§ 23.181 Dynamic stability.

(a) Any short period oscillation not including combined lateral-directional oscillations occurring between the stalling speed and the maximum allowable speed \( V_{YS}, V_{LS}, V_{NO}, V_{FC/MFC} \) appropriate to the configuration of the airplane must be heavily damped with the primary controls—

(1) Free; and

(2) In a fixed position.

(b) Any combined lateral-directional oscillations (Dutch roll) occurring between the stalling speed and the maximum allowable speed \( V_{YS}, V_{LS}, V_{NO}, V_{FC/MFC} \) appropriate to the configuration of the airplane with the primary controls in both free and fixed position, must be damped to \( \frac{1}{10} \) amplitude in:

(1) Seven (7) cycles below 18,000 feet and

(2) Thirteen (13) cycles from 18,000 feet to the certified maximum altitude.

(c) If it is determined that the function of a stability augmentation system, reference § 23.672, is needed to meet the flight characteristic requirements of this part, the primary control requirements of paragraphs (a)(2) and (b)(2) of this section are not applicable to the tests needed to verify the acceptability of that system.

(d) During the conditions as specified in § 23.175, when the longitudinal control force required to maintain speeds differing from the trim speed by at least plus and minus 15 percent is suddenly released, the response of the airplane must not exhibit any dangerous characteristics nor be excessive in relation to the magnitude of the control force released. Any long-period oscillation of flight path, phugoid oscillation, that results must not be so unstable as to increase the pilot’s workload or otherwise endanger the airplane.

§ 23.201 Wings level stall.

(a) It must be possible to produce and to correct roll by unreversed use of the rolling control and to produce and to correct yaw by unreversed use of the directional control, up to the time the airplane stalls.

(b) The wings level stall characteristics must be demonstrated in flight as follows. Starting from a speed at least 10 knots above the stall speed, the elevator control must be pulled back so that the rate of speed reduction will not exceed one knot per second until a stall is produced, as shown by either:

(1) An uncontrollable downward pitching motion of the airplane;
(2) A downward pitching motion of the airplane that results from the activation of a stall avoidance device (for example, stick pusher); or
(3) The control reaching the stop.

(c) Normal use of elevator control for recovery is allowed after the downward pitching motion of paragraphs (b)(1) or (b)(2) of this section has unmistakably been produced, or after the control has been held against the stop for not less than the longer of two seconds or the time employed in the minimum steady slight speed determination of §23.49.

(d) During the entry into and the recovery from the maneuver, it must be possible to prevent more than 15 degrees of roll or yaw by the normal use of controls except as provided for in paragraph (e) of this section.

(e) For airplanes approved with a maximum operating altitude at or above 25,000 feet during the entry into and the recovery from stalls performed at or above 25,000 feet, it must be possible to prevent more than 25 degrees of roll or yaw by the normal use of controls.

(f) Compliance with the requirements of this section must be shown under the following conditions:

(1) Wing flaps: Retracted, fully extended, and each intermediate normal operating position, as appropriate for the phase of flight.
(2) Landing gear: Retracted and extended as appropriate for the altitude.
(3) Cowl flaps: Appropriate to configuration.
(4) Spoilers/speedbrakes: Retracted and extended unless they have no measurable effect at low speeds.
(5) Power:
   (i) Power/Thrust off; and
   (ii) For reciprocating engine powered airplanes: 75 percent of maximum continuous power. However, if the power-to-weight ratio at 75 percent of maximum continuous power results in nose-high attitudes exceeding 30 degrees, the test may be carried out with the power required for level flight in the landing configuration at maximum landing weight and a speed of 1.4 V_so, except that the power may not be less than 50 percent of maximum continuous power; or
   (iii) For turbine engine powered airplanes: The maximum engine thrust, except that it need not exceed the thrust necessary to maintain level flight at 1.5 V_so (where V_so corresponds to the stalling speed with flaps in the approach position, the landing gear retracted, and maximum landing weight).
   (6) Trim: At 1.5 V_so, or the minimum trim speed, whichever is lower.
   (7) Propeller: Full increase r.p.m. position for the power off condition.


§ 23.203 Turning flight and accelerated turning stalls.

Turning flight and accelerated turning stalls must be demonstrated in tests as follows:

(a) Establish and maintain a coordinated turn in a 30 degree bank. Reduce speed by steadily and progressively tightening the turn with the elevator until the airplane is stalled, as defined in §23.201(b). The rate of speed reduction must be constant, and—

(1) For a turning flight stall, may not exceed one knot per second; and
(2) For an accelerated turning stall, be 3 to 5 knots per second with steadily increasing normal acceleration.

(b) After the airplane has stalled, as defined in §23.201(b), it must be possible to regain wings level flight by normal use of the flight controls, but without—

(1) Excessive loss of altitude;
(2) Undue pitchup;
(3) Uncontrollable tendency to spin;
(4) Exceeding a bank angle of 60 degrees in the original direction of the turn or 30 degrees in the opposite direction in the case of turning flight stalls; and
(5) Exceeding a bank angle of 90 degrees in the original direction of the turn or 60 degrees in the opposite direction in the case of accelerated turning stalls; and

(6) Exceeding the maximum permissible speed or allowable limit load factor.

(c) Compliance with the requirements of this section must be shown under the following conditions:

(1) Wings flaps: Retracted, fully extended, and each intermediate normal operating position as appropriate for the phase of flight.