of-view. A schematic representation of a collimated display is provided in Figure C2A.
- (3) Collimated displays are well suited to many simulation applications as the area of interest is relatively distant from the observer so the angles to objects should remain independent of viewing position. Consider the view of the runway seen by the flight crew lined up on an approach. In the real world, the runway is distant and the light rays from the runway to the eyes are parallel. The runway appears to be straight ahead to both crew members. This situation is well simulated by a collimated display and is presented in Figure C2B. Note that the distance to the runway has been shortened for clarity. If drawn to scale, the runway would be farther away and the rays from the two seats would be closer to being parallel.
- (4) While the horizontal field-of-view of a collimated display can be extended to approximately 210°-220°, the vertical field-of-

- view has been limited to about $40^\circ-45^\circ$. These limitations result from tradeoffs in optical quality and interference between the display components and flight deck structures, but were sufficient to meet FFS regulatory approval for Helicopter FFSs. However, recent designs have been introduced with vertical fields of view of up to 60° for helicopter applications.
- b. Basic principles of a FFS dome (or non-collimated) display:
- (1) The situation in a dome display is shown in Figure C2C. As the angles can be correct for only one eye point at a time, the visual system in the figure has been aligned for the right seat eye point position. The runway appears to be straight ahead of the aircraft for this viewer. For the left seat viewer, however, the runway appears to be somewhat to the right of the aircraft. As the aircraft is still moving towards the runway, the perceived velocity vector will be directed towards the runway and this will be interpreted as the aircraft having some yaw offset.
- (2) The situation is substantially different for near field objects encountered in helicopter operations close to the ground. In those cases, objects that should be interpreted as being close to the viewer will be misinterpreted as being distant in a collimated display. The errors can actually be reduced in a dome display.
- (3) The field-of-view possible with a dome display can be larger than that of a collimated display. Depending on the configuration, a field-of-view of 240° by 90° is possible and can be exceeded.

c. Additional display considerations

(1) While the situations described above are for discrete viewing positions, the same arguments can be extended to moving eye points produced by the viewer's head movement. In the real world, the parallax effects resulting from head movement provide distance cues. The effect is particularly strong for relative movement of flight deck structure in the near field and modeled objects in the distance. Collimated displays will provide accurate parallax cues for distant objects, but increasingly inaccurate cues for

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. C

near field objects. The situation is reversed for dome displays. $\,$

(2) Stereopsis cues resulting from the different images presented to each eye for objects relatively close to the viewer also provide depth cues. Again, the collimated and dome displays provide more or less accurate cues depending on the modeled distance of the objects being viewed.

d. Training implications

(1) In view of the basic principles described above, it is clear that neither display ap-

proach provides a completely accurate image for all possible object distances. The sponsor should consider the training role of the FFS when configuring the display system to make the optimum choice. Factors that should be considered include relative importance of training tasks at low altitudes, the role of the two crew members in the flying tasks, and the field-of-view required for specific training tasks.

Plan Views of Collimated and Dome (or Non-collimated) Visual Display Systems

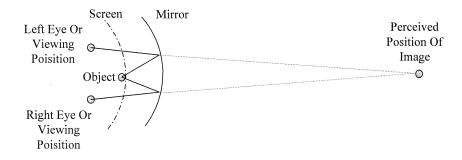


Figure C2I - Collimated display

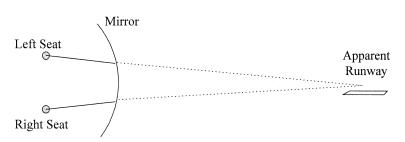


Figure C2J - Runway view in a collimated display

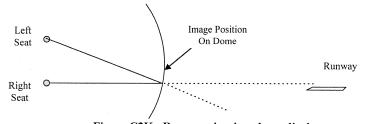


Figure C2K - Runway view in a dome display

End Information

ATTACHMENT 3 TO APPENDIX C TO PART 60— SIMULATOR SUBJECTIVE EVALUATION

BEGIN QPS REQUIREMENTS

1. Requirements

a. Except for special use airport models, all airport models required by this part must be

representations of real-world, operational airports or representations of fictional airports and must meet the requirements set out in Tables C3B or C3C of this attachment, as appropriate.

b. If fictional airports are used, the sponsor must ensure that navigational aids and all appropriate maps, charts, and other navigational reference material for the fictional

airports (and surrounding areas as necessary) are compatible, complete, and accurate with respect to the visual presentation and airport model of this fictional airport. An SOC must be submitted that addresses navigation aid installation and performance and other criteria (including obstruction clearance protection) for all instrument approaches to the fictional airports that are available in the simulator. The SOC must reference and account for information in the terminal instrument procedures manual and the construction and availability of the required maps, charts, and other navigational material. This material must be clearly marked "for training purposes only."

- c. When the simulator is being used by an instructor or evaluator for purposes of training, checking, or testing under this chapter, only airport models classified as Class I, Class II, or Class III may be used by the instructor or evaluator. Detailed descriptions/definitions of these classifications are found in Appendix F of this part.
- d. When a person sponsors an FFS maintained by a person other than a U.S. certificate holder, the sponsor is accountable for that FFS originally meeting, and continuing to meet, the criteria under which it was originally qualified and the appropriate Part 60 criteria, including the visual scenes and airport models that may be used by instructors or evaluators for purposes of training, checking, or testing under this chapter.
- e. Neither Class II nor Class III airport visual models are required to appear on the SOQ, and the method used for keeping instructors and evaluators apprised of the airport models that meet Class II or Class III requirements on any given simulator is at the option of the sponsor, but the method used must be available for review by the TPAA.
- f. When an airport model represents a real world airport and a permanent change is made to that real world airport (e.g., a new runway, an extended taxiway, a new lighting system, a runway closure) without a written extension grant from the responsible Flight Standards office (described in paragraph 1.g., of this section), an update to that airport model must be made in accordance with the following time limits:
- (1) For a new airport runway, a runway extension, a new airport taxiway, a taxiway extension, or a runway/taxiway closure—within 90 days of the opening for use of the new airport runway, runway extension, new airport taxiway, or taxiway extension; or within 90 days of the closure of the runway or taxiway.
- (2) For a new or modified approach light system—within 45 days of the activation of the new or modified approach light system.
- (3) For other facility or structural changes on the airport (e.g., new terminal, relocation of Air Traffic Control Tower)—within 180

days of the opening of the new or changed facility or structure.

g. If a sponsor desires an extension to the time limit for an update to a visual scene or airport model or has an objection to what must be updated in the specific airport model requirement, the sponsor must provide a written extension request to the responsible Flight Standards office stating the reason for the update delay and a proposed completion date or provide an explanation for the objection, explaining why the identified airport change will not have an impact on flight training, testing, or checking. A copy of this request or objection must also be sent to the POI/TCPM. The responsible Flight Standards office will send the official response to the sponsor and a copy to the POI/TCPM; however, if there is an objection, after consultation with the appropriate POI/ TCPM regarding the training, testing, or checking impact, the responsible Flight Standards office will send the official response to the sponsor and a copy to the POI/ TCPM.

END QPS REQUIREMENTS

BEGIN INFORMATION

2. Discussion

- a. The subjective tests provide a basis for evaluating the capability of the simulator to perform over a typical utilization period; determining that the simulator competently simulates each required maneuver, procedure, or task; and verifying correct operation of the simulator controls, instruments, and systems. The items listed in the following Tables are for simulator evaluation purposes only. They may not be used to limit or exceed the authorizations for use of a given level of simulator as described on the SOQ or as approved by the TPAA. All items in the following paragraphs are subject to an examination.
- b. The tests in Table C3A, Operations Tasks, in this attachment address pilot functions, including maneuvers and procedures (called flight tasks), and are divided by flight phases. The performance of these tasks by the responsible Flight Standards office includes an operational examination of the visual system and special effects. There are flight tasks included to address some features of advanced technology helicopters and innovative training programs.
- c. The tests in Table C3A, Operations Tasks, and Table C3G, Instructor Operating Station, in this attachment address the overall function and control of the simulator including the various simulated environmental conditions; simulated helicopter system operation (normal, abnormal, and emergency); visual system displays; and special effects

- d. All simulated helicopter systems functions will be assessed for normal and, where appropriate. alternate operations. Normal, abnormal, and emergency operations associated with a flight phase will be assessed during the evaluation of flight tasks or events within that flight phase. Simulated helicopter systems are listed separately under 'Any Flight Phase' to ensure appropriate attention to systems checks. Operational navigation systems (including inertial navigation systems, global positioning systems, or other long-range systems) and the associated electronic display systems will be evaluated if installed. The pilot will include in his report to the TPAA, the effect of the system operation and any system limitation.
- e. Simulators demonstrating a satisfactory circling approach will be qualified for the circling approach maneuver and may be approved for such use by the TPAA in the sponsor's FAA-approved flight training program. To be considered satisfactory, the circling approach will be flown at maximum gross weight for landing, with minimum visibility for the helicopter approach category, and must allow proper alignment with a landing runway at least 90° different from the instrument approach course while allowing the pilot to keep an identifiable portion of the airport in sight throughout the maneuver (reference—14 CFR 91.175(e)).
- f. At the request of the TPAA, the Pilot may assess the simulator for a special aspect of a sponsor's training program during the functions and subjective portion of an evaluation. Such an assessment may include a portion of a Line Oriented Flight Training (LOFT) scenario or special emphasis items in the sponsor's training program. Unless directly related to a requirement for the qualification level, the results of such an evaluation would not affect the qualification of the simulator.
- g. This appendix addresses helicopter simulators at Levels B, C, and D because there are no Level A Helicopter simulators.
- h. The FAA intends to allow the use of Class III airport models on a limited basis when the sponsor provides the TPAA (or other regulatory authority) an appropriate analysis of the skills, knowledge, and abilities (SKAs) necessary for competent performance of the tasks in which this particular media element is used. The analysis should describe the ability of the FFS/visual media to provide an adequate environment in which the required SKAs are satisfactorily performed and learned. The analysis should also include the specific media element, such as the visual scene or airport model.
- i. The TPAA may accept Class III airport models without individual observation provided the sponsor provides the TPAA with an

- acceptable description of the process for determining the acceptability of a specific airport model, outlines the conditions under which such an airport model may be used, and adequately describes what restrictions will be applied to each resulting airport or landing area model. Examples of situations that may warrant Class III model designation by the TPAA include the following:
- (a) Training, testing, or checking on very low visibility operations, including SMGCS operations.
- (b) Instrument operations training (including instrument takeoff, departure, arrival, approach, and missed approach training, testing, or checking) using—
- (i) A specific model that has been geographically "moved" to a different location and aligned with an instrument procedure for another airport.
- (ii) A model that does not match changes made at the real-world airport (or landing area for helicopters) being modeled.
- (iii) A model generated with an "off-board" or an "on-board" model development tool (by providing proper latitude/longitude reference; correct runway or landing area orientation, length, width, marking, and lighting information; and appropriate adjacent taxiway location) to generate a facsimile of a real world airport or landing area.
- j. Previously qualified simulators with certain early generation Computer Generated Image (CGI) visual systems, are limited by the capability of the Image Generator or the display system used. These systems are:
- (1) Early CGI visual systems that are exempt from the necessity of including runway numbers as a part of the specific runway marking requirements are:
 - (a) Link NVS and DNVS.
 - (b) Novoview 2500 and 6000.
- (c) FlightSafety VITAL series up to, and including, VITAL III, but not beyond.
- (d) Redifusion SP1, SP1T, and SP2.
- (2) Early CGI visual systems are excepted from the necessity of including runway numbers unless the runway is used for LOFT training sessions. These LOFT airport models require runway numbers, but only for the specific runway end (one direction) used in the LOFT session. The systems required to display runway numbers only for LOFT scenes are:
 - (a) FlightSafety VITAL IV.
 - (b) Redifusion SP3 and SP3T.
 - (c) Link-Miles Image II.
- (3) The following list of previously qualified CGI and display systems are incapable of generating blue lights. These systems are not required to have accurate taxi-way edge lighting are:
 - (a) Redifusion SP1 and SP1T.
- (b) FlightSafety Vital IV.
- (c) Link-Miles Image II and Image IIT
- (d) XKD displays (even though the XKD image generator is capable of generating

blue colored lights, the display cannot accommodate that color). $\,$

END INFORMATION

	QPS requirements				
Entry No.	Operations tasks		nulat level	or	
	·	В	С	D	
List or the level of sir	subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ of mulator qualification involved. Items not installed or not functional on the simulator and, there Configuration List, are not required to be listed as exceptions on the SOQ.				
1. Preparation for Flig					
1.a	Flight deck check: Switches, indicators, systems, and equipment	Х	Х	X	
2. APU/Engine start a	nd run-up				
2.a	Normal start procedures	Х	Х	X	
2.b	Alternate start procedures	Х	Х	X	
2.c	Abnormal starts and shutdowns (e.g., hot start, hung start)	Х	Х	X	
2.d	Rotor engagement	Х	Х	X	
2.e	System checks	Χ	Χ	X	
3. Taxiing—Ground				_	
3.a	Power required to taxi	Х	Х	X	
3.b	Brake effectiveness	Х	Х	X	
3.c	Ground handling	Х	Х	X	
3.d	Water handling (if applicable)		Х	Х	
3.e	Abnormal/emergency procedures:				
3.e.1	Brake system failure	Х	х	Х	
3.e.2	Ground resonance		х	Х	
3.e.3	Dynamic rollover		х	X	
3.e.4	Deployment of emergency floats/water landing		х	X	
3.e.5	Others listed on the SOQ	Α	х	Х	
4. Taxiing—Hover					
4.a	Takeoff to a hover	Х	х	Х	
4.b	Instrument response:				
4.b.1	Engine instruments	Х	Х	Х	
4.b.2	Flight instruments	Х	Х	X	
4.b.3	Hovering turns	Х	Х	X	
4.c	Hover power checks:		1		
4.c.1	In ground effect (IGE)	Х	Х	Х	
4.c.2	Out of ground effect (OGE)	Х	Х	X	
4.d	Crosswind/tailwind hover	Х	Х	X	
4.e	Translating tendency	X	X	Χ	

	QPS requirements			
Entry No.	Operations tasks		nulate level	or
		В	С	D
4.f.1	Hookup		Х	Х
4.f.2	Release		Х	X
4.f.3	Winch operations		Х	Х
4.g	Abnormal/emergency procedures:			
4.g.1	Engine failure	х	Х	Х
4.g.2	Fuel governing system failure	х	Х	Х
4.g.3	Settling with power (OGE)	Х	Х	Х
4.g.4	Hovering autorotation		Х	Х
4.g.5	Stability augmentation system failure	х	Х	Х
4.g.6	Directional control malfunction	х	Х	Х
4.g.7	Loss of tail rotor effectiveness (LTE)		х	х
4.g.8	Others listed on the SOQ	Α	Х	Х
4.h	Pre-takeoff checks	х	х	Х
5. Takeoff/Translation	al Flight			
5.a	Forward (up to effective translational lift)		Х	Х
5.b	Sideward (up to limiting airspeed)		х	Х
5.c	Rearward (up to limiting airspeed)		Х	Х
6. Takeoff and Depart	ure Phase			
6.a	Normal	х	х	Х
6.a.1	From ground	х	х	х
6.a.2	From hover	х	Х	Х
6.a.2.a	Cat A	х	х	Х
6.a.2.b	Cat B	х	х	Х
6.a.3	Running	х	х	Х
6.a.4	Crosswind/tailwind	х	х	Х
6.a.5	Maximum performance	х	х	Х
6.a.6	Instrument	х	х	Х
6.a.7	Takeoff from a confined area	х	х	Х
6.a.8	Takeoff from a pinnacle/platform	х	Х	Х
6.a.9	Takeoff from a slope	х	Х	Х
6.a.10	External load operations		Х	Х
6.b	Abnormal/emergency procedures:	Х	Х	Х
6.b.1	Takeoff with engine failure after critical decision point (CDP)	Х	Х	Х
6.b.1.a	Cat A		х	X
6.b.1.b	Cat B		х	X
-			Ь	Щ_

Fata Na	Occupiose tests		Simulator level		
Entry No.	Operations tasks	В	С	[
6.c	Rejected takeoff			T	
6.c.1	Land	Х	Х)	
6.c.2	Water (if appropriate)	Х	Х	1	
6.d	Instrument departure	Х	Х	:	
6.e	Others as listed on the SOQ	Α	Х		
7. Climb					
7.a	Normal	Х	Х		
7.b	Obstacle clearance	Х	Х		
7.c	Vertical		Х		
7.d	One engine inoperative	Х	Х		
7.e	Others as listed on the SOQ	Α	Х		
8. Cruise					
3.a	Performance	Х	Х	T	
3.b	Flying qualities	Х	Х	T	
3.c	Turns	Х	Х	Ì	
3.c.1	Timed	Х	Х	T	
3.c.2	Normal	Х	Х	l	
8.c.3	Steep	Х	Х		
8.d	Accelerations and decelerations	Х	Х		
8.e	High speed vibrations	Х	Х		
8.f	External Load Operations (see entry 4.f. of this table)		Х		
8.g	Abnormal/emergency procedures	Х	Х		
8.g.1	Engine fire	Х	Х	T	
3.g.2	Engine failure	Х	Х	T	
8.g.3	Inflight engine shutdown and restart	Х	Х		
3.g.4	Fuel governing system failures	Х	Х		
3.g.5	Directional control malfunction	Х	Х	T	
8.g.6	Hydraulic failure	Х	Х	ı	
8.g.7	Stability system failure	Х	Х	l	
8.g.8	Rotor vibrations	Х	Х		
8.g.9	Recovery from unusual attitudes	Х	Х	t	
9. Descent			-	_	
9.a	Normal	Х	Х	I	
9.b	Maximum rate	Х	Х	l	
9.c	Autorotative			t	

Entry No.	Operations tasks		Simulato level	
Lifting 140.	Operations tasks	В	С	Е
9.c.1	Straight-in	х	х	×
9.c.2	With turn	х	х	X
9.d	External Load		х	×
10. Approach				-
10.a	Non-precision	х	Х	>
10.a.1	All engines operating	х	х	>
10.a.2	One or more engines inoperative	х	х	>
10.a.3	Approach procedures:	х	х	>
10.a.3.a	NDB	х	х	×
10.a.3.b	VOR, RNAV, TACAN	х	х	>
10.a.3.c	ASR	х	х	>
10.a.3.d	Circling	х	х	>
10.a.3.e	Helicopter only	х	х	>
10.a.4	Missed approach	х	х	>
10.a.4.a	All engines operating	х	Х	>
10.a.4.b	One or more engines inoperative	х	х	>
10.b	Precision	х	х	X
10.b.1	All engines operating	х	Х	>
10.b.2	Manually controlled—one or more engines inoperative	х	х	>
10.b.3	Approach procedures:	х	х	×
10.b.3.a	PAR	х	х	>
10.b.3.b	MLS	х	х	>
10.b.3.c	ILS	х	х	>
10.b.3.c	(1) Manual (raw data)	х	х	>
10.b.3.c	(2) Flight director only	х	х	>
10.b.3.c	(3) Autopilot* only	х	х	>
10.b.3.c	(4) Cat I	х	х	>
10.b.3.c	(5) Cat II	х	х	>
10.b.4	Missed approach:			
10.b.4.a	All engines operating	Х	Х	>
10.b.4.b	One or more engines inoperative	х	Х	>
10.b.4.c	Stability system failure	Х	Х	>
10.c	Others as listed on the SOQ	Α	х	>

11.a. Visual Approaches:

TABLE C3A—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS requirements			
Entry No.	Operations tasks		nulat level	or
		В	С	D
11.a.1	Normal	Х	Х	Х
11.a.2	Steep	Х	Х	X
11.a.3	Shallow	Х	Х	Х
11.a.4	Crosswind	Х	Х	Х
11.a.5	Category A profile		Х	Х
11.a.6	Category B profile		Х	Х
11.a.7	External Load		Х	Х
11.b	Abnormal/emergency procedures:			
11.b.1	Directional control failure	х	Х	х
11.b.2	Hydraulics failure	Х	Х	х
11.b.3	Fuel governing failure	х	х	х
11.b.4	Autorotation	Х	Х	х
11.b.5	Stability system failure	х	Х	х
11.b.6	Others listed on the SOQ	Α	Х	х
11c	Landings:			
11.c.1	Normal:			
11.c.1.a	Running	Х	Х	Х
11.c.1.b	From Hover	Х	Х	х
11.c.2	Pinnacle/platform	х	х	х
11.c.3	Confined area	Х	X	х
11.c.4	Slope		Х	х
11.c.5	Crosswind	х	х	х
11.c.6	Tailwind	х	Х	х
11.c.7	Rejected Landing	х	Х	х
11.c.8	Abnormal/emergency procedures:			
11.c.8.a	From autorotation		х	х
11.c.8.b	One or more engines inoperative	х	Х	х
11.c.8.c	Directional control failure	Х	Х	Х
11.c.8.d	Hydraulics failure	Х	Х	х
11.c.8.e	Stability augmentation system failure	Х	Х	х
11.c.9	Other (listed on the SOQ)	Α	Х	х
12. Any Flight Phase				
12.a.1	Air conditioning	Х	Х	Х
12.a.2	Anti-icing/deicing	Х	Х	Х
12.a.3	Auxiliary power-plant	Х	Х	Х

	QPS requirements			
Entry No.	Operations tasks		nulate level	or
		В	С	D
12.a.4	Communications	Х	Х	X
12.a.5	Electrical	Х	Х	Х
12.a.6	Fire detection and suppression	Х	Х	Х
12.a.7	Stabilizer	Х	Х	Х
12.a.8	Flight controls	х	х	х
12.a.9	Fuel and oil	х	Х	Х
12.a.10	Hydraulic	х	х	Х
12.a.11	Landing gear	Х	х	х
12.a.12	Oxygen	х	х	х
12.a.13	Pneumatic	х	х	х
12.a.14	Powerplant	х	х	х
12.a.15	Flight control computers	х	х	х
12.a.16	Stability and control augmentation	Х	х	х
12.b	Flight management and guidance system:	•		
12.b.1	Airborne radar	х	х	х
12.b.2	Automatic landing aids	х	х	х
12.b.3	Autopilot	х	х	х
12.b.4	Collision avoidance system	Х	х	х
12.b.5	Flight data displays	х	х	х
12.b.6	Flight management computers	Х	х	х
12.b.7	Heads-up displays	х	Х	Х
12.b.8	Navigation systems	х	х	X
12.c	Airborne procedures:	•		
12.c.1	Holding	х	х	х
12.c.2	Air hazard avoidance	Х	х	х
12.c.3	Retreating blade stall recovery	х	х	х
12.c.4	Mast bumping	х	х	х
12.c.5	Loss of directional control	х	х	х
12.c.6	Loss of tail rotor effectiveness		х	х
12.c.7	Other (listed on the SOQ)	Α	х	х
13. Engine Shutdown	and Parking			
13.a	Engine and systems operation	Х	Х	Х
13.b	Parking brake operation	х	Х	Х
13.c	Rotor brake operation	Х	Х	Х

QPS requirements							
Entry No.	Operations tasks		nulate evel	or			
,			С	D			
13.d	Abnormal/emergency procedures	х	Х	X			

^{*&}quot;Autopilot" means attitude retention mode of operation.

Note: An "A" in the table indicates that the system, task, or procedure may be examined if the appropriate aircraft system or

	QPS requirements				
	Visual requirements for qualification at the stated level		nulatoi evel	r	
Entry No.	class I airport or landing area models	В		D	
table appl	pecifies the minimum airport visual model content and functionality to qualify a simulator at the indicate lies only to the airport scenes required for simulator qualification; i.e., two helicopter landing area models; four helicopter landing area models for Level C and Level D simulators.				
1	Functional test content requirements The following is the minimum airport/landing area model content requirement to satisfy visual capabilit provides suitable visual cues to allow completion of all functions and subjective tests described in this for simulators at Level B.				
1.a	A minimum of one (1) representative airport and one (1) representative helicopter landing area model. The airport and the helicopter landing area may be contained within the same model. If but if this option is selected, the approach path to the airport runway(s) and the approach path to the helicopter landing area must be different. The model(s) used to meet the following requirements may be demonstrated at either a fictional or a real-world airport or helicopter landing area, but each must be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.	х			
1.b					
1.c	Runways:				
1.c.1	Visible runway number	х			
1.c.2	Runway threshold elevations and locations must be modeled to provide sufficient correlation with helicopter systems (e.g., altimeter).	х			
1.c.3	Runway surface and markings	х			
1.c.4	Lighting for the runway in use including runway edge and centerline	х			
1.c.5	Lighting, visual approach aid (VASI or PAPI) and approach lighting of appropriate colors	х			
1.c.6	Representative taxiway lights	х			
1.d	Other helicopter landing area:	•			
1.d.1	Standard heliport designation ("H") marking, properly sized and oriented	Х			
1.d.2	Perimeter markings for the Touchdown and Lift-Off Area (TLOF) or the Final Approach and Takeoff Area (FATO), as appropriate.	х			
1.d.3	Perimeter lighting for the TLOF or the FATO areas, as appropriate	Х			
1.d.4	Appropriate markings and lighting to allow movement from the runway or helicopter landing area to another part of the landing facility.	х			
	<u> </u>				

	QPS requirements			
Entry No.	Visual requirements for qualification at the stated level class I airport or landing area models		nulate evel	or
	The following is the minimum airport/landing area model content requirement to satisfy visual capability provide suitable visual cues to allow completion of all functions and subjective tests described in this section must be found airport/landing area scene. However, all of the elements described in this section must be found airport/landing area scene. However, all of the elements described in this section must be found throub bination of the four (4) airport/landing area models described in entry 2.a. The representations of the loscribed in 2.d.) must be "hard objects" that interact as such if contacted by the simulated helicopte	attach I in a s ughout hazar r. Add	men single a co ds (a lition	t e om- is ally,
	surfaces on which the helicopter lands must be "hard surfaces." The model(s) used to meet the follow ments must be demonstrated at either a fictional or a real-world airport or helicopter landing area, and be acceptable to the sponsor's TPAA, selectable from the IOS, and listed on the SOQ.	ving re d each	equir mu	e- st
2.a	There must be at least the following airport/helicopter landing areas.			
2.a.1	At least one (1) representative airport		Χ	Х
2.a.2	At least three representative non-airport landing areas, as follows:			
2.a.2.a	At least one (1) representative helicopter landing area situated on a substantially elevated surface with respect to the surrounding structures or terrain (e.g., building top, offshore oil rig).		Х	х
2.a.2.b	At least one (1) helicopter landing area that meets the definition of a "confined landing area"		Χ	Х
2.a.2.c	At least one (1) helicopter landing area on a sloped surface where the slope is at least 21/2°		Χ	Х
2.b	For each of the airport/helicopter landing areas described in 2.a., the simulator must be able to provide at least the following:		Х	х
2.b.1	A night and twilight (dusk) environment.		Χ	Х
2.b.2	A daylight environment			х
2.c	Non-airport helicopter landing areas must have the following:			
2.c.1	Representative buildings, structures, and lighting within appropriate distances		Χ	Х
2.c.2	Representative moving and static clutter (e.g., other aircraft, power carts, tugs, fuel trucks)		Х	х
2.c.3	Representative depiction of terrain and obstacles as well as significant and identifiable natural and cultural features, within 25 NM of the reference landing area.		Х	Х
2.c.4	Standard heliport designation ("H") marking, properly sized and oriented		Х	х
2.c.5	Perimeter markings for the Touchdown and Lift-Off Area (TLOF) or the Final Approach and Takeoff Area (FATO), as appropriate.		Х	Х
2.c.6	Perimeter lighting for the TLOF or the FATO areas, as appropriate		Х	Х
2.c.7	Appropriate markings and lighting to allow movement from the area to another part of the landing facility, if appropriate.		Х	х
2.c.8	Representative markings, lighting, and signage, including a windsock that gives appropriate wind cues.		Х	Х
2.c.9	Appropriate markings, lighting, and signage necessary for position identification, and to allow movement from the landing area to another part of the landing facility.		Х	х
2.c.10	Representative moving and static ground traffic (e.g., vehicular and aircraft), including the ability to present surface hazards (e.g., conflicting traffic, vehicular or aircraft, on or approaching the landing area).		Х	х
2.c.11	Portrayal of landing surface contaminants, including lighting reflections when wet and partially obscured lights when snow is present, or suitable alternative effects.		Х	Х
2.d	All of the following three (3) hazards must be presented in a combination of the three (3) non-airport I (described in entry 2.a.2. of this table) and each of these non-airport landing areas must have at least following hazards:			
2.d.1	Other airborne traffic		Х	Х

Entry No.	Visual requirements for qualification at the stated level class I airport or landing area models		nulat level C		
2.d.2	Buildings, trees, or other vertical obstructions in the immediate landing area		х	X	
2.d.3	Suspended wires in the immediate landing area		Х	X	
2.e	Airport applications. Each airport must have the following:		_^		
				Ι.,	
2.e.1	At least one runway designated as "in-use", appropriately marked and capable of being lighted fully		Х	×	
2.e.2	Runway threshold elevations and locations must be modeled to provide sufficient correlation with helicopter systems (e.g., HGS, GPS, altimeter). Slopes in runways, taxiways, and ramp areas, if depicted in the visual scene, may not cause distracting or unrealistic effects, including pilot eye- point height variation.	Х	Х	×	
2.e.3	Appropriate approach lighting systems and airfield lighting for a VFR circuit and landing, non-precision approaches and landings, and precision approaches and landings, as appropriate		Х	×	
2.e.4	Representative taxiway lights			×	
3	Airport or landing area model management The following is the minimum visual scene management requirements	•	•	•	
3.a	Runway and helicopter landing area approach lighting must fade into view in accordance with the environmental conditions set in the simulator.	Х	Х	X	
3.b	The direction of strobe lights, approach lights, runway edge lights, visual landing aids, runway centerline lights, threshold lights, touchdown zone lights, and TLOF or FATO lights must be replicated.				
4	NO. 16				
	Visual feature recognition. The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing	ding	area	on	
	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a	ding	area	on e	
	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8)	ding pply	area to the	on >	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold.	ding pply	area to the	on >	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km)	ding pply	area to the	on ×	
4.a	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter land an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km)	ding pply	area to the	on x	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km)	x X	X X	on ×	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km) For runways: Visual Approach Aid lights (VASI or PAPI) from 3 sm (5 km) of the threshold For runways: Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold For runways: Runway threshold lights and touchdown zone lights from 2 sm (3 km) For runways and helicopter landing areas: Markings within range of landing lights for night/twilight	X X X	X X X	on ×	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter lan an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests a runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km)	x x x x x	X X X X X	on ×	
4.b	The following are the minimum distances at which runway features must be visible. Distances are me runway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter land an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests as runway used for the initial approach and to the runway of intended landing For runways: Runway definition, strobe lights, approach lights, and runway edge lights from 5 sm (8 km) of the runway threshold. For runways: Centerline lights and taxiway definition from 3 sm (5 km)	X X X X	X X X X X X	on	

	QPS requirements	Simulato			
Entry No.	Visual requirements for qualification at the stated level class I airport or landing area models		evel	UI .	
	olass i aliport of latituding area models	В	С	D	
	The following prescribes the minimum requirements for an airport/helicopter landing area model and it aspects of the environment that must correspond with that model for simulators at Level B, Level C, a For circling approaches, all tests apply to the runway used for the initial approach and to the runway landing. If all runways or landing areas in a visual model used to meet the requirements of this attach designated as "in use," then the "in use" runways/landing areas must be listed on the SOQ (e.g., KO 9R, 14L, 22R). Models of airports or helicopter landing areas with more than one runway or landing area not "in-use" visually depicted for airport runway/landing attached it is a superior to the second of the surface of the second of the surface depictions are acceptable for this requirement; and rectangular surface depictions are acceptable for scenes. A visual system's capabilities must be balanced between providing visual models with an accresentation of the airport and a realistic representation of the surrounding environment. Each runway landing area designated as an "in-use" runway or area must include the following detail that is develor airport pictures, construction drawings and maps, or other similar data, or developed in accordance we regulatory material; however, this does not require that such models contain details that are beyond the pability of the currently qualified visual system. Only one "primary" taxi route from parking to the runw helicopter takeoff/landing area will be required for each "in-use" runway or helicopter takeoff/landing area.	ind Lof interpretation of interpretation of the pretation	evel ender are Rwys nust recog and ylight rep- licop using ublish	D. d not s gni-ter l ned ca-	
5.a	The surface and markings for each "in-use" runway or helicopter landing area must include the follow	ing:			
5.a.1	For airports: Runway threshold markings, runway numbers, touchdown zone markings, fixed distance markings, runway edge markings, and runway centerline stripes.	Х	Х	Х	
5.a.2	For helicopter landing areas: Markings for standard heliport identification ("H") and TOFL, FATO, and safety areas.	Х	Х	х	
5.b	The lighting for each "in-use" runway or helicopter landing area must include the following:				
5.b.1	For airports: Runway approach, threshold, edge, end, centerline (if applicable), touchdown zone (if applicable), leadoff, and visual landing aid lights or light systems for that runway.	Х	Х	х	
5.b.2	For helicopter landing areas: landing direction, raised and flush FATO, TOFL, windsock lighting	Х	Х	х	
5.c	The taxiway surface and markings associated with each "in-use" runway or helicopter landing area m the following:	ust ir	clud	е	
5.c.1	For airports: Taxiway edge, centerline (if appropriate), runway hold lines, and ILS critical area(s)	Х	Х	х	
5.c.2	For helicopter landing areas: taxiways, taxi routes, and aprons	Х	Х	х	
5.d	The taxiway lighting associated with each "in-use" runway or helicopter landing area must include the	follo	wing	:	
5.d.1	For airports: Runway edge, centerline (if appropriate), runway hold lines, ILS critical areas	Х	Х	х	
5.d.2	For helicopter landing areas: taxiways, taxi routes, and aprons	Х	Х	х	
5.d.3	For airports: taxiway lighting of correct color			х	
5.e	Airport signage associated with each "in-use" runway or helicopter landing area must include the followed	wing	:		
5.e.1	For airports: Signs for runway distance remaining, intersecting runway with taxiway, and intersecting taxiway with taxiway.	Х	Х	Х	
5.e.2	For helicopter landing areas: as appropriate for the model used	Х	Х	х	
5.f	Required visual model correlation with other aspects of the airport or helicopter landing environment s	imula	ation:		
5.f.1	The airport or helicopter landing area model must be properly aligned with the navigational aids that are associated with operations at the "in-use" runway or helicopter landing area.	Х	Х	Х	
5.f.2	The simulation of runway or helicopter landing area contaminants must be correlated with the displayed runway surface and lighting where applicable.		Х	х	
6	Correlation with helicopter and associated equipment The following are the minimum correlation comparisons that must be made for simulators at Level B, Level D	Level	С, а	ınd	
6.a	Visual system compatibility with aerodynamic programming	Х	Х	Х	

