§ 23.641 Proof of strength.

(c) Any rational analysis used to predict freedom from flutter, control reversal and divergence must cover all speeds up to 1.2 \( V_D \).

(d) Compliance with the rigidity and mass balance criteria (pages 4–12), in Airframe and Equipment Engineering Report No. 45 (as corrected) “Simplified Flutter Prevention Criteria” (published by the Federal Aviation Administration) may be accomplished to show that the airplane is free from flutter, control reversal, or divergence if:

(1) \( V_D/M_D \) for the airplane is less than 260 knots (EAS) and less than Mach 0.5,

(2) The wing and aileron flutter prevention criteria, as represented by the wing torsional stiffness and aileron balance criteria, are limited in use to airplanes without large mass concentrations (such as engines, floats, or fuel tanks in outer wing panels) along the wing span, and

(3) The airplane—

(i) Does not have a T-tail or other unconventional tail configurations;

(ii) Does not have unusual mass distributions or other unconventional design features that affect the applicability of the criteria, and

(iii) Has fixed-fin and fixed-stabilizer surfaces.

(e) For turbopropeller-powered airplanes, the dynamic evaluation must include—

(1) Whirl mode degree of freedom which takes into account the stability of the plane of rotation of the propeller and significant elastic, inertial, and aerodynamic forces, and

(2) Propeller, engine, engine mount, and airplane structure stiffness and damping variations appropriate to the particular configuration.

(f) Freedom from flutter, control reversal, and divergence up to \( V_D/M_D \) must be shown as follows:

(1) For airplanes that meet the criteria of paragraphs (d)(1) through (d)(3) of this section, after the failure, malfunction, or disconnection of any single element in any tab control system.

(2) For airplanes other than those described in paragraph (f)(1) of this section, after the failure, malfunction, or disconnection of any single element in the primary flight control system, any tab control system, or any flutter damper.

(g) For airplanes showing compliance with the fail-safe criteria of §§23.571 and 23.572, the airplane must be shown by analysis to be free from flutter up to \( V_D/M_D \) after fatigue failure, or obvious partial failure, of a principal structural element.

(h) For airplanes showing compliance with the damage tolerance criteria of §23.573, the airplane must be shown by analysis to be free from flutter up to \( V_D/M_D \) with the extent of damage for which residual strength is demonstrated.

(i) For modifications to the type design that could affect the flutter characteristics, compliance with paragraph (a) of this section must be shown, except that analysis based on previously approved data may be used alone to show freedom from flutter, control reversal and divergence, for all speeds up to the speed specified for the selected method.

adjacent fixed structure, when one surface is held in its most critical clearance positions and the others are operated through their full movement.

(b) If an adjustable stabilizer is used, it must have stops that will limit its range of travel to that allowing safe flight and landing.

§ 23.657 Hinges.

(a) Control surface hinges, except ball and roller bearing hinges, must have a factor of safety of not less than 6.67 with respect to the ultimate bearing strength of the softest material used as a bearing.

(b) For ball or roller bearing hinges, the approved rating of the bearing may not be exceeded.

§ 23.659 Mass balance.

The supporting structure and the attachment of concentrated mass balance weights used on control surfaces must be designed for—

(a) 24 g normal to the plane of the control surface;

(b) 12 g fore and aft; and

(c) 12 g parallel to the hinge line.

§ 23.671 General.

(a) Each control must operate easily, smoothly, and positively enough to allow proper performance of its functions.

(b) Controls must be arranged and identified to provide for convenience in operation and to prevent the possibility of confusion and subsequent inadvertent operation.

§ 23.672 Stability augmentation and automatic and power-operated systems.

If the functioning of stability augmentation or other automatic or power-operated systems is necessary to show compliance with the flight characteristics requirements of this part, such systems must comply with §23.671 and the following:

(a) A warning, which is clearly distinguishable to the pilot under expected flight conditions without requiring the pilot’s attention, must be provided for any failure in the stability augmentation system or in any other automatic or power-operated system that could result in an unsafe condition if the pilot was not aware of the failure. Warning systems must not activate the control system.

(b) The design of the stability augmentation system or of any other automatic or power-operated system must permit initial counteraction of failures without requiring exceptional pilot skill or strength, by either the deactivation of the system or a failed portion thereof, or by overriding the failure by movement of the flight controls in the normal sense.

(c) It must be shown that, after any single failure of the stability augmentation system or any other automatic or power-operated system—

1. The airplane is safely controllable when the failure or malfunction occurs at any speed or altitude within the approved operating limitations that is critical for the type of failure being considered;

2. The controllability and maneuverability requirements of this part are met within a practical operational flight envelope (for example, speed, altitude, normal acceleration, and airplane configuration) that is described in the Airplane Flight Manual (AFM); and

3. The trim, stability, and stall characteristics are not impaired below a level needed to permit continued safe flight and landing.

§ 23.673 Primary flight controls.

Primary flight controls are those used by the pilot for the immediate control of pitch, roll, and yaw.

§ 23.675 Stops.

(a) Each control system must have stops that positively limit the range of motion of each movable aerodynamic surface controlled by the system.