

**§ 58.25-60**

must have an instantaneous trip set at a current of at least—

(1) 300% and not more than 375% of the rated full-load current of one steering-gear motor for a direct-current motor; or

(2) 175% and not more than 200% of the locked-rotor current of one steering-gear motor for an alternating-current motor.

(b) No feeder circuit for steering may have any overcurrent protection, except that required by paragraph (a) of this section.

(c) Neither a main or an auxiliary steering-gear motor, nor a motor for a steering-gear control system, may be protected by an overload protective device. The motor must have a device that activates an audible and a visible alarm at the main machinery-control station if there is an overload that would cause overheating of the motor.

(d) No control circuit of a motor controller, steering-gear control system, or indicating or alarm system may have overcurrent protection except short-circuit protection that is instantaneous and rated at 400% to 500% of—

(1) The current-carrying capacity of the conductor; or

(2) The normal load of the system.

(e) The short-circuit protective device for each steering-gear control system must be in the steering-gear compartment and in the control circuit immediately following the disconnect switch for the system.

(f) When, in a vessel of less than 1,600 gross tons, an auxiliary steering gear, which § 58.25-10(c)(3) requires to be operated by power, is not operated by electric power or is operated by an electric motor primarily intended for other service, the main steering gear may be fed by one circuit from the main switchboard. When such an electric motor is arranged to operate an auxiliary steering gear, neither § 58.25-25(e) nor paragraphs (a) through (c) of this section need be complied with if both the overcurrent protection and compliance with §§ 58.25-25(d), 58.25-30, and 58.25-70 (j) and (k) satisfy the Commanding Officer, Marine Safety Center.

**46 CFR Ch. I (10-1-10 Edition)**

**§ 58.25-60 Non-duplicated hydraulic rudder actuators.**

Non-duplicated hydraulic rudder actuators may be installed in the steering-gear control systems on each vessel of less than 100,000 deadweight tons. These actuators must meet IMO A.467(XII) (incorporated by reference, see 46 CFR 58.03-1) and be acceptable to the Commanding Officer, Marine Safety Center. Also, the piping for the main gear must comply with 46 CFR 58.25-10(e)(3).

[USCG-2003-16630, 73 FR 65187, Oct. 31, 2008]

**§ 58.25-65 Feeder circuits.**

(a) Each vessel with one or more electric-driven steering-gear power units must have at least two feeder circuits, which must be separated as widely as practicable. One or more of these circuits must be supplied from the vessel's service switchboard. On a vessel where the rudder stock is over 23 centimeters (9 inches) in diameter in way of the tiller, excluding strengthening for navigation in ice, and where a final source of emergency power is required by § 112.05-5(a) of this chapter, one or more of these circuits must be supplied from the emergency switchboard, or from an alternative source of power that—

(1) Is available automatically within 45 seconds of loss of power from the vessel's service switchboard;

(2) Comes from an independent source of power in the steering-gear compartment;

(3) Is used for no other purpose; and

(4) Has a capacity for one half-hour of continuous operation, to move the rudder from 15° on either side to 15° on the other in not more than 60 seconds with the vessel at its deepest loadline draft and running at one-half maximum ahead service speed or 7 knots, whichever is greater.

(b) Each vessel that has a steering gear with multiple electric-driven power units must be arranged so that each power unit is supplied by a separate feeder.

(c) Each feeder circuit must have a disconnect switch in the steering-gear compartment.

(d) Each feeder circuit must have a current-carrying capacity of—