	QPS requirements					
Entry No.	Visual requirements for qualification at the stated level class I airport or landing area models					
	olace i aliperi of latitaling aloa modele	В	С	D		
6.b	Visual cues to assess sink rate and depth perception during landings	х	Х	Х		
6.c	Accurate portrayal of environment relating to flight simulator attitudes	х	х	Х		
6.d	The visual scene must correlate with integrated helicopter systems (e.g., terrain, traffic and weather avoidance systems and Head-up Guidance System (HGS)).		Х	Х		
6.e	Representative visual effects for each visible, own-ship, helicopter external light(s)—taxi and landing light lobes (including independent operation, if appropriate).	х	Х	х		
6.f	The effect of rain removal devices		Х	Х		
7			C, a	nd		
7.a	Surfaces and textural cues must be free from apparent and distracting quantization (aliasing)		Х	Х		
7.b	System capable of portraying full color realistic textural cues		Х	Х		
7.c	The system light points must be free from distracting jitter, smearing or streaking	х	Х	Х		
7.d	Demonstration of occulting through each channel of the system in an operational scene	х	Х	Х		
7.e	Demonstration of a minimum of ten levels of occulting through each channel of the system in an operational scene.		Х	Х		
7.f	System capable of providing focus effects that simulate rain.		Х	Х		
7.g	System capable of providing focus effects that simulate light point perspective growth		Х	х		
7.h	Runway light controls capable of six discrete light steps (0–5)	х	х	х		
8	Environmental effects. The following are the minimum environmental effects that must be available in simulators at Level B, Level D.	Level	C, a	nd		
8.a	The displayed scene corresponding to the appropriate surface contaminants and include appropriate lighting reflections for wet, partially obscured lights for snow, or alternative effects.			Х		
8.b	Special weather representations which include:					
8.b.1	The sound, motion and visual effects of light, medium and heavy precipitation near a thunderstorm on take-off, approach, and landings at and below an altitude of 2,000 ft (600 m) above the surface and within a radius of 10 sm (16 km) from the airport or helicopter landing area.			х		
8.b.2	One airport or helicopter landing area with a snow scene to include terrain snow and snow-covered surfaces.			Х		
8.c	In-cloud effects such as variable cloud density, speed cues and ambient changes		х	х		
8.d	The effect of multiple cloud layers representing few, scattered, broken and overcast conditions giving partial or complete obstruction of the ground scene.		Х	Х		
8.e	Visibility and RVR measured in terms of distance. Visibility/RVR checked at 2,000 ft (600 m) above the airport or helicopter landing area and at two heights below 2,000 ft with at least 500 ft of separation between the measurements. The measurements must be taken within a radius of 10 sm (16 km) from the airport or helicopter landing area.	х	X	х		
8.f	Patchy fog giving the effect of variable RVR			Х		
8.g	Effects of fog on airport lighting such as halos and defocus		Х	Х		
8.h	Effect of own-ship lighting in reduced visibility, such as reflected glare, including landing lights, strobes, and beacons.		Х	Х		
8.i	Wind cues to provide the effect of blowing snow or sand across a dry runway or taxiway selectable from the instructor station.			Х		

			nulat	or		
Entry No.	Visual requirements for qualification at the stated level class I airport or landing area models	В	evel C	С		
8.j	"White-out" or "Brown-out" effects due to rotor downwash beginning at a distance above the ground equal to the rotor diameter.			Х		
9	Instructor control of the following: The following are the minimum instructor controls that must be available in Level B, Level C, and Level tors, as indicated.	el D s	simul	a-		
9.a	Environmental effects, e.g. cloud base, cloud effects, cloud density, visibility in statute miles/ kilometers and RVR in feet/meters.	Х	Х	X		
9.b	Airport or helicopter landing area selection					
9.c	Airport or helicopter landing area lighting, including variable intensity					
9.d	Dynamic effects including ground and flight traffic					
	End QPS Requirement					
	Begin Information					
11	ignated as the "in-use" runway in the first model of the airport, and the second runway designated as runway in the second model of the same airport. For example, the clearance is for the ILS approach t 27, Circle to Land on Runway 18 right. Two airport visual models might be used: the first with Runway ignated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pmake a visual approach and landing. This process is acceptable to the FAA as long as the temporary due to the visual model change is not distracting to the pilot. Sponsors are not required to provide every detail of a runway, but the detail that is provided should be	o Ru y 27 designanç chanç oilot v inter	nway des- gnate ge to vould ruptie	/ ed the		
	within reasonable limits.	e cor	rect			
	End Information					
	TABLE C3C—FUNCTIONS AND SUBJECTIVE TESTS					
	QPS requirements					
Entry No.	Visual scene content additional airport or landing area models beyond minimum required for qualification Class II airport or landing area models	Simulator level				
	Class II all port or landing area models	В	С	D		
ual model	pecifies the minimum airport or helicopter landing area visual model content and functionality necessar s to a simulator's visual model library (i.e., beyond those necessary for qualification at the stated level of further involvement of the responsible Flight Standards office or TPAA.					
1	Airport or landing area model management The following is the minimum visual scene management requirements for simulators at Levels B, C, a	nd D				
1.a	The installation and direction of the following lights must be replicated for the "in-use" surface:					
1.a.1	For "in-use" runways: Strobe lights, approach lights, runway edge lights, visual landing aids, runway centerline lights, threshold lights, and touchdown zone lights.	Х	Х	х		
1.a.2	For "in-use" helicopter landing areas: ground level TLOF perimeter lights, elevated TLOF perimeter lights (if applicable), Optional TLOF lights (if applicable), ground FATO perimeter lights, elevated TLOF lights (if applicable), landing direction lights.	Х	Х	х		
2	Visual feature recognition The following are the minimum distances at which runway or landing area features must be visible for Levels B, C, and D. Distances are measured from runway threshold or a helicopter landing area to an aligned with the runway or helicopter landing area on a 3° glide-slope from the aircraft to the touchdow simulated meteorological conditions. For circling approaches, all tests apply to the runway used for the proach and to the runway of intended landing.	airc	raft oint, i	in		

	QPS requirements			
Entry No	Visual scene content additional airport or landing area models beyond minimum required for qualification		nulato	or
0.0	Class II airport or landing area models	В	С	D
2.a	•		· ·	
2.a.1		Х	Х	X
2.a.2	Centerline lights and taxiway definition from 3 sm (5 km)	Х	Х	X
2.a.3	Visual Approach Aid lights (VASI or PAPI) from 3 sm (5 km) of the threshold	Х		
2.a.4	Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold		Х	Х
2.a.5	Threshold lights and touchdown zone lights from 2 sm (3 km)	Х	Х	Х
2.a.6	Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolution test on daylight scenes.	х	Х	X
2.a.7	For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-distracting manner.	Х	Х	X
2.b	For Helicopter landing areas:			
2.b.1	Landing direction lights and raised FATO lights from 1 sm (1.5 km)	х	Х	X
2.b.2	Flush mounted FATO lights, TOFL lights, and the lighted windsock from 0.5 sm (750 m)		Х	Х
2.b.3	Hover taxiway lighting (yellow/blue/yellow cylinders) from TOFL area		х	Х
2.b.4	Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolution test on daylight scenes.	х	Х	Х
3	Airport or Helicopter landing area model content The following prescribes the minimum requirements for what must be provided in an airport visual mo tifies other aspects of the airport environment that must correspond with that model for simulators at I and D. The detail must be developed using airport pictures, construction drawings and maps, or other or developed in accordance with published regulatory material; however, this does not require that air copter landing area models contain details that are beyond the designed capability of the currently qu system. For circling approaches, all requirements of this section apply to the runway used for the initia and to the runway of intended landing. Only one "primary" taxi route from parking to the runway end takeoff/landing area will be required for each "in-use" runway or helicopter takeoff/landing area.	evel simil port o alified al app	B, C, lar da or heli d visu oroacl	ita, i- ial h
3.a	The surface and markings for each "in-use" runway or helicopter landing area must include the follow	ing:		
3.a.1	For airports: Runway threshold markings, runway numbers, touchdown zone markings, fixed distance markings, runway edge markings, and runway centerline stripes.	Х	Х	Х
3.a.2	For helicopter landing areas: Standard heliport marking ("H"), TOFL, FATO, and safety areas	х	Х	X
3.b	The lighting for each "in-use" runway or helicopter landing area must include the following:			
3.b.1	For airports: Runway approach, threshold, edge, end, centerline (if applicable), touchdown zone (if applicable), leadoff, and visual landing aid lights or light systems for that runway.	Х	Х	Х
3.b.2	For helicopter landing areas: Landing direction, raised and flush FATO, TOFL, windsock lighting	х	Х	Х
3.c	The taxiway surface and markings associated with each "in-use" runway or helicopter landing area m the following:	ust in	clude)
3.c.1	For airports: Taxiway edge, centerline (if appropriate), runway hold lines, and ILS critical area(s)	х	х	X
3.c.2	For helicopter landing areas: Taxiways, taxi routes, and aprons	х	х	Х
3.d	The taxiway lighting associated with each "in-use" runway or helicopter landing area must include the	follo	wing:	_
3.d.1	For airports: Runway edge, centerline (if appropriate), runway hold lines, ILS critical areas	х	Х	X
3.d.2	For helicopter landing areas: Taxiways, taxi routes, and aprons	х	х	X
	For airports: Taxiway lighting of correct color			X
1 4				_
3.d.3 4	362			
₹ VerDate Sep<11>2014 14:00 Mar 14, 2024	Jkt 262047 PO 00000 Frm 00372 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31			

Pt. 60, App. C

TABLE C3C—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS re	quire	ments					
Entry No.		cation					nulat level	
	Class II airport or	landi	ng are	ea mod	els	В	С	D
	The following are the minimum visual model corr Level D simulators, as indicated.	relatio	n test	s that r	nust be conducted for Level B, Lev	el C,	and	
4.a	The airport model must be properly aligned with ations at the "in-use" runway.	the r	aviga	tional a	ids that are associated with oper-	х	х	х
4.b	Slopes in runways, taxiways, and ramp areas, tracting or unrealistic effects.	if dep	icted	in the v	visual scene, must not cause dis-	х	х	х
5	Correlation with helicopter and associated ed The following are the minimum correlation comp			must b	pe made for simulators at Level B,	C, ar	nd D.	
5.a Visual system compatibility with aerodynamic programming					х	Х	х	
5.b	Accurate portrayal of environment relating to flig	ht sim	ulator	attitud	es	х	х	Х
5.c	Visual cues to assess sink rate and depth perce	ption	during	landin	gs	х	х	х
6	Scene quality The following are the minimum scene quality tes	ts tha	t mus	t be co	nducted for simulators at Level B, (C, an	d D.	
6.a Light points free from distracting jitter, smearing or streaking				х	Х	Х		
6.b	6.b Surfaces and textural cues free from apparent and distracting quantization (aliasing)				ntization (aliasing)		х	х
6.c	Correct color and realistic textural cues							х
7	Instructor controls of the following: The following are the minimum instructor control tors, as indicated.	s that	must	be ava	ilable in Level B, Level C, and Lev	el D	simul	ia-
7.a	Environmental effects, e.g., cloud base (if use miles/kilometers and RVR in feet/meters.	d), cl	oud e	ffects,	cloud density, visibility in statute	х	Х	х
7.b	Airport/Heliport selection					Х	Х	Х
7.c 7.d	Airport lighting including variable intensity					X	X	X
	End QPS	Requ	ireme	ents				
	Begin	Infori	natio	1				
8	Sponsors are not required to provide every deta tail that is provided must be correct within the					х	х	х
	End li	nform	ation				-	
					_			
	TABLE C3D—FUNCTION	NS A	ND S	SUBJE	CTIVE TESTS			
	QPS requirements				Information			
Entry No.	Motion system (and special	Sim	nulato	level	Notes			
.,	aerodynamic model) effects	В	С	D				

This table specifies motion effects that are required to indicate the threshold at which a flight crewmember must be able to recognize an event or situation. Where applicable, flight simulator pitch, side loading and directional control characteristics must be representative of the helicopter.

TABLE C3D—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS requirements				Information
Entry No.	Motion system (and special	Sim	ulator	level	Notes
Entry No.	aerodynámic model) effects	В	С	D	Notes
1	Runway rumble, oleo deflection, ground speed, uneven runway, runway and taxiway centerline light characteristics: Procedure: After the helicopter has been preset to the takeoff position and then released, taxi at various speeds with a smooth runway and note the general characteristics of the simulated runway rumble effects of oleo deflections. Repeat the maneuver with a runway roughness of 50%, then with maximum roughness. Note the associated motion vibrations affected by ground speed and runway roughness	x	x	x	If time permits, different gross weights can also be selected as this may also affect the associated vibrations depending on helicopter type. The associated motion effects for the above tests should also include an assessment of the effects of rolling over centerline lights, surface discontinuities of uneven runways, and various taxiway characteristics.
2	Friction Drag from Skid-type Landing Gear: Procedure: Perform a running takeoff or a running landing and note an increase in a fuse-lage vibration (as opposed to rotor vibration) due to the friction of dragging the skid along the surface. This vibration will lessen as the ground speed decreases		x	X	
3	Rotor Out-of-Track and/or Out-of-Balance condition: Procedure: Select the malfunction or condition from the IOS. Start the engine(s) normally and check for an abnormal vibration for an Out-of-Track condition and check for an abnormal vibration for an Out-of-Balance condition	x	×	x	Does not require becoming airborne. The abnormal vibration for Out-of-Track and Out-of-Balance conditions should be recognized in the frequency range of the inverse of the period for each; i.e., 1/P for vertical vibration, and 1/P for lateral vibration.
4	Bumps associated with the landing gear: Procedure: Perform a normal take-off paying special attention to the bumps that could be perceptible due to maximum oleo extension after lift-off	x	х	х	When the landing gear is extended or re- tracted, motion bumps can be felt when the gear locks into position.
5	Buffet during extension and retraction of landing gear: Procedure: Operate the landing gear. Check that the motion cues of the buffet experienced represent the actual helicopter	х	х	Х	
6	Failure of Dynamic Vibration Absorber or similar system as appropriate for the helicopter (e.g., droop stop or static stop): Procedure: May be accomplished any time the rotor is engaged. Select the appropriate failure at the IOS, note an appropriate increase in vibration and check that the vibration intensity and frequency increases with an increase in RPM and an increase in collective application	X	X	X	
7	Tail Rotor Drive Failure: Procedure: With the engine(s) running and the rotor engaged—select the malfunction and note the immediate increase of medium frequency vibration	х	х	х	The tail rotor operates in the medium frequency range, normally estimated by multiplying the tail rotor gear box ratio by the main rotor RPM. The failure can be recognized by an increase in the vibrations in this frequency range.
8	Touchdown cues for main and nose gear: Procedure: Conduct several normal approaches with various rates of descent. Check that the motion cues for the touchdown bumps for each descent rate are representative of the actual helicopter	х	х	х	

TABLE C3D—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS requirements				Information		
Entry No.	Motion system (and special	Sim	ulator	level	Notes		
Litay 140.	aerodynamic model) effects	В	С	D	140.00		
9	Tire failure dynamics: Procedure: Simulate a single tire failure and a multiple tire failure		X	X	The pilot may notice some yawing with a multiple tire failure selected on the same side. This should require the use of the pedal to maintain control of the helicopter. Dependent on helicopter type, a single tire failure may not be noticed by the pilot and may not cause any special motion effect. Sound or vibration may be associated with the actual tire losing pressure.		
10	Engine malfunction and engine damage: Procedure: The characteristics of an engine malfunction as prescribed in the malfunction definition document for the particular flight simulator must describe the special motion effects felt by the pilot. Note the associated engine instruments varying according to the nature of the malfunction and note the rep- lication of the effects of the airframe vibra- tion	X	x	x			
11	Tail boom strikes: Procedure: Tail-strikes can be checked by over-rotation of the helicopter at a quick stop or autorotation to the ground	х	х	x	The motion effect should be felt as a notice- able nose down pitching moment.		
12	Vortex Ring State (Settling with Power): Procedure: Specific procedures may differ between helicopters and may be prescribed by the Helicopter Manufacturer or other subject matter expert. However, the following information is provided for illustrative purposes * * * To enter the maneuver, reduce power below hover power. Hold altitude with aft cyclic until the airspeed approaches 20 knots. Then allow the sink rate to increase to 300 feet per minute or more as the attitude is adjusted to obtain an airspeed of less than 10 knots		x	x	When the aircraft begins to shudder, the application of additional up collective increases the vibration and sink rate. One recovery method is to decrease collective to enter vertical autorotation and/or use cyclic inputs to gain horizontal airspeed and exit from vortex ring state.		
13	Retreating Blade Stall: Procedure: Specific procedures may differ between helicopters and may be prescribed by the Helicopter Manufacturer or other subject matter expert. However, the following information is provided for illustrative purposes: To enter the maneuver, increase forward airspeed; the effect will be recognized through the development of a low frequency vibration, pitching up of the nose, and a roll in the direction of the retreating blade. High weight, low rotor RPM, high density altitude, turbulence or steep, abrupt turns are all conducive to retreating blade stall at high forward airspeeds		x	x	Correct recovery from retreating blade stall requires the collective to be lowered first, which reduces blade angles and the angle of attack. Aft cyclic can then be used to slow the helicopter.		

14 CFR Ch. I (1-1-24 Edition)

TABLE C3D—FUNCTIONS AND SUBJECTIVE TESTS—Continued

	QPS requirements	Information			
Esta Ma	Motion system (and special	Simi	ulator I	level	Nata
Entry No.	aerodynámic model) effects	B C D		D	Notes
14	Translational Lift Effects: Procedure: From a stabilized in-ground-effect (IGE) Hover begin a forward acceleration. When passing through the effective translational lift range, the noticeable effect will be a possible nose pitch-up in some helicopters, an increase in the rate of climb, and a temporary increase in vibration level (in some cases this vibration may be pronounced). This effect is experienced again upon deceleration through the appropriate speed range. During deceleration, the pitch and rate of climb will have the reverse effect, but there will be a similar, temporary increase in vibration level	X	X	X	

TABLE C3E—FUNCTIONS AND SUBJECTIVE TESTS

	QPS Requirements								
	·								
Entry num-	Sound system	Simulator level							
ber	Sound System	В	С	D					
The following	ng checks are performed during a normal flight profile, motion system ON.			•					
1	Precipitation.		х	х					
2	Rain removal equipment.		х	х					
3	Helicopter noises used by the pilot for normal helicopter operation.		х	Х					
4	Abnormal operations for which there are associated sound cues, including engine malfunctions, landing gear or tire malfunctions, tail boom.		х	Х					
5	Sound of a crash when the flight simulator is landed in excess of limitations		Х	х					

TABLE C3F—FUNCTIONS AND SUBJECTIVE TESTS

	QPS Requirements			
Entry num-	Openial official	Simulator level		
ber			С	D
This table s	pecifies the minimum special effects necessary for the specified simulator level.			
1	Braking Dynamics: Representations of the dynamics of brake failure (flight simulator pitch, side-loading, and directional control characteristics representative of the helicopter), including antiskid and decreased brake efficiency due to high brake temperatures (based on helicopter related data), sufficient to enable pilot identification of the problem and implementation of appropriate procedures.		х	х
2	Effects of Airframe and Engine Icing: Required only for those helicopters authorized for operations in known icing conditions. Procedure: With the simulator airborne, in a clean configuration, nominal altitude and cruise airspeed, autopilot on and auto-throttles off, engine and airfoil anti-ice/de-ice systems deactivated; activate icing conditions at a rate that allows monitoring of simulator and systems response. Icing recognition will include an increase in gross weight, airspeed decay, change in simulator pitch attitude, change in engine performance indications (other than due to airspeed changes), and change in data from pitol/static system, or rotor out-of-track/balance. Activate heating, anti-ice, or de-ice systems independently. Recognition will include proper effects of these systems, eventually returning the simulated helicopter to normal flight.		x	x

TABLE C3G—FUNCTIONS AND SUBJECTIVE TESTS

	QPS Requirements				
Entry num-	Instructor Operating Station (IOS)	Simu	ılator I	evel	
ber	monator operating station (100)	В	С	D	
Functions in simulator.	this table are subject to evaluation only if appropriate for the helicopter or the system is installed	d on th	ne spe	ecific	
1	Simulator Power Switch(es)	х	х	х	
2	Helicopter conditions.				
2.a	Gross weight, center of gravity, fuel loading and allocation	х	х	х	
2.b	Helicopter systems status	х	х	х	
2.c	Ground crew functions	х	х	х	
3	Airports/Heliports.				
3.a	Number and selection	х	х	х	
3.b	Runway or landing area selection	х	х	х	
3.c	Landing surface conditions (rough, smooth, icy, wet, dry, snow)	х	х	х	
3.d	Preset positions	х	х	х	
3.e	Lighting controls	х	х	Х	
4	Environmental controls.				
4.a	Visibility (statute miles/kilometers)	х	х	х	
4.b	Runway visual range (in feet/meters)	х	х	х	
4.c	Temperature				
4.d	Climate conditions	Х	х	Х	
4.e	Wind speed and direction	Х	х	Х	
5	Helicopter system malfunctions (Insertion/deletion).	х	х	х	
6	Locks, Freezes, and Repositioning.				
6.a	Problem (all) freeze/release	Х	х	Х	
6.b	Position (geographic) freeze/release	Х	х	х	
6.c	Repositioning (locations, freezes, and releases)	х	х	Х	
6.d	Ground speed control	Х	х	Х	
7	Remote IOS.	х	х	Х	
8	Sound Controls. On/off/adjustment	х	х	Х	
9	Motion/Control Loading System.				
9.a	On/off/emergency stop	х	х	Х	
10	Observer Seats/Stations. Position/Adjustment/Positive restraint system	Х	х	Х	

14 CFR Ch. I (1-1-24 Edition)

ATTACHMENT 4 TO APPENDIX C TO PART 60— SAMPLE DOCUMENTS

TABLE OF CONTENTS

Title of Sample

Figure C4A Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation.

Figure C4B Attachment: FFS Information Form

Figure A4C Sample Letter of Compliance Figure C4D Sample Qualification Test Guide Cover Page

Figure C4E Sample Statement of Qualification—Certificate

Figure C4F Sample Statement of Qualification—Configuration List

Figure C4G Sample Statement of Qualification—List of Qualified Tasks

Figure C4H [Reserved]

Figure C4I Sample MQTG Index of Effective FFS Directives

ATTACHMENT 4 TO APPENDIX C TO PART 60-FIGURE C4A—SAMPLE LETTER, REQUEST FOR INITIAL, UPGRADE, OR REINSTATEMENT EVALUATION

Information

Date
RE: Request for Initial/Upgrade Evaluation Date
This is to advise you of our intent to request an (initial or upgrade) evaluation of our (FFS Manufacturer), (Aircraf
Type/Level) Full Flight Simulator (FFS), (FAA ID Number, if previously qualified), located in (City, State) at the
(Facility) on (Proposed Evaluation Date). (The proposed evaluation date shall not be more than 180 days following
the date of this letter.) The FFS will be sponsored by (Name of Training Center/Air Carrier), FAA Designator (4
<u>Letter Code</u>). The FFS will be sponsored as follows; (Select One)
☐ The FFS will be used within the sponsor's FAA approved training program and placed on the sponsor's
Training/Operations Specifications.
☐ The FFS will be used for dry lease only.
We agree to provide the formal request for the evaluation to your staff as follows: (check one)
For QTG tests run at the factory, not later, than 45 days prior to the proposed evaluation date with the
additional "1/3 on-site" tests provided not later than 14 days prior to the proposed evaluation date.
For QTG tests run on-site, not later than 30 days prior to the proposed evaluation date.
We understand that the formal request will contain the following documents:
1. Sponsor's Letter of Request (Company Compliance Letter).

- 2. Principal Operations Inspector (POI) or Training Center Program Manager's (TCPM) endorsement.
- 3. Complete QTG.

If we are unable to meet the above requirements, we understand this may result in a significant delay, perhaps 45 days or more, in rescheduling and completing the evaluation.

(The sponsor should add additional comments as necessary).

Please contact (Name Telephone and Fax Number of Sponsor's Contact) to confirm the date for this initial evaluation. We understand a member of your National Simulator Program staff will respond to this request within 14 days

A copy of this letter of intent has been provided to (Name), the Principal Operations Inspector (POI) and/or Training Center Program Manager (TCPM).

Sincerely,

Attachment: FFS Information Form

cc: POI/TCPM

Attachment 4 to Appendix C to Part 60— Figure C4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation Attachment: FFS Information Form INFORMATION

Date:								
	Section 1. FS	TD Informat	ion and Character	istics				
Sponsor Name:	***************************************		FSTD Location:					
Address:			Physical Address:					
City:								
State:	-		State:					
Country:			Country:					
ZIP:			ZIP:					
Manager								
Sponsor ID No: (Four Letter FAA Designator)			Nearest Airport: (Airport Designator)					
		100						
Type of Evaluation Requested:			al 🔲 Upgrade 🛄 Contin statement	uing Qualification 🗌 Special				
Aircraft Make/model/series:								
Initial Qualification: (If Applicable)	Date: Leve	el	Manufacturer's Identification or Serial Number					
Upgrade Qualification: (If Applicable)	Date:Leve	1	□ eMQTG					
Qualification Basis:	A	□ B	☐ Interim C					
	□6	7	Provisional	Status				
Other Technical Information:								
FAA FSTD ID No: (If Applicable)			FSTD Manufacturer:					
Convertible FSTD:	☐Yes:		Date of Manufacture:					
Related FAA ID No. (If Applicable)			Sponsor FSTD ID No:					
Engine model(s) and data revis	ion:		Source of aerodynamic	model:				
FMS identification and revision	n level:		Source of aerodynamic	coefficient data:				
Visual system manufacturer/m	odel:		Aerodynamic data revision number:					
Flight control data revision:			Visual system display:					
Mot ion system manufacturer/t	уре:		FSTD computer(s) identification:					
National Aviation Authority								
(NAA): (If Applicable)								
NAA FSTD ID No:			Last NAA Evaluation Date:					
NAA Qualification Level:								
NAA Qualification Basis:								
Visual System Manufacturer and Type:		FSTD Seats Available:	Motion System Man and Type:	ufacturer :				

Attachment 4 to Appendix C to Part 60— Figure C4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation Attachment: FFS Information Form INFORMATION

Aircraft Equipment:	Engine Typ	e(s):	Flight Instrumentation: EFIS			Engine Instrumentation: EICAS FADEC Other:	
Airport Models:		3.6.1		3,6,2			3.6.3
Airport Wodels.	An port Models.		signator	Airpor	– t Desig	nator	Airport Designator
Circle to Land:		3. 7.1 Airport De:	sianatar	3. 7.2	- oroach		3. 7.3 Landing Runway
Visual Ground Segmen	t	3.8.1Airport D		3.8.2	oroach		3. 8.3 Landing Runway
		Section 2	. Supplem	ientary Inf			
FAA Training Program	ı Approval Au	thority:			TCP	M 🔲 Other:	
Name:	***************************************			Office:			
Tel:				Fax:			
Email:							
FSTD Scheduling Perso	on:						
Name:				74-44-44-5-1			
Address 1:				Address 2			
City:			State:				
ZIP:				Email:			***************************************
Tel:			Fax:				
FSTD Technical Contact	ct:					E S	
Name:	T		······································			***************************************	
Address 1:				Address 2			
City:				State:			
ZIP:				Email:			
Tel:			Fax:				
		3. Training	g, Testing			Considera	tions
Area/Function/Maneuv	er			Reque	sted	Remarks	
Private Pilot - Training	/ Checks: (14	2)					
Commercial Pilot - Training /Checks:(142)		:(142)	***************************************				
Multi-Engine Rating - Training / Checks (142)							
Instrument Rating -Training / Checks (142)						With the second	The state of the s
Type Rating - Training / Checks (135/121/142)					***************************************		
Proficiency Checks (13:	5/121/142)						
CAT I: (RVR 2400/180	0 ft. DH200 ft)	I			·		
	CAT 1. (KVK 2400/1800 II. DH200 II)					1	

Attachment 4 to Appendix C to Part 60—
Figure C4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation
Attachment: FFS Information Form
INFORMATION

CAT II: (RVR 1200 ft. DH 100 ft)	
CAT III * (lowest minimum) RVR ft.	
* State CAT III (≤ 700 ft.), CAT IIIb (≤ 150 ft.), or CAT IIIc (0 ft.)	
Circling Approach	
Windshear Training:	
Windshear Training IAW 121.409(d) (121 Turbojets Only)	
Generic Unusual Attitudes and Recoveries within the Normal Flight Envelope	APARTONIA PROPERTY AND
Specific Unusual Attitudes Recoveries	
Auto-coupled Approach/Auto Go Around	
Auto-land / Roll Out Guidance	
TCAS/ACAS I / II	
WX-Radar	
HUD	
HGS	
EFVS	
Future Air Navigation Systems	
GPWS / EGPWS	
ETOPS Capability	
GPS	
SMGCS	
Helicopter Slope Landings	
Helicopter External Load Operations	Name of the Control o
Helicopter Pinnacle Approach to Landings	
Helicopter Night Vision Maneuvers	
Helicopter Category A Takeoffs	with the state of

ATTACHMENT 4 TO APPENDIX C TO PART 60— FIGURE C4C—Sample Letter of Compliance

INFORMATION

(Date)

Mr. (Name of Training Program Approval Authority): (Name of responsible Flight Standards office) (Address) (City/State/Zip)

Dear Mr. (Name of TPAA):

RE: Letter of Compliance

(Operator Sponsor Name) requests evaluation of our (Aircraft Type) FFS for Level (__) qualification. The (FFS Manufacturer Name) FFS with (Visual System Manufacturer Name/Model) system is fully defined on the FFS Information page of the accompanying Qualification Test Guide (QTG). We have completed the tests of the FFS and certify that it meets all applicable requirements of FAR parts 121, 125, or 135), and the guidance of (AC 120-40B or 14 CFR Part 60). Appropriate hardware and software configuration control procedures have been established. Our Pilot(s), (Name(s)), who are qualified on (Aircraft Type) aircraft have assessed the FFS and have found that it conforms to the (Operator/Sponsor) (Aircraft Type) flight deck configuration and that the simulated systems and subsystems function equivalently to those in the aircraft. The above named pilot(s) have also assessed the performance and the flying qualities of the FFS and find that it represents the respective aircraft. (Added Comments may be placed here)

Sincerely, (Sponsor Representative)

ATTACHMENT 4 TO APPENDIX C TO PART 60— FIGURE C4D—SAMPLE QUALIFICATION TEST GUIDE COVER PAGE

Information

SPONSOR NAME

SPONSOR ADDRESS

FAA QUALIFICATION TEST GUIDE

(SPECIFIC Helicopter MODEL)

for example

Farnsworth Z-100

(Type of Simulator)

(Simulator Identification Including Manufacturer, Serial Number, Visual System Used)

(Simulator Level)

(Qualification Performance Standard Used)

(Simulator Location)

FAA Initial Evaluation

Date: _____

Date: _

(Sponsor)

` 1

FAA

ATTACHMENT 4 TO APPENDIX C TO PART 60—FIGURE C4E—SAMPLE STATEMENT OF QUALIFICATION—CERTIFICATE

Information

Federal Aviation Administration



Certificate of Qualification

This is to certify that representatives of the FAA Completed an evaluation of the

Go-Fast Airlines Farnsworth Z-100 Full Flight Simulator

FAA Identification Number 0999

And pursuant to 14 CFR Part 60 found it to meet its original qualification basis, AC 120-63 (MM/DD/YY)

The Master Qualification Test Guide and the attached Configuration List and List of Qualified Tasks Provide the Qualification Basis for this device to operate at

Level D

Until April 30, 2010

Unless sooner rescinded or extended by the FAA

March 15, 2009	C. Nordlie
(date)	(for the FAA)

Attachment 4 to Appendix C to Part 60— Figure C4F – Sample Statement of Qualification; Configuration List INFORMATION

STATEMENT of QUALIFICATION **CONFIGURATION LIST**

Date:			·					
	Section 1. FSTD	Informat	ion and Characteri	stics				
Sponsor Name:	T		FSTD Location:					
Address:	ddress:							
City:		City:	With the state of					
State:			State:	324444444				
Country:			Country:					
ZIP:			ZIP:					
Manager								
Sponsor ID No: (Four Letter FAA Designator)			Nearest Airport: (Airport Designator)					
Type of Evaluation Requested:			ıl □ Upgrade □ Continu statement	ing Qualification Special				
Aircraft Make/model/series:		innoceine contrarent de la contrarent de		·				
Initial Qualification: (If Applicable)	Date:Level MM/DD/YYYY	A	Manufacturer's Identification or Serial Number					
Upgrade Qualification: (If Applicable)	Date: Level MM/DD/YYYY		□ eMQTG					
Qualification Basis:	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	□в	☐ Interim C	□ C				
	□ 6	7	☐ Provisional	Status				
Other Technical Information:								
FAA FSTD ID No: (If Applicable)			FSTD Manufacturer:					
Convertible FSTD:	□Yes:		Date of Manufacture: MM/DD/YYYY					
Related FAA ID No. (If Applicable)			Sponsor FSTD ID No:					
Engine model(s) and data revis	ion:		Source of aerodynamic model:					
FMS identification and revision	ı level:		Source of aerodynamic coefficient data:					
Visual system manufacturer/me	odel:		Aerodynamic data revision number:					
Flight control data revision:			Visual system display:					
Mot ion system manufacturer/t	ype:		FSTD computer(s) ident	ification:				
National Aviation Authority (NAA): (If Applicable)								
NAA FSTD ID No:			Last NAA Evaluation Date:					
NAA Qualification Level:								
NAA Qualification Basis:								
				L				

Attachment 4 to Appendix C to Part 60— Figure C4F – Sample Statement of Qualification; Configuration List INFORMATION

Visual System Manufacturer and Type:		FSTD Seats Available:	Motion Syst and Type:	em Manufacturer	·
Aircraft Equipment: Engine	ft Equipment: Engine Type(s): Flight Instrumentation: EFVS HUD HGS EFVS TCAS GPWS Plain View GPS FMS Type: WX Radar Other:		∃EFVS □	Engine Instrumentation: EICAS FADEC Other:	
	Table 1				
Airport Models:	3.6.1 Airport De		3.6.2 Airport Desi	gnator 3.6.	Airport Designator
Circle to Land:	3. 7.1 Airport De		3. 7.2 Approach	3. 7	
Visual Ground Segment	3.8.1Airport D		3.8.2Approach	3.8	
	Section 2	. Supplemen	tary Inform	ation	
FAA Training Program Approv		Supplemen	POI TCI	PM Dother:	
Name:			Office:		
Tel:			Fax:		
Email:				100	
				1, 2, 3	
FSTD Scheduling Person:					
Name:					
Address 1:			Address 2		
City:			State:		
ZIP:			Email:		
Tel:			Fax:		
FSTD Technical Contact:					
Name:					
Address 1:		, and a	Address 2		
City:		5	State:		
ZIP:		1	Email:		No. of Contract of
Tel:		I	ax:	***************************************	
Son	tion 3. Training	r Testing on	d Chaoleina	Cansidaration	
Area/Function/Maneuver	v. 11 amili)	5, 1 coung an	Requested	Remarks	io
Private Pilot - Training / Checks	s: (142)		10		
Commercial Pilot - Training /Cl	necks:(142)				
Multi-Engine Rating - Training	/ Checks (142)			***************************************	
Instrument Rating -Training / C	hecks (142)				-
Type Rating - Training / Check	s (135/121/142)				

Attachment 4 to Appendix C to Part 60— Figure C4F – Sample Statement of Qualification; Configuration List INFORMATION

INFORMATION	
Proficiency Checks (135/121/142)	
CAT I: (RVR 2400/1800 ft. DH200 ft)	
CAT II: (RVR 1200 ft. DH 100 ft)	
CAT III * (lowest minimum) RVR ft.	
* State CAT III (≤ 700 ft.), CAT IIIb (≤ 150 ft.), or CAT IIIc (0 ft.)	
Circling Approach	
Windshear Training:	
Windshear Training IAW 121.409(d) (121 Turbojets Only)	
Generic Unusual Attitudes and Recoveries within the Normal Flight Envelope	
Specific Unusual Attitudes Recoveries	
Auto-coupled Approach/Auto Go Around	
Auto-land / Roll Out Guidance	
TCAS/ACAS I / II	
WX-Radar	
HUD	
HGS	
EFVS	
Future Air Navigation Systems	
GPWS / EGPWS	
ETOPS Capability	
GPS	· ·
SMGCS	
Helicopter Slope Landings	
Helicopter External Load Operations	
Helicopter Pinnacle Approach to Landings	
Helicopter Night Vision Maneuvers	
Helicopter Category A Takeoffs	

Attachment 4 to Appendix C to Part 60— Figure C4G – Sample Statement of Qualification – List of Qualified Tasks INFORMATION

STATEMENT of QUALIFICATION List of Qualified Tasks

Go Fast Airline Training -- Farnsworth Z-100 -- Level D -- FAA ID# 0999

The FFS is qualified to perform all of the Maneuvers, Procedures, Tasks, and Functions Listed in Appendix A, Attachment 1, Table A1B, Minimum FFS Requirements In Effect on [mm/dd/yyyy] except for the following listed Tasks or Functions.

