§ 62.25–20 Instrumentation, alarms, and centralized stations.

(a) General. Minimum instrumentation and alarms required for specific types of automated vital systems are listed in Table 62.35–50.

(b) Instrumentation Location.

(1) Manual control locations, including remote manual control and manual alternate control, must be provided with the instrumentation necessary for safe operation from that location.

NOTE: Typically, instrumentation includes means to monitor the output of the monitored system.

(2) Systems with remote instrumentation must have provisions for the installation of instrumentation at the monitored system equipment.

(3) The status of automatically or remotely controlled vital auxiliaries, power sources, switches, and valves must be visually indicated in the machinery spaces or the cognizant remote control location, as applicable.

NOTE: Status indicators include run, standby, off, open, closed, tripped, and on, as applicable. Status indicators at remote control locations other than the ECC, if provided, may be summarized. Equipment normally provided with status indicators are addressed in Table 62.35–50 and subparts 58.01, 56.50, and 112.45.

(4) Sequential interlocks provided in control systems to ensure safe operation, such as boiler programming control or reversing of propulsion diesels, must have summary indicators in the machinery spaces and at the cognizant remote control location to show if the interlocks are satisfied.

(5) Instrumentation listed in Table 62.35–50 must be of the continuous display type or the demand display type. Displays must be in the ECC or in the machinery spaces if an ECC is not provided.

(c) Instrumentation details. Demand instrumentation displays must be clearly readable and immediately available to the operator.

(d) Alarms.

(1) All alarms must clearly distinguish among—

(i) Normal, alarm, and acknowledged alarm conditions; and

(ii) Fire, general alarm, carbon dioxide/Halon 1301/clean agent fire extinguishing system, vital machinery, flooding, engineers’ assistance-needed, and non-vital alarms.

(2) Required alarms in high ambient noise areas must be supplemented by visual means, such as rotating beacons, that are visible throughout these areas. Red beacons must only be used for general or fire alarm purposes.

(3) Automatic transfer to required backup or redundant systems or power sources must be alarmed in the machinery spaces.

(4) Flooding safety, fire, loss of power, and engineers’ assistance-needed alarms extended from the machinery spaces to a remote location must not have a duty crewmember selector.

NOTE: Other alarms may be provided with such a selector, provided there is no off position.

(5) Automation alarms must be separate and independent of the following:

(i) The fire detection and alarm systems.

(ii) The general alarm.

(iii) CO₂/halon release alarms.

(iv) Failure of an automatic control, remote control, or alarm system must be immediately alarmed in the machinery spaces and at the ECC, if provided.

(e) Alarm details.

(1) All alarms must—

(i) Have a manual acknowledgement device (No other means to reduce or eliminate the annunciated signal may be provided except dimmers described in paragraph (g)(2) of this section);

(ii) Be continuously powered;

(iii) Be provided with a means to test audible and visual annunciators;

(iv) Provide for normal equipment starting and operating transients and vessel motions, as applicable, without actuating the alarm;

(v) Be able to simultaneously indicate more than one alarm condition, as applicable;

(a) Programmable control or alarm system logic must not be altered after Design Verification testing without the approval of the cognizant Officer in Charge, Marine Inspection (OCMI). (See subpart 61.40 of this subchapter, Design Verification Tests). Safety control or automatic alarm systems must be provided with means, acceptable to the cognizant OCMI, to make sure setpoints remain within the safe operating range of the equipment.

(b) Operating programs for microprocessor-based or computer-based vital control, alarm, and monitoring systems must be stored in non-volatile memory and automatically operate on supply power resumption.

(c) If a microprocessor-based or computer-based system serves both vital and non-vital systems, hardware and software priorities must favor the vital systems.

(d) At least one copy of all required manuals, records, and instructions for automatic or remote control or monitoring systems required to be aboard the vessel must not be stored in electronic or magnetic memory.

§ 62.25–30 Environmental design standards.

(a) All automation must be suitable for the marine environment and must be designed and constructed to operate indefinitely under the following conditions:

(1) Ship motion and vibration described in Table 9 of section 4–9–7 of the ABS Steel Vessel Rules (incorporated by reference; see 46 CFR 62.05–1); note that inclination requirements for fire and flooding safety systems are described in 46 CFR 112.05–5(c).

(2) Ambient air temperatures described in Table 9 of part 4–9–7 of the ABS Steel Vessel Rules.

(3) Electrical voltage and frequency tolerances described in Table 9 of part 4–9–7 of the ABS Steel Vessel Rules.

(4) Relative humidity of 0 to 95% at 45 °C.