Qualified for all tasks in Table C1B for which the sponsor has requested qualification, except for the following:

- 6.e. Environmental system.
- 6.f. Fire detection and extinguisher system.
- 7.b. In-flight fire and smoke removal.
- 7.d. Ditching.

Additional tasks for which this FFS is qualified (i.e., in addition to the list in Table C1B)

Enhanced Visual System

ATTACHMENT 4 TO APPENDIX C TO PART 60—FIGURE C4H [RESERVED]

Attachment 4 to Appendix C to Part 60— Figure C4I – Sample MQTG Index of Effective FFS Directives INFORMATION

	Index of Effective FSTD Directives Filed in this Section								
Number	Effective Date	Date of Notification	Details						
			· · · · · · · · · · · · · · · · · · ·						

Continue as Necessary....

ATTACHMENT 5 TO APPENDIX C TO PART 60— FSTD DIRECTIVES APPLICABLE TO HELICOPTER FFSs

FLIGHT SIMULATION TRAINING DEVICE (FSTD) DIRECTIVE

FSTD Directive 1. Applicable to all FFSs, regardless of the original qualification basis and qualification date (original or upgrade), having Class II or Class III airport models available.

 $Agency\colon \operatorname{Federal}$ Aviation Administration (FAA), DOT

Action: This is a retroactive requirement to have all Class II or Class III airport models meet current requirements.

Summary: Notwithstanding the authorization listed in paragraph 13b in Appendices A and C of this part, this FSTD Directive requires each certificate holder to ensure that by May 30, 2009, except for the airport model(s) used to qualify the simulator at the designated level, each airport model used by the certificate holder's instructors or evaluators for training, checking, or testing under this chapter in an FFS, meets the definition of a Class II or Class III airport model as defined in 14CFR part 60. The completion of this requirement will not require a report, and the method used for keeping instructors and evaluators apprised of the airport models that meet Class II or Class III requirements on any given simulator is at the option of the certificate holder whose employees are using the FFS, but the method used must be available for review by the TPAA for that certificate holder.

Dates: FSTD Directive 1 becomes effective on May 30, 2008.

SPECIFIC REQUIREMENTS:

- 1. Part 60 requires that each FSTD be:
- a. Sponsored by a person holding or applying for an FAA operating certificate under Part 119, Part 141, or Part 142, or holding or applying for an FAA-approved training program under Part 63, Appendix C, for flight engineers, and
- b. Evaluated and issued an SOQ for a specific FSTD level.
- 2. FFSs also require the installation of a visual system that is capable of providing an out-of-the-flight-deck view of airport models. However, historically these airport models were not routinely evaluated or required to meet any standardized criteria. This has led to qualified simulators containing airport models being used to meet FAA-approved training, testing, or checking requirements with potentially incorrect or inappropriate visual references.
- 3. To prevent this from occurring in the future, by May 30, 2009, except for the airport model(s) used to qualify the simulator at the designated level, each certificate holder must assure that each airport model used for training, testing, or checking under this

chapter in a qualified FFS meets the definition of a Class II or Class III airport model as defined in Appendix F of this part.

- 4. These references describe the requirements for visual scene management and the minimum distances from which runway or landing area features must be visible for all levels of simulator. The visual scene or airport model must provide, for each "in-use runway" or "in-use landing area," runway or landing area surface and markings, runway or landing area lighting, taxiway surface and markings, and taxiway lighting. Additional requirements include correlation of the visual scenes or airport models with other aspects of the airport environment, correlation of the aircraft and associated equipment, scene quality assessment features, and the extent to which the instructor is able to exercise control of these scenes or models.
- 5. For circling approaches, all requirements of this section apply to the runway used for the initial approach and to the runway of intended landing.
- 6. The details in these scenes or models must be developed using airport pictures, construction drawings and maps, or other similar data, or be developed in accordance with published regulatory material. However, FSTD Directive 1 does not require that airport models contain details that are beyond the initially designed capability of the visual system, as currently qualified. The recognized limitations to visual systems are as follows:
- a. Visual systems not required to have runway numbers as a part of the specific runway marking requirements are:
 - (1) Link NVS and DNVS.
 - (2) Novoview 2500 and 6000.
- (3) FlightSafety VITAL series up to, and including, VITAL III, but not beyond.
 - (4) Redifusion SP1, SP1T, and SP2.
- b. Visual systems required to display runway numbers only for LOFT scenes are:
- (1) FlightSafety VITAL IV.
- (2) Redifusion SP3 and SP3T.
- (3) Link-Miles Image II.
- c. Visual systems not required to have accurate taxiway edge lighting are:
 - (1) Redifusion SP1.
 - (2) FlightSafety Vital IV.
- (3) Link-Miles Image II and Image IIT
- (4) XKD displays (even though the XKD image generator is capable of generating blue colored lights, the display cannot accommodate that color).
- 7. A copy of this Directive must be filed in the MQTG in the designated FSTD Directive Section, and its inclusion must be annotated on the Index of Effective FSTD Directives chart. See Attachment 4, Appendices A

through D of this part for a sample MQTG Index of Effective FSTD Directives chart.

[Doc. No. FAA-2002-12461, 73 FR 26490, May 9, 2008, as amended by Docket FAA-2018-0119, Amdt. 60-5, 83 FR 9170, Mar. 5, 2018; Amdt. 60-6, 83 FR 30275, June 27, 2018; Docket No. FAA-2022-1355; Amdt. No. 60-7; 87 FR 75822, Dec. 9, 20221

EDITORIAL NOTE: At 87 FR 75822, Dec. 9, 2022, appendix C to part 60 was amended in the introductory "Begin Information" text, by removing the word "NSPM" and adding in its place the words "Flight Standards Service" in the first sentence; however this amendment could not be incorporated due to inaccurate amendatory instruction.

APPENDIX D TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR HEL-ICOPTER FLIGHT TRAINING DEVICES

BEGIN INFORMATION

This appendix establishes the standards for Helicopter Flight Training Device (FTD) evaluation and qualification at Level 4, Level 5, Level 6, or Level 7. The Flight Standards Service is responsible for the development, application, and implementation of the standards contained within this appendix. The procedures and criteria specified in this appendix will be used by the responsible Flight Standards office when conducting helicopter FTD evaluations.

TABLE OF CONTENTS

- 1. Introduction.
- 2. Applicability (§§ 60.1, 60.2).
- 3. Definitions (§ 60.3).
- 4. Qualification Performance Standards (§ 60.4).
- 5. Quality Management System (§ 60.5).
- 6. Sponsor Qualification Requirements ($\S 60.7$).
- 7. Additional Responsibilities of the Sponsor (§60.9).
 - 8. FTD Use (§60.11).
- 9. FTD Objective Data Requirements ($\S 60.13$).
- 10. Special Equipment and Personnel Requirements for Qualification of the FTD (§60.14).
- 11. Initial (and Upgrade) Qualification Requirements (§60.15).
- 12. Additional Qualifications for Currently Qualified FTDs (§60.16).
 - 13. Previously Qualified FTDs (§60.17).
- 14. Inspection, Continuing Qualification Evaluation, and Maintenance Requirements (§60.19).
- 15. Logging FTD Discrepancies (§60.20). 16. Interim Qualification of FTDs for New Helicopter Types or Models (§60.21).
- 17. Modifications to FTDs (§ 60.23).

Federal Aviation Administration, DOT

- 18. Operations with Missing, Malfunctioning, or Inoperative Components (§ 60.25).
- 19. Automatic Loss of Qualification and Procedures for Restoration of Qualification (§60.27).
- 20. Other Losses of Qualification and Procedures for Restoration of Qualification (§60.29).
 - 21. Recordkeeping and Reporting (§ 60.31).
- 22. Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements (§ 60.33).
 - 23. [Reserved]
 - 24. Levels of FTD.
- 25. FTD Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA) (\$60.37).
- Attachment 1 to Appendix D to Part 60–General FTD Requirements.
- Attachment 2 to Appendix D to Part 60—Flight Training Device (FTD) Objective Tests.
- Attachment 3 to Appendix D to Part 60—Flight Training Device (FTD) Subjective Evaluation.
- Attachment 4 to Appendix D to Part 60—Sample Documents.

END INFORMATION

1. Introduction

BEGIN INFORMATION

- a. This appendix contains background information as well as regulatory and informative material as described later in this section. To assist the reader in determining what areas are required and what areas are permissive, the text in this appendix is divided into two sections: "QPS Requirements" and "Information." The QPS Requirements sections contain details regarding compliance with the part 60 rule language. These details are regulatory, but are found only in this appendix. The Information sections contain material that is advisory in nature, and designed to give the user general information about the regulation.
- b. [Reserved]
- c. The responsible Flight Standards office encourages the use of electronic media for all communication, including any record, report, request, test, or statement required by this appendix. The electronic media used must have adequate security provisions and be acceptable to the responsible Flight Standards office.
- d. Related Reading References.
- (1) 14 CFR part 60.
- (2) 14 CFR part 61.
- (3) 14 CFR part 63.(4) 14 CFR part 119.
- (5) 14 CFR part 121.
- (6) 14 CFR part 125.

- (7) 14 CFR part 135.
- (8) 14 CFR part 141.
- (9) 14 CFR part 142.
- (10) AC 120-28, as amended, Criteria for Approval of Category III Landing Weather Minima.
- (11) AC 120-29, as amended, Criteria for Approving Category I and Category II Landing Minima for part 121 operators.
- (12) AC 120-35, as amended, Flightcrew Member Line Operational Simulations: Line-Oriented Flight Training, Special Purpose Operational Training, Line Operational Evaluation.
- (13) AC 120-41, as amended, Criteria for Operational Approval of Airborne Wind Shear Alerting and Flight Guidance Systems
- (14) AC 120-57, as amended, Surface Movement Guidance and Control System (SMGCS).
- $\left(15\right)$ AC 120–63, as amended, Helicopter Simulator Qualification.
- (16) AC 150/5300–13, as amended, Airport Design.
- (17) AC 150/5340-1, as amended, Standards for Airport Markings.
- (18) AC 150/5340-4, as amended, Installation Details for Runway Centerline Touchdown Zone Lighting Systems.
- (19) AC 150/5390–2, as amended, Heliport Design.
- (20) AC 150/5340-19, as amended, Taxiway Centerline Lighting System.
- (21) AC 150/5340-24, as amended, Runway and Taxiway Edge Lighting System.
- (22) AC 150/5345-28, as amended, Precision Approach Path Indicator (PAPI) Systems.
- (23) International Air Transport Association document, "Flight Simulator Design and Performance Data Requirements," as amended.
- (24) AC 29–2, as amended, Flight Test Guide for Certification of Transport Category Rotorcraft.
- (25) AC 27–1, as amended, Flight Test Guide for Certification of Normal Category Rotor-craft.
- (26) International Civil Aviation Organization (ICAO) Manual of Criteria for the Qualification of Flight Simulators, as amended.
- (27) Airplane Flight Simulator Evaluation Handbook, Volume I, as amended and Volume II, as amended, The Royal Aeronautical Society, London, UK.
- (28) FAA Airman Certification Standards and Practical Test Standards for Airline Transport Pilot, Type Ratings, Commercial Pilot, and Instrument Ratings.
- (29) The FAA Aeronautical Information Manual (AIM). An electronic version of the AIM is on the Internet at http://www.faa.gov/atpubs.
- (30) Aeronautical Radio, Inc. (ARINC) document number 436, Guidelines For Electronic Qualification Test Guide (as amended).

(31) Aeronautical Radio, Inc. (ARINC) document 610, Guidance for Design and Integration of Aircraft Avionics Equipment in Simulators (as amended).

END INFORMATION

2. Applicability (§ 60.1 and 60.2)

BEGIN INFORMATION

No additional regulatory or informational material applies to \$60.1, Applicability, or to \$60.2, Applicability of sponsor rules to person who are not sponsors and who are engaged in certain unauthorized activities.

END INFORMATION

3. Definitions (§60.3)

BEGIN INFORMATION

See Appendix F of this part for a list of definitions and abbreviations from part 1, part 60, and the QPS appendices of part 60.

END INFORMATION

4. QUALIFICATION PERFORMANCE STANDARDS (§ 60.4)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.4, Qualification Performance Standards.

END INFORMATION

5. QUALITY MANAGEMENT SYSTEM (§ 60.5)

BEGIN INFORMATION

Additional regulatory material and informational material regarding Quality Management Systems for FTDs may be found in Appendix E of this part.

END INFORMATION

6. Sponsor Qualification Requirements $(\S 60.7)$

BEGIN INFORMATION

a. The intent of the language in 60.7(b) is to have a specific FTD, identified by the sponsor, used at least once in an FAA-approved flight training program for the heli-

copter simulated during the 12-month period described. The identification of the specific FTD may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FTD at least once during the prescribed period. There is no minimum number of hours or minimum FTD periods required.

- b. The following examples describe acceptable operational practices:
 - (1) Example One.
- (a) A sponsor is sponsoring a single, specific FTD for its own use, in its own facility or elsewhere—this single FTD forms the basis for the sponsorship. The sponsor uses that FTD at least once in each 12-month period in that sponsor's FAA-approved flight training program for the helicopter simulated. This 12-month period is established according to the following schedule:
- (i) If the FTD was qualified prior to May 30, 2008, the 12-month period begins on the date of the first continuing qualification evaluation conducted in accordance with \$60.19 after May 30, 2008, and continues for each subsequent 12-month period;
- (ii) A device qualified on or after May 30, 2008, will be required to undergo an initial or upgrade evaluation in accordance with \$60.15. Once the initial or upgrade evaluation is complete, the first continuing qualification evaluation will be conducted within 6 months. The 12 month continuing qualification evaluation cycle begins on that date and continues for each subsequent 12-month period.
- (b) There is no minimum number of hours of FTD use required.
- (c) The identification of the specific FTD may change from one 12-month period to the next 12-month period as long as that sponsor sponsors and uses at least one FTD at least once during the prescribed period.
- (2) Example Two.
- (a) A sponsor sponsors an additional number of FTDs, in its facility or elsewhere. Each additionally sponsored FTD must be—
- (i) Used by the sponsor in the sponsor's FAA-approved flight training program for the helicopter simulated (as described in §60.7(d)(1)); or
- (ii) Used by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the helicopter simulated (as described in §60.7(d)(1)). This 12-month period is established in the same manner as in example one; or
- (iii) Provided a statement each year from a qualified pilot, (after having flown the helicopter not the subject FTD or another FTD, during the preceding 12-month period) stating that the subject FTD's performance and handling qualities represent the helicopter (as described in §60.7(d)(2)). This statement is provided at least once in each 12-month period established in the same manner as in example one.

Federal Aviation Administration, DOT

- (b) There is no minimum number of hours of FTD use required.
- (3) Example Three.
- (a) A sponsor in New York (in this example, a Part 142 certificate holder) establishes "satellite" training centers in Chicago and Moscow.
- (b) The satellite function means that the Chicago and Moscow centers must operate under the New York center's certificate (in accordance with all of the New York center's practices, procedures, and policies; e.g., instructor and/or technician training/checking requirements, record keeping, QMS program).
- (c) All of the FTDs in the Chicago and Moscow centers could be dry-leased (i.e., the certificate holder does not have and use FAA-approved flight training programs for the FTDs in the Chicago and Moscow centers) because—
- (i) Each FTD in the Chicago center and each FTD in the Moscow center is used at least once each 12-month period by another FAA certificate holder in that other certificate holder's FAA-approved flight training program for the helicopter (as described in §60.7(d)(1)); or
- (ii) A statement is obtained from a qualified pilot (having flown the helicopter, not the subject FTD or another FTD during the preceding 12-month period) stating that the performance and handling qualities of each FTD in the Chicago and Moscow centers represents the helicopter (as described in §60.7(d)(2)).

END INFORMATION

7. Additional Responsibilities of the Sponsor (§60.9)

BEGIN INFORMATION

The phrase "as soon as practicable" in §60.9(a) means without unnecessarily disrupting or delaying beyond a reasonable time the training, evaluation, or experience being conducted in the FTD.

END INFORMATION

8. FTD USE (§60.11).

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.11, FTD Use.

END INFORMATION

9. FTD OBJECTIVE DATA REQUIREMENTS (§ 60.13)

BEGIN QPS REQUIREMENTS

- a. Flight test data used to validate FTD performance and handling qualities must have been gathered in accordance with a flight test program containing the following:
- (1) A flight test plan consisting of:
- (a) The maneuvers and procedures required for aircraft certification and simulation programming and validation.
 - (b) For each maneuver or procedure-
- (i) The procedures and control input the flight test pilot and/or engineer used.
- (ii) The atmospheric and environmental conditions.
- (iii) The initial flight conditions.
- (iv) The helicopter configuration, including weight and center of gravity.
 - (v) The data to be gathered.
- (vi) All other information necessary to recreate the flight test conditions in the FTD.
- (2) Appropriately qualified flight test personnel.
- (3) Appropriate and sufficient data acquisition equipment or system(s), including appropriate data reduction and analysis methods and techniques, acceptable to the FAA's Aircraft Certification Service.
- b. The data, regardless of source, must be presented:
- (1) In a format that supports the FTD validation process;
- (2) In a manner that is clearly readable and annotated correctly and completely;
- (3) With resolution sufficient to determine compliance with the tolerances set forth in Attachment 2, Table D2A Appendix D;
- (4) With any necessary guidance information provided; and
- (5) Without alteration, adjustments, or bias. Data may be corrected to address known data calibration errors provided that an explanation of the methods used to correct the errors appears in the QTG. The corrected data may be re-scaled, digitized, or otherwise manipulated to fit the desired presentation
- c. After completion of any additional flight test, a flight test report must be submitted in support of the validation data. The report must contain sufficient data and rationale to support qualification of the FTD at the level requested.
- d. As required by §60.13(f), the sponsor must notify the responsible Flight Standards office when it becomes aware that an addition to or a revision of the flight related data or helicopter systems related data is available if this data is used to program and operate a qualified FTD. The data referred to in this sub-section is data used to validate the performance, handling qualities, or other

characteristics of the aircraft, including data related to any relevant changes occurring after the type certification is issued. The sponsor must—

- (1) Within 10 calendar days, notify the responsible Flight Standards office of the existence of this data; and
- (a) Within 45 calendar days, notify the responsible Flight Standards office of—
- (b) The schedule to incorporate this data into the FTD; or
- (c) The reason for not incorporating this data into the FTD.
- e. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot tests" results in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.

END QPS REQUIREMENTS

BEGIN INFORMATION

f. The FTD sponsor is encouraged to maintain a liaison with the manufacturer of the aircraft being simulated (or with the holder of the aircraft type certificate for the aircraft being simulated if the manufacturer is no longer in business), and if appropriate, with the person having supplied the aircraft data package for the FTD in order to facilitate the notification described in this paragraph.

g. It is the intent of the responsible Flight Standards office that for new aircraft entering service, at a point well in advance of preparation of the QTG, the sponsor should submit to the responsible Flight Standards office for approval, a descriptive document (see Appendix C of this part, Table C2D, Sample Validation Data Roadmap for Helicopters) containing the plan for acquiring the validation data, including data sources. This document should clearly identify sources of data for all required tests, a description of the validity of these data for a specific engine type and thrust rating configuration, and the revision levels of all avionics affecting the performance or flying qualities of the aircraft. Additionally, this document should provide other information such as the rationale or explanation for cases where data or data parameters are missing, instances where engineering simulation data are used, or where flight test methods require further explanations. It should also provide a brief narrative describing the cause and effect of any deviation from data requirements. The aircraft manufacturer may provide this document.

h. There is no requirement for any flight test data supplier to submit a flight test plan or program prior to gathering flight test data. However, the responsible Flight Standards office notes that inexperienced data gatherers often provide data that is irrelevant, improperly marked, or lacking adequate justification for selection. Other problems include inadequate information regarding initial conditions or test maneuvers. The responsible Flight Standards office has been forced to refuse these data submissions as validation data for an FTD evaluation. For this reason the responsible Flight Standards office recommends that any data supplier not previously experienced in this area review the data necessary for programming and for validating the performance of the FTD and discuss the flight test plan anticipated for acquiring such data with the responsible Flight Standards office well in advance of commencing the flight tests.

i. The responsible Flight Standards office will consider, on a case-by-case basis, whether to approve supplemental validation data derived from flight data recording systems such as a Quick Access Recorder or Flight Data Recorder.

END INFORMATION

10. SPECIAL EQUIPMENT AND PERSONNEL RE-QUIREMENTS FOR QUALIFICATION OF THE FTD (§60.14).

BEGIN INFORMATION

a. In the event that the responsible Flight Standards office determines that special equipment or specifically qualified persons will be required to conduct an evaluation, the responsible Flight Standards office will make every attempt to notify the sponsor at least one (1) week, but in no case less than 72 hours, in advance of the evaluation. Examples of special equipment include flight control measurement devices, accelerometers, or oscilloscopes. Examples of specially qualified personnel include individuals specifically qualified to install or use any special equipment when its use is required.

b. Examples of a special evaluation include an evaluation conducted after an FTD is moved; at the request of the TPAA; or as a result of comments received from users of the FTD that raise questions about the continued qualification or use of the FTD.

END INFORMATION

11. Initial (and Upgrade) Qualification Requirements ($\S60.15$).

BEGIN QPS REQUIREMENT

- a. In order to be qualified at a particular qualification level, the FTD must:
- (1) Meet the general requirements listed in Attachment 1 of this appendix.
- (2) Meet the objective testing requirements listed in Attachment 2 of this appendix (Level 4 FTDs do not require objective tests).
- (3) Satisfactorily accomplish the subjective tests listed in Attachment 3 of this appendix.
- b. The request described in §60.15(a) must include all of the following:
- (1) A statement that the FTD meets all of the applicable provisions of this part and all applicable provisions of the QPS.
- (2) A confirmation that the sponsor will forward to the responsible Flight Standards office the statement described in §60.15(b) in such time as to be received no later than 5 business days prior to the scheduled evaluation and may be forwarded to the responsible Flight Standards office via traditional or electronic means.
- (3) Except for a Level 4 FTD, a QTG, acceptable to the responsible Flight Standards office, that includes all of the following:
- (a) Objective data obtained from aircraft testing or another approved source.
- (b) Correlating objective test results obtained from the performance of the FTD as prescribed in the appropriate QPS.
- (c) The result of FTD subjective tests prescribed in the appropriate QPS.
- (d) A description of the equipment necessary to perform the evaluation for initial qualification and the continuing qualification evaluations.
- c. The QTG described in paragraph a(3) of this section must provide the documented proof of compliance with the FTD objective tests in Attachment 2, Table D2A of this ap-
- d. The QTG is prepared and submitted by the sponsor, or the sponsor's agent on behalf of the sponsor, to the responsible Flight Standards office for review and approval, and must include, for each objective test:
- (1) Parameters, tolerances, and flight conditions.
- (2) Pertinent and complete instructions for conducting automatic and manual tests.
- (3) A means of comparing the FTD test results to the objective data.
- (4) Any other information as necessary to assist in the evaluation of the test results.
- (5) Other information appropriate to the qualification level of the FTD.
- e. The QTG described in paragraphs (a)(3) and (b) of this section, must include the following:
- (1) A QTG cover page with sponsor and FAA approval signature blocks (see Attachment 4, Figure D4C, of this appendix, for a sample QTG cover page).

- (2) A continuing qualification evaluation requirements page. This page will be used by the responsible Flight Standards office to establish and record the frequency with which continuing qualification evaluations must be conducted and any subsequent changes that may be determined by the responsible Flight Standards office in accordance with §60.19. See Attachment 4, Figure D4G, of this appendix for a sample Continuing Qualification Evaluation Requirements page.
- (3) An FTD information page that provides the information listed in this paragraph, if applicable (see Attachment 4, Figure D4B, of this appendix, for a sample FTD information page). For convertible FTDs, the sponsor must submit a separate page for each configuration of the FTD.
- (a) The sponsor's FTD identification number or code.
- (b) The helicopter model and series being simulated.
- (c) The aerodynamic data revision number or reference.
- (d) The source of the basic aerodynamic model and the aerodynamic coefficient data used to modify the basic model.
- (e) The engine model(s) and its data revision number or reference.
- (f) The flight control data revision number or reference.
- (g) The flight management system identification and revision level.
 - (h) The FTD model and manufacturer.
 - (i) The date of FTD manufacture.
 - (j) The FTD computer identification.
- (k) The visual system model and manufacturer, including display type.
- (1) The motion system type and manufacturer, including degrees of freedom.
 - (4) A Table of Contents.
- (5) A log of revisions and a list of effective pages.
 - (6) List of all relevant data references.
- (7) A glossary of terms and symbols used (including sign conventions and units).
- (8) Statements of Compliance and Capability (SOC) with certain requirements.
- (9) Recording procedures or equipment required to accomplish the objective tests.
- (10) The following information for each objective test designated in Attachment 2 of this appendix, as applicable to the qualification level sought:
 - (a) Name of the test.
 - (b) Objective of the test.
 - (c) Initial conditions.
- (d) Manual test procedures.
- (e) Automatic test procedures (if applicable).
- (f) Method for evaluating FTD objective test results.
- (g) List of all relevant parameters driven or constrained during the automatic test(s).
- (h) List of all relevant parameters driven or constrained during the manual test(s).
- (i) Tolerances for relevant parameters.

(j) Source of Validation Data (document and page number).

(k) Copy of the Validation Data (if located in a separate binder, a cross reference for the identification and page number for pertinent data location must be provided).

(1) FTD Objective Test Results as obtained by the sponsor. Each test result must reflect the date completed and must be clearly labeled as a product of the device being tested.

- f. A convertible FTD is addressed as a separate FTD for each model and series helicopter to which it will be converted and for the FAA qualification level sought. The responsible Flight Standards office will conduct an evaluation for each configuration. If a sponsor seeks qualification for two or more models of a helicopter type using a convertible FTD, the sponsor must provide a QTG for each helicopter model, or a QTG for the first helicopter model and a supplement to that QTG for each additional helicopter model. The responsible Flight Standards office will conduct evaluations for each helicopter model.
- g. The form and manner of presentation of objective test results in the QTG must include the following:
- (1) The sponsor's FTD test results must be recorded in a manner acceptable to the responsible Flight Standards office, that allows easy comparison of the FTD test results to the validation data (e.g., use of a multichannel recorder, line printer, cross plotting, overlays, transparencies).
- (2) FTD results must be labeled using terminology common to helicopter parameters as opposed to computer software identifications
- (3) Validation data documents included in a QTG may be photographically reduced only if such reduction will not alter the graphic scaling or cause difficulties in scale interpretation or resolution.
- (4) Scaling on graphical presentations must provide the resolution necessary to evaluate the parameters shown in Attachment 2, Table D2A of this appendix.
- (5) Tests involving time histories, data sheets (or transparencies thereof) and FTD test results must be clearly marked with appropriate reference points to ensure an accurate comparison between FTD and helicopter with respect to time. Time histories recorded via a line printer are to be clearly identified for cross-plotting on the helicopter data. Over-plots may not obscure the reference data.
- h. The sponsor may elect to complete the QTG objective and subjective tests at the manufacturer's facility or at the sponsor's training facility. If the tests are conducted at the manufacturer's facility, the sponsor must repeat at least one-third of the tests at the sponsor's training facility in order to substantiate FTD performance. The QTG must be clearly annotated to indicate when

and where each test was accomplished. Tests conducted at the manufacturer's facility and at the sponsor's training facility must be conducted after the FTD is assembled with systems and sub-systems functional and operating in an interactive manner. The test results must be submitted to the responsible Flight Standards office.

i. The sponsor must maintain a copy of the MQTG at the FTD location. $\,$

j. All FTDs for which the initial qualification is conducted after May 30, 2014, must have an electronic MQTG (eMQTG) including all objective data obtained from helicopter testing, or another approved source (reformatted or digitized), together with correlating objective test results obtained from the performance of the FTD (reformatted or digitized) as prescribed in this appendix. The eMQTG must also contain the general FTD performance or demonstration results (reformatted or digitized) prescribed in this appendix, and a description of the equipment necessary to perform the initial qualification evaluation and the continuing qualification evaluations. The eMQTG must include the original validation data used to validate FTD performance and handling qualities in either the original digitized format from the data supplier or an electronic scan of the original time-history plots that were provided by the data supplier. A copy of the eMQTG must be provided to the responsible Flight Standards office.

k. All other FTDs (not covered in subparagraph "j") must have an electronic copy of the MQTG by and after May 30, 2014. An electronic copy of the MQTG must be provided to the responsible Flight Standards office. This may be provided by an electronic scan presented in a Portable Document File (PDF), or similar format acceptable to the responsible Flight Standards office.

1. During the initial (or upgrade) qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FTD.

END QPS REQUIREMENTS

BEGIN INFORMATION

m. Only those FTDs that are sponsored by a certificate holder as defined in Appendix F of this part will be evaluated by the responsible Flight Standards office. However, other FTD evaluations may be conducted on a case-by-case basis as the Administrator deems appropriate, but only in accordance with applicable agreements.

n. The responsible Flight Standards office will conduct an evaluation for each configuration, and each FTD must be evaluated as completely as possible. To ensure a thorough

and uniform evaluation, each FTD is subjected to the general FTD requirements in Attachment 1 of this appendix, the objective tests listed in Attachment 2 of this appendix, and the subjective tests listed in Attachment 3 of this appendix. The evaluations described herein will include, but not necessarily be limited to the following:

- (1) Helicopter responses, including longitudinal and lateral-directional control responses (see Attachment 2 of this appendix).
- (2) Performance in authorized portions of the simulated helicopter's operating envelope, to include tasks evaluated by the responsible Flight Standards office in the areas of surface operations, takeoff, climb, cruise, descent, approach and landing, as well as abnormal and emergency operations (see Attachment 2 of this appendix).
- (3) Control checks (see Attachment 1 and Attachment 2 of this appendix).
- (4) Flight deck configuration (see Attachment 1 of this appendix).
- (5) Pilot, flight engineer, and instructor station functions checks (see Attachment 1 and Attachment 3 of this appendix).
- (6) Helicopter systems and sub-systems (as appropriate) as compared to the helicopter simulated (see attachment 1 and attachment 3 of this appendix).
- (7) FTD systems and sub-systems, including force cueing (motion), visual, and aural (sound) systems, as appropriate (see Attachment 1 and Attachment 2 of this appendix).
- (8) Certain additional requirements, depending upon the qualification level sought, including equipment or circumstances that may become hazardous to the occupants. The sponsor may be subject to Occupational Safety and Health Administration requirements.
- o. The responsible Flight Standards office administers the objective and subjective tests, which include an examination of functions. The tests include a qualitative assessment of the FTD by a pilot from the responsible Flight Standards office. The evaluation team leader may assign other qualified personnel to assist in accomplishing the functions examination and/or the objective and subjective tests performed during an evaluation when required.
- (1) Objective tests provide a basis for measuring and evaluating FTD performance and determining compliance with the requirements of this part.
 - (2) Subjective tests provide a basis for:
- (a) Evaluating the capability of the FTD to perform over a typical utilization period;
- (b) Determining that the FTD satisfactorily simulates each required task;
- (c) Verifying correct operation of the FTD controls, instruments, and systems; and
- (d) Demonstrating compliance with the requirements of this part.
- p. The tolerances for the test parameters listed in Attachment 2 of this appendix re-

flect the range of tolerances acceptable to the responsible Flight Standards office for FTD validation and are not to be confused with design tolerances specified for FTD manufacture. In making decisions regarding tests and test results, the responsible Flight Standards office relies on the use of operational and engineering judgment in the application of data (including consideration of the way in which the flight test was flown and way the data was gathered and applied), data presentations, and the applicable tolerances for each test.

- q. In addition to the scheduled continuing qualification evaluation, each FTD is subject to evaluations conducted by the responsible Flight Standards office at any time without prior notification to the sponsor. Such evaluations would be accomplished in a normal manner (i.e., requiring exclusive use of the FTD for the conduct of objective and subjective tests and an examination of functions) if the FTD is not being used for flight crewmember training, testing, or checking. However, if the FTD were being used, the evaluation would be conducted in a non-exclusive manner. This non-exclusive evaluation will be conducted by the FTD evaluator accompanying the check airman, instructor, Aircrew Program Designee (APD), or FAA inspector aboard the FTD along with the student(s) and observing the operation of the FTD during the training, testing, or checking activities.
- r. Problems with objective test results are handled as follows:
- (1) If a problem with an objective test result is detected by the evaluation team during an evaluation, the test may be repeated or the QTG may be amended.
- (2) If it is determined that the results of an objective test do not support the qualification level requested but do support a lower level, the responsible Flight Standards office may qualify the FTD at a lower level.
- s. After an FTD is successfully evaluated, the responsible Flight Standards office issues an SOQ to the sponsor. The responsible Flight Standards office recommends the FTD to the TPAA, who will approve the FTD for use in a flight training program. The SOQ will be issued at the satisfactory conclusion of the initial or continuing qualification evaluation and will list the tasks for which the FTD is qualified, referencing the tasks described in Table D1B in Attachment 1 of this appendix. However, it is the sponsor's responsibility to obtain TPAA approved flight training program.
- t. Under normal circumstances, the responsible Flight Standards office establishes a date for the initial or upgrade evaluation within ten (10) working days after determining that a complete QTG is acceptable.

Unusual circumstances may warrant establishing an evaluation date before this determination is made. A sponsor may schedule an evaluation date as early as 6 months in advance. However, there may be a delay of 45 days or more in rescheduling and completing the evaluation if the sponsor is unable to meet the scheduled date. See Attachment 4, of this appendix, Figure D4A, Sample Request for Initial, Upgrade, or Reinstatement Evaluation.

- u. The numbering system used for objective test results in the QTG should closely follow the numbering system set out in Attachment 2, FTD Objective Tests, Table D2A of this appendix.
- v. Contact the responsible Flight Standards office for additional information regarding the preferred qualifications of pilots used to meet the requirements of $\S60.15(d)$.
- w. Examples of the exclusions for which the FTD might not have been subjectively tested by the sponsor or the responsible Flight Standards office and for which qualification might not be sought or granted, as described in §60.15(g)(6), include approaches to and departures from slopes and pinnacles.

END INFORMATION

12. ADDITIONAL QUALIFICATIONS FOR CURRENTLY QUALIFIED FTDs (§60.16)

BEGIN INFORMATION

No additional regulatory or informational material applies to \$60.16, Additional Qualifications for a Currently Qualified FTD.

END INFORMATION

13. Previously Qualified FTDs (§60.17)

BEGIN QPS REQUIREMENTS

- a. In instances where a sponsor plans to remove an FTD from active status for a period of less than two years, the following procedures apply:
- (1) The responsible Flight Standards office must be notified in writing and the notification must include an estimate of the period that the FTD will be inactive.
- (2) Continuing Qualification evaluations will not be scheduled during the inactive period.
- (3) The responsible Flight Standards office will remove the FTD from the list of qualified FTDs on a mutually established date not later than the date on which the first missed continuing qualification evaluation would have been scheduled.

- (4) Before the FTD is restored to qualified status, it must be evaluated by the responsible Flight Standards office. The evaluation content and the time required to accomplish the evaluation is based on the number of continuing qualification evaluations and sponsor-conducted quarterly inspections missed during the period of inactivity.
- (5) The sponsor must notify the responsible Flight Standards office of any changes to the original scheduled time out of service.
- b. FTDs and replacement FTD systems qualified prior to May 30, 2008, are not required to meet the general FTD requirements, the objective test requirements, and the subjective test requirements of Attachments 1, 2, and 3, respectively, of this appendix as long as the FTD continues to meet the test requirements contained in the MQTG developed under the original qualification basis
- c. After (1 year after date of publication of the final rule in the FEDERAL REGISTER) each visual scene and airport model installed in and available for use in a qualified FTD must meet the requirements described in Attachment 3 of this appendix.
- d. Simulators qualified prior to May 30, 2008, may be updated. If an evaluation is deemed appropriate or necessary by the responsible Flight Standards office after such an update, the evaluation will not require an evaluation to standards beyond those against which the simulator was originally qualified.

END QPS REQUIREMENTS

BEGIN INFORMATION

- e. Other certificate holders or persons desiring to use an FTD may contract with FTD sponsors to use FTDs previously qualified at a particular level for a helicopter type and approved for use within an FAA-approved flight training program. Such FTDs are not required to undergo an additional qualification process, except as described in §60.16.
- f. Each FTD user must obtain approval from the appropriate TPAA to use any FTD in an FAA-approved flight training program.
- g. The intent of the requirement listed in §60.17(b), for each FTD to have an SOQ within 6 years, is to have the availability of that statement (including the configuration list and the limitations to authorizations) to provide a complete picture of the FTD inventory regulated by the FAA. The issuance of the statement will not require any additional evaluation or require any adjustment to the evaluation basis for the FTD.
- h. Downgrading of an FTD is a permanent change in qualification level and will necessitate the issuance of a revised SOQ to reflect the revised qualification level, as appropriate. If a temporary restriction is

Federal Aviation Administration, DOT

placed on an FTD because of a missing, malfunctioning, or inoperative component or ongoing repairs, the restriction is not a permanent change in qualification level. Instead, the restriction is temporary and is removed when the reason for the restriction has been resolved.

- i. It is not the intent of the responsible Flight Standards office to discourage the improvement of existing simulation (e.g., the "updating" of a control loading system, or the replacement of the IOS with a more capable unit) by requiring the "updated" device to meet the qualification standards current at the time of the update. Depending on the extent of the update, the responsible Flight Standards officemay require that the updated device be evaluated and may require that an evaluation include all or a portion of the elements of an initial evaluation. However, the standards against which the device would be evaluated are those that are found in the MQTG for that device.
- j. The responsible Flight Standards officewill determine the evaluation criteria for an FTD that has been removed from active status for a prolonged period. The criteria will be based on the number of continuing qualification evaluations and quarterly inspections missed during the period of inactivity. For example, if the FTD were out of service for a 1 year period, it would be necessary to complete the entire QTG, since all of the quarterly evaluations would have been missed. The responsible Flight Standards officewill also consider how the FTD was stored, whether parts were removed from the FTD and whether the FTD was disassembled.
- k. The FTD will normally be requalified using the FAA-approved MQTG and the criteria that was in effect prior to its removal from qualification. However, inactive periods of 2 years or more will require re-qualification under the standards in effect and current at the time of requalification.

END INFORMATION

14. Inspection, Continuing Qualification, Evaluation, and Maintenance Requirements (\$60.19)

BEGIN QPS REQUIREMENT

- a. The sponsor must conduct a minimum of four evenly spaced inspections throughout the year. The objective test sequence and content of each inspection in this sequence must be developed by the sponsor and must be acceptable to the responsible Flight Standards office.
- b. The description of the functional preflight check must be contained in the sponsor's QMS.

- c. Record "functional preflight" in the FTD discrepancy log book or other acceptable location, including any item found to be missing, malfunctioning, or inoperative.
- d. During the continuing qualification evaluation conducted by the responsible Flight Standards office, the sponsor must also provide a person knowledgeable about the operation of the aircraft and the operation of the FTD.

END QPS REQUIREMENTS

BEGIN INFORMATION

- e. The sponsor's test sequence and the content of each quarterly inspection required in §60.19(a)(1) should include a balance and a mix from the objective test requirement areas listed as follows:
 - (1) Performance.
 - (2) Handling qualities.
 - (3) Motion system (where appropriate).
 - (4) Visual system (where appropriate).
 - (5) Sound system (where appropriate).
 - (6) Other FTD systems.
- f. If the evaluator plans to accomplish specific tests during a normal continuing qualification evaluation that requires the use of special equipment or technicians, the sponsor will be notified as far in advance of the evaluation as practical; but not less than 72 hours. Examples of such tests include latencies and control sweeps.
- g. The continuing qualification evaluations described in §60.19(b) will normally require 4 hours of FTD time. However, flexibility is necessary to address abnormal situations or situations involving aircraft with additional levels of complexity (e.g., computer controlled aircraft). The sponsor should anticipate that some tests may require additional time. The continuing qualification evaluations will consist of the following:
- (1) Review of the results of the quarterly inspections conducted by the sponsor since the last scheduled continuing qualification evaluation.
- (2) A selection of approximately 8 to 15 objective tests from the MQTG that provide an adequate opportunity to evaluate the performance of the FTD. The tests chosen will be performed either automatically or manually and should be able to be conducted within approximately one-third (1/3) of the allotted FTD time.
- (3) A subjective evaluation of the FTD to perform a representative sampling of the tasks set out in attachment 3 of this appendix. This portion of the evaluation should take approximately two-thirds (2/3) of the allotted FTD time.
- (4) An examination of the functions of the FTD may include the motion system, visual

system, sound system as applicable, instructor operating station, and the normal functions and simulated malfunctions of the simulated helicopter systems. This examination is normally accomplished simultaneously with the subjective evaluation requirements.

h. The requirement established in \$60.19(b)(4) regarding the frequency of responsible Flight Standards office-conducted continuing qualification evaluations for each FTD is typically 12 months. However, the establishment and satisfactory implementation of an approved QMS for a sponsor will provide a basis for adjusting the frequency of evaluations to exceed 12-month intervals.

END INFORMATION

15. Logging FTD Discrepancies (§60.20)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.20. Logging FTD Discrepancies.

END INFORMATION

16. INTERIM QUALIFICATION OF FTDs FOR NEW HELICOPTER TYPES OR MODELS (§ 60.21)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.21, Interim Qualification of FTDs for New Helicopter Types or Models.

END INFORMATION

17. Modifications to FTDs (§60.23)

BEGIN QPS REQUIREMENTS

- a. The notification described in $\S 60.23(c)(2)$ must include a complete description of the planned modification, with a description of the operational and engineering effect the proposed modification will have on the operation of the FTD and the results that are expected with the modification incorporated.
- b. Prior to using the modified FTD:
- (1) All the applicable objective tests completed with the modification incorporated, including any necessary updates to the MQTG (e.g., accomplishment of FSTD Directives) must be acceptable to the responsible Flight Standards office; and
- (2) The sponsor must provide the responsible Flight Standards office with a statement signed by the MR that the factors list-

ed in $\S60.15(b)$ are addressed by the appropriate personnel as described in that section.

END QPS REQUIREMENTS

BEGIN INFORMATION

c. FSTD Directives are considered modification of an FTD. See Attachment 4 of this appendix, Figure D4I for a sample index of effective FSTD Directives. See Attachment 6 of this appendix for a list of all effective FSTD Directives applicable to Helicopter FTDs.

END INFORMATION

18. OPERATION WITH MISSING, MALFUNC-TIONING, OR INOPERATIVE COMPONENTS (§60.25)

BEGIN INFORMATION

- a. The sponsor's responsibility with respect to §60.25(a) is satisfied when the sponsor fairly and accurately advises the user of the current status of an FTD, including any missing, malfunctioning, or inoperative (MMI) component(s).
- b. It is the responsibility of the instructor, check airman, or representative of the administrator conducting training, testing, or checking to exercise reasonable and prudent judgment to determine if any MMI component is necessary for the satisfactory completion of a specific maneuver, procedure, or task.
- c. If the 29th or 30th day of the 30-day period described in §60.25(b) is on a Saturday, a Sunday, or a holiday, the FAA will extend the deadline until the next business day.
- d. In accordance with the authorization described in \$60.25(b), the sponsor may develop a discrepancy prioritizing system to accomplish repairs based on the level of impact on the capability of the FTD. Repairs having a larger impact on the FTD's ability to provide the required training, evaluation, or flight experience will have a higher priority for repair or replacement.

END INFORMATION

19. Automatic Loss of Qualification and Procedures for Restoration of Qualification ($\S 60.27$)

BEGIN INFORMATION

If the sponsor provides a plan for how the FTD will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems;

Federal Aviation Administration, DOT

routine replacement of hydraulic fluid; control of the environmental factors in which the FTD is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing that is required for requalification.

END INFORMATION

20. Other Losses of Qualification and Procedures for Restoration of Qualification (§ 60.29)

BEGIN INFORMATION

If the sponsor provides a plan for how the FTD will be maintained during its out-of-service period (e.g., periodic exercise of mechanical, hydraulic, and electrical systems; routine replacement of hydraulic fluid; control of the environmental factors in which the FTD is to be maintained) there is a greater likelihood that the responsible Flight Standards office will be able to determine the amount of testing that is required for requalification.

END INFORMATION

21. RECORD KEEPING AND REPORTING (§60.31)

BEGIN QPS REQUIREMENTS

a. FTD modifications can include hardware or software changes. For FTD modifications involving software programming changes, the record required by \$60.31(a)(2) must consist of the name of the aircraft system software, aerodynamic model, or engine model change, the date of the change, a summary of the change, and the reason for the change.

b. If a coded form for record keeping is used, it must provide for the preservation and retrieval of information with appropriate security or controls to prevent the inappropriate alteration of such records after the fact.

END INFORMATION

22. APPLICATIONS, LOGBOOKS, REPORTS, AND RECORDS: FRAUD, FALSIFICATION, OR INCORRECT STATEMENTS (§ 60.33)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.33, Applications, Logbooks, Reports, and Records: Fraud, Falsification, or Incorrect Statements 23 [Reserved]

END INFORMATION

24. Levels of FTD

BEGIN INFORMATION

a. The following is a general description of each level of FTD. Detailed standards and tests for the various levels of FTDs are fully defined in Attachments 1 through 3 of this appendix.

(1) Level 4. A Level 4 device is one that may have an open helicopter-specific flight deck area, or an enclosed helicopter-specific flight deck and at least one operating system. Air/ground logic is required (no aerodynamic programming required). All displays may be flat/LCD panel representations or actual representations of displays in the aircraft. All controls, switches, and knobs may be touch sensitive activation (not capable of manual manipulation of the flight controls) or may physically replicate the aircraft in control operation.

(2) Level 5. A Level 5 device is one that may have an open helicopter-specific flight deck area, or an enclosed helicopter-specific flight deck and a generic aerodynamic program with at least one operating system and control loading representative of the simulated helicopter. The control loading need only represent the helicopter at an approach speed and configuration. All displays may be flat/LCD panel representations or actual representations of displays in the aircraft. Primary and secondary flight controls (e.g., rudder, aileron, elevator, flaps, spoilers/speed brakes, engine controls, landing gear, nosewheel steering, trim, brakes) must be physical controls. All other controls, switches, and knobs may be touch sensitive activa-

(3) Level 6. A Level 6 device is one that has an enclosed helicopter-specific flight deck and aerodynamic program with all applicable helicopter systems operating and control loading that is representative of the simulated helicopter throughout its ground and flight envelope and significant sound representation. All displays may be flat/LCD panel representations or actual representations of displays in the aircraft, but all controls, switches, and knobs must physically replicate the aircraft in control operation.

(4) Level 7. A Level 7 device is one that has an enclosed helicopter-specific flight deck and aerodynamic program with all applicable helicopter systems operating and control loading that is representative of the simulated helicopter throughout its ground and flight envelope and significant sound representation. All displays may be flat/LCD

panel representations or actual representations of displays in the aircraft, but all controls, switches, and knobs must physically replicate the aircraft in control operation. It also has a visual system that provides an out-of-the-flight deck view, providing cross-flight deck viewing (for both pilots simultaneously) of a field-of-view of at least 146° horizontally and 36° vertically as well as a vibration cueing system for characteristic helicopter vibrations noted at the pilot station(s).

END INFORMATION

25. FTD QUALIFICATION ON THE BASIS OF A BI-LATERAL AVIATION SAFETY AGREEMENT (BASA) (§ 60.37)

BEGIN INFORMATION

No additional regulatory or informational material applies to §60.37, FTD Qualification on the Basis of a Bilateral Aviation Safety Agreement (BASA).

END INFORMATION

ATTACHMENT 1 TO APPENDIX D TO PART 60— GENERAL FTD REQUIREMENTS

BEGIN QPS REQUIREMENTS

1. Requirements

- a. Certain requirements included in this appendix must be supported with an SOC as defined in Appendix F, which may include objective and subjective tests. The requirements for SOCs are indicated in the "General FTD Requirements" column in Table D1A of this appendix.
- b. Table D1A describes the requirements for the indicated level of FTD. Many devices include operational systems or functions that exceed the requirements outlined in

14 CFR Ch. I (1-1-24 Edition)

this section. In any event, all systems will be tested and evaluated in accordance with this appendix to ensure proper operation.

END QPS REQUIREMENTS

BEGIN INFORMATION

2. Discussion

- a. This attachment describes the general requirements for qualifying Level 4 through Level 7 FTDs. The sponsor should also consult the objectives tests in Attachment 2 of this appendix and the examination of functions and subjective tests listed in Attachment 3 of this appendix to determine the complete requirements for a specific level FTD.
- b. The material contained in this attachment is divided into the following categories:
- (1) General Flight Deck Configuration.
- (2) Programming.
- (3) Equipment Operation.
- (4) Equipment and Facilities for Instructor/Evaluator Functions.
- (5) Motion System.
- (6) Visual System.
- (7) Sound System.
- c. Table D1A provides the standards for the General FTD Requirements.
- d. Table D1B provides the tasks that the sponsor will examine to determine whether the FTD satisfactorily meets the requirements for flight crew training, testing, and experience.
- e. Table D1C provides the functions that an instructor/check airman must be able to control in the simulator.
- f. It is not required that all of the tasks that appear on the List of Qualified Tasks (part of the SOQ) be accomplished during the initial or continuing qualification evaluation.

END INFORMATION

TABLE D1A—MINIMUM FTD REQUIREMENTS

	TABLE BITT WINNIN	0.0.			QU.	TEMENTO
QPS requirements					Information	
Entry No.	General FTD requirements		FTD	level		Notes
Lilliy No.	deneral 1 15 requirements	4	5	6	7	Notes

1. General Flight Deck Configuration.

	QPS requirements					Information
Entry No.	General FTD requirements		FTD	level		Notes
		4	5	6	7	
1.a	The FTD must have a flight deck that is a replica of the helicopter, or set of helicopters simulated with controls, equipment, observable flight deck indicators, circuit breakers, and bulkheads properly located, functionally accurate and replicating the helicopter or set of helicopters. The direction of movement of controls and switches must be identical to that in the helicopter or set of helicopters. Crewmember seats must afford the capability for the occupant to be able to achieve the design "eye position." Equipment for the operation of the flight deck windows must be included, but the actual windows need not be operable. Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate. Fire axes, extinguishers, landing gear pins, and spare light bulbs must be available, and may be represented in silhouette, in the flight simulator. This equipment must be present as near as practical to the original position			X	X	For FTD purposes, the flight deck consists of all that space forward of a cross section of the flight deck at the most extreme aft set ting of the pillots' seats including additional required crewmember duty stations and those required bulkheads aft of the pillot seats. Bulkheads containing only items such as landing gear pin storage compart ments, fire axes and extinguishers, sparr light bulbs, and aircraft documents pouches are not considered essential and may be omitted. If omitted, these items, or the sil houettes of these items, may be placed on the wall of the simulator, or in any other location as near as practical to the original position of these items.
1.b	The FTD must have equipment (i.e., instruments, panels, systems, circuit breakers, and controls) simulated sufficiently for the authorized training/checking events to be accomplished. The installed equipment, must be located in a spatially correct configuration, and may be in a flight deck or an open flight deck area. Those circuit breakers that affect procedures or result in observable flight deck indications must be properly located and functionally accurate. Additional equipment required for the authorized training and checking events must be available in the FTD but may be located in a suitable location as near as practical to the spatially correct position. Actuation of this equipment must replicate the appropriate function in the helicopter. Fire axes, landing gear pins, and any similar purpose instruments need only be represented in silhouette	X	X			
2. Programn	ning.					
2.a	The FTD must provide the proper effect of aerodynamic changes for the combinations of drag and thrust normally encountered in flight. This must include the effect of change in helicopter attitude, thrust, drag, altitude, temperature, and configuration. Levels 6 and 7 additionally require the effects of changes in gross weight and center of gravity.Level 5 requires only generic aerodynamic programming. An SOC is required.		x	x	x	
2.b	The FTD must have the computer (analog or digital) capability (i.e., capacity, accuracy, resolution, and dynamic response) needed to meet the qualification level sought. An SOC is required	х	х	х	х	

14 CFR Ch. I (1-1-24 Edition)

TABLE D1A—MINIMUM FTD REQUIREMENTS—Continued

	QPS requirements					Information
Entry No.	General FTD requirements	4	5	level 6	7	Notes
2.c	Relative responses of the flight deck instruments must be measured by latency tests or transport delay tests, and may not exceed 150 milliseconds. The instruments must respond to abrupt input at the pilot's position within the allotted time, but not before the time that the helicopter or set of helicopters respond under the same conditions • Latency: The FTD instrument and, if applicable, the motion system and the visual system response must not be prior to that time when the helicopter responds and may respond up to 150 milliseconds after that time under the same conditions. • Transport Delay: As an alternative to the Latency requirement, a transport delay objective test may be used to demonstrate that the FTD system does not exceed the specified limit. The sponsor must measure all the delay encountered by a step signal migrating from the pilot's control through all the simulation software modules in the correct order, using a handshaking protocol, finally through the normal output interfaces to the instrument display and, if applicable, the motion system, and the visual system.		X	X	X	The intent is to verify that the FTD provides instrument cues that are, within the stated time delays, like the helicopter responses. For helicopter response, acceleration in the appropriate, corresponding rotational axis is preferred.
3.a	All relevant instrument indications involved in the simulation of the helicopter must automatically respond to control movement or external disturbances to the simulated helicopter or set of helicopters; e.g., turbulence or winds	А	х	х	х	
3.b	Navigation equipment must be installed and operate within the tolerances applicable for the helicopter or set of helicopters. Levels 6 and 7 must also include communication equipment (inter-phone and air/ground) like that in the helicopter. Level 5 only needs that navigation equipment necessary to fly an instrument approach	А	х	х	х	
3.c	Installed systems must simulate the applicable helicopter system operation both on the ground and in flight. At least one helicopter system must be represented. Systems must be operative to the extent that applicable normal, abnormal, and emergency operating procedures included in the sponsor's training programs can be accomplished. Levels 6 and 7 must simulate all applicable helicopter flight, navigation, and systems operation. Level 5 must have functional flight and navigational controls, displays, and instrumentation	A	x	x	x	
3.d	The lighting environment for panels and instruments must be sufficient for the operation being conducted	х	х	х	х	Back-lighted panels and instruments may be installed but are not required.

	QPS requirements					Information		
Entry No.	General FTD requirements			level		Notes		
3.e	The FTD must provide control forces and control travel that correspond to the replicated helicopter or set of helicopters. Control forces must react in the same manner as in the helicopter or set of helicopters under the same flight conditions	4	5	6 X	7 X			
3.f	The FTD must provide control forces and control travel of sufficient precision to manually fly an instrument approach. The control forces must react in the same manner as in the helicopter or set of helicopters under the same flight conditions		х					
4. Instructor	or Evaluator Facilities.							
4.a	In addition to the flight crewmember stations, suitable seating arrangements for an instructor/check airman and FAA Inspector must be available. These seats must provide adequate view of crewmember's panel(s)	x	x	x	x	These seats need not be a replica of an aircraft seat and may be as simple as an office chair placed in an appropriate position.		
4.b	The FTD must have instructor controls that permit activation of normal, abnormal, and emergency conditions, as appropriate. Once activated, proper system operation must result from system management by the crew and not require input from the instructor controls.	x	x	x	x			
5. Motion Sy	/stem				•			
5.a	A motion system may be installed in an FTD. If installed, the motion system operation must not be distracting. If a motion system is installed and additional training, testing, or checking credits are being sought, sensory cues must also be integrated. The motion system must respond to abrupt input at the pilot's position within the allotted time, but not before the time when the helicopter responds under the same conditions. The motion system must be measured by latency tests or transport delay tests and may not exceed 150 milliseconds. Instrument response must not occur prior to motion onset	×	×	×	X			
5.b	The FTD must have at least a vibration cue- ing system for characteristic helicopter vi- brations noted at the pilot station(s)				х	May be accomplished by a "seat shaker" or a bass speaker sufficient to provide the necessary cueing.		
6. Visual Sy	stem							
6.a 6.a.1	The FTD may have a visual system, if desired, although it is not required. If a visual system is installed, it must meet the following criteria: The visual system must respond to abrupt input at the pilot's position. An SOC is required	x	x	x				
6.a.2	The visual system must be at least a single channel, non-collimated display. An SOC is required	х	х	х				

14 CFR Ch. I (1-1-24 Edition)

TABLE D1A—MINIMUM FTD REQUIREMENTS—Continued

	QPS requirements					Information		
Entry No.	General FTD requirements	4	FTD 5	level 6	7	Notes		
6.a.3	The visual system must provide at least a field-of-view of 18° vertical/24° horizontal for the pilot flying. An SOC is required	х	х	х				
6.a.4	The visual system must provide for a maximum parallax of 10° per pilot. An SOC is required	х	х	х				
6.a.5	The visual scene content may not be distracting. An SOC is required	Х	х	х				
6.a.6	The minimum distance from the pilot's eye position to the surface of a direct view display may not be less than the distance to any front panel instrument. An SOC is required	x	x	x				
6.a.7	The visual system must provide for a minimum resolution of 5 arc-minutes for both computed and displayed pixel size. An SOC is required	х	х	х				
6.b	If a visual system is installed and additional training, testing, or checking credits are being sought on the basis of having a visual system, a visual system meeting the standards set out for at least a Level A FFS (see Appendix A of this part) will be required. A "direct-view," non-collimated visual system (with the other requirements for a Level A visual system met) may be considered satisfactory for those installations where the visual system design "eye point" is appropriately adjusted for each pilot's position such that the parallax error is at or less than 10° simultaneously for each pilot.	x	x	x				
6.c	The FTD must provide a continuous visual field-of-view of at least 146° horizontally and 36° vertically for both pilot seats, simultaneously. The minimum horizontal field-of-view coverage must be plus and minus one-half (½) of the minimum continuous field-of-view requirement, centered on the zero degree azimuth line relative to the aircraft fuselage. Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained. Capability for a field-of-view in excess of these minima is not required for qualification at Level 7. However, where specific tasks require extended fields of view beyond the 146° by 36° (e.g., to accommodate the use of "chin windows" where the accommodation is either integral with or separate from the primary visual system display), then such extended fields of view must be provided An SOC is required and must explain the geometry of the installation.				x	Optimization of the vertical field-of-view may be considered with respect to the specific helicopter flight deck cut-off angle. When considering the installation/use of augmented fields of view, as described here, it will be the responsibility of the sponsor to meet with the responsible Flight Standards office to determine the training, testing, checking, or experience tasks for which the augmented field-of-view capability may be critical to that approval.		

7. Sound System

TABLE D1A—MINIMUM FTD REQUIREMENTS—Continued

	QPS requirements					Information
Entry No.	General FTD requirements		FTD	level		Notes
Entry No.	General Fib requirements	4	5	6	7	Notes
7.a	The FTD must simulate significant flight deck sounds resulting from pilot actions that correspond to those heard in the helicopter			х	х	

Note: An "A" in the table indicates that the system, task, or procedure may be examined if the appropriate helicopter system or control is simulated in the FTD and is working properly.

TABLE D1B—MINIMUM FTD REQUIREMENTS

	QPS requirements					Information
Entry No.	Subjective requirements The FTD must be able to perform the tasks associated with the level of qualification sought.	4	FTD 4 5		7	Notes
1. Prefligh	t Procedures			6		
1.a		Α	Α	х	х	
1.b	. APU/Engine start and run-up.					
1.b.1	. Normal start procedures	Α	Α	Х	х	
1.b.2	. Alternate start procedures	Α	Α	Х	х	
1.b.3	. Abnormal starts and shutdowns (hot start, hung start).	Α	Α	х	х	
1.c	. Taxiing—Ground				х	
1.d	. Taxiing—Hover				х	
1.e	. Pre-takeoff Checks	Α	Α	Х	х	
2. Takeoff	and Departure Phase	•	•	•		
2.a	. Normal takeoff.					
2.a.1	. From ground				х	
2.a.2	. From hover				х	
2.a.3	Running				х	
2.b	. Instrument			Х	х	
2.c	. Powerplant Failure During Takeoff			Х	х	
2.d	. Rejected Takeoff				х	
2.e	. Instrument Departure			Х	х	
3. Climb						
3.a	Normal			Х	х	
3.b	. Obstacle clearance				х	
3.c	. Vertical			Х	х	
3.d	. One engine inoperative			х	х	
4. In-flight	Maneuvers					
4.a	. Turns (timed, normal, steep)		Х	Х	х	
4.b	. Powerplant Failure—Multiengine Helicopters			Х	х	
		397	7			
rDate Sep<11>2014 14:00 Mar 14, 2024	. Turns (timed, normal, steep)	<i>ວອ</i> 10	Sfmt	: 800	2 0	Ω:\14\14V2.TXT PC31

TABLE D1B—MINIMUM FTD REQUIREMENTS—Continued

	QPS requirements					Information
Entry No.	Subjective requirements The FTD must be able to perform the tasks associated with the level of qualification			level		Notes
	sought.	4	5	6	7	
4.c	Powerplant Failure—Single-Engine Helicopters.			Х	Х	
4.d	Recovery From Unusual Attitudes				Х	
4.e	Settling with Power				х	
5. Instrume	nt Procedures					
5.a	Instrument Arrival			Х	Х	
5.b	Holding			х	х	
5.c	Precision Instrument Approach					
5.c.1	Normal—All engines operating		х	х	х	
5.c.2	Manually controlled—One or more engines in- operative.			Х	Х	
5.d	Non-precision Instrument Approach		Х	х	х	
5.e	Missed Approach.					
5.e.1	All engines operating			х	х	
5.e.2	One or more engines inoperative			х	х	
5.e.3	Stability augmentation system failure			х	х	
6. Landings	and Approaches to Landings					
6.a	Visual Approaches (normal, steep, shallow)		Х	Х	х	
6.b	Landings.					
6.b.1	Normal/crosswind.					
6.b.1.a	Running				х	
6.b.1.b	From Hover				х	
6.b.2	One or more engines inoperative				х	
6.b.3	Rejected Landing				х	
7. Normal a	nd Abnormal Procedures					
7.a	Powerplant	Α	Α	Х	х	
7.b	Fuel System	Α	Α	х	х	
7.c	Electrical System	Α	Α	х	х	
7.d	Hydraulic System	Α	Α	х	х	
7.e	Environmental System(s)	Α	Α	х	х	
7.f	Fire Detection and Extinguisher Systems	Α	Α	Х	Х	
7.g	Navigation and Aviation Systems	Α	Α	Х	х	
7.h	Automatic Flight Control System, Electronic Flight Instrument System, and Related Subsystems.	Α	Α	X	x	
7.i	Flight Control Systems	Α	Α	Х	Х	
7.j	Anti-ice and Deice Systems	Α	Α	Х	Х	

TABLE D1B—MINIMUM FTD REQUIREMENTS—Continued

	QPS requirements					Information
Entry No.	Subjective requirements The FTD must be able to perform the tasks associated with the level of qualification		FTD	level		Notes
	associated with the level of qualification sought.	4	5	6	7	
7.k	Aircraft and Personal Emergency Equipment	Α	Α	Х	х	
7.l	Special Missions tasks (e.g., Night Vision gog- gles, Forward Looking Infrared System, Ex- ternal Loads and as listed on the SOQ.).				х	
8. Emergen	cy procedures (as applicable)					
8.a	Emergency Descent			х	х	
8.b	Inflight Fire and Smoke Removal			х	х	
8.c	Emergency Evacuation			Х	х	
8.d	Ditching				х	
8.e	Autorotative Landing				х	
8.f	Retreating blade stall recovery				х	
8.g	Mast bumping				х	
8.h	Loss of tail rotor effectiveness			Х	х	
9. Postflight	Procedures					
9.a	After-Landing Procedures	Α	Α	Х	Х	
9.b	Parking and Securing					
9.b.1	Rotor brake operation	Α	Α	Х	х	
9.b.2	Abnormal/emergency procedures	Α	Α	Х	Х	

Note: An "A" in the table indicates that the system, task, or procedure may be examined if the appropriate aircraft system or control is simulated in the FTD and is working properly.

TABLE D1C—TABLE OF FTD SYSTEM TASKS

	QPS requirements					Information		
Entry No.	Subjective requirements In order to be qualified at the FTD qualification level indicated, the FTD must be able to perform at least the tasks as-		FTD	level		Notes		
ĺ	sociate with that level of qualification.	4	5	6	7			
1. Instructor	. Instructor Operating Station (IOS)							
1.a	Power switch(es)	Α	х	х	х			
1.b	Helicopter conditions	Α	Α	х	х	e.g., GW, CG, Fuel loading, Systems, Ground. Crew.		
1.c	Airports/Heliports/Helicopter Landing Areas	Α	Х	х	х	e.g., Selection, Surface, Presets, Lighting controls		
1.d	Environmental controls	Α	х	x	x	e.g., Temp and Wind.		
1.e	Helicopter system malfunctions (Insertion/deletion)	Α	Α	х	х			
1.f	Locks, Freezes, and Repositioning (as appropriate)	Α	х	х	х			
1.g	Sound Controls. (On/off/adjustment)		х	х	х			
1.h	Motion/Control Loading System, as appropriate. On/off/emergency stop.		Α	х	х			

2. Observer Seats/Stations

QPS requirements					Information	
Entry No.	Subjective requirements In order to be qualified at the FTD qualification level indicated, the FTD must be able to perform at least the tasks associate with that level of qualification.	FTD level				Notes
		4	5	6	7	
2.a	Position/Adjustment/Positive restraint system	Α	х	х	х	

Note: An "A" in the table indicates that the system, task, or procedure may be examined if the appropriate simulator system or control is in the FTD and is working properly.

ATTACHMENT 2 TO APPENDIX D TO PART 60— FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TEXTS

BEGIN INFORMATION

1. DISCUSSION

a. If relevant winds are present in the objective data, the wind vector (magnitude and direction) should be noted as part of the data presentation, expressed in conventional terminology, and related to the runway being used for the test.

b. The format for numbering the objective tests in Appendix C of this part, Attachment 2, Table C2A, and the objective tests in Appendix D of this part, Attachment 2, Table D2A, is identical. However, each test required for FFSs is not necessarily required for FTDs, and each test required for FTDs is not necessarily required for FFSs. When a test number (or series of numbers) is not required, the term "Reserved" is used in the table at that location. Following this numbering format provides a degree of commonality between the two tables and substantially reduces the potential for confusion when referring to objective test numbers for either FFSs or FTDs.

c. A Level 4 FTD does not require objective tests and is not addressed in the following table.

END INFORMATION

BEGIN QPS REQUIREMENTS

2. Test Requirements

a. The ground and flight tests required for qualification are listed in Table D2A Objective Evaluation Tests. Computer generated FTD test results must be provided for each test except where an alternate test is specifically authorized by the responsible Flight Standards office. If a flight condition or operating condition is required for the test but does not apply to the helicopter being simulated or to the qualification level sought, it may be disregarded (e.g., engine out climb capability for a single-engine helicopter). Each test result is compared against the val-

idation data described in §60.13, and in Appendix B of this part. The results must be produced on an appropriate recording device acceptable to the responsible Flight Standards office and must include FTD number, date, time, conditions, tolerances, and appropriate dependent variables portrayed in comparison to the validation data. Time histories are required unless otherwise indicated in Table D2A. All results must be labeled using the tolerances and units given.

b. Table D2A in this attachment sets out the test results required, including the parameters, tolerances, and flight conditions for FTD validation. Tolerances are provided for the listed tests because mathematical modeling and acquisition and development of reference data are often inexact. All tolerances listed in the following tables are applied to FTD performance. When two tolerance values are given for a parameter, the less restrictive may be used unless otherwise indicated. In those cases where a tolerance is expressed only as a percentage, the tolerance percentage applies to the maximum value of that parameter within its normal operating range as measured from the neutral or zero position unless otherwise indicated.

c. Certain tests included in this attachment must be supported with an SOC. In Table D2A, requirements for SOCs are indicated in the "Test Details" column.

d. When operational or engineering judgment is used in making assessments for flight test data applications for FTD validity, such judgment must not be limited to a single parameter. For example, data that exhibit rapid variations of the measured parameters may require interpolations or a "best fit" data section. All relevant parameters related to a given maneuver or flight condition must be provided to allow overall interpretation. When it is difficult or impossible to match FTD to helicopter data throughout a time history, differences must be justified by providing a comparison of other related variables for the condition being assessed.

e. The FTD may not be programmed so that the mathematical modeling is correct only at the validation test points. Unless noted otherwise, tests must represent helicopter performance and handling qualities at operating weights and centers of gravity

(CG) typical of normal operation. If a test is supported by aircraft data at one extreme weight or CG, another test supported by aircraft data at mid-conditions or as close as possible to the other extreme is necessary. Certain tests that are relevant only at one extreme CG or weight condition need not be repeated at the other extreme. The results of the tests for Level 6 are expected to be indicative of the device's performance and handling qualities throughout all of the following:

- (1) The helicopter weight and CG envelope.
- (2) The operational envelope.
- (3) Varying atmospheric ambient and environmental conditions—including the extremes authorized for the respective helicopter or set of helicopters.
- f. When comparing the parameters listed to those of the helicopter, sufficient data must also be provided to verify the correct flight condition and helicopter configuration changes. For example, to show that control force is within the parameters for a static stability test, data to show the correct airspeed, power, thrust or torque, helicopter configuration, altitude, and other appropriate datum identification parameters must also be given. If comparing short period dynamics, normal acceleration may be used to establish a match to the helicopter, but airspeed, altitude, control input, helicopter configuration, and other appropriate data must also be given. If comparing landing gear change dynamics, pitch, airspeed, and altitude may be used to establish a match to the helicopter, but landing gear position must also be provided. All airspeed values must be properly annotated (e.g., indicated versus calibrated). In addition, the same variables must be used for comparison (e.g., compare inches to inches rather than inches to centimeters).
- g. The QTG provided by the sponsor must clearly describe how the FTD will be set up and operated for each test. Each FTD subsystem may be tested independently, but overall integrated testing of the FTD must be accomplished to assure that the total FTD system meets the prescribed standards. A manual test procedure with explicit and detailed steps for completing each test must also be provided.
- h. For previously qualified FTDs, the tests and tolerances of this attachment may be used in subsequent continuing qualification evaluations for any given test if the sponsor has submitted a proposed MQTG revision to the responsible Flight Standard office and has received responsible Flight Standards office approval.
- i. Tests of handling qualities must include validation of augmentation devices. FTDs for highly augmented helicopters will be validated both in the unaugmented configuration (or failure state with the maximum

permitted degradation in handling qualities) and the augmented configuration. Where various levels of handling qualities result from failure states, validation of the effect of the failure is necessary. For those performance and static handling qualities tests where the primary concern is control position in the unaugmented configuration, unaugmented data are not required if the design of the system precludes any affect on control position. In those instances where the unaugmented helicopter response is divergent and non-repeatable, it may not be feasible to meet the specified tolerances. Alternative requirements for testing will be mutually agreed upon by the sponsor and the responsible Flight Standards office on a case-by-case basis.

- j. Some tests will not be required for helicopters using helicopter hardware in the FTD flight deck (e.g., "helicopter modular controller"). These exceptions are noted in Section 2 "Handling Qualities" in Table D2A of this attachment. However, in these cases, the sponsor must provide a statement that the helicopter hardware meets the appropriate manufacturer's specifications and the sponsor must have supporting information to that fact available for responsible Flight Standards office review.
- k. In cases where light-class helicopters are being simulated, prior coordination with the responsible Flight Standards office on acceptable weight ranges is required. The terms "light," "medium," and "near maximum," may not be appropriate for the simulation of light-class helicopters.

END QPS REQUIREMENTS

BEGIN INFORMATION

- 1. In those cases where the objective test results authorize a "snapshot test" or a "series of snapshot test" results in lieu of a time-history result, the sponsor or other data provider must ensure that a steady state condition exists at the instant of time captured by the "snapshot." The steady state condition must exist from 4 seconds prior to, through 1 second following, the instant of time captured by the snap shot.
- m. Refer to AC 120-27, Aircraft Weight and Balance; and FAA-H-8083-1, Aircraft Weight and Balance Handbook, for more information

END INFORMATION

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS

		QPS requirements	ents				Information
	Test	- Constant	440:10	Circles to C	E	FTD level	2
Entry No.	Title	loreralices	riigiri coridirions	ופאן מפומווא	2	2 9	9000
1.	Performance						
1.a.	Engine Assessment.						
1.a.1.	Start Operations.						
1.a.1.a.	Engine start and acceleration (transient).	Light Off Time—±10% or ±1 sec. Torque—±5% Rotor Speed— ±3% Fuel Flow—±10% Gas Generator Speed—±5% Power Turbine Speed—±5% Gas Tur- bine Temp—±30 °C.	Ground with the Rotor Brake Used and Not Used.	Record each engine start from the initiation of the start se- quence to steady state idle and from steady state idle to oper- ating RPM.	^	×	
1.a.1.b	Steady State Idle and Operating RPM condi- tions.	Torque—±3% Rotor Speed— ±1.5% Fuel Flow—±5% Gas Generator Speed—±2% Power Turbine Speed—±2% Turbine Gas Temp—±20 °C.		Ground	×	×	
1.a.2.	1.a.2 Power Turbine Speed Trim.	±10% of total change of power Groundturbine speed or ±0.5% change of rotor speed.	Ground	Record engine response to trim system actuation in both directions.		× ×	
1.a.3	Engine and Rotor Speed Governing.	Engine and Rotor Speed Torque—±5% Rotor Speed— Climb Descent	Climb Descent	Record results using a step input to the collective. May be conducted concurrently with climb and descent performance tests.	^	×	
1.b	Reserved.						
1.c Takeoff.	Takeoff.						

								This test validates performance at speeds above maximum endurance air speed.	
	×			×		×		×	
								×	
								×	
	Record results of takeoff flight path (unning takeoff and takeoff from a hover). The criteria apply only to those segments at airspeeds above effective translational lift. Results must be recorded from the initiation of the takeoff to at least 200 ft (61 m) AGL.			Record results for light and heavy gross weights. May be a series of snapshot tests.		Record results for light and heavy gross weights. May be a series of snapshot tests.		Record results for two gross weight and CG combinations with varying trim speeds throughout the airspeed envelope. May be a series of snapshot tests.	
	Ground/Takeoff and Initial Segment of Climb.			In Ground Effect (IGE); and Out of Ground Effect (OGE).		From OGE Hover		Cruise (Augmentation On and Off).	
	Airspeed—±3 kt, Altitude—±20 ft (6.1 m) Torque—±3%. Rotor Speed—±1.5%, Vertical Velocity—±1.5%, Vertical Velocity—±1.00 fpm (0.50 m/sec) or 10%. Pitch Attitude—±1.5°. Bank Attitude—±2°. Heading—±2°, Longitudinal Control Position—±10%, Literal Control Position—±10%. Collective Control Position—±10%. Collective Control Position—±10%. Collective			Torque—±3%, Pitch Attitude—±1.5°, Bank Attitude—±1.5°, Longitudinal Control Position—±5%, Lateral Control Position—±5%, Directional Control Position—±5%. Collective Control Position—±5%.		Vertical Velocity—±100 fpm (0.50 m/sec) or ±10%, Directional Control Position—±5%, Collective Control Position—±5%.		Torque—±3% Pitch Attitude—±1.5° Sideslip Angle—±2° Longitudinal Control Position—±5% Latreal Control position—±5% Collective Control Position—±5% Collective Control Position—±5%.	
	All Engines	Reserved.	Hover.	Performance	Vertical Climb.	Performance	Level Flight.	Performance and Trimmed Flight Con- trol Positions.	Climb.
ah DISTILLER	1.6.1.	1.c.2. through 1.c.3	1.d.		1.e		1.f		1.g
RETITIES ON LAPBH6H6L3 with DISTILLER on LAPBH6H6L3 with DISTILLER on CAPBH6H6L3 with DISTILLER on LAPBH6H6L3 with DISTILLER on LAPBH6H6H6L3 with DISTILLER on LA	Mar 14, 2024 Jkt 262047 PO	0000	00 F		403		Q:\14	\14V2.TXT PC31	

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued

		Information	Social	6900					
			evel	7	×		×	×	
			FTD level	5 6	× ×		×	× ×	
	JECTIVE TESTS—Continued		Toch total		Record results for two gross x weight and CG combinations. The data presented must be for normal climb power conditions. May be a series of snapshot tests.		Record results for two gross x weight and CG combinations. May be a series of snapshot tests.	Record results for two gross x weight conditions. Data must be recorded for normal operating RPM. (Rotor speed tolerance applies only if collective control position is full down.) Data must be recorded for speeds from 50 kts, ±5 kts through at least maximum glide distance airspeed. May be a series of snapshot tests.	
	DEVICE (FTD) OB	ents	additional their		All engines operating One engine inoper- ative. Augmentation Sys- tem(s) On and Off.		At or near 1,000 fpm (5 m/sec) rate of descent (RoD) at normal approach speed. Augmentation System(s) On and Off.	Steady descents. Augmentation System(s) On and Off.	
	TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued	QPS requirements	Tolomoro	00000	Vertical Velocity—±100 fpm (61 m/sec) or ±10% Pitch Atti-tude—±15° Sidesip Angiel 22° Longitudinal Control Position—±5% Lateral Control Position—±5% Directional Control Position—±5% Collective Control Position—±5% Collective Control Position—±5%.		Torque—±3% Pitch Attitude— ±1.5° Sideslip Angle—±2° Lon- gitudinal Control Position—±5% Lateral Control Position—±5% Directional Control Position— ±5% Collective Control Posi- tion—±5%.	Pitch Attitude—±1.5° Sideslip Argle—±2° Longitudinal Con- trol Position—±5% Lateral Con- trol Position—±5% Diectonal Control Position—±5% Collec- tive Control Position—±5%.	
	Ĺ		Test	Title	Performance and Trimmed Flight Control Positions.	Descent.	Descent Performance and Trimmed Flight Control Positions.	Autorotation Performance and Trimmed Flight Control Positions.	Autorotation.
N DISTILLER				Entry No.		1.h.	1.h.1	1.6.2.	1.1
MIND SAUCH OF THE							404		

	×		×	-	
	×	-			
	Record results of a rapid throttle reduction to idle. If accomplished in cruise, results must be for the maximum range airspeed. If accomplished in climb, results must be for the maximum rate of climb airspeed at or near maximum continuous power.		Record results of the approach and landing profile (tunning landing or approach to a hover). The oriteria apply only to those segments at airspeeds above effective translational lift. Record the results from 200 ft AGL (61 m) to the landing or to where the hover is established prior to landing.		
	Cruise; or Climb		Approach		
	Rotor Speed—±3% Pitch Attitude ±2° Roli Attitude—±3° Yaw Atti- tude—±5° Airspeed—±5 kts. Vertical Velocity—±200 pm (1.00 m/sec) or 10%.		Airspeed—±3 kts, Altitude—±20 ft (6.1 m) Torque—±3%, Rotor Speed—±1.5%, Pitch Attitude—±1.5°, East Attitude—±1.5°, Longitudinal Control Position—±10%, Lateral Control Position—±10%, Lateral Control Position—±10%, Lateral Control Position—±10%, Collective Control Position—±10%, Lateral Control Position—±10%, Lateral L		
	Entry	Landing.	All Engines	Reserved.	
IN DISTILLER		1.j.	1,1.1	1.j.2. through 1.j.3	
Namonley on LAPBH6H6L3 with DISTILLER Amonley on LAPBH6H6L3 with DISTILLER Amonley on LAPBH6H6L3 with DISTILLER	14:00 Mar 14, 2024 Jkt 262047	PO	00000 Frm 00415 Fm		05 Sfmt 8002 Q:\14\14V2.TXT PC31

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued

		QPS requirements	ents				Information
	Test	Topogogo	accition the second	olistot tag	E	FTD level	2
Entry No.	Title	l Olei al Idea		ופאן תפומווא	2	2 9	
1.].4	Autorotational Landing.	Torque—±3%, Rotor Speed—±3%, Vertical Velocity—±100 fpm (0.56 m/seol or 10%, Pitch Attlude—±2°, Bank Attlude—±2°, Heading—±5°, Longitudinal Control Position—±10%, Directional Control Position—±10%, Directional Control Position—±10%, Collective	Landing	Record the results of an autorotational deceleration and fanding from a stabilized autorotational descent, to touch down	· i	^ 	If flight test data containing all required parameters of na a complete power-off landing is not available from the aircraft manufacturer for this test, and other qualified flight test personnel are not available to acquire this data, the sponsor must coordinate with the responsible Flight Standards office to determine if it would be appropriate to accept alternative testing means. Alternative testing means. Alternative testing means. Alternative approaches training be amongated to accept alternative testing means. Alternative approaches training and reduction of rate of descent (ROD) at attitude: or (2) a power-on termination following an autorotational approach and flare.
2.	Handling Qualities						
2.a	Control System Mechanical Characteristics	Contact the responsible Flight Standards office for clarification of any issue regarding helicopters with reversible controls.					
2.a.1	Oydlic	Breakout—±0.25 lbs (0.112 daN) or 25%. Force—±1.0 lb (0.224 daN) or 10%.	Ground; Static conditions. Trim On and Off. Friction Off. Augmentation On and Off.	Record results for an uninter- rupted control sweep to the stops. (This test does not apply if aircraft hardware modular controllers are used.).	×	×	

× ×	× ×	× ×	X X Control Dynamics for irreversible control systems may be evaluated in a ground/static condition. Refer to paragraph 3 of this attachment for additional information. 'N'' is the sequential period of a full cycle of oscillation.	× ×		×	×	
×	×	×		×				-
Record results for an uninter- rupted control sweep to the stops.		The tolerance applies to the recorded value of the trim rate.	Results must be recorded for a normal control displacement in both directions in each axis, using 25% to 50% of full throw.	Record and compare results for all controls.		Record results for several air- speed increments to the translational airspeed limits and for 45 kts. forward airspeed. May be a series of snapshot tests.	Record results for three relative wind directions (including the most critical case) in the critical quadrant. May be a series of snapshot tests.	
Ground: Static conditions. Trim On and Off. Friction Off. Augmentation On and Off.	Ground; Static conditions.	Ground; Static conditions. Trim On. Friction Off.	Hover/Cruise Trim On Friction Off.	Ground; Static conditions.		Translational Flight IGE—Sideward, rearward, and for- ward flight. Aug- mentation On and Off.	Stationary Hover. Augmentation On and Off.	
Breakout—±0.5 lb (0.224 daN) or 25%. Force—±1.0 lb (0.224 daN) or 10%.	±5 lbs (2.224 daN) or 10%	Rate—±10%	±10% of time for first zero crossing and ±10 (N + 1)% of period thereaftr. ±10% of amplitude of first overshoot. ±20% of amplitude of 2nd and subsequent overshoots greater than 5% of initial displacement. ±1 overshoot.	±0.10 in. (±2.5 mm)	ualities.	Torque ±3% Pitch Attitude ±1.5° Bank Attitude ±2° Longitudinal Control Position ±5% Lateral Control Position ±5% Directional Control Position ±5% Collective Control Position ±5%	Torque ±3% Pitch Attitude ±1.5°, Bank Attitude ±2°, Longitudinal Control Position ±5%, Lateral Control Position ±5%, Directional Control Position ±5%, Collective Control Position ±5%, Collective Control Position ±5%,	
Collective and Pedals	Brake Pedal Force vs. Position.	Trim System Rate (all applicable systems).	Control Dynamics (all axes).	Freeplay	Low Airspeed Handling Qualities.	Trimmed Flight Control Positions.	Critical Azimuth	Control Response.
2.a.2.	2.a.3	2.a.4	2.a.5	2.a.6	2.b	2.b.1	2.b.2	2.b.3
				407				

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued

			Information	setoN		This is a "short time" test.	This is a "short time" test conducted in a hover, in ground effect, without entering translational flight, to provide better visual reference.	This is a "short time" test.			
				avel	7	×	×	×	×		×
				FTD level	9						×
		_			2						×
		JECTIVE TESTS—Continued		Test details		Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases. This test must be conducted in a hover, in ground effect, without entering translational flight.	Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.	Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases. This test must be conducted in a hover, in ground effect, without entering translational flight.	Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.		Results must be recorded for two cruise airspeeds to include minimum power required speed. Record data for a step control input. The Off-axis response must show correct trend for unaugmented cases.
		DEVICE (FTD) OB	ents	Eliabt conditions		Hover. Augmentation On and Off.	Hover Augmentation On and Off.	Hover Augmentation On and Off.	Hover Augmentation On and Off.		Cruise Augmentation On and Off.
		TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued	QPS requirements	Tolerances		Pitch Rate—±10% or ±2°/sec. Pitch Attitude Change—±10% or 1.5°.	Roll Rate—±10% or ±3°/sec. Roll Attitude Change—±10% or ±3°.	Yaw Rate—±10% or ±2º/sec. Heading Change—±10% or ±2°.	Normal Acceleration ±0.1g	alities.	Pitch Rate—±10% or ±2°/sec. Pitch Attitude Change—±10% or ±1.5°.
		7		Test	Title	Longitudinal	Lateral	Directional	Vertical	Longitudinal Handling Qualities.	Control Response
th DISTILLER					Entry No.	2.b.3.a	2.b.3.b	2.b.3.c.	2.b.3.d	2.c	2.6.1.
aworley on LAPBH6H6L3 with DISTILLER	VerDate Sep<11>2014	14:00 Mar 14, 20	024	Jkt	: 262	047 PO 00000	Frm 00418 Fmt	408 8010 Sfmt 8002	Q:\14\14V2	ı.TXT	PC31

			The response for certain helicopters may be unrepeatable throughout the stated time. In these cases, the test should show at least that a divergence is identifiable. For example: Displacing the cyclic for a given time normally excites this test or until a given pitch attude is achieved and then return the cyclic to the original position. For the original position, For the original position, For the original position for the original position for the original position for when the convergent ordiverses, results should show the same convergent ordiverses the flight test data.	A control doublet inserted at the natural frequency of the aircraft normally excites this test. How excites this test. How ever, while input doublets are preferred over pulse inputs for Augmentation-Off tests, for Augmentation-Off tests, for Augmentation-Off tests, for Augmentation-Off tests, for Augmentation-Deater or dead-beat characteristics, longitudinal pulse inputs may produce a more coherent response.
	×		×	×
	×		×	×
	×		×	
	Record results for a minimum of two speeds on each side of the tim speed. May be a series of snapshot fests.		Record results for three full cycles (6 overshoots after input completed) or that sufficient to determine time to ½ or double amplitude, whichever is less. For non-periodic responses, the test may be terminated prior to 20 sec if the test pilot determines that the results are becoming uncontrollably divergent, Displace the cyclic for one second or less to excite the test. The result will be in the test. The result will be in the convergent or divergent and must be recorded. If this method fails to excite the test, displace the cyclic to the predetermined maximum desired pitch attitude and return to the original position. If this method is used, record the results.	Record results for at least two airspeeds.
	Cruise or Climb. Autorotation. Aug- mentation On and Off.		Cruise Augmentation On and Off.	Oruise or Climb. Augmentation On and Off.
	Longitudinal Control Position: ±10% of change from trim or ±0.28 in. (6.3 mm) or Longitu- dinal Control Force: ±0.5 lb. (0.223 daN) or ±10%.		±10% of calculated period. ±10% of time to ½ or double amplitude, or ±0.02 of damping ratio. For non-periodic responses, the time history must be matched within ±3° pitch; and ±5 kts airspeed over a 20 sec period following release of the controls.	±1.5° Pitch or ±2°/sec. Pitch Rate. ±0.1 g Normal Accelera- tion.
	Static Stability	Dynamic Stability.	Long Term Response	Short Term Response
vih DISTILLER	262	2.c.3.	2c3a	26.3b
aworley on LAPBH6H6L3 with DISTILLER Aworley on LAPBH6H6L3 with DISTILLER	14:00 Mar 14, 2024 Jk	t 262	409 047 PO 00000 Frm 00419 Fmt 8010 Sfmt 8002	2 Q:\14\14V2.TXT PC31

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued

		QPS requirements	ents				Information
	Test	F	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		FF	FTD level	200
Entry No.	Title	loerances	riigni conditions	lest details	2	2 9	Notes
2.6.4.		Maneuvering Stability Longitudinal Control Position—±10% of change from trim or ±0.25 in. (6.3 mm) or Longitudinal Control Forces—±0.5 lb. (0.223 daN) or ±10%.	Cruise or Climb. Augmentation On and Off.	Record results for at least two airspeeds at 30°-45° bank angle. The force may be shown as a cross plot for irreversible systems. May be a series of snapshot tests.	^	×	
2.d.	2.d Lateral and Directional Handling Qualities.	andling Qualities.					
2.d.1	Control Response.						
2.d.1.a	Lateral	Roll Rate—±10% or ±3*/sec. Roll Attitude Change—±10% or ±3°.	Cruise Augmentation On and Offd.	Record results for at least two airspeeds, including the speed at or near the minimum power required airspeed. Record results for a step control input. The Of-axis response must show correct trend for unaugmented cases.	×	×	
2d.1b	Directional	Yaw Rate—±10% or ±2-/sec. Yaw Attitude Change—±10% or ±2°.	Cruise Augmentation On and Off.	Record data for at least two Airspeeds, including the speed at or near the minimum power required airspeed. Record results for a step control input. The Off-axis response must show correct trend for unaugmented cases.	×	×	

	X	_	× ×	× ×	× ×	
	×	1	×	×	×	
	Record results for at least two sidestip angles on either side of the tim point. The force may be shown as a cross plot for inreversible systems. May be a series of snapshot tests.		Record results for at least two airspeeds. The test must be initiated with a cyclic or a pedal doublet input. Record results for six full cycles (12 overshoots after input completed) or that sufficient to determine time to $\frac{1}{12}$ or double amplitude, whichever is less. The test may be terminated prior to 20 sec if the test pilot determines that the results are becoming uncontrollably divergent.	Record the results of a release from pedal only or cyclic only turns for 20 sec. Results must be recorded from turns in both directions. Terminate check at zero roll angle or when the test pilot determines that the attitude is becoming uncontrollably divergent.	Record the time history of initial entry into cyclic only turns, using only a moderate rate for cyclic input. Results must be recorded for turns in both directions.	
	Cruise; or Climb (may use Descent instead of Climb if desired) Aug-mentation On and Off.		Cruise or Climb Augmentation On and Off.	Cruise or Climb. Aug- mentation On and Off.	Cruise or Climb. Augmentation On and Off.	
	Lateral Control Position—±10% of change from trim or ±0.25 in. (6.3 mm) or Lateral Control Force—±0.5 ib. (0.223 daN) or 10%. Roll Attitude—±1.5 Directional Control Position—±10% of change from trim or ±0.25 in. (6.3 mm) or Directional Control Force—±1 ib. (0.448 daN) or 10%. Longitudinal Control Position—±10% of change from trim or ±0.25 in. (6.3 mm). Vertical Velocity—±10% of change from trim or ±0.25 in. (6.3 mm). Vertical Velocity—±10% of pm (0.50m/sec) or 10%.	tional Stability.	±0.5 sec. or ±10% of period. ±10% of time to ½ or double amplitude or ±0.02 of damping ratio. ±20% or ±1 sec of time difference between peaks of bank and sideslip. For non-peri- odic responses, the time history must be matched within ±10 knots Airspeed, ±5% Roll Rate or ±5° Roll Attitude: ±4% Yaw Rate or ±4° Yaw Angle over a 20 sec period roll angle fol- lowing release of the controls.	±2° or ±10% roll angle	Correct Trend, ±2° transient sidesilp angle.	
	Directional Static Stability.	Dynamic Lateral and Directional Stability.	Lateral-Directional Oscil- lations.	Spiral Stability	Adverse/Proverse Yaw	Reserved
h DISTILLER	2.d.2.	2.d.3	2.d.3.a.	2.d.3.b	2.d.3.c.	9.
RETURNS ON LAPBH6H6L3 with DISTILLER on LAPBH	- 14:00 Mar 14, 2024 Jkt 262047 PO 00000	Fri	411 m 00421 Fmt 8010 Sfmt 8002	Q:\14\14V2.TXT PC3	1	

aworley on LAPBH6H8L3 with DISTILLER Applied 2 with DISTILLER Seb < 111 > 5014	vih DISTILLER						
14:00 Mar 14,		7	TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued	DEVICE (FTD) OBJ	ECTIVE TESTS—Continued		
2024			QPS requirements	nts			Information
Jk		Test	ŀ	i	: :	FTD level	
st 262	Entry No.	Title	Tolerances	Flight conditions	Test details	5 6 7	Notes
2047	4.	Visual System	_				
PO 0	4.a.		Visual System Response Time: (Choose either test 4.a.1. or 4.a.2. to satisfy test 4.a., Visual System Response Time Test. This test is also sufficient for flight deck instrument response timing.)	a.2. to satisfy test 4.a., '	Visual System Response Time Test.	!	
0000	4.a.1	Latency.					
Frm 00422			150 ms (or less) after helicopter response.	Takeoff, climb, and descent.	One test is required in each axis (pitch, roll and yaw) for each of the three conditions (take-off, cruise, and approach or landing).	×	
Fmt	4.a.2.	Transport Delay.					
412 8010			150 ms (or less) after controller novement.	N/A	A separate test is required in each axis (pitch, roll, and yaw).	×	
	4.b.	Field-of-view.					
8002	4.b.1.	Reserved.					
. Q:\14\14V2.TXT PC31	4.6.2.	Continuous visual field- of-view.	Minimum continuous field-of-view providing 146° horizontal and 36° vertical field-of-view for each pilot simulatiously and any geometric error between the Image Generator eye point and the pilot eye point is 8° or less.	N/A	An SOC is required and must explain the geometry of the installation. Horizontal field-of-view must not be less than a total of 146° (including not less than 73° measured either side of the center of the design eye point). Additional horizontal field-of-view capability may be added at the sponsor's discretion provided the minimum field-of-view is retained. Ventical field-of-view is measured from the pilot's and co-pilot's eye point.	×	Horizontal field-of-view is centered on the zero degree azimuth line relative to the aircraft fuselage.
	4.b.3	Reserved.					

	Measurements may be made using a 1° spot photometer and a raster drawn test pattern filling the entire visual scene (all channels) with a test pattern of black and white squares, 5 per square, with a white square in the center of each channel. During contrast ratio testing, simulator aff-cab and flight deck ambient light levels should be zero.	Measurements may be made using a 1° spot photometer and a raster drawn test pattern filling the entire visual scene (all channels) with a test pattern of black and white squares, 5 per square in the center of each channel.	When the eye is positioned on a 3° glide slope at the slant range distances indicated with white runway surface, the eye way markings on a black runway surface, the eye will subtend wo (2) arc minutes: (1) A slant range of 6.876 ft with stripes 150 ft long and 16 ft wide, spaced 4 ft apart (2) For Configuration A; a slant range of 5.157 feet with stripes 150 ft long and 12 ft wide, spaced 3 ft apart (3) For Configuration B; a stant range of 9.884 feet, with stripes 150 ft long and 5.75 ft wide, spaced 5.75 ft wide, spaced 5.75 ft apart.
	×	×	×
	The ratio is calculated by dividing the brightness level of the center, bright square (providing at least 2 foot-lamberts or 7 cd/m²) by the brightness level of any adjacent dark square.	Measure the brightness of the center white square while superimposing a highlight on that white square. The use of calligraphic capabilities to enhance the raster brightness is acceptable, but measuring light points is not acceptable.	An SOC is required and must include the relevant calculations.
	N/A	N/A	N/A
	Not less than 5:1	Not less than three (3) foot-lamberts (10 cd/m²),	Not greater than two (2) arc minutes.
	Surface contrast ratio	Highlight brightness	Surface resolution
ih DISTILLER	4.6.	4.d.	4.e.
Manuely on LAPBH8H6L3 with DISTILLER on LAPBH8H6L3 with DISTILLER on Section 2017 of the Carlon of t		413	
₹ VerDate Sep<11>2014	14:00 Mar 14, 2024 Jkt 262047 PO 00000	Frm 00423 Fmt 8010 Sfmt	8002 Q:\14\14V2.TXT PC31

TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued

Information Notes Notes Light point size may be measured using a test pattern consisting of a centrally located single row of light points reduced in length until modulation is just discernible in each visual channel. A row of 48 lights will form a 4° angle or less. A 1° spot photometer may be used to measure a square of at least 1° filled with light point modulation is just discernible) and compare the results to the measured adjacent background. During contrast ratio testing, simulator affords and flight deck ambient light levels should be zero.	-		
FID level		×	
JECTIVE TESTS—Continued Test details An SOC is required and must include the relevant calculations.		An SOC is required and must include the relevant calculations.	
BEVICE (FTD) OB Felight conditions N/A		N/A	
TABLE D2A—FLIGHT TRAINING DEVICE (FTD) OBJECTIVE TESTS—Continued OPS requirements Tolerances Flight conditions Not greater than five (5) arc-min-utes.		Not less than 25:1	
Test Title Light point size	Reserved.		Visual ground segment.
Entry No. 4.f	4.g.1.	4.g.2	4.h
## Hand	I\1 <i>A</i> \4	/2 TYT	PC21

	Pre-position for this test is encouraged, but may be achieved via manual or autopilot control to the desired position.
	~
	The OTG must contain relevant calculations and a drawing showing the data used to establish the theiropter location and the segment of the ground that is visible considering design eyepoint, helicopter attitude, flight deck cut-off angle, and a visibility of 1200 ft (350 m) RVR. Simulator performace must be measured against the OTG calculations. The data submitted must include at least the following: (1) Static helicopter dimensions as follows: (1) Horizontal and vertical distance from MulCa to pilot's eyepoint. (iii) Static flight deck cutoff angle (2) Approach data as follows: (i) Identification of runway. (iii) Static flight deck cutoff angle (2) Approach data as follows: (i) Identification of runway. (iii) Glideslope angle. (iv) Helicopter configuration. (iii) Approach airspeed. If mon-homogenous fog is used to obscure visibility, the variation in horizontal visibility must be described and be in-bility calculation.
	Landing configura- tion, timmed for appropriate air- speed, at 100 ft (30m) above the touchdown zone, on gilde stope with an RVR value set at 1,200 ft (350m).
	The visible segment in the sinulator must be within 20% of the segment computed to be visible from the helicopter flight deck. The tolerance(s) may be applied at either end or at both ends of the displayed segment. However, lights and grund objects computed to be visible from the helicopter flight deck at the near end of the visible segment must be visible in the simulator.
	Bastrad
vih DISTILLER	, cc
REPLICED AND DISTILLER OF A PROPERTY OF THE PR	415
verDate Sep<11>2014 14:00 M⋅	ar 14, 2024 Jkt 262047 PO 00000 Frm 00425 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31

BEGIN INFORMATION

3. Control Dynamics

a. The characteristics of a helicopter flight control system have a major effect on the handling qualities. A significant consideration in pilot acceptability of a helicopter is the "feel" provided through the flight deck controls. Considerable effort is expended on helicopter feel system design in order to deliver a system with which pilots will be comfortable and consider the helicopter desirable to fly. In order for an FTD to be representative, it too must present the pilot with the proper feel: that of the respective helicopter. Compliance with this requirement is determined by comparing a recording of the control feel dynamics of the FFS to actual helicopter measurements in the hover and cruise configurations.

(1) Recordings such as free response to an impulse or step function are classically used to estimate the dynamic properties of electromechanical systems. It is only possible to estimate the dynamic properties as a result of only being able to estimate true inputs and responses. Therefore, it is imperative that the best possible data be collected since close matching of the FTD control loading system to the helicopter systems is essential. Control feel dynamic tests are described in the Table of Objective Tests in this appendix. Where accomplished, the free response is measured after a step or pulse input is used to excite the system.

(2) For initial and upgrade evaluations, it is required that control dynamic characteristics be measured at and recorded directly from the flight deck controls. This procedure is usually accomplished by measuring the free response of the controls using a step or pulse input to excite the system. The procedure must be accomplished in hover, climb, cruise, and autorotation. For helicopters with irreversible control systems, measurements may be obtained on the ground. The procedure should be accomplished in the hover and cruise flight conditions and configurations. Proper pitot-static inputs (if appropriate) must be provided to represent airspeeds typical of those encountered in flight.

(3) It may be shown that for some helicopters, climb, cruise, and autorotation have like effects. Thus, some tests for one may suffice for some tests for another. If either or both considerations apply, engineering validation or helicopter manufacturer rationale must be submitted as justification for

ground tests or for eliminating a configuration. For FTDs requiring static and dynamic tests at the controls, special test fixtures will not be required during initial and upgrade evaluations if the sponsor's QTG shows both test fixture results and the results of an alternative approach, such as computer plots which were produced concurrently and show satisfactory agreement. Repeat of the alternative method during the initial evaluation satisfies this test requirement.

b. Control Dynamics Evaluations. The dynamic properties of control systems are often stated in terms of frequency, damping, and a number of other classical measurements which can be found in texts on control systems. In order to establish a consistent means of validating test results for FTD control loading, criteria are needed that will clearly define the interpretation of the measurements and the tolerances to be applied. Criteria are needed for both the underdamped system and the overdamped system. including the critically damped case. In the case of an underdamped system with very light damping, the system may be quantified in terms of frequency and damping. In critically damped or overdamped systems, the frequency and damping is not readily measured from a response time history. Therefore, some other measurement must be used.

(1) Tests to verify that control feel dynamics represent the helicopter must show that the dynamic damping cycles (free response of the control) match that of the helicopter within specified tolerances. The method of evaluating the response and the tolerance to be applied are described below for the underdamped and critically damped cases.

(a) Underdamped Response. Two measurements are required for the period, the time to first zero crossing (in case a rate limit is present) and the subsequent frequency of oscillation. It is necessary to measure cycles on an individual basis in case there are non-uniform periods in the response. Each period will be independently compared to the respective period of the helicopter control system and, consequently, will enjoy the full tolerance specified for that period.

(b) The damping tolerance will be applied to overshoots on an individual basis. Care must be taken when applying the tolerance to small overshoots since the significance of such overshoots becomes questionable. Only those overshoots larger than 5 percent of the total initial displacement will be considered significant. The residual band, labeled T(A_d) on Figure 1 of this attachment is ±5 percent of the initial displacement amplitude, Ad, from the steady state value of the oscillation. Oscillations within the residual band are considered insignificant. When comparing simulator data to helicopter data, the process would begin by overlaying or aligning the simulator and helicopter steady state

Federal Aviation Administration, DOT

values and then comparing amplitudes of oscillation peaks, the time of the first zero crossing, and individual periods of oscillation. To be satisfactory, the simulator must show the same number of significant overshoots to within one when compared against the helicopter data. The procedure for evaluating the response is illustrated in Figure 1 of this attachment.

- (c) Critically Damped and Overdamped Response. Due to the nature of critically damped responses (no overshoots), the time to reach 90 percent of the steady state (neutral point) value must be the same as the helicopter within ±10 percent. The simulator response must be critically damped also. Figure 2 of this attachment illustrates the procedure.
- (d) Special considerations. Control systems that exhibit characteristics other than classical overdamped or underdamped responses should meet specified tolerances. In addition, special consideration should be given to

ensure that significant trends are maintained.

- (2) Tolerances.
- (a) The following summarizes the tolerances, "T" for underdamped systems, and "n" is the sequential period of a full cycle of oscillation. See Figure D2A of this attachment for an illustration of the referenced measurements.

 $T(P_0) \pm 10\%$ of P_0

 $T(P_1)$ ±20% of P_1

 $T(P_2)$ ±30% of P_2

 $T(P_n) \, \pm \! 10(n$ + 1)% of P_n

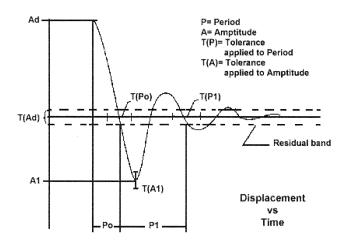
 $T(A_n)$ ±10% of A_1

 $T(A_d) \pm 5\%$ of A_d = residual band

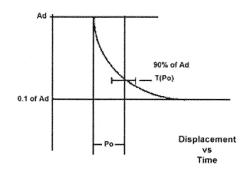
- Significant overshoots First overshoot and ±1 subsequent overshoots
- (b) The following tolerance applies to critically damped and overdamped systems only. See Figure D2B for an illustration of the reference measurements:

 $T(P_0) \pm 10\%$ of P_0

Attachment 2 to Appendix D to Part 60— Figure D2A. Under-Damped Step Response



Attachment 2 to Appendix D to Part 60— Figure D2B. Critically-Damped Step Response



End Information

Begin QPS Requirement

- c. Alternative method for control dynamics evaluation. $\,$
- (1) An alternative means for validating control dynamics for aircraft with hydraulically powered flight controls and artificial feel systems is by the measurement of con-

trol force and rate of movement. For each axis of pitch, roll, and yaw, the control must be forced to its maximum extreme position for the following distinct rates. These tests are conducted under normal flight and ground conditions.

- (a) Static test—Slowly move the control so that a full sweep is achieved within 95–105 seconds. A full sweep is defined as movement of the controller from neutral to the stop, usually aft or right stop, then to the opposite stop, then to the neutral position.
- (b) Slow dynamic test—Achieve a full sweep within 8–12 seconds.
- (c) Fast dynamic test—Achieve a full sweep within 3–5 seconds.

Note: Dynamic sweeps may be limited to forces not exceeding 100 lbs. (44.5 daN).

- (d) Tolerances.
- (i) Static test; see Table D2A, Flight Training Device (FTD) Objective Tests, Entries 2.a.1., 2.a.2., and 2.a.3.
- (ii) Dynamic test— ± 2 lbs (0.9 daN) or $\pm 10\%$ on dynamic increment above static test.

END QPS REQUIREMENT

BEGIN INFORMATION

- d. The FAA is open to alternative means that are justified and appropriate to the application. For example, the method described here may not apply to all manufacturers' systems and certainly not to aircraft with reversible control systems. Each case is considered on its own merit on an ad hoc basis. If the FAA finds that alternative methods do not result in satisfactory performance, more conventionally accepted methods will have to be used.
- 4. FOR ADDITIONAL INFORMATION ON THE FOL-LOWING TOPICS, PLEASE REFER TO APPENDIX C OF THIS PART, ATTACHMENT 2, AND THE INDICATED PARAGRAPH WITHIN THAT AT-TACHMENT
- Additional Information About Flight Simulator Qualification for New or Derivative Helicopters, paragraph 8.
- \bullet Engineering Simulator Validation Data, paragraph 9.
- Validation Test Tolerances, paragraph 11.
- \bullet Validation Data Road Map, paragraph 12.
- Acceptance Guidelines for Alternative Avionics, paragraph 13.
 - Transport Delay Testing, paragraph 15.
- Continuing Qualification Evaluation Validation Data Presentation, paragraph 16.

END INFORMATION

ATTACHMENT 3 TO APPENDIX D TO PART 60— FLIGHT TRAINING DEVICE (FTD) SUB-JECTIVE EVALUATION

BEGIN OPS REQUIREMENTS

1. Requirements

- a. Except for special use airport models, all airport models required by this part must be representations of real-world, operational airports or representations of fictional airports and must meet the requirements set out in Tables D3B or D3C of this attachment, as appropriate.
- b. If fictional airports are used, the sponsor must ensure that navigational aids and all appropriate maps, charts, and other navigational reference material for the fictional airports (and surrounding areas as necessary) are compatible, complete, and accurate with respect to the visual presentation and the airport model of this fictional airport. An SOC must be submitted that addresses navigation aid installation and performance and other criteria (including obstruction clearance protection) for all instrument approaches to the fictional airports that are available in the simulator. The SOC must reference and account for information in the terminal instrument procedures manual and the construction and availability of the required maps, charts, and other navigational material. This material must be clearly marked "for training purposes only.
- c. When the simulator is being used by an instructor or evaluator for purposes of training, checking, or testing under this chapter, only airport models classified as Class I, Class II, or Class III may be used by the instructor or evaluator. Detailed descriptions/definitions of these classifications are found in Appendix F of this part.
- d. When a person sponsors an FTD maintained by a person other than a U.S. certificate holder, the sponsor is accountable for that FTD originally meeting, and continuing to meet, the criteria under which it was originally qualified and the appropriate Part 60 criteria, including the visual scenes and airport models that may be used by instructors or evaluators for purposes of training, checking, or testing under this chapter.
- e. Neither Class II nor Class III airport visual models are required to appear on the SOQ, and the method used for keeping instructors and evaluators apprised of the airport models that meet Class II or Class III requirements on any given simulator is at the option of the sponsor, but the method used must be available for review by the TPAA.
- f. When an airport model represents a real world airport and a permanent change is made to that real world airport (e.g., a new runway, an extended taxiway, a new lighting system, a runway closure) without a written extension grant from the responsible Flight Standards office (described in paragraph 1.g., of this section), an update to that airport

model must be made in accordance with the following time limits:

(1) For a new airport runway, a runway extension, a new airport taxiway, a taxiway extension, or a runway/taxiway closure—within 90 days of the opening for use of the new airport runway, runway extension, new airport taxiway, or taxiway extension; or within 90 days of the closure of the runway or taxiway.

(2) For a new or modified approach light system—within 45 days of the activation of the new or modified approach light system.

(3) For other facility or structural changes on the airport (e.g., new terminal, relocation of Air Traffic Control Tower)—within 180 days of the opening of the new or changed facility or structure.

g. If a sponsor desires an extension to the time limit for an update to a visual scene or airport model or has an objection to what must be updated in the specific airport model requirement, the sponsor must provide a written extension request to the responsible Flight Standards office stating the reason for the update delay and a proposed completion date or provide an explanation for the objection, explaining why the identified airport change will not have an impact on flight training, testing, or checking. A copy of this request or objection must also be sent to the POI/TCPM.

h. Examples of situations that may warrant Class_III model designation by the TPAA include the following:

(a) Training, testing, or checking on very low visibility operations, including SMGCS operations.

(b) Instrument operations training (including instrument takeoff, departure, arrival, approach, and missed approach training, testing, or checking) using—

(i) A specific model that has been geographically "moved" to a different location and aligned with an instrument procedure for another airport.

(ii) A model that does not match changes made at the real-world airport (or landing area for helicopters) being modeled.

(iii) A model generated with an "off-board" or an "on-board" model development tool (by providing proper latitude/longitude reference; correct runway or landing area orientation, length, width, marking, and lighting information; and appropriate adjacent taxiway location) to generate a facsimile of a real world airport or landing area.

These airport models may be accepted by the TPAA without individual observation provided the sponsor provides the TPAA with an acceptable description of the process for determining the acceptability of a specific airport model, outlines the conditions under which such an airport model may be used, and adequately describes what restrictions will be applied to each resulting airport or landing area model.

BEGIN INFORMATION

END OPS REQUIREMENTS

2. Discussion

a. The subjective tests and the examination of functions provide a basis for evaluating the capability of the FTD to perform over a typical utilization period; determining that the FTD satisfactorily meets the appropriate training/testing/checking objectives and competently simulates each required maneuver, procedure, or task; and verifying correct operation of the FTD controls, instruments, and systems. The items in the list of operations tasks are for FTD evaluation purposes only. They must not be used to limit or exceed the authorizations for use of a given level of FTD as found in the Practical Test Standards or as approved by the TPAA. All items in the following paragraphs are subject to an examination of function

b. The List of Operations Tasks in Table D3A addressing pilot functions and maneuvers is divided by flight phases. All simulated helicopter systems functions will be assessed for normal and, where appropriate, alternate operations. Normal, abnormal, and emergency operations associated with a flight phase will be assessed during the evaluation of maneuvers or events within that flight phase.

c. Systems to be evaluated are listed separately under "Any Flight Phase" to ensure appropriate attention to systems checks. Operational navigation systems (including inertial navigation systems, global positioning systems, or other long-range systems) and the associated electronic display systems will be evaluated if installed. The pilot will include in his report to the TPAA, the effect of the system operation and any system limitation.

d. At the request of the TPAA, the Pilot may assess the FTD for a special aspect of a sponsor's training program during the functions and subjective portion of an evaluation. Such an assessment may include a portion of a specific operation (e.g., a Line Oriented Flight Training (LOFT) scenario) or special emphasis items in the sponsor's training program. Unless directly related to a requirement for the qualification level, the results of such an evaluation would not necessarily affect the qualification of the FTD.

e. The FAA intends to allow the use of Class III airport models on a limited basis when the sponsor provides the TPAA (or other regulatory authority) an appropriate analysis of the skills, knowledge, and abilities (SKAs) necessary for competent performance of the tasks in which this particular media element is used. The analysis should describe the ability of the FTD/visual

media to provide an adequate environment in which the required SKAs are satisfactorily performed and learned. The analysis should also include the specific media element, such as the visual scene or airport model. Additional sources of information on the conduct of task and capability analysis

may be found on the FAA's Advanced Qualification Program (AQP) Web site at: http://www.faa.gov/education_research/training/aqp.

END INFORMATION

TABLE D3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD

	QPS requirements
Entry No.	Operations tasks
	are subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ Configuration

Tasks in this table are subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ Configuration List or a Level 7 FTD. Items not installed, not functional on the FTD, and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

not required to be listed as exceptions on the SOQ.			
1. Preflight Procedu	1. Preflight Procedures		
1.a	Preflight Inspection (Flight Deck Only) switches, indicators, systems, and equipment.		
1.b	APU/Engine start and run-up.		
1.b.1	Normal start procedures.		
1.b.2	Alternate start procedures.		
1.b.3	Abnormal starts and shutdowns (hot start, hung start).		
1.b.4	Rotor engagement.		
1.b.5	System checks.		
1.c	Taxiing—Ground.		
1.c.1	Power required to taxi.		
1.c.2	Brake effectiveness.		
1.c.3	Ground handling.		
1.c.4	Abnormal/emergency procedures, for example:		
1.c.4.a	Brake system failure.		
1.c.4.b	Ground resonance.		
1.c.4.c	Other (listed on the SOQ).		
1.d	Taxiing—Hover.		
1.d.1	Takeoff to a hover.		
1.d.2	Instrument response.		
1.d.2.a	Engine instruments.		
1.d.2.a	Flight instruments.		
1.d.3	Hovering turns.		
1.d.4	Hover power checks.		
1.d.4.a	In ground effect (IGE).		
1.d.4.b	Out of ground effect (OGE).		
1.d.5	Crosswind/tailwind hover.		
1.d.6	Abnormal/emergency procedures:		
1.d.6.a	Engine failure.		
1.d.6.b	Fuel governing system failure.		

TABLE D3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD—Continued

QPS requirements		
Entry No.	Operations tasks	
1.d.6.c	Settling with power (OGE).	
1.d.6.d	Stability augmentation system failure.	
1.d.6.e	Directional control malfunction (including Loss of Tail Rotor Effectiveness, LTE).	
1.d.6.f	Other (listed on the SOQ).	
1.e	Pre-takeoff Checks.	
2. Takeoff and Depa	arture Phase	
2.a	Normal and Crosswind Takeoff.	
2.a.1	From ground.	
2.a.2	From hover.	
2.a.3	Running.	
2.a.4	Crosswind/tailwind.	
2.a.5	Maximum performance.	
2.b	Instrument.	
2.c	Powerplant Failure During Takeoff.	
2.c.1	Takeoff with engine failure after critical decision point (CDP).	
2.d	Rejected Takeoff.	
2.e	Instrument Departure.	
2.f	Other (listed on the SOQ).	
3. Climb		
3.a	Normal.	
3.b	Obstacle clearance.	
3.c	Vertical.	
3.d	One engine inoperative.	
3.e	Other (listed on the SOQ).	
4. Inflight Maneuver	rs	
4.a	Performance.	
4.b	Flying qualities.	
4.c	Turns.	
4.c.1	Timed.	
4.c.2	Normal.	
4.c.3	Steep.	
4.d	Accelerations and decelerations.	
4.e	High-speed vibrations.	
4.f	Abnormal/emergency procedures, for example:	
4.f.1	Engine fire.	
4.f.2	Engine failure.	

QPS requirements		
Entry No.	Operations tasks	
4.f.2.a	Powerplant Failure—Multiengine Helicopters.	
4.f.2.b	Powerplant Failure—Single-Engine Helicopters.	
4.f.3	Inflight engine shutdown (and restart, if applicable).	
4.f.4	Fuel governing system failures (e.g., FADEC malfunction).	
4.f.5	Directional control malfunction.	
4.f.6	Hydraulic failure.	
4.f.7	Stability augmentation system failure.	
4.f.8	Rotor vibrations.	
4.f.9	Recovery From Unusual Attitudes.	
4.f.10	Settling with Power.	
4.g	Other (listed on the SOQ).	
5. Instrument Proce	edures	
5.a	Instrument Arrival.	
5.b	Holding.	
5.c	Precision Instrument Approach.	
5.c.1	Normal—All engines operating.	
5.c.2	Manually controlled—One or more engines inoperative.	
5.c.3	Approach procedures:	
5.c.3.a	PAR.	
5.c.3.b	GPS.	
5.c.3.c	ILS.	
5.c.3.c.1	Manual (raw data).	
5.c.3.c.2	Autopilot* only.	
5.c.3.c.3	Flight director only.	
5.c.3.c.4	Autopilot* and flight director (if appropriate) coupled.	
5.c.3.d	Other (listed on the SOQ).	
5.d	Non-precision Instrument Approach.	
5.d.1	Normal—All engines operating.	
5.d.2	One or more engines inoperative.	
5.d.3	Approach procedures:	
5.d.3.a	NDB.	
5.d.3.b	VOR, RNAV, TACAN, GPS.	
5.d.3.c	ASR.	
5.d.3.d	Circling.	
5.d.3.e	Helicopter only.	
5.d.3.f	Other (listed on the SOQ).	

TABLE D3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD—Continued

QPS requirements		
Entry No.	Operations tasks	
5.e	Missed Approach.	
5.e.1	All engines operating.	
5.e.2	One or more engines inoperative.	
5.e.3	Stability augmentation system failure.	
5.e.4	Other (listed on the SOQ).	
6. Landings and Ap	proaches to Landings	
6.a	Visual Approaches.	
6.a.1	Normal.	
6.a.2	Steep.	
6.a.3	Shallow.	
6.a.4	Crosswind.	
6.b	Landings.	
6.b.1	Normal.	
6.b.1.a	Running.	
6.b.1.b	From Hover.	
6.b.2	Crosswind.	
6.b.3	Tailwind.	
6.b.4	One or more engines inoperative.	
6.b.5	Rejected Landing.	
6.b.6	Other (listed on the SOQ).	
7. Normal and Abno	ormal Procedures (any phase of flight)	
7.a	Helicopter and powerplant systems operation (as applicable).	
7.a.1	Anti-icing/deicing systems.	
7.a.2	Auxiliary powerplant.	
7.a.3	Communications.	
7.a.4	Electrical system.	
7.a.5	Environmental system.	
7.a.6	Fire detection and suppression.	
7.a.7	Flight control system.	
7.a.8	Fuel system.	
7.a.9	Engine oil system.	
7.a.10	Hydraulic system.	
7.a.11	Landing gear.	
7.a.12	Oxygen.	
7.a.13	Pneumatic.	
7.a.14	Powerplant.	

QPS requirements		
Entry No.	Operations tasks	
7.a.15	Flight control computers.	
7.a.16	Fly-by-wire controls.	
7.a.17	Stabilizer.	
7.a.18	Stability augmentation and control augmentation system(s).	
7.a.19	Other (listed on the SOQ).	
7.b	Flight management and guidance system (as applicable).	
7.b.1	Airborne radar.	
7.b.2	Automatic landing aids.	
7.b.3	Autopilot.*	
7.b.4	Collision avoidance system.	
7.b.5	Flight data displays.	
7.b.6	Flight management computers.	
7.b.7	Head-up displays.	
7.b.8	Navigation systems.	
7.b.9	Other (listed on the SOQ).	
8. Emergency Proce	edures (as applicable)	
8.a	Autorotative Landing.	
8.b	Air hazard avoidance.	
8.c	Ditching.	
8.d	Emergency evacuation.	
8.e	Inflight fire and smoke removal.	
8.f	Retreating blade stall recovery.	
8.g	Mast bumping.	
8.h	Loss of tail rotor effectiveness.	
8.i	Other (listed on the SOQ).	
9. Postflight Proced	dures	
9.a	After-Landing Procedures.	
9.b	Parking and Securing.	
9.b.1	Engine and systems operation.	
9.b.2	Parking brake operation.	
9.b.3	Rotor brake operation.	
9.b.4	Abnormal/emergency procedures.	
10. Instructor Opera	ating Station (IOS), as appropriate	
10.a	Power Switch(es).	
10.b	Helicopter conditions.	
10.b.1	Gross weight, center of gravity, fuel loading and allocation, etc.	

TABLE D3A—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD—Continued

QPS requirements	
Entry No.	Operations tasks
10.b.2	Helicopter systems status.
10.b.3	Ground crew functions (e.g., ext. power).
10.c	Airports.
10.c.1	Selection.
10.c.2	Runway selection.
10.c.3	Preset positions (e.g., ramp, over final approach fix).
10.d	Environmental controls.
10.d.1	Temperature.
10.d.2	Climate conditions (e.g., ice, rain).
10.d.3	Wind speed and direction.
10.e	Helicopter system malfunctions.
10.e.1	Insertion/deletion.
10.e.2	Problem clear.
10.f	Locks, Freezes, and Repositioning.
10.f.1	Problem (all) freeze/release.
10.f.2	Position (geographic) freeze/release.
10.f.3	Repositioning (locations, freezes, and releases).
10.f.4	Ground speed control.
10.g	Sound Controls.
10.g.1	On/off/adjustment.
10.h	Control Loading System (as applicable).
10.h.1	On/off/emergency stop.
10.i	Observer Stations.
10.i.1	Position.
10.i.2	Adjustments.
+ " A	

 $[\]ensuremath{^{\star}}$ "Autopilot" means attitude retention mode of operation.

TABLE D3B—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS AIRPORT OR LANDING AREA CONTENT REQUIREMENTS FOR QUALIFICATION AT LEVEL 7 FTD

	QPS requirements	
Entry No.	Operations tasks	
	pecifies the minimum airport visual model content and functionality to qualify an FTD at the indicated level. This es only to the airport/helicopter landing area scenes required for FTD qualification.	
1	Functional test content requirements for Level 7 FTDs. The following is the minimum airport/landing area model content requirement to satisfy visual capability tests, and provides suitable visual cues to allow completion of all functions and subjective tests described in this attachment for Level 7 FTDs.	

Entry No. Operations tasks 1.a	d, the ap- rent. The world air- the IOS, entify the al scene; nelicopter
and the helicopter landing area may be contained within the same visual model. If this option is selected proach path to the airport runway(s) and the approach path to the helicopter landing area must be differ model(s) used to meet the following requirements may be demonstrated at either a fictional or a real-port or helicopter landing area, but each must be acceptable to the sponsor's TPAA, selectable from and listed on the SOQ. 1.b	d, the ap- rent. The world air- the IOS, entify the al scene; nelicopter
airport and/or helicopter landing area; determine the position of the simulated helicopter within the visus successfully accomplish take-offs, approaches, and landings; and maneuver around the airport and/or handing area on the ground, or hover taxi, as necessary. 1.b.1 For each of the airport/helicopter landing areas described in 1.a., the FTD visual system must be able to p least the following: 1.b.1.a A night and twilight (dusk) environment. 1.b.1.b A daylight environment. 1.c	al scene; nelicopter
least the following: 1.b.1.a A night and twilight (dusk) environment. 1.b.1.b A daylight environment. 1.c Runways:	provide at
1.b.1.b A daylight environment. 1.c Runways:	
1.c Runways:	
1.c.1 Visible runway number.	
1.c.2 Runway threshold elevations and locations must be modeled to provide sufficient correlation with helico tems (e.g., altimeter).	pter sys-
1.c.3 Runway surface and markings.	
1.c.4 Lighting for the runway in use including runway edge and centerline.	
1.c.5 Lighting, visual approach aid (VASI or PAPI) and approach lighting of appropriate colors.	
1.c.6 Taxiway lights.	
1.d Helicopter landing area.	
1.d.1 Standard heliport designation ("H") marking, properly sized and oriented.	
1.d.2 Perimeter markings for the Touchdown and Lift-Off Area (TLOF) or the Final Approach and Takeoff Area as appropriate.	(FATO),
1.d.3 Perimeter lighting for the TLOF or the FATO areas, as appropriate.	
1.d.4 Appropriate markings and lighting to allow movement from the runway or helicopter landing area to another the landing facility.	er part of
2	
2.a Runway and helicopter landing area approach lighting must fade into view appropriately in accordance with vironmental conditions set in the FTD.	h the en-
2.b	ne lights,
Visual feature recognition. The following are the minimum distances at which runway features must be visible. Distances are measurunway threshold or a helicopter landing area to a helicopter aligned with the runway or helicopter landing on an extended 3° glide-slope in simulated meteorological conditions. For circling approaches, all tests the runway used for the initial approach and to the runway of intended landing.	ding area
3.a For runways: Runway definition, strobe lights, approach lights, and edge lights from 5 sm (8 km) of the thro	eshold.
3.b For runways: Centerline lights and taxiway definition from 3 sm (5 km).	
3.c For runways: Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold.	
3.d For runways: Runway threshold lights and touchdown zone from 2 sm (3 km).	

TABLE D3B—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS AIRPORT OR LANDING AREA CONTENT REQUIREMENTS FOR QUALIFICATION AT LEVEL 7 FTD—Continued

	QPS requirements
Entry No.	Operations tasks
3.e	For runways and helicopter landing areas: Markings within range of landing lights for night/twilight scenes and the surface resolution test on daylight scenes, as required.
3.f	For circling approaches: The runway of intended landing and associated lighting must fade into view in a non-distracting manner.
3.g	For helicopter landing areas: Landing direction lights and raised FATO lights from 1 sm (1.5 km).
3.h	For helicopter landing areas: Flush mounted FATO lights, TLOF lights, and the lighted windsock from 0.5 sm (750 m).
4	Airport or Helicopter Landing Area Model Content. The following prescribes the minimum requirements for an airport/helicopter landing area visual model and identifies other aspects of the environment that must correspond with that model for a Level 7 FTD. For circling approaches, all tests apply to the runway used for the initial approach and to the runway or intended landing. If all runways or landing areas in a visual model used to meet the requirements of this attachment are not designated as "in use," then the "in use" runways/landing areas must be listed on the SOQ (e.g., KORD, Rwys 9R, 14L, 22R). Models of airports or helicopter landing areas with more than one runway or landing area must have all significant runways or landing areas not "in-use" visually depicted for airport/runway/landing area recognition purposes. The use of white or off white light strings that identify the runway or landing area for twilight and night scenes are acceptable for this requirement; and rectangular surface depictions are acceptable for daylight scenes. A visual system's capabilities must be balanced between providing visual models with an accurate representation of the airport and a realistic representation of the surrounding environment. Each runway or helicopter landing area designated as an "in-use" runway or area must include the following detail that is developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that such models contain details that are beyond the design capability of the currently qualified visual system. Only one "primary" taxi route from parking to the runway end or helicopter takeoff/landing area will be required for each "in-use" runway or helicopter takeoff/landing area.
4.a	The surface and markings for each "in-use" runway or helicopter landing area must include the following:
4.a.1	For airports: Runway threshold markings, runway numbers, touchdown zone markings, fixed distance markings, runway edge markings, and runway centerline stripes.
4.a.2	For helicopter landing areas: Markings for standard heliport identification ("H") and TLOF, FATO, and safety areas.
4.b	The lighting for each "in-use" runway or helicopter landing area must include the following:
4.b.1	For airports: Runway approach, threshold, edge, end, centerline (if applicable), touchdown zone (if applicable), leadoff, and visual landing aid lights or light systems for that runway.
4.b.2	For helicopter landing areas: Landing direction, raised and flush FATO, TLOF, windsock lighting.
4.c	The taxiway surface and markings associated with each "in-use" runway or helicopter landing area must include the following:
4.c.1	For airports: Taxiway edge, centerline (if appropriate), runway hold lines, and ILS critical area(s).
4.c.2	For helicopter landing areas: Taxiways, taxi routes, and aprons.
4.d	The taxiway lighting associated with each "in-use" runway or helicopter landing area must include the following:
4.d.1	For airports: Taxiway edge, centerline (if appropriate), runway hold lines, ILS critical areas.
4.d.2	For helicopter landing areas: Taxiways, taxi routes, and aprons.
4.d.3	For airports: Taxiway lighting of correct color.
4.e	Airport signage associated with each "in-use" runway or helicopter landing area must include the following:
4.e.1	For airports: Signs for runway distance remaining, intersecting runway with taxiway, and intersecting taxiway with taxiway.
4.e.2	For helicopter landing areas: As appropriate for the model used.
4.f	Required visual model correlation with other aspects of the airport or helicopter landing environment simulation:

TABLE D3B—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS AIRPORT OR LANDING AREA CONTENT REQUIREMENTS FOR QUALIFICATION AT LEVEL 7 FTD—Continued

	QPS requirements
Entry No.	Operations tasks
4.f.1	The airport or helicopter landing area model must be properly aligned with the navigational aids that are associated with operations at the "in-use" runway or helicopter landing area.
4.f.2	The simulation of runway or helicopter landing area contaminants must be correlated with the displayed runway surface and lighting, if applicable.
5	Correlation with helicopter and associated equipment. The following are the minimum correlation comparisons that must be made for a Level 7 FTD.
5.a	Visual system compatibility with aerodynamic programming.
5.b	Visual cues to assess sink rate and depth perception during landings.
5.c	Accurate portrayal of environment relating to FTD attitudes.
5.d	The visual scene must correlate with integrated helicopter systems, where installed (e.g., terrain, traffic and weather avoidance systems and Head-up Guidance System (HGS)).
5.e	Representative visual effects for each visible, own-ship, helicopter external light(s)—taxi and landing light lobes (including independent operation, if appropriate).
5.f	The effect of rain removal devices.
6	Scene quality. The following are the minimum scene quality tests that must be conducted for a Level 7 FTD.
6.a	System light points must be free from distracting jitter, smearing and streaking.
6.b	Demonstration of occulting through each channel of the system in an operational scene.
6.c	Six discrete light step controls (0–5).
7	Special weather representations, which include visibility and RVR, measured in terms of distance. Visibility/RVR checked at 2,000 ft (600 m) above the airport or helicopter landing area and at two heights below 2,000 ft with at least 500 ft of separation between the measurements. The measurements must be taken within a radius of 10 sm (16 km) from the airport or helicopter landing area.
7.a	Effects of fog on airport lighting such as halos and defocus.
7.b	Effect of own-ship lighting in reduced visibility, such as reflected glare, including landing lights, strobes, and beacons.
8	Instructor control of the following: The following are the minimum instructor controls that must be available in a Level 7 FTD.
8.a	Environmental effects: E.g., cloud base, cloud effects, cloud density, visibility in statute miles/kilometers and RVR in feet/meters.
8.b	Airport or helicopter landing area selection.
8.c	Airport or helicopter landing area lighting, including variable intensity.
8.d	Dynamic effects including ground and flight traffic.
	End QPS Requirement
	Begin Information
9	An example of being able to combine two airport models to achieve two "in-use" runways: One runway designated as the "in-use" runway in the first model of the airport, and the second runway designated as the "in-use" runway in the second model of the same airport. For example, the clearance is for the ILS approach to Runway 27 descipated as the "in use" runway 18 right. Two airport visual models might be used: The first with Runway 27 designated as the "in use" runway for the approach to runway 27, and the second with Runway 18 Right designated as the "in use" runway. When the pilot breaks off the ILS approach to runway 27, the instructor may change to the second airport visual model in which runway 18 Right is designated as the "in use" runway, and the pilot would make a visual approach and landing. This process is acceptable to the FAA as long as the temporary interruption due to the visual model change is not distracting to the pilot.

TABLE D3B—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS AIRPORT OR LANDING AREA CONTENT REQUIREMENTS FOR QUALIFICATION AT LEVEL 7 FTD—Continued

	QPS requirements		
Entry No.	Operations tasks		
10	Sponsors are not required to provide every detail of a runway, but the detail that is provided should be correct within reasonable limits.		

End Information

TABLE D3C—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD VISUAL REQUIREMENTS ADDITIONAL VISUAL MODELS BEYOND MINIMUM REQUIRED FOR QUALIFICATION CLASS II AIRPORT OR HELICOPTER LANDING AREA MODELS

QPS requirements	
Entry No.	Operations tasks

This table specifies the minimum airport or helicopter landing area visual model content and functionality necessary to add visual models to an FTD's visual model library (i.e., beyond those necessary for qualification at the stated level) without the necessity of further involvement of the responsible Flight Standards office or TPAA.

lights, threshold lights, and touchdown zone lights. 1.a.2. For "in-use" helicopter landing areas: Ground level TLOF perimeter lights, elevated TLOF perimeter lights (if applicable), Optional TLOF lights (if applicable), ground FATO perimeter lights, elevated TLOF lights (if applicable landing direction lights. 2. Wisual feature recognition. The following are the minimum distances at which runway or landing area features must be visible. Distances a measured from runway threshold or a helicopter landing area to an aircraft aligned with the runway or helicopter landing area on a 3° glide-slope from the aircraft to the touchdown point, in simulated meteorological condition For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intend landing. 2.a. For Runways. 2.a.1. Strobe lights, approach lights, and edge lights from 5 sm (8 km) of the threshold. 2.a.2. Centerline lights and taxiway definition from 3 sm (5 km). 2.a.3. Wisual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4. Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5. Markings within range of landing lights for night/twillight (dusk) scenes and as required by the surface resolutitest on daylight scenes.		s to an FTD's visual model library (i.e., beyond those necessary for qualification at the stated level) without the ne- further involvement of the responsible Flight Standards office or TPAA.
 1.a.1	1	
lights, threshold lights, and touchdown zone lights. 1.a.2. For "in-use" helicopter landing areas: Ground level TLOF perimeter lights, elevated TLOF perimeter lights (if applicable), Optional TLOF lights (if applicable), ground FATO perimeter lights, elevated TLOF lights (if applicable landing direction lights. 2. Wisual feature recognition. The following are the minimum distances at which runway or landing area features must be visible. Distances a measured from runway threshold or a helicopter landing area to an aircraft aligned with the runway or helicopter landing area on a 3° glide-slope from the aircraft to the touchdown point, in simulated meteorological condition For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intendianding. 2.a. For Runways. 2.a.1. Strobe lights, approach lights, and edge lights from 5 sm (8 km) of the threshold. 2.a.2. Centerline lights and taxiway definition from 3 sm (5 km). 2.a.3. Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4. Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5. Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutitest on daylight scenes. 2.a.6. For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuiting manner. 2.b. For Helicopter landing areas.	1.a	The installation and direction of the following lights must be replicated for the "in-use" surface:
cable), Optional TLOF lights (if applicable), ground FATO perimeter lights, elevated TLOF lights (if applicable landing direction lights. Visual feature recognition. The following are the minimum distances at which runway or landing area features must be visible. Distances a measured from runway threshold or a helicopter landing area to an aircraft aligned with the runway or helicopter landing area on a 3° glide-slope from the aircraft to the touchdown point, in simulated meteorological condition For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intend landing. 2.a. For Runways. 2.a.1. Strobe lights, approach lights, and edge lights from 5 sm (8 km) of the threshold. 2.a.2. Centerline lights and taxiway definition from 3 sm (5 km). 2.a.3. Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4. Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5. Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutitest on daylight scenes. 2.a.6. For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuiting manner. 2.b. For Helicopter landing areas.	1.a.1	
The following are the minimum distances at which runway or landing area features must be visible. Distances a measured from runway threshold or a helicopter landing area to an aircraft aligned with the runway or helicopte landing area on a 3° glide-slope from the aircraft to the touchdown point, in simulated meteorological condition. For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intend landing. 2.a	1.a.2	cable), Optional TLOF lights (if applicable), ground FATO perimeter lights, elevated TLOF lights (if applicable),
2.a.1 Strobe lights, approach lights, and edge lights from 5 sm (8 km) of the threshold. 2.a.2 Centerline lights and taxiway definition from 3 sm (5 km). 2.a.3 Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4 Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5 Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutitest on daylight scenes. 2.a.6 For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuit manner. 2.b For Helicopter landing areas.	2	The following are the minimum distances at which runway or landing area features must be visible. Distances are measured from runway threshold or a helicopter landing area to an aircraft aligned with the runway or helicopter landing area on a 3° glide-slope from the aircraft to the touchdown point, in simulated meteorological conditions. For circling approaches, all tests apply to the runway used for the initial approach and to the runway of intended
2.a.2 Centerline lights and taxiway definition from 3 sm (5 km). 2.a.3 Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4 Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5 Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutitest on daylight scenes. 2.a.6 For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuit manner. 2.b For Helicopter landing areas.	2.a	For Runways.
2.a.3 Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold. 2.a.4 Threshold lights and touchdown zone lights from 2 sm (3 km). 2.a.5 Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutitest on daylight scenes. 2.a.6 For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuit manner. 2.b For Helicopter landing areas.	2.a.1	Strobe lights, approach lights, and edge lights from 5 sm (8 km) of the threshold.
Threshold lights and touchdown zone lights from 2 sm (3 km). Answer in the surface resolution of lights for night/twilight (dusk) scenes and as required by the surface resolution test on daylight scenes. For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circumpular formular intended landing and associated lighting must fade into view in a non-circumpular face. For Helicopter landing areas.	2.a.2	Centerline lights and taxiway definition from 3 sm (5 km).
2.a.5 Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolutivest on daylight scenes. 2.a.6 For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuit manner. 2.b For Helicopter landing areas.	2.a.3	Visual Approach Aid lights (VASI or PAPI) from 5 sm (8 km) of the threshold.
test on daylight scenes. 2.a.6 For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-circuit manner. 2.b For Helicopter landing areas.	2.a.4	Threshold lights and touchdown zone lights from 2 sm (3 km).
tracting manner. 2.b	2.a.5	Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolution test on daylight scenes.
	2.a.6	For circling approaches, the runway of intended landing and associated lighting must fade into view in a non-distracting manner.
2.b.1 Landing direction lights and raised FATO lights from 2 sm (3 km).	2.b	For Helicopter landing areas.
	2.b.1	Landing direction lights and raised FATO lights from 2 sm (3 km).
2.b.2 Flush mounted FATO lights, TOFL lights, and the lighted windsock from 1 sm (1500 m).	2.b.2	Flush mounted FATO lights, TOFL lights, and the lighted windsock from 1 sm (1500 m).
2.b.3 Hover taxiway lighting (yellow/blue/yellow cylinders) from TOFL area.	2.b.3	Hover taxiway lighting (yellow/blue/yellow cylinders) from TOFL area.
2.b.4 Markings within range of landing lights for night/twilight (dusk) scenes and as required by the surface resolution test on daylight scenes.	2.b.4	

- -		QPS requirements
_	Entry No.	Operations tasks
3	J.	Airport or Helicopter Landing Area Model Content. The following prescribes the minimum requirements for what must be provided in an airport visual model and identifies other aspects of the airport environment that must correspond with that model. The detail must be developed using airport pictures, construction drawings and maps, or other similar data, or developed in accordance with published regulatory material; however, this does not require that airport or helicopter landing area models contain details that are beyond the designed capability of the currently qualified visual system. For circling approaches, all requirements of this section apply to the runway used for the initial approach and to the runway of intended landing. Only one "primary" taxi route from parking to the runway end or helicopter takeoff/landing area will be required for each "in-use" runway or helicopter takeoff/landing area.
3	3.a	The surface and markings for each "in-use" runway or helicopter landing area must include the following:
3	3.a.1	For airports: Runway threshold markings, runway numbers, touchdown zone markings, fixed distance markings, runway edge markings, and runway centerline stripes.
3	3.a.2	For helicopter landing areas: Standard heliport marking ("H"), TOFL, FATO, and safety areas.
3	3.b	The lighting for each "in-use" runway or helicopter landing area must include the following:
3	3.b.1	For airports: Runway approach, threshold, edge, end, centerline (if applicable), touchdown zone (if applicable), leadoff, and visual landing aid lights or light systems for that runway.
3	3.b.2	For helicopter landing areas: Landing direction, raised and flush FATO, TOFL, windsock lighting.
3	3.c	The taxiway surface and markings associated with each "in-use" runway or helicopter landing area must include the following:
3	3.c.1	For airports: Taxiway edge, centerline (if appropriate), runway hold lines, and ILS critical area(s).
3	3.c.2	For helicopter landing areas: Taxiways, taxi routes, and aprons.
3	3.d	The taxiway lighting associated with each "in-use" runway or helicopter landing area must include the following:
3	3.d.1	For airports: Runway edge, centerline (if appropriate), runway hold lines, ILS critical areas.
3	3.d.2	For helicopter landing areas: Taxiways, taxi routes, and aprons.
4	l	Required visual model correlation with other aspects of the airport environment simulation. The following are the minimum visual model correlation tests that must be conducted for Level 7 FTD.
4	I.a	The airport model must be properly aligned with the navigational aids that are associated with operations at the "in-use" runway.
4	l.b	Slopes in runways, taxiways, and ramp areas, if depicted in the visual scene, must not cause distracting or unreal- istic effects.
5	i	Correlation with helicopter and associated equipment. The following are the minimum correlation comparisons that must be made.
5	i.a	Visual system compatibility with aerodynamic programming.
5	5.b	Accurate portrayal of environment relating to flight simulator attitudes.
5	5.c	Visual cues to assess sink rate and depth perception during landings.
6	5.	Scene quality. The following are the minimum scene quality tests that must be conducted.
6	3.a	Light points free from distracting jitter, smearing or streaking.
6	3.b	Surfaces and textural cues free from apparent and distracting quantization (aliasing).
	7.	Instructor controls of the following. The following are the minimum instructor controls that must be available.
7 ZILLE	7.a	Environmental effects, e.g., cloud base (if used), cloud effects, cloud density, visibility in statute miles/kilometers and RVR in feet/meters.
## CT 14:00 Mar 1		431
o	4, 2024 J	Jkt 262047 PO 00000 Frm 00441 Fmt 8010 Sfmt 8002 Q:\14\14V2.TXT PC31

TABLE D3C—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 7 FTD VISUAL REQUIREMENTS ADDITIONAL VISUAL MODELS BEYOND MINIMUM REQUIRED FOR QUALIFICATION CLASS II AIRPORT OR HELICOPTER LANDING AREA MODELS—Continued

	QPS requirements	
Entry No.	Operations tasks	
7.b	Airport/Heliport selection.	
7.c	Airport/Heliport lighting including variable intensity.	
7.d	Dynamic effects including ground and flight traffic.	
	End QPS Requirements	
	Begin Information	
8	Sponsors are not required to provide every detail of a runway or helicopter landing area, but the detail that is provided must be correct within the capabilities of the system.	
	End Information	

TABLE D3D—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 6 FTD

QPS requirements	
Entry No.	Operations tasks

Tasks in this table are subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ Configuration List or for a Level 6 FTD. Items not installed or not functional on the FTD and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

1. Preflight Procedures	
1.a	Preflight Inspection (Flight Deck Only) switches, indicators, systems, and equipment.
1.b	APU/Engine start and run-up.
1.b.1	Normal start procedures.
1.b.2	Alternate start procedures.
1.b.3	Abnormal starts and shutdowns.
1.b.4	Rotor engagement.
1.b.5	System checks.
2. Takeoff and Dep	arture Phase
2.a	Instrument.
2.b	Takeoff with engine failure after critical decision point (CDP).
3. Climb	
3.a	Normal.
3.b	One engine inoperative.

4. Inflight Maneuvers	
4.a	Performance.
4.b	Flying qualities.
4.c	Turns.
4.c.1	Timed.
4.c.2	Normal.
4.c.3	Steep.
4.d	Accelerations and decelerations.

QPS requirements		
Entry No.	Operations tasks	
4.e	Abnormal/emergency procedures:	
4.e.1	Engine fire.	
4.e.2	Engine failure.	
4.e.3	In-flight engine shutdown (and restart, if applicable).	
4.e.4	Fuel governing system failures (e.g., FADEC malfunction).	
4.e.5	Directional control malfunction (restricted to the extent that the maneuver may not terminate in a landing).	
4.e.6	Hydraulic failure.	
4.e.7	Stability augmentation system failure.	
5. Instrument Proce	edures	
5.a	Holding.	
5.b	Precision Instrument Approach.	
5.b.1	All engines operating.	
5.b.2	One or more engines inoperative.	
5.b.3	Approach procedures:	
5.b.4	PAR.	
5.b.5	ILS.	
5.b.6	Manual (raw data).	
5.b.7	Flight director only.	
5.b.8	Autopilot* and flight director (if appropriate) coupled.	
5.c	Non-precision Instrument Approach.	
5.c	Normal—All engines operating.	
5.c	One or more engines inoperative.	
5.c	Approach procedures:	
5.c.1	NDB.	
5.c.2	VOR, RNAV, TACAN, GPS.	
5.c.3	ASR.	
5.c.4	Helicopter only.	
5.d	Missed Approach.	
5.d.1	All engines operating.	
5.d.2	One or more engines inoperative.	
5.d.3	Stability augmentation system failure.	
6. Normal and Abnormal Procedures (any phase of flight)		
6.a	Helicopter and powerplant systems operation (as applicable).	
6.a.1	Anti-icing/deicing systems.	
6.a.2	Auxiliary power-plant.	
6.a.3	Communications.	

TABLE D3D—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 6 FTD—Continued

QPS requirements		
Entry No.	Operations tasks	
6.a.4	Electrical system.	
6.a.5	Environmental system.	
6.a.6	Fire detection and suppression.	
6.a.7	Flight control system.	
6.a.8	Fuel system.	
6.a.9	Engine oil system.	
6.a.10	Hydraulic system.	
6.a.11	Landing gear.	
6.a.12	Oxygen.	
6.a.13	Pneumatic.	
6.a.14	Powerplant.	
6.a.15	Flight control computers.	
6.a.16	Stability augmentation and control augmentation system(s).	
6.b	Flight management and guidance system (as applicable).	
6.b.1	Airborne radar.	
6.b.2	Automatic landing aids.	
6.b.3	Autopilot.*	
6.b.4	Collision avoidance system.	
6.b.5	Flight data displays.	
6.b.6	Flight management computers.	
6.b.7	Navigation systems.	
7. Postflight Proced	dures	
7.a	Parking and Securing.	
7.b	Engine and systems operation.	
7.c	Parking brake operation.	
7.d	Rotor brake operation.	
7.e	Abnormal/emergency procedures.	
8. Instructor Operating Station (IOS), as appropriate		
8.a	Power Switch(es).	
8.b.1	Helicopter conditions.	
8.b.2	Gross weight, center of gravity, fuel loading and allocation, etc.	
8.b.3	Helicopter systems status.	
8.b.4	Ground crew functions (e.g., ext. power).	
8.c	Airports and landing areas.	
8.c.1	Number and selection.	
8.c.2	Runway or landing area selection.	

QPS requirements	
Entry No.	Operations tasks
8.c.3	Preset positions (e.g., ramp, over FAF).
8.c.4	Lighting controls.
8.d	Environmental controls.
8.d.1	Temperature.
8.d.2	Climate conditions (e.g., ice, rain).
8.d.3	Wind speed and direction.
8.e	Helicopter system malfunctions.
8.e.1	Insertion/deletion.
8.e.2	Problem clear.
8.f	Locks, Freezes, and Repositioning.
8.f.1	Problem (all) freeze/release.
8.f.2	Position (geographic) freeze/release.
8.f.3	Repositioning (locations, freezes, and releases).
8.f.4	Ground speed control.
8.g	Sound Controls. On/off/adjustment.
8.h	Control Loading System (as applicable) On/off/emergency stop.
8.i	Observer Stations.
8.i.1	Position.
8.i.2	Adjustments.

^{*&}quot;Autopilot" means attitude retention mode of operation.

TABLE D3E—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 5 FTD

QPS requirements	
Entry No.	Operations tasks

Tasks in this table are subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ Configuration List or for a Level 5 FTD. Items not installed or not functional on the FTD and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

1. Preflight Procedures

3. Inflight Maneuvers	
2.a	Normal.
2. Climb	
1.b.3	Abnormal starts and shutdowns.
1.b.2	Alternate start procedures.
1.b.1	Normal start procedures.
1.b	APU/Engine start and run-up.
1.a	Preflight Inspection (Flight Deck Only) switches, indicators, systems, and equipment.

3.a	Performance.
3.b	Turns, Normal.

TABLE D3E—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 5 FTD—Continued

QPS requirements		
Entry No.	Operations tasks	
4. Instrument Procedures		
4.a	Coupled instrument approach maneuvers (as applicable for the systems installed).	
5. Normal and Abnormal Procedures (any phase of flight)		
5.a	Normal system operation (installed systems).	
5.b	Abnormal/Emergency system operation (installed systems).	
6. Postflight Procedures		
6.a	Parking and Securing.	
6.b	Engine and systems operation.	
6.c	Parking brake operation.	
6.d	Rotor brake operation.	
6.e	Abnormal/emergency procedures.	
7. Instructor Operat	ing Station (IOS), as appropriate	
7.a	Power Switch(es).	
7.b	Preset positions (ground; air)	
7.c	Helicopter system malfunctions.	
7.c.1	Insertion/deletion.	
7.c.2	Problem clear.	
7.d	Control Loading System (as applicable) On/off/emergency stop.	
7.e	Observer Stations.	
7.e.1	Position.	
7.e.2	Adjustments.	

TABLE D3F—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 4 FTD

QPS requirements	
Entry No.	Operations tasks

Tasks in this table are subject to evaluation if appropriate for the helicopter simulated as indicated in the SOQ Configuration List or for a Level 4 FTD. Items not installed or not functional on the FTD and not appearing on the SOQ Configuration List, are not required to be listed as exceptions on the SOQ.

1. Preflight Procedures

1.a	Preflight Inspection (Flight Deck Only) switches, indicators, systems, and equipment.
1.b	APU/Engine start and run-up.
1.b.1	Normal start procedures.
1.b.2	Alternate start procedures.
1.b.3	Abnormal starts and shutdowns.
2. Normal and Abnormal Procedures (any phase of flight)	

2.a	Normal system operation (installed systems).
2.b	Abnormal/Emergency system operation (installed systems).

Federal Aviation Administration, DOT

Pt. 60, App. D

TABLE D3F—TABLE OF FUNCTIONS AND SUBJECTIVE TESTS LEVEL 4 FTD—Continued

	QPS requirements							
Entry No.	Entry No. Operations tasks							
3. Postflight Proced	3. Postflight Procedures							
3.a	Parking and Securing.							
3.b	Engine and systems operation.							
3.c	Parking brake operation.							
4. Instructor Operat	ting Station (IOS), as appropriate							
4.a	Power Switch(es).							
4.b	Preset positions (ground; air)							
4.c	Helicopter system malfunctions.							
4.c.1	Insertion/deletion.							
.c.2 Problem clear.								

ATTACHMENT 4 TO APPENDIX D TO PART 60—SAMPLE DOCUMENTS

TABLE OF CONTENTS

Figure D4A Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation

Figure D4B Attachment: FTD Information Form

 $\begin{array}{lll} Figure \ D4C & Sample \ Letter \ of \ Compliance \\ Figure \ D4D \ Sample \ Qualification \ Test \\ Guide \ Cover \ Page \end{array}$

Figure D4E Sample Statement of Qualification—Certificate

Figure D4F Sample Statement of Qualification—Configuration List

Figure D4G $\,$ Sample Statement of Qualification—List of Qualified Tasks

Figure D4H [Reserved]

Figure D4I Sample MQTG Index of Effective FTD Directives

ATTACHMENT 4 TO APPENDIX D TO PART 60—FIGURE D4A—SAMPLE LETTER, REQUEST FOR INITIAL, UPGRADE, OR REINSTATEMENT EVALUATION

Date
RE: Request for Initial/Upgrade Evaluation Date
This is to advise you of our intent to request an (initial or upgrade) evaluation of our (FTD Manufacturer), (Aircraft Type/Level) Flight Training Device (FTD), (FAA ID Number, if previously qualified), located in (City, State) at the (Facility) on (Proposed Evaluation Date). (The proposed evaluation date shall not be more than 180 days following the date of this letter.) The FTD will be sponsored by (Name of Training Center/Air Carrier), FAA Designator (4 Letter Code). The FTD will be sponsored as follows; (Select One)
☐ The FTD will be used within the sponsor's FAA approved training program and placed on the sponsor's Training/Operations Specifications.
☐ The FTD will be used for dry lease only.
We agree to provide the formal request for the evaluation to your staff as follows: (check one)

14 CFR Ch. I (1-1-24 Edition)

Pt. 60, App. D

For Q1G tests run at the factory, not later, than 45 days prior to the proposed evaluation date with the
additional "I/3 on-site" tests provided not later than 14 days prior to the proposed evaluation date.

For QTG tests run on-site, not later than 30 days prior to the proposed evaluation date.

We understand that the formal request will contain the following documents:

- 1. Sponsor's Letter of Request (Company Compliance Letter).
- 2. Principal Operations Inspector (POI) or Training Center Program Manager's (TCPM) endorsement.
- 3. Complete QTG.

If we are unable to meet the above requirements, we understand this may result in a significant delay, perhaps 45 days or more, in rescheduling and completing the evaluation.

(The sponsor should add additional comments as necessary).

Please contact (Name Telephone and Fax Number of Sponsor's Contact) to confirm the date for this initial evaluation. We understand a member of your National Simulator Program staff will respond to this request within 14 days.

A copy of this letter of intent has been provided to (Name), the Principal Operations Inspector (POI) and/or Training Center Program Manager (TCPM).

Sincerely,

Attachment: FTD Information Form

cc: POI/TCPM

Federal Aviation Administration, DOT

Pt. 60, App. D

Attachment 4 to Appendix D to Part 60—
Figure D4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation
Attachment: FSTD Information Form INFORMATION

Date:						*****************	PER PROPERTY OF THE PERSON NAMED IN COLUMN		oneconsonus
	Section 1.	FSTD Info	ormat		l Characteri	stics			
Sponsor Name:				FSTI	D Location:				
Address:	and projection and the second			Physical Address:					
City:		- Particular and a second and a							
State:				State	:				
Country:				Coun	itry:				
ZIP:				ZIP:					
Manager									
Sponsor ID No: (Four Letter FAA Designator)					est Airport: ort Designator)				
Type of Evaluation Requested	d:			al 🔲 Upg statement	rade 🗌 Continu	ing Qu	alification	☐ Special	
Aircraft Make/model/series:	.,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,								
Initial Qualification: (If Applicable)	Date: MM/DD/YYY	Level		Manufa Identific Number	ation or Serial				
Upgrade Qualification: (If Applicable)	Date: MM/DD/YYY	Level		☐ eMQ	TG				
Qualification Basis:] A	В		☐ Interim C		□ C	D	
] 6	7		Provisional	Status			
					- 22				
Other Technical Information	:								
FAA FSTD ID No: (If Applicable)				FSTD Manufacturer:					
Convertible FSTD:	□Yes:			Date of Manufacture: MM/I			D/YYYY		
Related FAA ID No. (If Applicable)				Sponsor FSTD ID No:					
Engine model(s) and data rev	ision:	MINISTER STATE OF THE STATE OF		Source of aerodynamic model:					
FMS identification and revisi	on level:			Source of aerodynamic coefficient data:					
Visual system manufacturer/	model:			Aerodynamic data revision number:					
Flight control data revision:				Visual system display:					
Mot ion system manufactures	/type:			FSTD computer(s) identification:					
					•				
National Aviation Authority (NAA): (If Applicable)		-							
NAA FSTD ID No:				Last NAA Evaluation Date:					***************************************
NAA Qualification Level:		-			· · · · · · · · · · · · · · · · · · ·				
NAA Qualification Basis:								***************************************	
					1000000				
Visual System Manufacturer and Type:		FSTD Availa			on System Manι Γype:	ıfacture	er	•	
		1							

Pt. 60, App. D

Attachment 4 to Appendix D to Part 60— Figure D4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation Attachment: FSTD Information Form INFORMATION

Aircraft Equipment:	Engine Type(s):	☐ EFIS [☐ TCAS [☐ GPS [umentation: HUD HO GPWS Pla FMS Type: dar Other:	Engine Instrumentation: EICAS FADEC Other: _				
Airport Models:	3.6.1		3.6.2		3,6,3			
•		Designator		Designator	Airport Designator			
Circle to Land:	3. 7.1	— Designator	3. 7.2Appro	nach	3. 7.3 Landing Runway			
Visual Ground Segmen	Visual Ground Segment 3.8.1 3.8.2				3. 8.3 Landing Runway			
	Section	ı 2. Supplen	nentary Info					
FAA Training Program	n Approval Authority:	***************************************		ГСРМ □ Othe	r:			
Name:			Office:					
Tel:	,		Fax:					
Email:								
FSTD Scheduling Pers	on:							
Name:								
Address 1:			Address 2					
City:			State:					
ZIP:			Email:	Email:				
Tel:			Fax:		A			
FSTD Technical Conta	et:							
Name:								
Address 1:			Address 2					
City:			State:					
ZIP:			Email:					
Tel:		***************************************	Fax:		Section to the section of the sectio			
	Section 3. Traini	ing, Testing	and Checkin	ng Consider	rations			
Area/Function/Maneuv			Request					
Private Pilot - Training / Checks: (142)								
Commercial Pilot - Training /Checks:(142)								
Multi-Engine Rating - Training / Checks (142)								
Instrument Rating -Training / Checks (142)								
	g / Checks (135/121/142)							
Proficiency Checks (13	5/121/142)							
CAT I: (RVR 2400/1800 ft. DH200 ft)								

Attachment 4 to Appendix D to Part 60— Figure D4B – Sample Letter, Request for Initial, Upgrade, or Reinstatement Evaluation Attachment: FSTD Information Form INFORMATION

ATTACHMENT 4 TO APPENDIX D TO PART 60-FIGURE D4C—SAMPLE LETTER OF COMPLIANCE

(Date)

Mr. (Name of Training Program Approval Authority): (Name of responsible Flight Standards office) (Address) (City/State/Zip)

Dear Mr. (Name of TPAA):

RE: Letter of Compliance

(<u>Operator Sponsor Name</u>) requests evaluation of our (<u>Aircraft Type</u>) FTD for Level (<u>___)</u> qualification. The (<u>FTD Manufacturer Name</u>) FTD with (<u>Visual System Manufacturer Name/Model</u>) system is fully defined on the FTD Information page of the accompanying Qualification Test Guide (QTG). We have completed the tests of the FTD and certify that it meets all applicable requirements of FAR parts <u>121</u>, <u>125</u>, <u>or 135</u>), and the guidance of (<u>AC 120-40B or 14 CFR Part 60</u>). Appropriate hardware and software configuration control procedures have been

established. Our Pilot(s), (Name(s)), who are qualified on (Aircraft Type) aircraft have assessed the FTD and have found that it conforms to the (Operator/Sponsor) (Aircraft Type) flight deck configuration and that the simulated systems and subsystems function equivalently to those in the aircraft. The above named pilot(s) have also assessed the performance and the flying qualities of the FTD and find that it represents the respective aircraft.

(Added Comments may be placed here)

Sincerely, (Sponsor Representative)

ATTACHMENT 4 TO APPENDIX D TO PART 60— FIGURE D4D—SAMPLE QUALIFICATION TEST GUIDE COVER PAGE

SPONSOR NAME

SPONSOR ADDRESS

		FAA QU	JALIFICATION TEST	T GUIDE				
(SPECIFIC HELICOPTER MODEL)								
		(for example)				
		(Vertiflite AB-320)				
(FTD Ide	entification	Including	Manufacturer, Serial (FTD Level)	Number, Visual System Used)				
	(Qualifica	tion Performance Stan	ndard Used)				
	(FTD Location)							
FAA Initial Ev	aluation							
Date:								
				_				
-				Date:				
			(Sponsor)					
				Date:				
	FAA							

ATTACHMENT 4 TO APPENDIX D TO PART 60—FIGURE D4E—SAMPLE STATEMENT OF QUALIFICATION—CERTIFICATE

Federal Aviation Administration



Certificate of Qualification

This is to certify that representatives of the FAA Completed an evaluation of the

Go-Fast Training Center Vertiflite AB-320 Flight Training Device

FAA Identification Number 889

And found it to meet the standards set forth in

14 CFR Part 60, Appendix D Qualification Performance Standards

The Master Qualification Test Guide and the attached Configuration List and List of Qualified Tasks Provide the Qualification Basis for this device to operate at

Level 6

Until April 30, 2010

Unless sooner rescinded or extended by the FAA

March 15, 2009	C. Nordlie
(date)	(for the FAA)

Attachment 4 to Appendix D to Part 60— Figure D4F – Sample Statement of Qualification – Configuration List INFORMATION

STATEMENT of QUALIFICATION CONFIGURATION LIST

Date:								
	Section 1. FSTD I	nformat	ion and Characteri	stics				
Sponsor Name:			FSTD Location:					
Address:			Physical Address:	Physical Address:				
City:			City:					
State:			State:					
Country:			Country:					
ZIP:			ZIP:					
Manager								
Sponsor ID No: (Four Letter FAA Designator)	-		Nearest Airport: (Airport Designator)	Anniholating-gala-				
Type of Evaluation Requested:			al 🔲 Upgrade 🔲 Continu statement	ing Qualification 🗌 Special				
Aircraft Make/model/series:			4					
Initial Qualification: (If Applicable)	Date: Level MM/DD/YYYY		Manufacturer's Identification or Serial Number					
Upgrade Qualification: (If Applicable)	Date: Level MM/DD/YYYY		□ eMQTG					
Qualification Basis:	_ A	□В	☐ Interim C	□ C □ D				
	□ 6	7	☐ Provisional	Status				
Other Technical Information:			-					
FAA FSTD ID No: (If Applicable)			FSTD Manufacturer:					
Convertible FSTD:	□Yes:		Date of Manufacture: MM/DD/YYYY					
Related FAA ID No. (If Applicable)			Sponsor FSTD ID No:					
Engine model(s) and data revision	on:		Source of aerodynamic model:					
FMS identification and revision	level:		Source of aerodynamic coefficient data:					
Visual system manufacturer/mo	del:		Aerodynamic data revision number:					
Flight control data revision:			Visual system display:					
Mot ion system manufacturer/ty	ype:		FSTD computer(s) identification:					
and the second s	-							
National Aviation Authority (NAA): (If Applicable)								
NAA FSTD ID No:			Last NAA Evaluation Date:					
NAA Qualification Level:								
NAA Qualification Basis:								

Pt. 60, App. D

Attachment 4 to Appendix D to Part 60—
Figure D4F – Sample Statement of Qualification – Configuration List

INFORMATION

m Manufacturer FSTD Seats Motion System Manufactur

		Available:		and Type:	em Manuiaco	urei		
Aircraft Equipment:	Engine Ty	pe(s):	☐ EFIS ☐ TCAS ☐ GPS ☐	Flight Instrumentation: EFIS			Engine Instrumentation: □ EICAS □ FADEC □ Other: □	
Airport Models:		3.6.1		3,6	2		3.6.3	
		Airport D	Designator		Airport Desi	gnator	Air	port Designator
Circle to Land:		3. 7.1	Designator	3. 1	7.2 Approach		3. 7.3 Landing Runway	
Visual Ground Segmen	t	3.8.1		3.8	.2		3. 8.3	
L		Airport	Designator		Approach		La La	anding Runway
		Section	2. Supplem	enta	rv Inform	ation		
FAA Training Program	Approval A		2. Supplem		POI 🔲 TCF	M 🔲 Other:		
Name:		************************			fice:			***************************************
Tel:				Fa	x:			
Email:								
FSTD Scheduling Person	on:							
Name:		_						
Address 1:				Ad	Address 2			
City:				Sta	State:			
ZIP:			Email:					
Tel:		_		Fax:				
		14.65						
FSTD Technical Conta	et:							
Name:		_	····					
Address 1:					lress 2			
City:		_		Stat				
ZIP:				Ema				
Tel:				Fax	:			
			De No. Philadelphia and American State of the Company of the Compa	enesana e				
Area/Function/Maneuv		ı 3. Trainii	ng, Testing a	and (tions	
					Requested	Remarks		
Private Pilot - Training			****				-	
Commercial Pilot - Tra	ining /Check	s:(142)						
Multi-Engine Rating - Training / Checks (142)							_	
Instrument Rating -Tra	ining / Chec	ks (142)						
Type Rating - Training	J Checks (13	35/121/142)					-	
Proficiency Checks (13:	5/121/142)	·				1	*	
L						I	-	

Attachment 4 to Appendix D to Part 60— Figure D4F – Sample Statement of Qualification – Configuration List

INFORMATION		
CAT I: (RVR 2400/1800 ft. DH200 ft)		
CAT II: (RVR 1200 ft. DH 100 ft)		
CAT III * (lowest minimum) RVR ft.	10	
* State CAT III (≤ 700 ft.), CAT IIIb (≤ 150 ft.), or CAT IIIc (0 ft.)	į	
Circling Approach		
Windshear Training:		
Windshear Training IAW 121.409(d) (121 Turbojets Only)		
Generic Unusual Attitudes and Recoveries within the Normal Flight		
Envelope		
Specific Unusual Attitudes Recoveries		***************************************
Auto-coupled Approach/Auto Go Around		
Auto-land / Roll Out Guidance		
TCAS/ACAS I / II		
WX-Radar		
HUD		
HGS		
EFVS		
Future Air Navigation Systems		
GPWS / EGPWS		
ETOPS Capability		
GPS		
SMGCS		
Helicopter Slope Landings		
Helicopter External Load Operations		
Helicopter Pinnacle Approach to Landings		
Helicopter Night Vision Maneuvers		
Helicopter Category A Takeoffs	to	

Pt. 60, App. D

Attachment 4 to Appendix D to Part 60-Figure D4G - Sample Statement of Qualification - List of Qualified Tasks INFORMATION

STATEMENT of QUALIFICATION LIST of QUALIFIED TASKS

Go-Fast Training Center Vertiflite AB-320 -- Level C -- FAA ID# 888

The FTD is qualified to perform all of the Maneuvers, Procedures, Tasks, and Functions Listed in Appendix D, Attachment 1, Table D1B, Minimum FTD Requirements In Effect on [mm/dd/yyyy] except for the following listed Tasks or Functions.

(Example)
Excepted Tasks:
6.f. Fire Detection and Extinguisher System.7.d. Ditching.
Excepted Simulator Systems:
Remote IOS
Additional Qualified Tasks or Functions in addition to those listed in Appendix D, Attachment 3, Table D1B, Minimum FTD Requirements.
(None)

ATTACHMENT 4 TO APPENDIX D TO PART 60—FIGURE D4H [RESERVED]

Attachment 4 to Appendix D to Part 60— Figure D4I – Sample MQTG Index of Effective FTD Directives INFORMATION

Index of Effective FSTD Directives Filed in this Section					
Number	Effective Date	Date of Notification	Details		
<u> </u>					
<u> </u>					
<u> </u>	•				

Continue as Necessary....

[Doc. No. FAA–2002–12461, 73 FR 26490, May 9, 2008, as amended by Amdt. 60–6, 83 FR 30276, June 27, 2018; Docket No. FAA–2022–1355, Amdt. No. 60–7, 87 FR 75832, Dec. 9, 2022]

APPENDIX E TO PART 60—QUALIFICATION PERFORMANCE STANDARDS FOR QUALITY MANAGEMENT SYSTEMS FOR FLIGHT SIMULATION TRAINING DEVICES

BEGIN QPS REQUIREMENTS

a. Not later than May 30, 2010, each current sponsor of an FSTD must submit to the responsible Flight Standards office a proposed Quality Management System (QMS) program as described in this appendix. The responsible Flight Standards office will notify the sponsor of the acceptability of the program, including any required adjustments. Within 6 months of the notification of acceptability, the sponsor must implement the program, conduct internal audits, make required program adjustments as a result of any internal audit, and schedule the responsible Flight Standards office initial audit.

b. First-time FSTD sponsors must submit to the responsible Flight Standards office the proposed QMS program no later than 120 days before the initial FSTD evaluation. The responsible Flight Standards office will notify the sponsor of the acceptability of the program, including any required adjustments. Within 6 months of the notification of acceptability, the sponsor must implement the program, conduct internal audits, make required program adjustments as a result of any internal audit, and schedule the responsible Flight Standards office initial audit.

c. The Director of Operations for a Part 119 certificate holder, the Chief Instructor for a Part 141 certificate holder, or the equivalent for a Part 142 or Flight Engineer School sponsor must designate a Management Representative (MR) who has the authority to establish and modify the sponsor's policies, practices, and procedures regarding the QMS program for the recurring qualification and the daily use of each FSTD.

d. The minimum content required for an acceptable QMS is found in Table E1. The policies, processes, or procedures described in this table must be maintained in a Quality Manual and will serve as the basis for the following:

(1) The sponsor-conducted initial and recurring periodic assessments;

Pt. 60, App. E

- (2) The responsible Flight Standards office-conducted initial and recurring periodic assessments; and
- (3) The continuing surveillance and analysis by the responsible Flight Standards office of the sponsor's performance and effectiveness in providing a satisfactory FSTD for use on a regular basis.
- e. The sponsor must conduct assessments of its QMS program in segments. The segments will be established by the responsible Flight Standards office at the initial assessment, and the interval for the segment assessments will be every 6 months. The intervals for the segment assessments may be extended beyond 6 months as the QMS program matures, but will not be extended beyond 12 months. The entire QMS program must be assessed every 24 months.
- f. The periodic assessments conducted by the responsible Flight Standards office will be conducted at intervals not less than once every 24 months, and include a comprehensive review of the QMS program. These reviews will be conducted more frequently if warranted.

END QPS REQUIREMENTS

BEGIN INFORMATION

- g. An example of a segment assessment— At the initial QMS assessment, the responsible Flight Standards office will divide the QMS program into segments (e.g., 6 separate segments). There must be an assessment of a certain number of segments every 6 months (i.e., segments 1 and 2 at the end of the first 6 month period; segments 3 and 4 at the end of the second 6 month period (or one year); and segments 5 and 6 at the end of the third 6 month period (or 18 months). As the program matures, the interval between assessments may be extended to 12 months (e.g., segments 1, 2, and 3 at the end of the first year; and segments 4, 5, and 6 at the end of the second year). In both cases, the entire QMS program is assessed at least every 24 months.
- h. The following materials are presented to assist sponsors in preparing for an responsible Flight Standards office evaluation of the QMS program. The sample documents include:
- (1) The desk assessment tool for initial evaluation of the required elements of a QMS program.
- (2) The on-site assessment tool for initial and continuing evaluation of the required elements of a QMS program.
- (3) An Element Assessment Table that describes the circumstances that exist to warrant a finding of "non-compliance," or "non-conformity"; "partial compliance," or "partial conformity"; and "acceptable compliance," or "acceptable conformity."

- (4) A sample Continuation Sheet for additional comments that may be added by the sponsor or the responsible Flight Standards office during a QMS evaluation.
- (5) A sample Sponsor Checklist to assist the sponsor in verifying the elements that comprise the required QMS program.
- (6) A table showing the essential functions, processes, and procedures that relate to the required QMS components and a cross-reference to each represented task.
- i. Additional Information.
- (1) In addition to specifically designated QMS evaluations, the responsible Flight Standards office will evaluate the sponsor's QMS program as part of regularly scheduled FSTD continuing qualification evaluations and no-notice FSTD evaluations, focusing in part on the effectiveness and viability of the QMS program and its contribution to the overall capability of the FSTD to meet the requirements of this part.
- (2) The sponsor or MR may delegate duties associated with maintaining the qualification of the FSTD (e.g., corrective and preventive maintenance, scheduling and conducting tests or inspections, functional preflight checks) but retain the responsibility and authority for the day-to-day qualification of the FSTD. One person may serve as the sponsor or MR for more than one FSTD, but one FSTD may not have more than one sponsor or MR.
- (3) A QMS program may be applicable to more than one certificate holder (e.g., part 119 and part 142 or two part 119 certificate holders) and an MR may work for more than one certificate holder (e.g., part 119 and part 142 or two part 119 certificate holders) as long as the sponsor's QMS program requirements and the MR requirements are met for each certificate holder.
- j. The FAA does not mandate a specific QMS program format, but an acceptable QMS program should contain the following:
- (1) A Quality Policy. This is a formal written Quality Policy Statement that is a commitment by the sponsor outlining what the Quality System will achieve.
- (2) A MR who has overall authority for monitoring the on-going qualification of assigned FSTDs to ensure that all FSTD qualification issues are resolved as required by this part. The MR should ensure that the QMS program is properly implemented and maintained and should:
- (a) Brief the sponsor's management on the qualification processes;
- (b) Serve as the primary contact point for all matters between the sponsor and the responsible Flight Standards office regarding the qualification of the assigned FSTDs; and
- (c) Oversee the day-to-day quality control.
- (3) The system and processes outlined in the QMS should enable the sponsor to monitor compliance with all applicable regulations and ensure correct maintenance and

Federal Aviation Administration, DOT

performance of the FSTD in accordance with part 60.

- (4) A QMS program and a statement acknowledging completion of a periodic review by the MR should include the following:
- (a) A maintenance facility that provides suitable FSTD hardware and software tests and maintenance capability.
- (b) A recording system in the form of a technical log in which defects, deferred defects, and development projects are listed, assigned and reviewed within a specified time period.

 (c) Routine maintenance of the FSTD and
- (c) Routine maintenance of the FSTD and performance of the QTG tests with adequate staffing to cover FSTD operating periods.
- (d) A planned internal assessment schedule and a periodic review should be used to verify that corrective action was complete and effective. The assessor should have adequate knowledge of FSTDs and should be acceptable to the responsible Flight Standards office
- (5) The MR should receive Quality System training and brief other personnel on the procedures.

END INFORMATION

TABLE E1—FSTD QUALITY MANAGEMENT SYSTEM

Entry No.	QPS Requirement	Information (Reference)
E1.1	A QMS manual that prescribes the policies, processes, or procedures outlined in this table.	§ 60.5(a).
E1.2	A policy, process, or procedure specifying how the sponsor will identify defi- ciencies in the QMS.	§ 60.5(b).
E1.3	A policy, process, or procedure specifying how the sponsor will document how the QMS program will be changed to address deficiencies.	§ 60.5(b).
E1.4	A policy, process, or procedure specifying how the sponsor will address pro- posed program changes (for programs that do not meet the minimum re- quirements as notified by the responsible Flight Standards office) to the re- sponsible Flight Standards office and receive approval prior to their imple- mentation.	§ 60.5(c).
E1.5	A policy, process, or procedure specifying how the sponsor will document that at least one FSTD is used within the sponsor's FAA-approved flight training program for the aircraft or set of aircraft at least once within the 12-month period following the initial or upgrade evaluation conducted by the responsible Flight Standards office and at least once within each subsequent 12-month period thereafter.	§ 60. 7(b)(5).
E1.6	A policy, process, or procedure specifying how the sponsor will document that at least one FSTD is used within the sponsor's FAA-approved flight training program for the aircraft or set of aircraft at least once within the 12-month period following the first continuing qualification evaluation conducted by the responsible Flight Standards office and at least once within each subsequent 12-month period thereafter.	§ 60.7(b)(6).
E1.7	A policy, process, or procedure specifying how the sponsor will obtain an annual written statement from a qualified pilot (who has flown the subject aircraft or set of aircraft during the preceding 12-month period) that the performance and handling qualities of the subject FSTD represents the subject aircraft or set of aircraft (within the normal operating envelope). Required only if the subject FSTD is not used in the sponsor's FAA-approved flight training program for the aircraft or set of aircraft at least once within the preceding 12-month period.	§ 60.5(b)(7) and § 60.7(d)(2).
E1.8		§ 60.9(b)(1).
E1.9	A policy, process, or procedure specifying how and where the FSTD SOQ will be posted, or accessed by an appropriate terminal or display, in or adjacent to the FSTD.	§ 60.9(b)(2).
E1.10	A policy, process, or procedure specifying how the sponsor's management representative (MR) is selected and identified by name to the responsible Flight Standards office.	§ 60.9(c) and Appendix E, paragraph(d).
E1.11	A policy, process, or procedure specifying the MR authority and responsibility for the following:	§ 60.9(c)(2), (3), and (4).
E1.11.a	Monitoring the on-going qualification of assigned FSTDs to ensure all matters regarding FSTD qualification are completed as required by this part.	
E1.11.b		
E1.11.c	Regularly briefing sponsor's management on the status of the on-going FSTD qualification program and the effectiveness and efficiency of the QMS.	

TABLE E1—FSTD QUALITY MANAGEMENT SYSTEM—Continued

Entry No.	QPS Requirement	Information (Reference)
E1.11.d	Serving as the primary contact point for all matters between the sponsor and the responsible Flight Standards office regarding the qualification of assigned FSTDs.	
E1.11.e	Delegating the MR assigned duties to an individual at each of the sponsor's locations, as appropriate.	
E1.12	A policy, process, or procedure specifying how the sponsor will:	§60.13; QPS Appendices A, B, C, and D.
E1.12.a	Ensure that the data made available to the responsible Flight Standards of- fice (the validation data package) includes the aircraft manufacturer's flight test data (or other data approved by the responsible Flight Standards of- fice) and all relevant data developed after the type certificate was issued (e.g., data developed in response to an airworthiness directive) if the data results from a change in performance, handling qualities, functions, or other characteristics of the aircraft that must be considered for flight crew- member training, evaluation, or experience requirements.	b, c, and b.
E1.12.b	Notify the responsible Flight Standards office within 10 working days of be- coming aware that an addition to or a revision of the flight related data or airplane systems related data is available if this data is used to program or operate a qualified FSTD.	
E1.12.c	Maintain a liaison with the manufacturer of the aircraft being simulated (or with the holder of the aircraft type certificate for the aircraft being simulated if the manufacturer is no longer in business), and if appropriate, with the person who supplied the aircraft data package for the FFS for the purposes of receiving notification of data package changes.	
E1.13	A policy, process, or procedure specifying how the sponsor will make available all special equipment and qualified personnel needed to conduct tests during initial, continuing qualification, or special evaluations.	§ 60.14.
E1.14	A policy, process, or procedure specifying how the sponsor will submit to the responsible Flight Standards office a request to evaluate the FSTD for initial qualification at a specific level and simultaneously request the TPAA forward a concurring letter to the responsible Flight Standards office; including how the MR will use qualified personnel to confirm the following:.	§ 60.15(a)–(d); § 60.15(b); § 60.15(b)(i); § 60.15(b)(ii); § 60.15(b)(iii).
E1.14.a	That the performance and handling qualities of the FSTD represent those of the aircraft or set of aircraft within the normal operating envelope.	
E1.14.b	The FSTD systems and sub-systems (including the simulated aircraft systems) functionally represent those in the aircraft or set of aircraft.	
E1.14.c	The flight deck represents the configuration of the specific type or aircraft make, model, and series aircraft being simulated, as appropriate.	
E1.15	A policy, process, or procedure specifying how the subjective and objective tests are completed at the sponsor's training facility for an initial evaluation.	§ 60.15(e).
E1.16	A policy, process, or procedure specifying how the sponsor will update the QTG with the results of the FAA-witnessed tests and demonstrations together with the results of the objective tests and demonstrations after the responsible Flight Standards office completes the evaluation for initial qualification.	§ 60.15(h).
E1.17	A policy, process, or procedure specifying how the sponsor will make the MQTG available to the responsible Flight Standards office upon request.	§ 60.15(i).
E1.18	A policy, process, or procedure specifying how the sponsor will apply to the responsible Flight Standards office for additional qualification(s) to the SOQ.	§ 60.16(a); § 60.16(a)(1)(i); and § 60.16(a)(1)(ii).
E1.19	A policy, process, or procedure specifying how the sponsor completes all required Attachment 2 objective tests each year in a minimum of four evenly spaced inspections as specified in the appropriate QPS.	§ 60.19(a)(1) QPS Appendices A, B, C, or D.
E1.20	A policy, process, or procedure specifying how the sponsor completes and records a functional preflight check of the FSTD within the preceding 24 hours of FSTD use, including a description of the functional preflight.	§ 60.19(a)(2) QPS Appendices A, B, C, or D.
E1.21	A policy, process, or procedure specifying how the sponsor schedules continuing qualification evaluations with the responsible Flight Standards office.	§ 60.19(b)(2).
E1.22	A policy, process, or procedure specifying how the sponsor ensures that the FSTD has received a continuing qualification evaluation at the interval described in the MQTG.	§ 60.19(b)(5)–(6).
E1.23	A policy, process, or procedure describing how discrepancies are recorded in the FSTD discrepancy log, including.	§ 60.19(c); § 60.19(c)(2)(i); § 60.19(c)(2)(ii).
E1.23.a	A description of how the discrepancies are entered and maintained in the log until corrected.	
E1.23.b	A description of the corrective action taken for each discrepancy, the identity of the individual taking the action, and the date that action is taken.	

TABLE E1—FSTD QUALITY MANAGEMENT SYSTEM—Continued

Entry No.	QPS Requirement	Information (Reference)
E1.24	A policy, process, or procedure specifying how the discrepancy log is kept in a form and manner acceptable to the Administrator and kept in or adjacent to the FSTD. (An electronic log that may be accessed by an appropriate	§ 60.19(c)(2)(iii).
E1.25	terminal or display in or adjacent to the FSTD is satisfactory.). A policy, process, or procedure that requires each instructor, check airman, or representative of the Administrator conducting training, evaluation, or flight experience, and each person conducting the preflight inspection, who discovers a discrepancy, including any missing, malfunctioning, or inoperative components in the FSTD, to write or cause to be written a description of that discrepancy into the discrepancy log at the end of the FSTD preflight or FSTD use session.	§ 60.20.
E1.26	A policy, process, or procedure specifying how the sponsor will apply for initial qualification based on the final aircraft data package approved by the aircraft manufacturer if operating an FSTD based on an interim qualification.	§ 60.21(c).
E1.27	A policy, process, or procedure specifying how the sponsor determines whether an FSTD change qualifies as a modification as defined in §60.23.	§ 60.23(a)(1)–(2).
E1.28	A policy, process, or procedure specifying how the sponsor will ensure the FSTD is modified in accordance with any FSTD Directive regardless of the original qualification basis.	§ 60.23(b).
E1.29	A policy, process, or procedure specifying how the sponsor will notify the re- sponsible Flight Standards office and TPAA of their intent to use a modi- fied FSTD and to ensure that the modified FSTD will not be used prior to:	§ 60.23(c)(1)(i),(ii), and (iv).
E1.29.a	Twenty-one days since the sponsor notified the responsible Flight Standards office and the TPAA of the proposed modification and the sponsor has not received any response from either the responsible Flight Standards office or the TPAA; or.	
E1.29.b	Twenty-one days since the sponsor notified the responsible Flight Standards office and the TPAA of the proposed modification and one has approved	
E1.29.c	the proposed modification and the other has not responded; or. The FSTD successfully completing any evaluation the responsible Flight Standards office may require in accordance with the standards for an evaluation for initial qualification or any part thereof before the modified FSTD is placed in service.	
E1.30	A policy, process, or procedure specifying how, after an FSTD modification is approved by the responsible Flight Standards office, the sponsor will: Post an addendum to the SOQ until as the responsible Flight Standards of-	§ 60.23(d)–(e).
E1.30.b	fice issues a permanent, updated SOQ. Update the MQTG with current objective test results and appropriate objective data for each affected objective test or other MQTG section affected by the modification.	
E1.30.c	File in the MQTG the requirement from the responsible Flight Standards of- fice to make the modification and the record of the modification completion.	
E1.31	A policy, process, or procedure specifying how the sponsor will track the length of time a component has been missing, malfunctioning, or inoperative (MMI), including:	§ 60.25(b)–(c), and QPS Appendices A, B, C, or D.
E1.31.a	How the sponsor will post a list of MMI components in or adjacent to the FSTD.	
E1.31.b	How the sponsor will notify the responsible Flight Standards office if the MMI has not been repaired or replaced within 30 days.*. A policy, process, or procedure specifying how the sponsor will notify the re-	§ 60.27(a)(3).
21.02.	sponsible Flight Standards office and how the sponsor will seek requalification of the FSTD if the FSTD is moved and reinstalled in a different location.	300.27(0)(0).
E1.33	A policy, process, or procedure specifying how the sponsor will maintain control of the following: (The sponsor must specify how these records are maintained in plain language form or in coded form; but if the coded form is used, the sponsor must specify how the preservation and retrieval of information will be conducted.).	§ 60.31.
E1.33.a E1.33.b	The MQTG and each amendment. A record of all FSTD modifications required by this part since the issuance of the original SOQ.	
E1.33.c	Results of the qualification evaluations (initial and each upgrade) since the issuance of the original SOQ.	
E1.33.d	Results of the objective tests conducted in accordance with this part for a period of 2 years.	
E1.33.e	Results of the previous three continuing qualification evaluations, or the continuing qualification evaluations from the previous 2 years, whichever covers a longer period.	
E1.33.f	Comments obtained in accordance with § 60.9(b);.	

Entry No.	QPS Requirement	Information (Reference)
E1.33.g	A record of all discrepancies entered in the discrepancy log over the previous 2 years, including the following:	
E1.33.g.1	A list of the components or equipment that were or are missing, malfunctioning, or inoperative.	
E1.33.g.2	The action taken to correct the discrepancy.	
E1.33.g.3	The date the corrective action was taken.	
E1.33.g.4	The identity of the person determining that the discrepancy has been corrected	

^{*}Note: If the sponsor has an approved discrepancy prioritization system, this item is satisfied by describing how discrepancies are prioritized, what actions are taken, and how the sponsor will notify the responsible Flight Standards office if the MMI has not been repaired or replaced within the specified timeframe.

[Doc. No. FAA-2002-12461, 73 FR 26490, May 9, 2008, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75842, Dec. 9, 2022]

APPENDIX F TO PART 60—DEFINITIONS AND ABBREVIATIONS FOR FLIGHT SIMULATION TRAINING DEVICES

BEGIN INFORMATION

1. Some of the definitions presented below are repeated from the definitions found in 14 CFR part 1, as indicated parenthetically

END INFORMATION

BEGIN QPS REQUIREMENTS

2. Definitions

1st Segment—the portion of the takeoff profile from liftoff to gear retraction.

2nd Segment—the portion of the takeoff profile from after gear retraction to initial flap/slat retraction.

 $3rd\ Segment$ —the portion of the takeoff profile after flap/slat retraction is complete.

Aircraft Data Package—a combination of the various types of data used to design, program, manufacture, modify, and test the FSTD.

Airspeed—calibrated airspeed unless otherwise specified and expressed in terms of nautical miles per hour (knots).

Airport Model-

Class I. Whether modeling real world or fictional airports (or landing areas for helicopters), these airport models (or landing areas for helicopters) are those that meet the requirements of Table A3B or C3B, found in attachment 2 of Appendix A or C, as appropriate, are evaluated by the responsible Flight Standards office, and are listed on the SOQ.

Class II. Whether modeling real world or fictional airports (or landing areas for helicopters), these airport models (or landing areas for helicopters) are those models that are in excess of those used for simulator qualification at a specified level. The FSTD sponsor is responsible for determining that these models meet the requirements set out in Table A3C or C3C, found in attachment 2 of Appendix A or C, as appropriate.

Class III. This is a special class of airport model (or landing area for helicopters), used for specific purposes, and includes models that may be incomplete or inaccurate when viewed without restriction, but when appropriate limits are applied (e.g., "valid for use only in visibility conditions less than ½ statute mile or RVR2400 feet," "valid for use only for approaches to Runway 22L and 22R''), those features that may be incomplete or inaccurate may not be able to be recognized as such by the crewmember being trained, tested, or checked. Class III airport models used for training, testing, or checking activities under this Chapter requires the certificate holder to submit to the TPAA an appropriate analysis of the skills, knowledge, and abilities necessary for competent performance of the task(s) in which this particular model is to be used, and requires TPAA acceptance of each Class III model.

Altitude—pressure altitude (meters or feet) unless specified otherwise.

Angle of Attack—the angle between the airplane longitudinal axis and the relative wind vector projected onto the airplane plane of symmetry.

Automatic Testing—FSTD testing where all stimuli are under computer control.

Bank—the airplane attitude with respect to or around the longitudinal axis, or roll angle (degrees).

Breakout—the force required at the pilot's primary controls to achieve initial movement of the control position.

Closed Loop Testing—a test method where the input stimuli are generated by controllers that drive the FSTD to follow a pre-defined target response.

Computer Controlled Aircraft—an aircraft where all pilot inputs to the control surfaces are transferred and augmented by computers.

Confined Area (helicopter operations)—an area where the flight of the helicopter is limited in some direction by terrain or the presence of natural or man-made obstructions (e.g., a clearing in the woods, a city street, or a road bordered by trees or power lines are regarded as confined areas).

Control Sweep—movement of the appropriate pilot controller from neutral to an extreme limit in one direction (Forward, Aft, Right, or Left), a continuous movement back through neutral to the opposite extreme position, and then a return to the neutral position.

Convertible FSTD—an FSTD in which hardware and software can be changed so that the FSTD becomes a replica of a different model, usually of the same type aircraft. The same FSTD platform, flight deck shell, motion system, visual system, computers, and peripheral equipment can be used in more than one simulation.

Critical Engine Parameter—the parameter that is the most accurate measure of propulsive force.

Deadband—the amount of movement of the input for a system for which there is no reaction in the output or state of the system observed.

Distance—the length of space between two points, expressed in terms of nautical miles unless otherwise specified.

Discrepancy—as used in this part, an aspect of the FSTD that is not correct with respect to the aircraft being simulated. This includes missing, malfunctioning, or inoperative components that are required to be present and operate correctly for training, evaluation, and experience functions to be creditable. It also includes errors in the documentation used to support the FSTD (e.g., MQTG errors, information missing from the MQTG, or required statements from appropriately qualified personnel).

Downgrade—a permanent change in the qualification level of an FSTD to a lower level.

Driven—a test method where the input stimulus or variable is positioned by automatic means, usually a computer input.

Electronic Copy of the MQTG—an electronic copy of the MQTG provided by an electronic scan presented in a format, acceptable to the responsible Flight Standards office.

Electronic Master Qualification Test Guide—an electronic version of the MQTG (eMQTG), where all objective data obtained from airplane testing, or another approved source, together with correlating objective test results obtained from the performance of the FSTD and a description of the equipment necessary to perform the evaluation for the initial and the continuing qualification evaluations is stored, archived, or presented in either reformatted or digitized electronic format.

Engine—as used in this part, the appliance or structure that supplies propulsive force for movement of the aircraft: i.e., The turbine engine for turbine powered aircraft; the turbine engine and propeller assembly for turbo-propeller powered aircraft; and the reciprocating engine and propeller assembly for reciprocating engine powered aircraft. For purposes of this part, engine failure is the failure of either the engine or propeller assembly to provide thrust higher than idle power thrust due to a failure of either the engine or the propeller assembly.

Evaluation—with respect to an individual, the checking, testing, or review associated with flight crewmember qualification, training, and certification under parts 61, 63, 121, or 135 of this chapter. With respect to an FSTD, the qualification activities for the device (e.g., the objective and subjective tests, the inspections, or the continuing qualification evaluations) associated with the requirements of this part.

Fictional Airport—a visual model of an airport that is a collection of "non-real world" terrain, instrument approach procedures, navigation aids, maps, and visual modeling detail sufficient to enable completion of an Airline Transport Pilot Certificate or Type Rating.

Flight Experience—recency of flight experience for landing credit purposes.

Flight Simulation Training Device (FSTD)—a full flight simulator (FFS) or a flight training device (FTD). (Part 1)

Flight Test Data—(a subset of objective data) aircraft data collected by the aircraft manufacturer or other acceptable data supplier during an aircraft flight test program.

Flight Training Device (FTD)—a replica of aircraft instruments, equipment, panels, and controls in an open flight deck area or an enclosed aircraft flight deck replica. It includes the equipment and computer programs necessary to represent aircraft (or set of aircraft) operations in ground and flight conditions having the full range of capabilities of the systems installed in the device as described in part 60 of this chapter and the qualification performance standard (QPS) for a specific FTD qualification level. (Part 1)

Free Response—the response of the FSTD after completion of a control input or disturbance.

Pt. 60, App. F

Frozen—a test condition where one or more variables are held constant with time.

FSTD Approval—the extent to which an FSTD may be used by a certificate holder as authorized by the FAA.

FSTD Directive—a document issued by the FAA to an FSTD sponsor requiring a modification to the FSTD due to a safety-of-flight issue and amending the qualification basis for the FSTD.

FSTD Latency—the additional time for the FSTD to respond to input that is beyond the response time of the aircraft.

FSTD Performance—the overall performance of the FSTD, including aircraft performance (e.g., thrust/drag relationships, climb, range) and flight and ground handling.

Full Flight Simulator (FFS)—a replica of a specific type, make, model, or series aircraft. It includes the equipment and computer programs necessary to represent aircraft operations in ground and flight conditions, a visual system providing an out-of-the-flight deck view, a system that provides cues at least equivalent to those of a three-degree-of-freedom motion system, and has the full range of capabilities of the systems installed in the device as described in part 60 of this chapter and the QPS for a specific FFS qualification level. (Part 1)

Gate Clutter—the static and moving ground traffic (e.g., other airplanes; tugs; power or baggage carts; fueling, catering, or cargo trucks; pedestrians) presented to pose a potential conflict with the simulated aircraft during ground operations around the point where the simulated airplane is to be parked between flights

Generic Airport Model—a Class III visual model that combines correct navigation aids for a real world airport with a visual model that does not depict that same airport.

Grandfathering-as used in this part, the practice of assigning a qualification basis for an FSTD based on the period of time during which a published set of standards governed the requirements for the initial and continuing qualification of FSTDs. Each FSTD manufactured during this specified period of time is "grandfathered" or held to the standards that were in effect during that time period. The grandfathered standards remain applicable to each FSTD manufactured during the stated time period regardless of any subsequent modification to those standards and regardless of the sponsor, as long as the FSTD remains qualified or is maintained in a non-qualified status in accordance with the specific requirements and time periods prescribed in this part.

Gross Weight—For objective test purposes: Basic Operating Weight (BOW)—the empty

Basic Operating Weight (BOW)—the empty weight of the aircraft plus the weight of the following: Normal oil quantity; lavatory servicing fluid; potable water; required crew-

members and their baggage; and emergency equipment.

Light Gross Weight—a weight chosen by the sponsor or data provider that is not more than 120% of the BOW of the aircraft being simulated or the minimum practical operating weight of the test aircraft.

Medium Gross Weight—a weight chosen by the sponsor or data provider that is within 10% of the average of the numerical values of the BOW and the maximum certificated gross weight.

Near Maximum Gross Weight—a weight chosen by the sponsor or data provider that is not less than the BOW of the aircraft being simulated plus 80% of the difference between the maximum certificated gross weight (either takeoff weight or landing weight, as appropriate for the test) and the BOW.

Ground Effect—the change in aerodynamic characteristics due to of the change in the airflow past the aircraft caused by the proximity of the earth's surface to the airplane.

Hands Off—a test maneuver conducted without pilot control inputs.

Hands On—a test maneuver conducted with pilot control inputs as required.

Heave—FSTD movement with respect to or along the vertical axis.

Height—the height above ground level (or AGL) expressed in meters or feet.

"In Use" Runway—as used in this part, the runway that is currently selected, able to be used for takeoffs and landings, and has the surface lighting and markings required by this part. Also known as the "active" runway.

Integrated Testing—testing of the FSTD so that all aircraft system models are active and contribute appropriately to the results. With integrated testing, none of the models used are substituted with models or other algorithms intended for testing only.

Irreversible Control System—a control system where movement of the control surface will not backdrive the pilot's control on the flight deck.

Locked—a test condition where one or more variables are held constant with time.

Manual Testing—FSTD testing conducted without computer inputs except for initial setup, and all modules of the simulation are active.

Master Qualification Test Guide (MQTG) the FAA-approved Qualification Test Guide with the addition of the FAA-witnessed test results, applicable to each individual FSTD.

Medium—the normal operational weight for a given flight segment.

Near Limiting Performance—the performance level the operating engine must be required to achieve to have sufficient power to land a helicopter after experiencing a single engine failure during takeoff of a multiengine helicopter. The operating engine must be required to operate within at least 5 percent of the maximum RPM or temperature

Nominal—the normal operating configuration, atmospheric conditions, and flight parameters for the specified flight segment.

Non-Normal Control—a term used in reference to Computer Controlled Aircraft. It is the state where one or more of the intended control, augmentation, or protection functions are not fully working. Note: Specific terms such as ALTERNATE, DIRECT, SECONDARY, or BACKUP may be used to define an actual level of degradation.

Normal Control—a term used in reference to Computer Controlled Aircraft. It is the state where the intended control, augmentation, and protection functions are fully working.

Objective Data—quantitative data, acceptable to the NSPM, used to evaluate the FSTD

Objective Test—a quantitative measurement and evaluation of FSTD performance.

Pitch—the airplane attitude with respect to, or around, the lateral axis expressed in degrees.

Power Lever Angle (PLA)—the angle of the pilot's primary engine control lever(s) on the flight deck. This may also be referred to as THROTTLE or POWER LEVER.

Predicted Data—estimations or extrapolations of existing flight test data or data from other simulation models using engineering analyses, engineering simulations, design data, or wind tunnel data.

Protection Functions—systems functions designed to protect an airplane from exceeding its flight maneuver limitations.

Pulse Input—a step input to a control followed by an immediate return to the initial position

Qualification Level—the categorization of an FSTD established by the NSPM based on the FSTDs demonstrated technical and operational capabilities as prescribed in this part.

Qualification Performance Standard (QPS)—the collection of procedures and criteria used when conducting objective and subjective tests, to establish FSTD qualification levels. The QPS are published in the appendices to this part, as follows: Appendix A, for Airplane Simulators; Appendix B, for Airplane Flight Training Devices; Appendix C, for Helicopter Simulators; Appendix D, for Helicopter Flight Training Devices; Appendix E, for Quality Management Systems for Flight Simulation Training Devices; and Appendix F, for Definitions and Abbreviations for Flight Simulation Training Devices.

Qualification Test Guide (QTG)—the primary reference document used for evaluating an aircraft FSTD. It contains test results, statements of compliance and capa-

bility, the configuration of the aircraft simulated, and other information for the evaluator to assess the FSTD against the applicable regulatory criteria.

Quality Management System (QMS)—a flight simulation quality-systems that can be used for external quality-assurance purposes. It is designed to identify the processes needed, determine the sequence and interaction of the processes, determine criteria and methods required to ensure the effective operation and control of the processes, ensure the availability of information necessary to support the operation and monitoring of the processes, measure, monitor, and analyze the processes, and implement the actions necessary to achieve planned results.

Real-World Airport—as used in this part in reference to airport visual models, a computer generated visual depiction of an existing airport.

Representative—when used as an adjective in this part, typical, demonstrative, or characteristic of, the feature being described. For example, "representative sampling of tests" means a sub-set of the complete set of all tests such that the sample includes one or more of the tests in each of the major categories, the results of which provide the evaluator with an overall understanding of the performance and handling characteristics of the FSTD.

Reversible Control System—a control system in which movement of the control surface will backdrive the pilot's control on the flight deck.

Roll—the airplane attitude with respect to, or around, the longitudinal axis expressed in degrees.

Set of Aircraft—aircraft that share similar handling and operating characteristics, similar operating envelopes, and have the same number and type of engines or powerplants.

Sideslip Angle—the angle between the relative wind vector and the airplane plane of symmetry. (Note: this definition replaces the current definition of "sideslip.")

Simulation Quality Management System (SQMS)—the elements of a quality management system for FSTD continuing qualification.

Snapshot—a presentation of one or more variables at a given instant of time.

Special Evaluation—an evaluation of the FSTD for purposes other than initial, upgrade, or continuing qualification. Circumstances that may require a special evaluation include movement of the FSTD to a different location, or an update to FSTD software or hardware that might affect performance or flying qualities.

Sponsor—a certificate holder who seeks or maintains FSTD qualification and is responsible for the prescribed actions as prescribed in this part and the QPS for the appropriate FSTD and qualification level.

Pt. 60, App. F

Statement of Compliance and Capability (SOC)—a declaration that a specific requirement has been met and explaining how the requirement was met (e.g., gear modeling approach, coefficient of friction sources). The SOC must also describe the capability of the FSTD to meet the requirement, including references to sources of information for showing compliance, rationale to explain how the referenced material is used, mathematical equations and parameter values used, and conclusions reached.

Step Input—an abrupt control input held at a constant value.

Subjective Test—a qualitative assessment of the performance and operation of the FSTD. Surge—FSTD movement with respect to or along the longitudinal axis.

Sway—FSTD movement with respect to or along the lateral axis.

T_f-Total time of the flare maneuver.

Ti—Total time from initial throttle movement until a 10% response of a critical engine parameter.

T.—Total time from initial throttle movement to an increase of 90% of go around power or a decrease of 90% from maximum take-off power.

Time History—a presentation of the change of a variable with respect to time.

Training Program Approval Authority (TPAA)—a person authorized by the Administrator to approve the aircraft flight training program in which the FSTD will be used.

Training Restriction—a temporary condition where an FSTD with missing, malfunctioning, or inoperative (MMI) components may continue to be used at the qualification level indicated on its SOQ, but restricted from completing the tasks for which the correct function of the MMI component is required.

Transport Delay or "Throughput"—the total FSTD system processing time required for an input signal from a pilot primary flight control until motion system, visual system, or instrument response. It is the overall time delay incurred from signal input to output response. It does not include the characteristic delay of the airplane simulated.

Update—an improvement to or modernization of the quality or the accuracy of the FSTD without affecting the qualification level of the FSTD.

Upgrade—the improvement or enhancement of an FSTD for the purpose of achieving a higher qualification level.

Validation Data—objective data used to determine if the FSTD performance is within the tolerances prescribed in the QPS.

Validation Test—an objective test where FSTD parameters are compared to the relevant validation data to ensure that the FSTD performance is within the tolerances prescribed in the QPS.

Visual Data Base—a display that may include one or more airport models.

Visual System Response Time—the interval from a control input to the completion of the visual display scan of the first video field containing the resulting different information.

Yaw—the airplane attitude with respect to, or around, the vertical axis expressed in degrees.

3. Abbreviations

AFM Airplane Flight Manual.

AGL Above Ground Level (meters or feet).

AOA Angle of Attack (degrees).

APD Aircrew Program Designee.

CCA Computer Controlled Aircraft.

cd/m2 candela/meter², 3.4263 candela/m² = 1 ft-Lambert.

CFR Code of Federal Regulations.

cm(s) centimeter, centimeters.

daN decaNewtons, one (1) decaNewton = 2.27 pounds.

deg(s) degree, degrees.

DOF Degrees-of-freedom.

 $\begin{array}{ll} \mathbf{eMQTG} & \mathbf{Electronic} & \mathbf{Master} & \mathbf{Qualification} \\ \mathbf{Test} & \mathbf{Guide}. \end{array}$

 ${\bf EPR}\quad {\bf Engine\ Pressure\ Ratio}.$

FAA Federal Aviation Administration (U.S.).

FATO Final Approach and Take Off area fpm feet per minute.

ft foot/feet, 1 foot = 0.304801 meters.

ft-Lambert foot-Lambert, 1 ft-Lambert = 3.4263 candela/m².

g Acceleration due to Gravity (meters or feet/sec²); 1g = 9.81 m/sec² or 32.2 feet/sec². G/S Glideslope.

IATA International Airline Transport Association.

ICAO International Civil Aviation Organization.

IGE In ground effect.

ILS Instrument Landing System.

IOS Instructor Operating Station.

IQTG International Qualification Test Guide.

km Kilometers; 1 km = 0.62137 Statute Miles.

k Pa Kilo
Pascal (Kilo Newton/Meters2). 1 psi = 6.89476 k Pa.

kts Knots calibrated airspeed unless otherwise specified, 1 knot = 0.5148 m/sec or 1.689 ft/sec.

lb(s) pound(s), one (1) pound = 0.44 decaNewton.

LDP Landing decision point.

MQTG Master Qualification Test Guide M,m Meters, 1 Meter = 3.28083 feet.

Min(s) Minute, minutes.

MLG Main Landing Gear.

Mpa MegaPascals (1 psi = 6894.76 pascals). ms millisecond(s).

N NORMAL CONTROL Used in reference to Computer Controlled Aircraft.

nm Nautical Mile(s) 1 Nautical Mile = 6,080 feet.

NN NON-NORMAL CONTROL Used in reference to Computer Controlled Aircraft.

N1 Low Pressure Rotor revolutions per minute, expressed in percent of maximum. N2 High Pressure Rotor revolutions per

minute, expressed in percent of maximum. N3 High Pressure Rotor revolutions per minute, expressed in percent of maximum. NWA Nosewheel Angle (degrees).

OGE Out of ground effect.

PAPI Precision Approach Path Indicator System.

Pf Impact or Feel Pressure, often expressed

PLA Power Lever Angle.

PLF Power for Level Flight.

psi pounds per square inch.

QPS Qualification Performance Standard.

QTG Qualification Test Guide.

RAE Royal Aerospace Establishment.

R/C Rate of Climb (meters/sec or feet/min). R/D Rate of Descent (meters/sec or feet/ min).

REIL Runway End Identifier Lights. RVR Runway Visual Range (meters or feet).

s second(s).

sec(s) second, seconds.

sm Statute Mile(s) 1 Statute Mile = 5,280 feet.

SMGCS Surface Movement Guidance and Control System.

SOC Statement of Compliance and Capability.

SOQ Statement of Qualification.

TIR Type Inspection Report.

TLOF Touchdown and Loft Off area.

T/O Takeoff.

VASI Visual Approach Slope Indicator System.

VGS Visual Ground Segment.

V₁ Decision speed.

V₂ Takeoff safety speed.

Vmc Minimum Control Speed.

Vmca Minimum Control Speed in the air. Vmcg Minimum Control Speed on the ground.

Vmcl Minimum Control Speed—Landing. Vmu The speed at which the last main landing gear leaves the ground.

V_R Rotate Speed.

V_s Stall Speed or minimum speed in the stall.

WAT Weight, Altitude, Temperature.

END QPS REQUIREMENTS

[Doc. No. FAA-2002-12461, 73 FR 26490, May 9, 2008, as amended by Docket No. FAA-2022-1355, Amdt. No. 60-7, 87 FR 75845, Dec. 9, 2022]

PART 61—CERTIFICATION: PILOTS INSTRUCTORS, FLIGHT AND **GROUND INSTRUCTORS**

SPECIAL FEDERAL AVIATION REGULATION NO.

SPECIAL FEDERAL AVIATION REGULATION NO. 100-2

Subpart A—General

Sec.

- 61.1 Applicability and definitions.
- Exercise of Privilege.
- 61.3 Requirement for certificates, ratings, and authorizations.
- 61.4 Qualification and approval of flight simulators and flight training devices.
- 61.5 Certificates and ratings issued under this part.
- 61.7 Obsolete certificates and ratings.
- 61.8 Inapplicability of unmanned aircraft operations.

61.9 [Reserved]

61.11 Expired pilot certificates and reissuance.

61.13 Issuance of airman certificates, ratings, and authorizations.

61.14 [Reserved]

61.15 Offenses involving alcohol or drugs.

61.16 Refusal to submit to an alcohol test or to furnish test results.

61.17 Temporary certificate.

61.18 [Reserved]

61.19 Duration of pilot and instructor certificates and privileges.

61.21 Duration of a Category II and a Category III pilot authorization (for other than part 121 and part 135 use)

61.23 Medical certificates: Requirement and duration.

61.25 Change of name.

61.27 Voluntary surrender or exchange of certificate.

61.29 Replacement of a lost or destroyed airman or medical certificate or knowledge test report.

61.31 Type rating requirements, additional training, and authorization requirements.

61.33 Tests: General procedure.

61.35 Knowledge test: Prerequisites and passing grades.

61.37 Knowledge tests: Cheating or other unauthorized conduct.

61.39 Prerequisites for practical tests.

61.41 Flight training received from flight instructors not certificated by the FAA.

61.43 Practical tests: General procedures.

61.45 Practical tests: Required aircraft and equipment.

61.47 Status of an examiner who is authorized by the Administrator to conduct practical tests.

61.49 Retesting after failure.

61.51 Pilot logbooks.

61.52 Use of aeronautical experience obtained in ultralight vehicles.

61.53 Prohibition on operations during medical deficiency.

61.55 Second-in-command qualifications.

61.56 Flight review.

459